

Complexity of the Exact Domatic Number Problem and of the Exact Conveyor Flow Shop Problem

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Abstract

We prove that the exact versions of the domatic number problem are complete for the levels of the boolean hierarchy over NP. The domatic number problem, which arises in the area of computer networks, is the problem of partitioning a given graph into a maximum number of disjoint dominating sets. This number is called the domatic number of the graph. We prove that the problem of determining whether or not the domatic number of a given graph is *exactly* one of k given values is complete for $BH_{2k}(NP)$, the $2k$ th level of the boolean hierarchy over NP. In particular, for $k = 1$, it is DP-complete to determine whether or not the domatic number of a given graph equals exactly a given integer. Note that $DP = BH_2(NP)$. We obtain similar results for the exact versions of generalized dominating set problems and of the conveyor flow shop problem, which arises in real-world applications in the wholesale business, where warehouses are supplied with goods from a central storehouse. Our reductions apply Wagner's conditions sufficient to prove hardness for the levels of the boolean hierarchy over NP.

Key words: *Computational complexity; completeness; domatic number problem; conveyor flow shop problem; boolean hierarchy*

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1 Introduction

A dominating set in an undirected graph G is a subset D of the vertex set $V(G)$ such that every vertex of $V(G)$ either belongs to D or is adjacent to some vertex in D . The domatic number problem is the problem of partitioning the vertex set $V(G)$ into a maximum number of disjoint dominating sets. This number, denoted by $\delta(G)$, is called the domatic number of G . The domatic number problem arises in various areas and scenarios. In particular, this problem is related to the task of distributing resources in a computer network, and also to the task of locating facilities in a communication network.

Suppose, for example, that resources are to be allocated in a computer network such that expensive services are quickly accessible in the immediate neighborhood of each vertex. If every vertex has only a limited capacity, then there is a bound on the number of resources that can be supported. In particular, if every vertex can serve a single resource only, then the maximum number of resources that can be supported equals the domatic number of the network graph. In the communication network scenario, n cities are linked via communication channels. A transmitting group is a subset of those cities that are able to transmit messages to every city in the network. Such a transmitting group is nothing else than a dominating set in the network graph, and the domatic number of this graph is the maximum number of disjoint transmitting groups in the network.

Motivated by these scenarios, the domatic number problem has been thoroughly investigated. Its decision version, denoted by DNP, asks whether or not $\delta(G) \geq k$ for a given graph G and a positive integer k . This problem is known to be NP-complete (cf. [GJ79]), and it remains NP-complete even if the given graph belongs to certain special classes of perfect graphs including chordal and bipartite graphs; see the references in Section 2. Feige et al. [FHK00] established nearly optimal approximation algorithms for the domatic number.

Expensive resources should not be wasted. Given a graph G and a positive integer i , how hard is it to determine whether or not $\delta(G)$ equals i *exactly*? More generally, given a graph G and a list $M_k = \{i_1, i_2, \dots, i_k\}$ of k positive integers, how hard is it to determine whether or not $\delta(G)$ equals some i_j *exactly*? Motivated by such *exact versions of NP-complete optimization problems*, Papadimitriou and Yannakakis introduced in their seminal paper [PY84] the class DP, which consists of the differences of any two NP sets. They also studied various other important classes of problems that belong to DP, including *facet problems*, *unique solution problems*, and *critical problems*, and they proved many of them complete for DP. Cai and Meyer [CM87] showed that **Minimal-3-Uncolorability** is DP-complete, a critical graph problem that asks whether a given graph is not 3-colorable, but deleting any of its vertices makes it 3-colorable.

Generalizing DP, Cai et al. [CGH⁺88, CGH⁺89] introduced and studied $\text{BH}(\text{NP}) = \bigcup_{k \geq 1} \text{BH}_k(\text{NP})$, the boolean hierarchy over NP; see Section 2 for the definition. Note that DP is the second level of this hierarchy. Wagner [Wag87] identified a set of conditions sufficient to prove $\text{BH}_k(\text{NP})$ -hardness for each k , and he applied his sufficient conditions to prove a host of exact versions of NP-complete optimization problems complete for the levels of the boolean hierarchy. To state just one such result, Wagner [Wag87] proved that the problem of determining whether or not the chromatic number of a given graph is *exactly* one of k given values is complete for $\text{BH}_{2k}(\text{NP})$. The chromatic number of a graph G , denoted by $\chi(G)$, is the minimum number of colors needed

to color the vertices of G such that no two adjacent vertices receive the same color. In particular, for $k = 1$, Wagner showed that for any fixed integer $i \geq 7$, it is DP-complete to determine whether or not $\chi(G) = i$ for a given graph G . Recently, Rothe [Rot03] (see also [RSV02]) optimally strengthened Wagner’s result by showing $\text{BH}_{2k}(\text{NP})$ -completeness of the exact chromatic number problem using the smallest number of colors possible. In particular, it is DP-complete to determine whether or not $\chi(G) = 4$, yet the problem of determining whether or not $\chi(G) = 3$ is in NP and thus cannot be DP-complete unless the boolean hierarchy over NP collapses to its first level.

Wagner’s technique was also useful in proving certain natural problems complete for $\text{P}_{\parallel}^{\text{NP}}$, the class of problems solvable in polynomial time via parallel (i.e., truth-table) access to NP. For example, the winner problem for Carroll elections [HHR97a,HHR97b] and for Young elections [RSV02,RSV03] as well as the problem of determining when certain graph heuristics work well [HR98,HRS02] each are complete for $\text{P}_{\parallel}^{\text{NP}}$.

In Section 2, we prove that determining whether or not the domatic number of a given graph equals exactly one of k given values is complete for $\text{BH}_{2k}(\text{NP})$. In particular, for $k = 1$ and any fixed integer $i \geq 5$, it is DP-complete to determine whether or not $\delta(G) = i$ for a given graph G . Section 3 raises the results of Section 2 to prove various variants of the domatic number problem complete for $\text{P}_{\parallel}^{\text{NP}}$. In Section 4, we study the exact versions of generalized dominating set problems that are parameterized by two sets of nonnegative integers, σ and ρ , which restrict the number of neighbors for each vertex in the partition. We obtain DP-completeness results for a number of graph problems based on this uniform approach proposed by Heggernes and Telle [HT98]. Finally, in Section 5, we prove similar results for the exact conveyor flow shop problem.

2 The Exact Domatic Number Problem

We start by introducing some graph-theoretical notation. For any graph G , $V(G)$ denotes the vertex set of G , and $E(G)$ denotes the edge set of G . All graphs in this paper are undirected, simple graphs. That is, edges are unordered pairs of vertices, and there are neither multiple nor reflexive edges (i.e., for any two vertices u and v , there is at most one edge of the form $\{u, v\}$, and there is no edge of the form $\{u, u\}$). Also, all graphs considered do not have isolated vertices. For any vertex $v \in V(G)$, the *degree of v* (denoted by $\text{deg}_G(v)$) is the number of vertices adjacent to v in G ; if G is clear from the context, we omit the subscript and simply write $\text{deg}(v)$. Let $\text{max-deg}(G) = \max_{v \in V(G)} \text{deg}(v)$ denote the maximum degree of the vertices of graph G , and let $\text{min-deg}(G) = \min_{v \in V(G)} \text{deg}(v)$ denote the minimum degree of the vertices of graph G .

A graph G is said to be k -colorable if its vertices can be colored with no more than k colors such that no two adjacent vertices receive the same color. The *chromatic number of G* , denoted by $\chi(G)$, is defined to be the smallest k such that G is k -colorable. In particular, define the decision version of the 3-colorability problem, which is one of the standard NP-complete problems (cf. [GJ79]), by:

$$\text{3-Colorability} = \{G \mid G \text{ is a graph with } \chi(G) \leq 3\}.$$

For some of the reductions presented in this paper, we will need the following operations on graphs.

Definition 1 The join operation on graphs, denoted by \oplus , is defined as follows: Given two disjoint graphs A and B , their join $A \oplus B$ is the graph with vertex set $V(A \oplus B) = V(A) \cup V(B)$ and edge set $E(A \oplus B) = E(A) \cup E(B) \cup \{\{a, b\} \mid a \in V(A) \text{ and } b \in V(B)\}$.

The disjoint union of any two graphs A and B is defined as the graph $A \cup B$ with vertex set $V(A) \cup V(B)$ and edge set $E(A) \cup E(B)$.

Note that \oplus is an associative operation on graphs and $\chi(A \oplus B) = \chi(A) + \chi(B)$. We now define the domatic number problem.

