

Approximating Dense Cases of Covering Problems

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Abstract

We study dense instances of several covering problems. An instance of the set cover problem with m sets is dense if there is $\epsilon > 0$ such that any element belongs to at least ϵm sets. We show that the dense set cover problem can be approximated with the performance ratio $c \log n$ for any $c > 0$ and it is unlikely to be NP-hard. We construct a polynomial-time approximation scheme for the dense Steiner tree problem in n -vertex graphs, i.e. for the case when each terminal is adjacent to at least ϵn vertices. We also study the vertex cover problem in ϵ -dense graphs. Though this problem is shown to be still MAX-SNP-hard as in general graphs, we find a better approximation algorithm with the performance ratio $\frac{2}{1+\epsilon}$. The *superdense* cases of all these problems are shown to be solvable in polynomial time.

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1 Dense Set Cover Problem

We start with the Dense Set Cover Problem. Let $X = \{x_1, \dots, x_k\}$ be a finite set and $P = \{p_1, \dots, p_m\} \subseteq 2^X$ be a family of its subsets. The **Set Cover Problem** (SCP) asks for a minimum size sub-family M of P such that $X \subseteq \cup\{p|p \in M\}$.

The greedy heuristic gives $1 + \ln k$ approximation for SCP [5]. Moreover, SCP cannot be approximated to within less than $\ln k$ -factor unless $NP \subseteq DTIME[n^{\log \log n}]$ [6].

The B -sparse SCP has a constant upper bound $B > 1$ on the number of sets in P which cover the same element of X . The Vertex Cover Problem is a well-known representative of B -sparse SCP ($B=2$). There is a simple B -approximation algorithm for this problem. From the other side, the B -sparse SCP is MAX SNP-complete.

In an ϵ -dense SCP, any element of X belongs to at least $\epsilon|P|$ sets for some $\epsilon < 1$.

We will analyze the greedy heuristic applied to ϵ -dense SCP. This heuristic repeatedly choose a maximum size set in P , remove its elements from X and all other sets in P . All chosen sets form the output set cover *Greedy*.

Lemma 1 *The size of Greedy is at most $\log_{1/(1-\epsilon)} k$.*

Proof. At first we will show that the maximum size of a set in P is at least ϵk . Consider a bipartite graph $G = (P \cup X, E)$ where $x \in X$ and $p \in P$ are adjacent if and only if $x \in p$. The degree of any $x \in X$ is at least ϵm , so the number of edges in this graph is at least ϵmk and, therefore, there is a set $p \in P$ with degree at least ϵm .

Each iteration of the greedy heuristic does not decrease density, since all elements which belong to the chosen set are removed from X . So the size of X after the i th iteration is at most $(1 - \epsilon)^i k$. \diamond

This lemma shows that the size of the optimal set cover is $O(\log k)$. So we cannot expect that the ϵ -dense SCP is NP-complete, since a simple $O(m^{O(\log k)})$ -time exhaustive search chooses the optimal solution.

Theorem 1 *Unless $NP \subseteq DTIME[n^{\log n}]$, the ϵ -dense SCP is not NP-complete.*

Note that $O(\log k)$ is the tight bound for the performance ratio of the greedy heuristic applied to ϵ -dense SCP. To show this for $\epsilon = \frac{1}{2}$, we can construct an instance of this problem with the size of optimal solution of $O(\log k)$ and then add two sets A and B such that $A \cup B = X$, $A \cap B = \emptyset$. On the other hand, unlike to the general case of SCP, we may decrease the constant factor as far as we want.

Lemma 2 *For any $c > 0$ and $1 > \epsilon > 0$, there is a $c \ln k$ -approximation algorithm for ϵ -dense SCP.*

Proof. Indeed, let transform an instance of ϵ -dense SCP to an instance of $(1 - (1 - \epsilon)^2)$ -dense SCP in the following way. Consider a family $P^2 = \{p \cup q : p, q \in P\}$. It is easy to see that any solution for SCP with the family P^2 gives a solution for initial SCP. An ϵ -density means that at most $(1 - \epsilon)m$ sets do not contain a given element of X . But then at most $(1 - \epsilon)^2 m^2$ sets in P^2 do not contain a given element of X .