Definition 2 For any graph G , a dominating set of G is a subset $D \subseteq V(G)$ such that for each vertex $u \in V(G) - D$, there exists a vertex $v \in D$ with $\{u, v\} \in E$. The domatic number of G , denoted by $\delta(G)$, is the maximum number of disjoint dominating sets. Define the decision version of the domatic number problem by:

$$\text{DNP} = \{\langle G, k \rangle \mid G \text{ is a graph and } k \text{ is a positive integer such that } \delta(G) \geq k\}.$$

Note that $\delta(G) \leq \min\text{-deg}(G) + 1$. For general graphs and for each fixed $k \geq 3$, DNP is known to be NP-complete (cf. [GJ79]), and it remains NP-complete for circular-arc graphs [Bon85], for split graphs (thus, in particular, for chordal and co-chordal graphs) [KS94], and for bipartite graphs (thus, in particular, for comparability graphs) [KS94]. In contrast, DNP is known to be polynomial-time solvable for certain other graph classes, including strongly chordal graphs (thus, in particular, for interval graphs and path graphs) [Far84] and proper circular-arc graphs [Bon85]. For graph-theoretical notions and special graph classes not defined in this extended abstract, we refer to the monograph by Brandstadt et al. [BLS99], which is a follow-up to the classic text by Golumbic [Gol80]. Feige et al. [FHK00] show that every graph G with n vertices has a domatic partition with $(1 - o(1))(\min\text{-deg}(G) + 1)/\ln n$ sets that can be found in polynomial time, which implies a $(1 - o(1)) \ln n$ approximation algorithm for the domatic number $\delta(G)$. This is a tight bound, since they also show that, for any fixed constant $\varepsilon > 0$, the domatic number cannot be approximated within a factor of $(1 - \varepsilon) \ln n$, unless $\text{NP} \subseteq \text{DTIME}(n^{\log \log n})$. Finally, Feige et al. [FHK00] give a refined algorithm that yields a domatic partition of $\Omega(\delta(G)/\ln \max\text{-deg}(G))$, which implies a $\mathcal{O}(\ln \max\text{-deg}(G))$ approximation algorithm for the domatic number $\delta(G)$. For more results on the domatic number problem, see [FHK00,KS94] and the references therein.

We assume that the reader is familiar with standard complexity-theoretic notions and notation. For more background, we refer to any standard textbook on computational complexity theory such as Papadimitriou's book [Pap94]. All completeness results in this paper are with respect to the polynomial-time many-one reducibility, denoted by \leq_m^p . For sets A and B , define $A \leq_m^p B$ if and only if there is a polynomial-time computable function f such that for each $x \in \Sigma^*$, $x \in A$ if and only if $f(x) \in B$. A set B is \mathcal{C} -hard for a complexity class \mathcal{C} if and only if $A \leq_m^p B$ for each $A \in \mathcal{C}$. A set B is \mathcal{C} -complete if and only if B is \mathcal{C} -hard and $B \in \mathcal{C}$. To define the boolean hierarchy over NP, we use the symbols \wedge and \vee , respectively, to denote the *complex intersection* and the *complex union* of set classes. That is, for classes \mathcal{C} and \mathcal{D} of sets, define

$$\begin{aligned} \mathcal{C} \wedge \mathcal{D} &= \{A \cap B \mid A \in \mathcal{C} \text{ and } B \in \mathcal{D}\}; \\ \mathcal{C} \vee \mathcal{D} &= \{A \cup B \mid A \in \mathcal{C} \text{ and } B \in \mathcal{D}\}. \end{aligned}$$

Definition 3 (Cai et al. [CGH⁺88]) *The boolean hierarchy over NP is inductively defined by:*

$$\begin{aligned} \text{BH}_1(\text{NP}) &= \text{NP}, \\ \text{BH}_2(\text{NP}) &= \text{NP} \wedge \text{coNP}, \\ \text{BH}_k(\text{NP}) &= \text{BH}_{k-2}(\text{NP}) \vee \text{BH}_2(\text{NP}) \quad \text{for } k \geq 3, \text{ and} \\ \text{BH}(\text{NP}) &= \bigcup_{k \geq 1} \text{BH}_k(\text{NP}). \end{aligned}$$

Note that $\text{DP} = \text{BH}_2(\text{NP})$. In his seminal paper [Wag87], Wagner provided a set of conditions sufficient to prove hardness results for the levels of the boolean hierarchy over NP and for other complexity classes, respectively. His sufficient conditions were successfully applied to classify the complexity of a variety of natural, important problems, see, e.g., [Wag87,HHR97a,HHR97b,HR98, Rot03,HRS02,RSV02,RSV03]. Below, we state that one of Wagner's sufficient conditions that is relevant for this paper.

Lemma 4 (Wagner; see Thm. 5.1(3) of [Wag87]) *Let A be some NP-complete problem, let B be an arbitrary problem, and let $k \geq 1$ be fixed. If there exists a polynomial-time computable function f such that the equivalence*

$$\|\{i \mid x_i \in A\}\| \text{ is odd} \iff f(x_1, x_2, \dots, x_{2k}) \in B \quad (2.1)$$

is true for all strings $x_1, x_2, \dots, x_{2k} \in \Sigma^$ satisfying that for each j with $1 \leq j < 2k$, $x_{j+1} \in A$ implies $x_j \in A$, then B is $\text{BH}_{2k}(\text{NP})$ -hard.*

Definition 5 *Let $M_k \subseteq \mathbb{N}$ be any set containing k noncontiguous integers. Define the exact version of the domatic number problem by:*

$$\text{Exact-}M_k\text{-DNP} = \{G \mid G \text{ is a graph and } \delta(G) \in M_k\}.$$

In particular, for each singleton $M_1 = \{t\}$, we write $\text{Exact-}t\text{-DNP} = \{G \mid \delta(G) = t\}$.

To apply Wagner's sufficient condition from Lemma 4 in the proof of the main result of this section, Theorem 7 below, we need the following lemma due to Kaplan and Shamir [KS94] that gives a reduction from 3-Colorability to DNP with useful properties. Since Kaplan and Shamir's construction will be used explicitly in the proof of Theorem 7, we present it below.

Lemma 6 (Kaplan and Shamir [KS94]) *There exists a polynomial-time many-one reduction g from 3-Colorability to DNP with the following properties:*

$$G \in 3\text{-Colorability} \implies \delta(g(G)) = 3; \quad (2.2)$$

$$G \notin 3\text{-Colorability} \implies \delta(g(G)) = 2. \quad (2.3)$$

Proof. The reduction g maps any given graph G to a graph H such that the implications (2.2) and (2.3) are satisfied. Since it can be tested in polynomial time whether or not a given graph is 2-colorable, we may assume, without loss of generality, that G is not 2-colorable. Recall that we

also assume that G has no isolated vertices; note that the domatic number of any graph is always at least 2 if it has no isolated vertices (cf. [GJ79]). Graph H is constructed from G by creating $\|E(G)\|$ new vertices, one on each edge of G , and by adding new edges such that the original vertices of G form a clique. Thus, every edge of G induces a triangle in H , and every pair of nonadjacent vertices in G is connected by an edge in H . Our construction in the proof of Theorem 7 below explicitly uses this construction and, in particular, such triangles.

Let $V(G) = \{v_1, v_2, \dots, v_n\}$. Formally, define the vertex set and the edge set of H by:

$$\begin{aligned} V(H) &= V(G) \cup \{u_{i,j} \mid \{v_i, v_j\} \in E(G)\}; \\ E(H) &= \{\{v_i, u_{i,j}\} \mid \{v_i, v_j\} \in E(G)\} \cup \{\{v_j, u_{i,j}\} \mid \{v_i, v_j\} \in E(G)\} \\ &\quad \cup \{\{v_i, v_j\} \mid 1 \leq i, j \leq n \text{ and } i \neq j\}. \end{aligned}$$

Since, by construction, $\min\text{-deg}(H) = 2$ and H has no isolated vertices, the inequality $\delta(H) \leq \min\text{-deg}(H) + 1$ implies that $2 \leq \delta(H) \leq 3$.

Suppose $G \in 3\text{-Colorability}$. Let $C_1, C_2,$ and C_3 be the three color classes of G , i.e., $C_k = \{v_i \in V(G) \mid v_i \text{ is colored by color } k\}$, for $k \in \{1, 2, 3\}$. Form a partition of $V(H)$ by $\hat{C}_k = C_k \cup \{u_{i,j} \mid v_i \notin C_k \text{ and } v_j \notin C_k\}$, for $k \in \{1, 2, 3\}$. Since for each k , $\hat{C}_k \cap V(G) \neq \emptyset$ and $V(G)$ induces a clique in H , every \hat{C}_k dominates $V(G)$ in H . Also, every triangle $\{v_i, u_{i,j}, v_j\}$ contains one element from each \hat{C}_k , so every \hat{C}_k also dominates $\{u_{i,j} \mid \{v_i, v_j\} \in E(G)\}$ in H . Hence, $\delta(H) = 3$, which proves the implication (2.2).

Conversely, suppose $\delta(H) = 3$. Given a partition of $V(H)$ into three dominating sets, $\hat{C}_1, \hat{C}_2,$ and \hat{C}_3 , color the vertices in \hat{C}_k by color k . Every triangle $\{v_i, u_{i,j}, v_j\}$ is 3-colored, which implies that this coloring on $V(G)$ induces a legal 3-coloring of G ; so $G \in 3\text{-Colorability}$. Hence, $\chi(G) = 3$ if and only if $\delta(H) = 3$. Since $2 \leq \delta(H) \leq 3$, the implication (2.3) follows. \blacksquare

Next, we state the main result of this section: For each fixed set M_k containing k noncontiguous integers not smaller than $4k + 1$, $\text{Exact-}M_k\text{-DNP}$ is complete for $\text{BH}_{2k}(\text{NP})$, the $2k$ th level of the boolean hierarchy over NP.