Lemma 1 implies that such transformation decrease the performance ratio of the greedy algorithm twice. \diamond

Theorem 1 arises the following two open problems:

Problem 1 *Can ϵ -dense SCP be solved in polynomial time?*

Problem 2 *Can ϵ -dense SCP be approximated in polynomial time to within constant factor?*

Further densification leads to polynomial solvability of SCP. The δ -superdense SCP is the case of SCP where each element of X is covered by at least $m - o(m^\delta)$ sets of P for some $\delta < 1$.

Theorem 2 *The δ -superdense SCP can be solved in polynomial time.*

Proof. Let each element of X is covered by at least $m - \gamma m^\delta = m(1 - \gamma m^{\delta-1})$ sets of P for some $\gamma < m^{1-\delta}$. By Lemma 1 for $\epsilon = 1 - \gamma m^{\delta-1}$, the size of optimal solution is at most

$$\log_{\gamma^{-1}m^{1-\delta}} k = \frac{1}{(1 - \delta)(1 - \log_m \gamma)} \log_m k.$$

Thus, exhaustive search for finding an exact solution has at most $k^{((1-\delta)\delta)^{-1}}$ cases to consider. \diamond

2 Dense Steiner Tree Problem

Consider a connected graph $G = (V, E)$ with a *terminal* set $S \subseteq V$. The **Steiner Tree Problem** (STP) asks for a minimum size tree within G which spans all terminals from S . Further, $d(F)$ denotes the length of a graph F , $|S| = k$ and $|V| = n$. A well-known *minimum spanning tree* heuristic (MSTH) [9] finds a minimum spanning tree M of a weighted complete graph $G' = (S, E', c)$, where the weight of any edge equals to the length of the shortest path between its ends in G . Then MSTH replaces all edges of M with the corresponding paths in G and extracts a tree from the subgraph obtained.

An optimal Steiner tree contains also non-terminals. Each such vertex of degree at least 3 is called a *Steiner point*. It is easy to see that there are at most $k - 2$ Steiner points. Using MSTH we can find an optimal Steiner tree if we add all Steiner points to the terminal set.

Remark 1 *An optimal Steiner tree can be found exactly in $O(n^k)$ time.*

MSTH gives 2-approximation for STP [9] and the best up-today polynomial-time approximation guarantee is about 1.644 [7]. From the other side, STP is known to be MAX SNP - complete [4].

In the *B-sparse* STP the degree of any vertex is bounded by a constant B . It is known that STP in the rectilinear metric (a sub-case of 4-sparse STP) is *NP*-complete but the question whether it is MAX SNP-hard or not is still open.

In an ϵ -dense instance of STP (for some $\epsilon < 1$) any terminal has at least ϵn neighbors outside S .

Note that for $\epsilon > \frac{1}{2}$, ϵ -dense STP is a sub-case of Network STP with distances 1 and 2 which is still MAX SNP-complete [4]. The Rayward-Smith heuristic [8] was proposed for the latter problem in [4]. It achieves a better approximation guarantee ($\frac{4}{3}$) than MSTH which has the tight bound 2 as for the general case. MSTH also does not differ the dense and general case of STP.

If the number of terminals is small enough, i.e. $k \leq \frac{1}{\epsilon}$, then we can find an exact solution in polynomial time. Otherwise, we apply to the dense STP the following variant of Rayward-Smith heuristic (or the greedy algorithm [10]).