Theorem 7 *For fixed $k \geq 1$, let $M_k = \{4k + 1, 4k + 3, \dots, 6k - 1\}$. Then, $\text{Exact-}M_k\text{-DNP}$ is $\text{BH}_{2k}(\text{NP})$ -complete. In particular, for $k = 1$, Exact-5-DNP is DP-complete. In contrast, Exact-2-DNP is in coNP (and even coNP-complete) and thus cannot be DP-complete unless the boolean hierarchy over NP collapses.*

Proof. To show that $\text{Exact-}M_k\text{-DNP}$ is in $\text{BH}_{2k}(\text{NP})$, partition the problem into k subproblems

$$\text{Exact-}M_k\text{-DNP} = \bigcup_{i \in M_k} \text{Exact-}i\text{-DNP}.$$

Every set $\text{Exact-}i\text{-DNP}$ can be rewritten as

$$\text{Exact-}i\text{-DNP} = \{G \mid \delta(G) \geq i\} \cap \{G \mid \delta(G) < i + 1\}.$$

Clearly, the set $\{G \mid \delta(G) \geq i\}$ is in NP, and the set $\{G \mid \delta(G) < i + 1\}$ is in coNP. It follows that $\text{Exact-}i\text{-DNP}$ is in DP, for each $i \in M_k$. By definition, $\text{Exact-}M_k\text{-DNP}$ is in $\text{BH}_{2k}(\text{NP})$.

In particular, suppose $k = 1$ and consider the problem

$$\text{Exact-2-DNP} = \{G \mid \delta(G) \leq 2\} \cap \{G \mid \delta(G) \geq 2\}.$$

Since every graph without isolated vertices has a domatic number of at least 2 (cf. [GJ79]), the set $\{G \mid \delta(G) \geq 2\}$ is in P. On the other hand, the set $\{G \mid \delta(G) \leq 2\}$ is in coNP, so **Exact-2-DNP** is also in coNP and, thus, cannot be DP-complete unless the boolean hierarchy over NP collapses to its first level. Note that the coNP-hardness of **Exact-2-DNP** follows immediately via the Lemma 6 reduction g from **3-Colorability** to DNP.

The proof that **Exact- M_k -DNP** is $\text{BH}_{2k}(\text{NP})$ -hard draws on Lemma 4 with **3-Colorability** being the NP-complete set A and with **Exact- M_k -DNP** being the set B from this lemma. Fix any $2k$ graphs G_1, G_2, \dots, G_{2k} satisfying that for each j with $1 \leq j < 2k$, if G_{j+1} is in **3-Colorability**, then so is G_j . Without loss of generality, we assume that none of these graphs G_j is 2-colorable, nor does it contain isolated vertices, and we assume that $\chi(G_j) \leq 4$ for each j . Applying the Lemma 6 reduction g from **3-Colorability** to DNP, we obtain $2k$ graphs $H_j = g(G_j)$, $1 \leq j \leq 2k$, each satisfying the implications (2.2) and (2.3). Hence, for each j , $\delta(H_j) \in \{2, 3\}$, and $\delta(H_{j+1}) = 3$ implies $\delta(H_j) = 3$.

We now define a polynomial-time computable function f that maps the graphs G_1, G_2, \dots, G_{2k} to a graph H such that Equation (2.1) from Lemma 4 is satisfied. The graph H is constructed from the graphs H_1, H_2, \dots, H_{2k} such that $\delta(H) = \sum_{j=1}^{2k} \delta(H_j)$. Note that the analogous property for the chromatic number (i.e., $\chi(H) = \sum_{j=1}^{2k} \chi(H_j)$) is easy to achieve by simply joining (see Definition 1) the graphs H_j ([Wag87], see also [Rot03]). However, for the domatic number, the construction is more complicated. We first describe it for the special case that $k = 1$, and then explain the general case. For $k = 1$, we are given two graphs, H_1 and H_2 , as above. Construct a gadget connecting H_1 and H_2 as follows. Recalling the construction from Lemma 6, let T_1 with $V(T_1) = \{v_q, u_{q,r}, v_r\}$ be any fixed triangle in H_1 , and let T_2 with $V(T_2) = \{v_s, u_{s,t}, v_t\}$ be any fixed triangle in H_2 . Connect T_1 and T_2 using the gadget that is shown in Figure 1. That is, add six new vertices a_1, a_2, \dots, a_6 , and add the following set of edges:

$$\begin{aligned} & \{\{v_q, a_1\}, \{v_q, a_2\}, \{v_q, a_4\}, \{v_q, a_5\}, \{v_q, a_6\}, \\ & \{u_{q,r}, a_1\}, \{u_{q,r}, a_3\}, \{u_{q,r}, a_4\}, \{u_{q,r}, a_5\}, \{u_{q,r}, a_6\}, \\ & \{v_r, a_2\}, \{v_r, a_3\}, \{v_r, a_4\}, \{v_r, a_5\}, \{v_r, a_6\}, \\ & \{v_s, a_1\}, \{v_s, a_2\}, \{v_s, a_3\}, \{v_s, a_4\}, \{v_s, a_5\}, \\ & \{u_{s,t}, a_1\}, \{u_{s,t}, a_2\}, \{u_{s,t}, a_3\}, \{u_{s,t}, a_4\}, \{u_{s,t}, a_6\}, \\ & \{v_t, a_1\}, \{v_t, a_2\}, \{v_t, a_3\}, \{v_t, a_5\}, \{v_t, a_6\}\}. \end{aligned}$$

Using pairwise disjoint copies of the gadget from Figure 1, connect each pair of triangles from H_1 and H_2 and call the resulting graph H . Since $\deg(a_i) = 5$ for each gadget vertex a_i , we have $\delta(H) \leq 6$, regardless of the domatic numbers of H_1 and H_2 . We now show that $\delta(H) = \delta(H_1) + \delta(H_2)$.

Let $D_1, D_2, \dots, D_{\delta(H_1)}$ be $\delta(H_1)$ pairwise disjoint sets dominating H_1 , and let $D_{\delta(H_1)+1}, D_{\delta(H_1)+2}, \dots, D_{\delta(H_1)+\delta(H_2)}$ be $\delta(H_2)$ pairwise disjoint sets dominating H_2 . Distinguish the

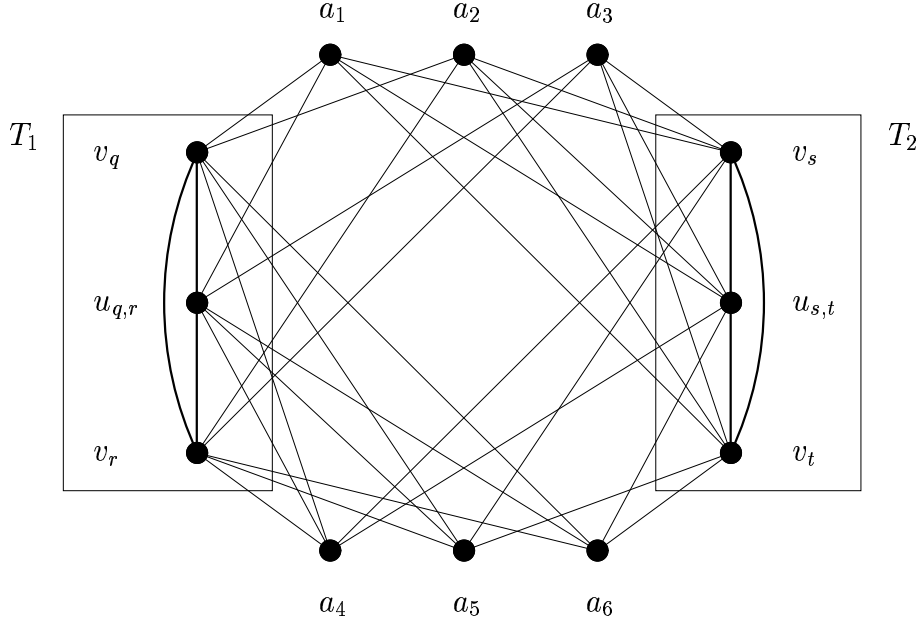


Figure 1: Gadget connecting two triangles T_1 and T_2 .

following three cases.

Case 1: $\delta(H_1) = \delta(H_2) = 3$. Consider any fixed D_j , where $1 \leq j \leq 3$. Since D_j dominates H_1 , every triangle T_1 of H_1 has exactly one vertex in D_j . Fix T_1 , and suppose $V(T_1) = \{v_q, u_{q,r}, v_r\}$ and, say, $V(T_1) \cap D_j = \{v_q\}$; the other cases are analogous. For each triangle T_2 of H_2 , say T_2 with $V(T_2) = \{v_s, u_{s,t}, v_t\}$, let $a_1^{T_2}, a_2^{T_2}, \dots, a_6^{T_2}$ be the gadget vertices connecting T_1 and T_2 as in Figure 1. Note that exactly one of these gadget vertices, $a_3^{T_2}$, is not adjacent to v_q . For each triangle T_2 , add the missing gadget vertex to D_j , and define $\hat{D}_j = D_j \cup \{a_i^{T_2} \mid T_2 \text{ is a triangle of } H_2\}$. Since every vertex of H_2 is contained in some triangle T_2 of H_2 and since $a_3^{T_2}$ is adjacent to each vertex in T_2 , \hat{D}_j dominates H_2 . Also, $\hat{D}_j \supseteq D_j$ dominates H_1 , and since v_q is adjacent to each $a_i^{T_2}$ except $a_3^{T_2}$ for each triangle T_2 of H_2 , \hat{D}_j dominates every gadget vertex of H . Hence, \hat{D}_j dominates H . By a symmetric argument, every set D_j , where $4 \leq j \leq 6$, dominating H_2 can be extended to a set \hat{D}_j dominating the entire graph H . By construction, the sets \hat{D}_j with $1 \leq j \leq 6$ are pairwise disjoint. Hence, $\delta(H) = 6 = \delta(H_1) + \delta(H_2)$.