Algorithm DSTP

- ```
(0) $SP \leftarrow \emptyset;$
 $\mathcal{C} \leftarrow \{\{s\} : s \in S\}$
(1) while $|\mathcal{C}| > \frac{1}{\epsilon}$ do
 find $v \in V \setminus S$ with the maximum size of
 $D(v) = \{C \in \mathcal{C} : C \text{ contains a neighbor of } v\}$
 $SP \leftarrow SP \cup v;$
 $\mathcal{C} \leftarrow \mathcal{C} \setminus D(v) \cup \{\cup_{C \in D(v)} C\};$
(2) find an optimal Steiner tree T for a terminal set $S \cup SP$.
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Let  $\mathcal{C}$  consist of sets  $C_1, \dots, C_r$  after Step (1) of Algorithm DSTP. Let add edges between all terminals of the same set  $C_i, i = 1, \dots, r$ . The length of the optimal Steiner tree in the graph  $G'$  obtained cannot be longer than in  $G$ . There is an optimal Steiner tree  $OPT'$  in  $G'$  containing spanning trees  $M_i$  for each set  $C_i, i = 1, \dots, r$ . If we contract any such tree  $M_i$  to a vertex, then  $OPT'$  appears to be an optimal Steiner tree  $M_0$  spanning vertices corresponding to  $C_i$ . Thus, the edge set of  $OPT'$  is a union of edges of  $M_i, i = 0, 1, \dots, r$ .

Algorithm DSTP constructs some Steiner trees  $M'_i$  in  $G$  for terminals of  $C_i$  (step (1)) and then finds the shortest tree  $M'_0$  spanning  $M'_i, i = 1, \dots, r$  (step (2)).  $M'_0$  cannot be longer than  $M_0$ , since  $M_0$  also spans  $M'_i$ . Remark 1 implies that an exhaustive search in Step (2) can be executed in time  $O(n^{1/\epsilon})$ .

An approximation ratio of Algorithm DSTP is at most

$$\frac{\sum_{i=0}^r d(M'_i)}{\sum_{i=0}^r d(M_i)} \leq \frac{\sum_{i=1}^r d(M'_i)}{\sum_{i=1}^r d(M_i)} = \frac{k - r + |SP|}{k - r} \leq 1 + \frac{|SP|}{k - \frac{1}{\epsilon}}. \quad (1)$$

The size of  $SP$  equals to the number of iterations in Step (1). Each iteration of (1) decreases the size of  $\mathcal{C}$  by at least  $\epsilon|\mathcal{C}| - 1$ . Thus, after  $i$ -th iteration  $|\mathcal{C}| \leq (k - \frac{1}{\epsilon})(1 - \epsilon)^i + \frac{1}{\epsilon}$ . The procedure (1) interrupts when  $|\mathcal{C}| < \frac{1}{\epsilon} + 1$ , so

$$|SP| \leq \log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon}).$$

Thus, (1) implies the following

**Lemma 3** *An approximation ratio of Algorithm DSTP is at most*

$$1 + \frac{\log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon})}{k - \frac{1}{\epsilon}} \quad . \quad \diamond$$

Given an arbitrary approximation ratio  $1 + \gamma$ ,  $\gamma > 0$ , our strategy is to solve exactly in polynomial time (for fixed  $\epsilon$  and  $\gamma$ ) instances of DSTP with small number of terminals, i.e. when  $k$  satisfies the following inequality

$$\frac{\log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon})}{k - \frac{1}{\epsilon}} \leq \gamma.$$

If the number of terminals is sufficiently big, then we apply Algorithm DSTP. Thus we obtain the following

**Theorem 3** *There is a polynomial-time approximation scheme for the  $\epsilon$ -dense STP.*  $\diamond$

It is not difficult to see that there is a polynomial time reduction of the  $\epsilon$ -dense SCP to the  $\epsilon$ -dense STP and vice versa, thus, the problem of polynomial time solvability of  $\epsilon$ -dense STP is equivalent to Problem 1.

Similarly to SCP, we define  $\delta$ -superdense STP to be the case of STP where any terminal has at least  $n - o(n^\delta)$  neighbors outside  $S$ .