Case 2: $\delta(H_1) = 3$ and $\delta(H_2) = 2$. As in Case 1, we can add appropriate gadget vertices to the five given sets D_1, D_2, \dots, D_5 to obtain five pairwise disjoint sets $\hat{D}_1, \hat{D}_2, \dots, \hat{D}_5$ such that each \hat{D}_i dominates the entire graph H . It follows that $5 \leq \delta(H) \leq 6$. It remains to show that $\delta(H) \neq 6$. For a contradiction, suppose that $\delta(H) = 6$. Look at Figure 1 showing the gadget between any two triangles T_1 and T_2 belonging to H_1 and H_2 , respectively. Fix T_1 with $V(T_1) = \{v_q, u_{q,r}, v_r\}$. The only way (except for renaming the dominating sets) to

partition the graph H into six dominating sets, say E_1, E_2, \dots, E_6 , is to assign to the sets E_i the vertices of T_1 , of H_2 , and of the gadgets connected with T_1 as follows:

- E_1 contains v_q and $\{a_3^{T_2} \mid T_2 \text{ is a triangle in } H_2\}$,
- E_2 contains $u_{q,r}$ and $\{a_2^{T_2} \mid T_2 \text{ is a triangle in } H_2\}$,
- E_3 contains v_r and $\{a_1^{T_2} \mid T_2 \text{ is a triangle in } H_2\}$,
- E_4 contains $v_s \in T_2$, for each triangle T_2 of H_2 , and $\{a_6^{T_2} \mid T_2 \text{ is a triangle in } H_2\}$,
- E_5 contains $u_{s,t} \in T_2$, for each triangle T_2 of H_2 , and $\{a_5^{T_2} \mid T_2 \text{ is a triangle in } H_2\}$,
- E_6 contains $v_t \in T_2$, for each triangle T_2 of H_2 , and $\{a_4^{T_2} \mid T_2 \text{ is a triangle in } H_2\}$.

Hence, all vertices from H_2 must be assigned to the three dominating sets E_4, E_5 , and E_6 , which induces a partition of H_2 into three dominating sets. This contradicts the case assumption that $\delta(H_2) = 2$. Hence, $\delta(H) = 5 = \delta(H_1) + \delta(H_2)$.

Case 3: $\delta(H_1) = \delta(H_2) = 2$. As in the previous two cases, we can add appropriate gadget vertices to the four given sets D_1, D_2, D_3 , and D_4 to obtain a partition of $V(H)$ into four sets $\hat{D}_1, \hat{D}_2, \hat{D}_3$, and \hat{D}_4 such that each \hat{D}_i dominates the entire graph H . It follows that $4 \leq \delta(H) \leq 6$. By the same arguments as in Case 2, $\delta(H) \neq 6$. It remains to show that $\delta(H) \neq 5$. For a contradiction, suppose that $\delta(H) = 5$. Look at Figure 1 showing the gadget between any two triangles T_1 and T_2 belonging to H_1 and H_2 , respectively. Suppose H is partitioned into five dominant sets E_1, E_2, \dots, E_5 .

First, we show that neither T_1 nor T_2 can have two vertices belonging to the same dominating set. Suppose otherwise, and let, for example, v_q and $u_{q,r}$ be both in E_1 , and let v_r be in E_2 ; all other cases are treated analogously. This implies that the vertices $v_s, u_{s,t}$, and v_t in T_2 must be assigned to the other three dominating sets, E_3, E_4 , and E_5 , since otherwise one of the sets E_i would not dominate all gadget vertices $a_j, 1 \leq j \leq 6$. Since T_1 is connected with each triangle of H_2 via some gadget, the same argument shows that $V(H_2)$ can be partitioned into three dominating sets, which contradicts the assumption that $\delta(H_2) = 2$.

Hence, the vertices of T_1 are assigned to three different dominating sets, say E_1, E_2 , and E_3 . Then, every triangle T_2 of H_2 must have one of its vertices in E_4 , one in E_5 , and one in either one of E_1, E_2 , and E_3 . Again, this induces a partition of H_2 into three dominating sets, which contradicts the assumption that $\delta(H_2) = 2$. It follows that $\delta(H) \neq 5$, so $\delta(H) = 4 = \delta(H_1) + \delta(H_2)$.

By construction, $\delta(H_2) = 3$ implies $\delta(H_1) = 3$, and thus the case “ $\delta(H_1) = 2$ and $\delta(H_2) = 3$ ” cannot occur. The case distinction is complete.

Define $f(G_1, G_2) = H$. Note that f is polynomial-time computable and, by the case distinction

above, f satisfies Equation (2.1):

$$\begin{aligned}
& G_1 \in \text{3-Colorability} \text{ and } G_2 \notin \text{3-Colorability} \\
& \iff \delta(H_1) = 3 \text{ and } \delta(H_2) = 2 \\
& \iff \delta(H) = \delta(H_1) + \delta(H_2) = 5 \\
& \iff f(G_1, G_2) = H \in \text{Exact-5-DNP}.
\end{aligned}$$

Applying Lemma 4 with $k = 1$, it follows that **Exact-5-DNP** is DP-complete.

To prove the general case, fix any $k \geq 1$. Recall that we are given the graphs H_1, H_2, \dots, H_{2k} that are constructed from G_1, G_2, \dots, G_{2k} . Generalize the above construction of graph H as follows. For any fixed sequence T_1, T_2, \dots, T_{2k} of triangles, where T_i belongs to H_i , add $6k$ new gadget vertices a_1, a_2, \dots, a_{6k} and, for each i with $1 \leq i \leq 2k$, associate the three gadget vertices $a_{1+3(i-1)}, a_{2+3(i-1)}$, and a_{3i} with the triangle T_i . For each i with $1 \leq i \leq 2k$, connect T_i with every T_j , where $1 \leq j \leq 2k$ and $i \neq j$, via the same three gadget vertices $a_{1+3(i-1)}, a_{2+3(i-1)}$, and a_{3i} associated with T_i the same way T_1 and T_2 are connected in Figure 1 via the vertices a_1, a_2 , and a_3 . It follows that $\deg(a_i) = 6k - 1$ for each i , so $\delta(H) \leq 6k$. An argument analogous to the above case distinction shows that $\delta(H) = \sum_{j=1}^{2k} \delta(H_j)$, and it follows that:

$$\begin{aligned}
& \|\{i \mid G_i \in \text{3-Colorability}\}\| \text{ is odd} \\
& \iff (\exists i : 1 \leq i \leq k) [\chi(G_1) = \dots = \chi(G_{2i-1}) = 3 \text{ and } \chi(G_{2i}) = \dots = \chi(G_{2k}) = 4] \\
& \iff (\exists i : 1 \leq i \leq k) [\delta(H_1) = \dots = \delta(H_{2i-1}) = 3 \text{ and } \delta(H_{2i}) = \dots = \delta(H_{2k}) = 2] \\
& \iff (\exists i : 1 \leq i \leq k) \left[\delta(H) = \sum_{j=1}^{2k} \delta(H_j) = 3(2i - 1) + 2(2k - 2i + 1) \right] \\
& \iff (\exists i : 1 \leq i \leq k) [\delta(H) = 4k + 2i - 1] \\
& \iff \delta(H) \in \{4k + 1, 4k + 3, \dots, 6k - 1\} \\
& \iff f(G_1, G_2, \dots, G_{2k}) = H \in \text{Exact-}M_k\text{-DNP}.
\end{aligned}$$

Thus, f satisfies Equation (2.1). By Lemma 4, **Exact- M_k -DNP** is $\text{BH}_{2k}(\text{NP})$ -complete. \blacksquare

3 Domatic Number Problems Complete for Parallel Access to NP

In this section, we consider the problem of deciding whether or not the domatic number of a given graph is an odd integer, and the problem of comparing the domatic numbers of two given graphs. Applying the techniques of the previous section, we prove in Theorem 10 below that these variants of the domatic number problem are complete for $\text{P}_{\parallel}^{\text{NP}}$, the class of problems that can be solved by a deterministic polynomial-time Turing machine making parallel (i.e., truth-table) queries to some NP oracle set. Among many other characterizations, $\text{P}_{\parallel}^{\text{NP}}$ is known to be equal to $\text{P}^{\text{NP}[\mathcal{O}(\log)]}$, the

class of problems solvable by logarithmically many Turing queries to an NP oracle; see [Hem89, Wag90,BH91,KS87].

Definition 8 Define the following variants of the domatic number problem:

$$\begin{aligned} \text{DNP-Odd} &= \{G \mid G \text{ is a graph such that } \delta(G) \text{ is odd}\}; \\ \text{DNP-Equ} &= \{(G, H) \mid G \text{ and } H \text{ are graphs such that } \delta(G) = \delta(H)\}; \\ \text{DNP-Geq} &= \{(G, H) \mid G \text{ and } H \text{ are graphs such that } \delta(G) \geq \delta(H)\}. \end{aligned}$$

Wagner [Wag87] provided a sufficient condition for proving $P_{||}^{\text{NP}}$ -hardness that is analogous to Lemma 4 except that in Lemma 9 the value of k is not fixed.¹ The introduction gives a list of related $P_{||}^{\text{NP}}$ -completeness results for which Wagner's technique [Wag87] was applied.

Lemma 9 (Wagner; see Thm. 5.2 of [Wag87]) Let A be some NP-complete problem and B be an arbitrary problem. If there exists a polynomial-time computable function f such that the equivalence

$$||\{i \mid x_i \in A\}|| \text{ is odd} \iff f(x_1, x_2, \dots, x_{2k}) \in B \quad (3.4)$$

is true for each $k \geq 1$ and for all strings $x_1, x_2, \dots, x_{2k} \in \Sigma^*$ satisfying that for each j with $1 \leq j < 2k$, $x_{j+1} \in A$ implies $x_j \in A$, then B is $P_{||}^{\text{NP}}$ -hard.

Theorem 10 DNP-Odd, DNP-Equ, and DNP-Geq each are $P_{||}^{\text{NP}}$ -complete.

Proof. It is easy to see that each of the problems DNP-Odd, DNP-Equ, and DNP-Geq belongs to $P_{||}^{\text{NP}}$, since the domatic number of a given graph can be determined exactly by parallel queries to the NP oracle DNP. It remains to prove that each of these problems is $P_{||}^{\text{NP}}$ -hard. For DNP-Odd, this follows immediately from the proof of Theorem 7 using Lemma 9.

We now show that DNP-Equ is $P_{||}^{\text{NP}}$ -hard by applying Lemma 9 with A being the NP-complete problem 3-Colorability and B being DNP-Equ. Fix any $k \geq 1$, and let G_1, G_2, \dots, G_{2k} be any given sequence of graphs satisfying that for each j with $1 \leq j < 2k$, if G_{j+1} is 3-colorable, then so is G_j . Since $P_{||}^{\text{NP}}$ is closed under complement, Equation (3.4) from Lemma 9 can be replaced by:

$$||\{i \mid G_i \in 3\text{-Colorability}\}|| \text{ is even} \iff f(G_1, G_2, \dots, G_{2k}) \in \text{DNP-Equ}. \quad (3.5)$$

As in the proof of Theorem 7, construct the graphs H_1, H_2, \dots, H_{2k} from the given graphs G_1, G_2, \dots, G_{2k} according to Lemma 6, where each $H_j = g(G_j)$ satisfies the implications (2.2) and (2.3). Let \times denote the associative operation on graphs constructed in the proof of Theorem 7 to sum up the domatic numbers of the given graphs, and define the graphs:

$$\begin{aligned} G_{\text{odd}} &= H_1 \times H_3 \times \dots \times H_{2k-1}, \\ G_{\text{even}} &= H_2 \times H_4 \times \dots \times H_{2k}. \end{aligned}$$

¹Wagner actually states a criterion for $P_{\text{bf}}^{\text{NP}}$ -hardness in [Wag87], but he later proved in [Wag90] that $P_{\text{bf}}^{\text{NP}} = P_{||}^{\text{NP}}$.

We now prove Equation (3.5). From left to right we have:

$$\begin{aligned}
& ||\{i \mid G_i \in \text{3-Colorability}\}|| \text{ is even} \\
& \Rightarrow (\forall i : 1 \leq i \leq k) [\delta(H_{2i-1}) = \delta(H_{2i})] \\
& \Rightarrow \sum_{1 \leq i \leq k} \delta(H_{2i-1}) = \sum_{1 \leq i \leq k} \delta(H_{2i}) \\
& \Rightarrow \delta(G_{\text{odd}}) = \delta(G_{\text{even}}) \\
& \Rightarrow \langle G_{\text{odd}}, G_{\text{even}} \rangle = f(G_1, G_2, \dots, G_{2k}) \in \text{DNP-Equ.}
\end{aligned}$$

From right to left we have:

$$\begin{aligned}
& ||\{i \mid G_i \in \text{3-Colorability}\}|| \text{ is odd} \\
& \Rightarrow (\exists i : 1 \leq i \leq k) [\delta(H_{2i-1}) = 3 \wedge \delta(H_{2i}) = 2 \text{ and } \delta(H_{2j-1}) = \delta(H_{2j}) \text{ for } j \neq i] \\
& \Rightarrow -1 + \sum_{1 \leq i \leq k} \delta(H_{2i-1}) = \sum_{1 \leq i \leq k} \delta(H_{2i}) \\
& \Rightarrow \delta(G_{\text{odd}}) - 1 = \delta(G_{\text{even}}) \\
& \Rightarrow \langle G_{\text{odd}}, G_{\text{even}} \rangle = f(G_1, G_2, \dots, G_{2k}) \notin \text{DNP-Equ.}
\end{aligned}$$

Lemma 9 implies that DNP-Equ is $P_{||}^{\text{NP}}$ -complete.

The above proof for DNP-Equ also gives $P_{||}^{\text{NP}}$ -completeness for DNP-Geq. ■

4 Exact Versions of Generalized Dominating Set Problems

Heggernes and Telle [HT98] proposed a general, uniform approach to define graph problems by partitioning the vertex set of a graph into generalized dominating sets. Generalized dominating sets are parameterized by two sets of nonnegative integers, σ and ρ , which restrict the number of neighbors for each vertex in the partition. We use this approach to define the exact versions of such generalized dominating set problems and to study their computational complexity. In particular, we prove DP-completeness for a number of these problems. Using the techniques of Section 2, our results in the present section can easily be extended to more general results involving slightly more general problems and showing completeness in the higher levels of the boolean hierarchy.

4.1 Preliminaries

Let G be a graph. The *neighborhood of a vertex v in G* is the set of all vertices adjacent to v , i.e., $N(v) = \{w \in V(G) \mid \{v, w\} \in E(G)\}$. A *partition of $V(G)$* into k pairwise disjoint subsets V_1, V_2, \dots, V_k satisfies $V(G) = \bigcup_{i=1}^k V_i$ and $V_i \cap V_j = \emptyset$ for $1 \leq i < j \leq k$. Let $\mathbb{N} = \{0, 1, 2, \dots\}$ denote the set of nonnegative integers, and let $\mathbb{N}^+ = \{1, 2, 3, \dots\}$ denote the set of positive integers.

We now define the notions of (σ, ρ) -sets and (k, σ, ρ) -partitions introduced by Heggenes and Telle [HT98].

Definition 11 (Heggenes and Telle [HT98]) *Let G be a given graph, let $\sigma \subseteq \mathbb{N}$ and $\rho \subseteq \mathbb{N}$ be given sets, and let $k \in \mathbb{N}^+$.*

1. *A subset $U \subseteq V(G)$ of the vertices of G is said to be a (σ, ρ) -set if and only if for each $u \in U$, $\|N(u) \cap U\| \in \sigma$, and for each $u \notin U$, $\|N(u) \cap U\| \in \rho$.*
2. *A (k, σ, ρ) -partition of G is a partition of $V(G)$ into k pairwise disjoint subsets V_1, V_2, \dots, V_k such that V_i is a (σ, ρ) -set for each i , $1 \leq i \leq k$.*
3. *Define the problem*

$$(k, \sigma, \rho)\text{-Partition} = \{G \mid G \text{ is a graph that has a } (k, \sigma, \rho)\text{-partition}\}.$$

Heggenes and Telle [HT98] examined the (k, σ, ρ) -partitions of graphs for the parameters σ and ρ chosen among $\{0\}$, $\{1\}$, $\{0, 1\}$, \mathbb{N} , and \mathbb{N}^+ . In particular, they determined the precise cut-off points between tractability and intractability for these problems, that is, they determined the precise value of k for which the resulting (k, σ, ρ) -Partition problem is NP-complete, yet it can be decided in polynomial time whether or not a given graph has a $(k - 1, \sigma, \rho)$ -partition. An overview of their (and previously known) results is given in Table 1.

σ	ρ	\mathbb{N}	\mathbb{N}^+	$\{1\}$	$\{0, 1\}$
\mathbb{N}		∞^-	3^+	2	∞^-
\mathbb{N}^+		∞^-	2^+	2	∞^-
$\{1\}$		2^-	2	3	3^-
$\{0, 1\}$		2^-	2	3	3^-
$\{0\}$		3^-	3	4	4^-

Table 1: NP-completeness cut-off points for (k, σ, ρ) -Partition

For example, $(3, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ is nothing else than the NP-complete domatic number problem: Given a graph G , decide whether or not G can be partitioned into three dominating sets. In contrast, $(2, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ is in P, and therefore the corresponding entry in Table 1 is 3 for $\sigma = \mathbb{N}$ and $\rho = \mathbb{N}^+$. A value of ∞ in Table 1 means that this problem is efficiently solvable for all values of k . The value of $\rho = \{0\}$ is not considered, since all graphs have a $(k, \sigma, \{0\})$ -partition if and only if they have the trivial partition into k disjoint $(\sigma, \{0\})$ -sets $V_1 = V(G)$ and $V_i = \emptyset$, for each $i \in \{2, \dots, k\}$.

The problems in Table 1 that are marked by a “+” are maximum problems, and the problems that are marked by a “-” are minimum problems. That is, for all $k \geq 1$, we have that $(k + 1, \sigma, \rho)\text{-Partition} \subseteq (k, \sigma, \rho)\text{-Partition}$ for the maximum problems, and we have that $(k, \sigma, \rho)\text{-Partition} \subseteq (k + 1, \sigma, \rho)\text{-Partition}$ for the minimum problems. These properties are stated in the following fact.

- Fact 12** 1. For each $k \geq 1$ and for each $\sigma \in \{\mathbb{N}, \mathbb{N}^+, \{0\}, \{0, 1\}, \{1\}\}$, it holds that $(k, \sigma, \mathbb{N})\text{-Partition} \subseteq (k + 1, \sigma, \mathbb{N})\text{-Partition}$
2. For each $k \geq 1$ and for each $\sigma \in \{\mathbb{N}, \mathbb{N}^+, \{0\}, \{0, 1\}, \{1\}\}$, it holds that $(k, \sigma, \{0, 1\})\text{-Partition} \subseteq (k + 1, \sigma, \{0, 1\})\text{-Partition}$
3. For each $k \geq 1$ and for each $\sigma \in \{\mathbb{N}, \mathbb{N}^+\}$, it holds that $(k + 1, \sigma, \mathbb{N}^+)\text{-Partition} \subseteq (k, \sigma, \mathbb{N}^+)\text{-Partition}$

Proof. To see that all (k, σ, ρ) -Partition problems with $\rho = \mathbb{N}$ are minimum problems, note that we obtain a $(k + 1, \sigma, \mathbb{N})$ -partition from a (k, σ, \mathbb{N}) -partition by simply adding the empty set $V_{k+1} = \emptyset$. The proof for the case $\rho = \{0, 1\}$ is similar.