**Corollary 1** *The  $\delta$ -superdense STP can be solved exactly in polynomial time.*

### 3 Dense Vertex Cover Problem

**Vertex Cover Problem (VCP).** *Given a graph  $G = (V, E)$ , find a minimum size vertex set  $OPT \subseteq V$  such that at least one end of any edge belongs to  $OPT$ .*

The following algorithm is suggested for VCP in  $\epsilon$ -dense graphs, i.e., in graphs where any vertex has at least  $\epsilon n$  neighbors for some  $\epsilon > 0$  ( $|V| = n$ ). Let  $O(v)$  denote the set of neighbors of a vertex  $v$ ,  $G(V')$  denote a subgraph induced by a vertex set  $V' \subseteq V$  and 2VC denote the well-known 2-approximation algorithm for VCP.

### Algorithm DVC

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for all $v \in V$
do $V' \leftarrow V \setminus (O(v) \cup \{v\})$;
 find a vertex cover $VC(v)$ for $G(V')$ using 2VC;
 $VC(v) \leftarrow O(v) \cup VC(v)$;
 $APPR \leftarrow \arg \min_{v \in V} |VC(v)|$.

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Let  $v \notin OPT$ . Then  $O(v) \subseteq OPT$  since all edges incident to  $v$  should be covered by  $OPT$ . Moreover,  $O(v)$  covers all edges between  $O(v)$  and the corresponding  $V'$ . So the rest of vertices of  $OPT$  cover the edges of  $G(V')$ .

Let  $OPT' = OPT - O(v)$ . The output vertex cover of 2VC applied to  $V'$  has a size at most  $\min\{2|OPT'|, |V'|\}$ . So the approximation ratio can be bounded as follows.

$$\frac{|APPR|}{|OPT|} \leq \frac{|O(v)| + \min\{2|OPT'|, |V'|\}}{|O(v)| + |OPT'|} \leq \min\left\{\frac{|O(v)| + 2|OPT'|}{|O(v)| + |OPT'|}, \frac{n}{|O(v)| + |OPT'|}\right\}$$

If  $2|OPT'| \leq (1 - \epsilon)n$ , then

$$\frac{|APPR|}{|OPT|} \leq \frac{\epsilon n + 2|OPT'|}{\epsilon n + |OPT'|} = 2 - \frac{1}{1 + \frac{|OPT'|}{\epsilon n}}$$

Thus, the more  $|OPT'|$  corresponds to the more bound for the approximation ratio. Therefore,

$$\frac{|APPR|}{|OPT|} \leq 2 - \frac{1}{1 + \frac{0.5(1-\epsilon)n}{\epsilon n}} = \frac{2}{1 + \epsilon}.$$

If  $2|OPT'| \geq (1 - \epsilon)n$ , then we obtain the same bound for the approximation ratio as follows

$$\frac{|APPR|}{|OPT|} \leq \frac{n}{\epsilon n + 0.5(1 - \epsilon)n} = \frac{2}{1 + \epsilon}.$$

**Theorem 4** *The algorithm DVC has an approximation ratio at most  $\frac{2}{1+\epsilon}$  for  $\epsilon$ -dense graphs.*

**Theorem 5** *The  $\epsilon$ -dense Vertex Cover Problem is MAX SNP-hard.*

**Proof.** (Sketch.) Starting with an instance of the Vertex Cover Problem in a graph  $G$  with  $n$  vertices we densify it joining all vertices of a clique of size  $\frac{\epsilon}{1-\epsilon}n$  with all vertices of  $G$ . The resulting graph is  $\epsilon$ -dense and, therefore, if we have an  $\alpha$ -approximation for DVC, then the reduction above gives  $\alpha(1 + \epsilon)$ -approximation algorithm for the general problem which is MAX SNP-hard.  $\diamond$

Further densification (as for SCP and STP) leads to decrease of approximation complexity.

We say that an instance of VCP is  $\delta$ -superdense if the degree of any vertex is at least  $n - o(n^\delta)$ . Theorem 4 implies

**Corollary 2** *The  $\delta$ -superdense VCP has a polynomial-time approximation scheme.*

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