To prove that the (k, σ, ρ) -Partition problems with $\rho = \mathbb{N}^+$ are maximum problems, note that once we have found a $(k + 1, \sigma, \mathbb{N}^+)$ -partition into $k + 1$ pairwise disjoint sets V_1, V_2, \dots, V_{k+1} , the sets $V_1, V_2, \dots, V_{k-1}, \tilde{V}_k$ with $\tilde{V}_k = V_k \cup V_{k+1}$ are a $(k, \sigma, \mathbb{N}^+)$ -partition as well. \blacksquare

Observe that those problems in Table 1 that are marked neither by a “+” nor by a “−” are neither maximum nor minimum problems in the sense defined above. That is, we have neither $(k + 1, \sigma, \rho)\text{-Partition} \subseteq (k, \sigma, \rho)\text{-Partition}$ nor $(k, \sigma, \rho)\text{-Partition} \subseteq (k + 1, \sigma, \rho)\text{-Partition}$, since for each $k \geq 1$, there exist graphs G with $G \in (k, \sigma, \rho)\text{-Partition}$ and $G \notin (\ell, \sigma, \rho)\text{-Partition}$ for any $\ell \geq 1$ with $\ell \neq k$. For example, consider the problem $(k, \{1\}, \{1\})\text{-Partition}$. By definition, $(k, \{1\}, \{1\})\text{-Partition}$ contains all those graphs G that can be partitioned into k subsets V_1, V_2, \dots, V_k such that, for each i , if $v \in V_i$ then $\|N(v) \cap V_i\| = 1$, and if $v \notin V_i$ then $\|N(v) \cap V_i\| = 0$. It follows that every graph in $(k, \{1\}, \{1\})\text{-Partition}$ must be k -regular; that is, every vertex has degree k . Hence, for all $k \geq 1$, $(k, \{1\}, \{1\})\text{-Partition}$ and $(k + 1, \{1\}, \{1\})\text{-Partition}$ are disjoint, so neither $(k, \{1\}, \{1\})\text{-Partition} \subseteq (k + 1, \{1\}, \{1\})\text{-Partition}$ nor $(k + 1, \{1\}, \{1\})\text{-Partition} \subseteq (k, \{1\}, \{1\})\text{-Partition}$. In the case of $(k, \{0\}, \mathbb{N}^+)\text{-Partition}$, the complete graph K_n with n vertices is in $(n, \{0\}, \mathbb{N}^+)\text{-Partition}$ but not in $(k, \{0\}, \mathbb{N}^+)\text{-Partition}$ for any $k \geq 1$ with $k \neq n$. Almost the same argument applies to the case $\sigma = \mathbb{N}$ and $\rho = \{1\}$, except that now K_n is in $(k, \mathbb{N}, \{1\})\text{-Partition}$ for $k \in \{1, n\}$ but not in $(\ell, \mathbb{N}, \{1\})\text{-Partition}$ for any $\ell \geq 1$ with $\ell \notin \{1, n\}$. Similar arguments work in the other cases.

Therefore, when defining the exact versions of generalized dominating set problems, we confine ourselves to those (k, σ, ρ) -Partition problems that are minimum or maximum problems in the above sense. For a maximum problem, its exact version asks whether $G \in (k, \sigma, \rho)\text{-Partition}$ but $G \notin (k + 1, \sigma, \rho)\text{-Partition}$, and for a minimum problem, its exact version asks whether $G \in (k, \sigma, \rho)\text{-Partition}$ but $G \notin (k - 1, \sigma, \rho)\text{-Partition}$.

Definition 13 Let σ and ρ be chosen among $\mathbb{N}, \mathbb{N}^+, \{0\}, \{0, 1\}, \{1\}$, let $k \in \mathbb{N}^+$, and let $(k, \sigma, \rho)\text{-Partition}$ be a minimum or a maximum problem. Define its exact version as follows:

- $\text{Exact-}(k, \sigma, \rho)\text{-Partition} = (k, \sigma, \rho)\text{-Partition} \cap \overline{(k - 1, \sigma, \rho)\text{-Partition}}$ if $k \geq 2$ and $(k, \sigma, \rho)\text{-Partition}$ is a minimum problem.
- $\text{Exact-}(k, \sigma, \rho)\text{-Partition} = (k, \sigma, \rho)\text{-Partition} \cap \overline{(k + 1, \sigma, \rho)\text{-Partition}}$ if $k \geq 1$ and $(k, \sigma, \rho)\text{-Partition}$ is a maximum problem.

For example, the problem $(k, \{0\}, \mathbb{N})$ -Partition is equal to the k -colorability problem, which is a minimization problem: Given a graph G , find a partition into at most k color classes such that any two adjacent vertices belong to distinct color classes. In contrast, $(k, \mathbb{N}, \mathbb{N}^+)$ -Partition is equal to DNP, the domatic number problem, which is a maximization problem.

Clearly, since (k, σ, ρ) -Partition is in NP, $\text{Exact-}(k, \sigma, \rho)$ -Partition is in DP.

We now define two well-known problems that will be used later in our reductions. Both problems were shown to be NP-complete by Schaefer [Sch78]. Note that 1-3-SAT remains NP-complete even if all literals are positive.

Definition 14 Let $X = \{x_1, x_2, \dots, x_n\}$ be a finite set of variables.

- **1-3-SAT (“one-in-three satisfiability”)**: Let H be a boolean formula consisting of a collection $\mathcal{S} = \{S_1, S_2, \dots, S_m\}$ of m sets of literals over X such that each S_i has exactly three members. H is in 1-3-SAT if and only if there exists a subset T of the literals over X with $\|T \cap S_i\| = 1$ for each i , $1 \leq i \leq m$.
- **NAE-3-SAT (“not-all-equal satisfiability”)**: Let H be a boolean formula consisting of a collection $\mathcal{C} = \{c_1, c_2, \dots, c_m\}$ of m clauses over X such that each c_i contains exactly three literals. H is in NAE-3-SAT if and only if there exists a truth assignment for X that satisfies all clauses in \mathcal{C} and such that in none of the clauses, all literals are true.

4.2 The case $\rho = \mathbb{N}$

In this section, we are concerned with the minimum problems $\text{Exact-}(k, \sigma, \mathbb{N})$ -Partition, where σ is chosen from $\{\mathbb{N}, \mathbb{N}^+, \{0\}, \{0, 1\}, \{1\}\}$. Depending on the value $k \geq 2$, we ask how hard it is to decide whether a given graph G has a (k, σ, \mathbb{N}) -partition but not a $(k-1, \sigma, \mathbb{N})$ -partition.

The cases $\sigma = \mathbb{N}$ and $\sigma = \mathbb{N}^+$ are trivial, since for all $k \geq 1$, $(k, \mathbb{N}, \mathbb{N})$ -Partition and $(k, \mathbb{N}^+, \mathbb{N})$ -Partition are in P, which implies that the problems $\text{Exact-}(k, \mathbb{N}, \mathbb{N})$ -Partition and $\text{Exact-}(k, \mathbb{N}^+, \mathbb{N})$ -Partition are in P as well.

Now, suppose that $\sigma = \{0\}$. Recall that the problem $(k, \{0\}, \mathbb{N})$ -Partition is equal to the k -colorability problem. The question about the complexity of the exact versions of this problem was optimally solved by Rothe [Rot03]: $\text{Exact-}(4, \{0\}, \mathbb{N})$ -Partition is DP-complete, yet $\text{Exact-}(3, \{0\}, \mathbb{N})$ -Partition is NP-complete and thus cannot be DP-complete unless the boolean hierarchy collapses to the first level.

Now, suppose that $\sigma = \{0, 1\}$.

Definition 15 For every graph G , define the minimum value of k for which G has a $(k, \{0, 1\}, \mathbb{N})$ -partition as follows:

$$\alpha(G) = \min\{k \in \mathbb{N}^+ \mid G \in (k, \{0, 1\}, \mathbb{N})\text{-Partition}\}.$$

Theorem 16 1. $\text{Exact-}(5, \{0, 1\}, \mathbb{N})$ -Partition is DP-complete.

2. $\text{Exact-}(2, \{0, 1\}, \mathbb{N})$ -Partition is NP-complete.

Proof. 1. Since we have already noted that $\text{Exact-}(5, \{0, 1\}, \mathbb{N})\text{-Partition}$ is contained in DP, it remains to prove DP-hardness. Again, we apply Wagner's Lemma 4 with 1-3-SAT being the NP-complete problem A and with $\text{Exact-}(5, \{0, 1\}, \mathbb{N})\text{-Partition}$ being the set B from this lemma.

In their paper [HT98], Heggernes and Telle presented a \leq_m^P -reduction f from 1-3-SAT to $(2, \{0, 1\}, \mathbb{N})\text{-Partition}$ with the following properties:

$$\begin{aligned} H \in 1\text{-3-SAT} &\implies \alpha(f(H)) = 2 \\ H \notin 1\text{-3-SAT} &\implies \alpha(f(H)) = 3. \end{aligned}$$

In short, reduction f works as follows. Let H be any given boolean formula that consists of a collection $\mathcal{S} = \{S_1, S_2, \dots, S_m\}$ of m sets of literals over $X = \{x_1, x_2, \dots, x_n\}$. Without loss of generality, we may assume that all literals in H are positive. Reduction f maps H to a graph G as follows. For each set $S_i = \{x, y, z\}$, there is a 4-clique C_i in G induced by the vertices x_i, y_i, z_i , and a_i . For each literal x , there is an edge e_x in G . For each S_i in which x occurs, both endpoints of e_x are connected to the vertex x_i in C_i corresponding to $x \in S_i$. Finally, there is yet another 4-clique induced by the vertices s, t_1, t_2 , and t_3 . For each i with $1 \leq i \leq m$, vertex s is connected to a_i . This completes the reduction f . Figure 2 shows the graph G resulting from the reduction f applied to the formula $H = (x \vee y \vee z) \wedge (v \vee w \vee x) \wedge (u \vee w \vee z)$.

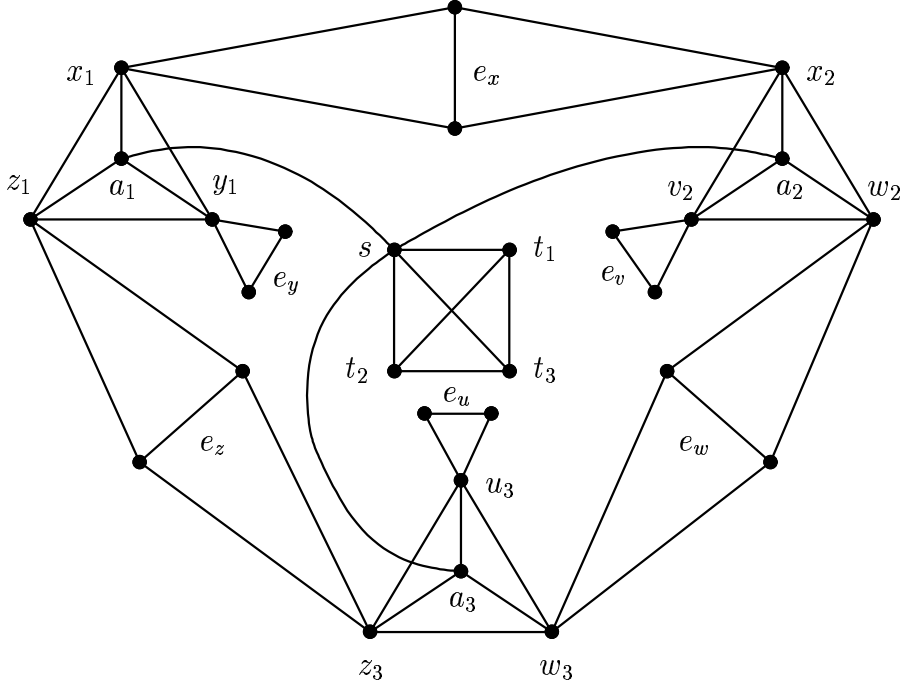


Figure 2: Heggernes and Telle's reduction f from 1-3-SAT to $(2, \{0, 1\}, \mathbb{N})\text{-Partition}$.

In order to apply Lemma 4, we need to find a reduction g satisfying

$$(H_1 \in 1\text{-3-SAT} \wedge H_2 \notin 1\text{-3-SAT}) \iff \alpha(g(H_1, H_2)) = 5 \quad (4.6)$$

for any two given instances H_1 and H_2 such that $H_2 \in 1\text{-3-SAT}$ implies $H_1 \in 1\text{-3-SAT}$.

Reduction g is constructed from f as follows. Let $G_{1,1}$ and $G_{1,2}$ be two disjoint copies of the graph $f(H_1)$, and let $G_{2,1}$ and $G_{2,2}$ be two disjoint copies of the graph $f(H_2)$. For $i \in \{1, 2\}$, define G_i to be the disjoint union of $G_{i,1}$ and $G_{i,2}$. Define the graph $G = g(H_1, H_2)$ to be the join of G_1 and G_2 . That is,

$$g(H_1, H_2) = G = G_1 \oplus G_2 = (G_{1,1} \cup G_{1,2}) \oplus (G_{2,1} \cup G_{2,2}).$$

Figure 3 shows the graph G resulting from the reduction g applied to the formulas

$$\begin{aligned} H_1 &= (x \vee y \vee z) \wedge (v \vee w \vee x) \wedge (u \vee w \vee z) \quad \text{and} \\ H_2 &= (c \vee d \vee e) \wedge (e \vee f \vee g) \wedge (g \vee h \vee i) \wedge (i \vee j \vee c). \end{aligned}$$

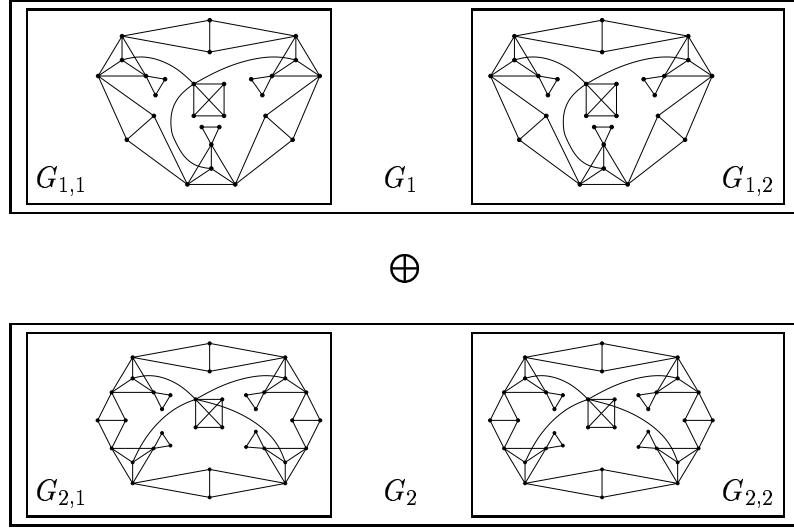


Figure 3: Graph $G = g(H_1, H_2)$ showing that $\text{Exact-}(5, \{0, 1\}, \mathbb{N})\text{-Partition}$ is DP-complete.

Let $a = \alpha(G_{1,1}) = \alpha(G_{1,2})$ and $b = \alpha(G_{2,1}) = \alpha(G_{2,2})$. Clearly, $\alpha(G_1) = a$, $\alpha(G_2) = b$, and $\alpha(G) \leq a + b$. Simply partition G the same way as graphs G_1 and G_2 were partitioned before. Note that we obtain 8-cliques in G as a result of joining pairs of 4-cliques from G_1 and G_2 . Thus, $\alpha(G) \geq 4$, since an 8-clique has to be partitioned into at least four disjoint $(\{0, 1\}, \mathbb{N})$ -sets.

To prove that $\alpha(G) = \alpha(G_1) + \alpha(G_2) = a + b$, let $k = \alpha(G)$. Thus, we know $4 \leq k \leq a + b$. For a contradiction, suppose that $k < a + b$. Distinguish the following cases.

Case 1: $a = b = 2$. Then $k < 4$ is a contradiction to $k \geq 4$.

Case 2: $a = 2$ and $b = 3$. Then $k = 4 < 5 = a + b$. One of the four disjoint $(\{0, 1\}, \mathbb{N})$ -sets consists of at least one vertex u in G_1 and one vertex v in G_2 . (Otherwise, it would induce a partition of less than two $(\{0, 1\}, \mathbb{N})$ -sets in G_1 or of less than three $(\{0, 1\}, \mathbb{N})$ -sets in G_2 , which contradicts our assumption $a = 2$ and $b = 3$.) Suppose that this set is V_1 . Then,

since $\sigma = \{0, 1\}$ and since u is adjacent to every vertex in G_2 and v is adjacent to every vertex in G_1 , we have $V_1 = \{u, v\}$. But there is no way to assign the 8-cliques, which do not contain u or v , to the remaining three $(\{0, 1\}, \mathbb{N})$ -sets in order to obtain a $(4, \{0, 1\}, \mathbb{N})$ -partition for G . This is a contradiction, and our assumption $k < a + b = 5$ does not hold. Thus, $k = 5$.

Case 3: $a = 3$ and $b = 2$. This case cannot occur, since we have to prove Equation (4.6) only for instances H_1 and H_2 such that $H_2 \in 1\text{-3-SAT}$ implies $H_1 \in 1\text{-3-SAT}$.

Case 4: $a = b = 3$. By the same argument used in Case 2, $k = 4$ does not hold. Suppose $k = 5$. As seen before, one of the sets in the partition must contain exactly one vertex u from G_1 and exactly one vertex v from G_2 . Let $V_1 = \{u, v\}$ be this set. There are four sets left for the partition, say V_2, V_3, V_4 , and V_5 . Every set V_i can have only vertices from either G_1 or G_2 . This means that two of these sets cover all vertices in G_1 except for u . Vertex u is either in $G_{1,1}$ or in $G_{1,2}$, which implies that one of these induced subgraphs ($G_{1,1}$ or $G_{1,2}$) has a $(2, \{0, 1\}, \mathbb{N})$ -partition. This is a contradiction to $a = 3$. Thus, $k = 6$.

Thus, $\alpha(G) = \alpha(G_1) + \alpha(G_2)$, which implies Equation (4.6) and thus fulfills Equation (2.1) of Lemma 4:

$$\begin{aligned} \|\{i \mid H_i \in 1\text{-3-SAT}\}\| \text{ is odd} &\iff H_1 \in 1\text{-3-SAT} \wedge H_2 \notin 1\text{-3-SAT} \\ &\iff \alpha(G_1) = 2 \wedge \alpha(G_2) = 3 \\ &\iff \alpha(G) = 5. \end{aligned}$$

By Lemma 4, **Exact-(5, $\{0, 1\}, \mathbb{N}$)-Partition** is DP-complete.

2. **Exact-(2, $\{0, 1\}, \mathbb{N}$)-Partition** is in NP, since **Exact-(2, $\{0, 1\}, \mathbb{N}$)-Partition** = $A \cap \overline{B}$ with $A = (2, \{0, 1\}, \mathbb{N})\text{-Partition}$ being in NP and $B = (1, \{0, 1\}, \mathbb{N})\text{-Partition}$ being in P. NP-hardness follows immediately via the reduction f :

$$H \in 1\text{-3-SAT} \iff f(H) \in \text{Exact-(2, } \{0, 1\}, \mathbb{N}\text{-Partition)}.$$

Thus, **Exact-(2, $\{0, 1\}, \mathbb{N}$)-Partition** is NP-complete. ■

Finally, suppose that $\sigma = \{1\}$.

Definition 17 For every graph G , define the minimum value k for which G has a $(k, \{1\}, \mathbb{N})$ -partition as follows:

$$\beta(G) = \min\{k \in \mathbb{N}^+ \mid G \in (k, \{1\}, \mathbb{N})\text{-Partition}\}.$$

Theorem 18 1. **Exact-(5, $\{1\}, \mathbb{N}$)-Partition** is DP-complete.

2. **Exact-(2, $\{1\}, \mathbb{N}$)-Partition** is NP-complete.

Proof. Clearly, $\alpha(G) \leq \beta(G)$ for all graphs G . Conversely, we show that $\alpha(G) \geq \beta(G)$. It is enough to do so for all graphs $G = f(H)$ resulting from any given instance H of 1-3-SAT via the reduction f in Theorem 16. If $H \in 1\text{-3-SAT}$, we have $\alpha(G) = 2$. Using the same partition, we even

get two $(\{1\}, \mathbb{N})$ -sets for G . Every vertex of G has exactly one neighbor, which is in the same set of the partition as the vertex itself. If $S \notin 1\text{-3-SAT}$, then $\alpha(G) = 3$. We can then partition G into three $(\{1\}, \mathbb{N})$ -sets: V_1 consists of the vertices s and t_1 plus the endpoints of each edge e_x . V_2 consists of t_2 and t_3 , every vertex a_i , and one more vertex in the 4-clique C_i , for each i with $1 \leq i \leq 2m$. The two remaining vertices in each C_i are then put into the set V_3 .

Hence, $\alpha(G) = \beta(G)$. The rest of the proof is analogous to the proof of Theorem 16. \blacksquare

4.3 The case $\rho = \mathbb{N}^+$

We consider the cases $\sigma = \mathbb{N}$ and $\sigma = \mathbb{N}^+$ only. These two are the only maximum problems in Table 1. Recall that since $(k, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ and $(k, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ are maximum problems, their exact versions are defined as follows:

$$\text{Exact-}(k, \sigma, \mathbb{N}^+)\text{-Partition} = \left\{ G \mid \begin{array}{l} G \in (k, \sigma, \mathbb{N}^+)\text{-Partition and} \\ G \notin (k+1, \sigma, \mathbb{N}^+)\text{-Partition} \end{array} \right\},$$

where $\sigma \in \{\mathbb{N}, \mathbb{N}^+\}$.

Again, note that $\text{Exact-}(k, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ and $\text{Exact-}(k, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ are in DP.

Suppose that $\sigma = \mathbb{N}$. Recall that the problem $(k, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ is equal to DNP, the domatic number problem. The exact version of this problem was already analyzed in Section 2. In the notation used in the present section, Theorem 7 (for the special case of $k = 1$) gives the following.

Corollary 19 1. $\text{Exact-}(5, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ is DP-complete.

2. $\text{Exact-}(2, \mathbb{N}, \mathbb{N}^+)\text{-Partition}$ is coNP-complete.

Now, suppose that $\sigma = \mathbb{N}^+$.

Definition 20 For every graph G , define the maximum value k for which G has a $(k, \mathbb{N}^+, \mathbb{N}^+)\text{-partition}$ as follows:

$$\gamma(G) = \max\{k \in \mathbb{N}^+ \mid G \in (k, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}\}.$$

Theorem 21 1. $\text{Exact-}(3, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ is DP-complete.

2. $\text{Exact-}(1, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ is coNP-complete.

Proof. 1. Heggernes and Telle [HT98] presented a reduction from the problem NAE-3-SAT to the problem $(2, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ to prove the latter problem NP-complete. We modify their reduction as follows. Let two boolean formulas $H_1 = (X, \hat{C})$ and $H_2 = (Y, \hat{D})$ be given, with disjoint variable sets, $X = \{x_1, x_2, \dots, x_n\}$ and $Y = \{y_1, y_2, \dots, y_r\}$, and with disjoint clause sets, $\hat{C} = \{c_1, c_2, \dots, c_m\}$ and $\hat{D} = \{d_1, d_2, \dots, d_s\}$. If the variable sets consist of less than two variables, we put additional variables into the sets. Moreover, we may assume without loss of generality that every literal appears in at least one clause, since otherwise we can easily alter the

given formulas H_1 and H_2 , without changing membership in NAE-3-SAT, so that they are of this form.

For any clause $c = (x \vee y \vee z)$, define $\check{c} = (\bar{x} \vee \bar{y} \vee \bar{z})$, where \bar{x} , \bar{y} , and \bar{z} , respectively, denotes the negation of the literal x , y , and z . Define $\hat{C} = \{\check{c}_1, \check{c}_2, \dots, \check{c}_m\}$ and $\check{D} = \{\check{d}_1, \check{d}_2, \dots, \check{d}_s\}$, and define $C = \hat{C} \cup \check{C}$ and $D = \hat{D} \cup \check{D}$. Note that due to the not-all-equal property, we have:

$$\begin{aligned} (X, C) \in \text{NAE-3-SAT} &\iff (X, \hat{C}) \in \text{NAE-3-SAT} \\ &\iff (X, \check{C}) \in \text{NAE-3-SAT} \end{aligned}$$

and

$$\begin{aligned} (Y, D) \in \text{NAE-3-SAT} &\iff (Y, \hat{D}) \in \text{NAE-3-SAT} \\ &\iff (Y, \check{D}) \in \text{NAE-3-SAT}. \end{aligned}$$

We apply Lemma 4 with $k = 1$ and with NAE-3-SAT being the NP-complete problem A and with **Exact-(3, \mathbb{N}^+ , \mathbb{N}^+)-Partition** being the set B from this lemma. Let H_1 and H_2 be such that $H_2 \in \text{NAE-3-SAT}$ implies $H_1 \in \text{NAE-3-SAT}$. Our polynomial-time reduction f transforms H_1 and H_2 into a graph $G = f(H_1, H_2)$ with the property:

$$(H_1 \in \text{NAE-3-SAT} \wedge H_2 \notin \text{NAE-3-SAT}) \iff \gamma(G) = 3. \quad (4.7)$$

The reduction f is defined as follows. For H_1 , we create an 8-clique A_8 with vertices a_1, a_2, \dots, a_8 . We do the same for H_2 , creating an 8-clique B_8 with vertices b_1, b_2, \dots, b_8 . For each i with $1 \leq i \leq n$, we create two vertices, x_i and \bar{x}_i , for the variable x_i . For each j with $1 \leq j \leq r$, we create two vertices, y_j and \bar{y}_j , for the variable y_j . Every vertex x_i and \bar{x}_i is connected to both a_1 and a_2 , and every vertex y_j and \bar{y}_j is connected to both b_1 and b_2 . For each pair of variables (x_i, y_j) , we create one vertex $u_{i,j}$ that is connected to the four vertices x_i, \bar{x}_i, y_j , and \bar{y}_j . Finally, for each clause $c_i \in C$ and $d_j \in D$ with $1 \leq i \leq m$ and $1 \leq j \leq s$, we create the two vertices c_i and d_j . Each such clause vertex is connected to the vertices representing the literals in that clause. Additionally, every vertex c_i is connected to both a_1 and a_2 , and every vertex d_j is connected to both b_1 and b_2 . This completes the construction of the graph $G = f(H_1, H_2)$.

Figure 4 shows the graph G resulting from the reduction f applied to the two formulas

$$\begin{aligned} H_1 &= (x_1 \vee \bar{x}_2 \vee x_3) \wedge (\bar{x}_1 \vee x_2 \vee x_3) \quad \text{and} \\ H_2 &= (y_1 \vee y_2 \vee y_3) \wedge (\bar{y}_1 \vee \bar{y}_2 \vee \bar{y}_3). \end{aligned}$$

Note that $\gamma(G) \leq 4$, since the degree of each $u_{i,j}$ is four. We have four cases to distinguish.

Case 1: $H_1 \in \text{NAE-3-SAT}$ and $H_2 \in \text{NAE-3-SAT}$. Let t be a truth assignment satisfying H_1 , and let \tilde{t} be a truth assignment satisfying H_2 . We can partition G into four $(\mathbb{N}^+, \mathbb{N}^+)$ -sets $V_1, V_2,$

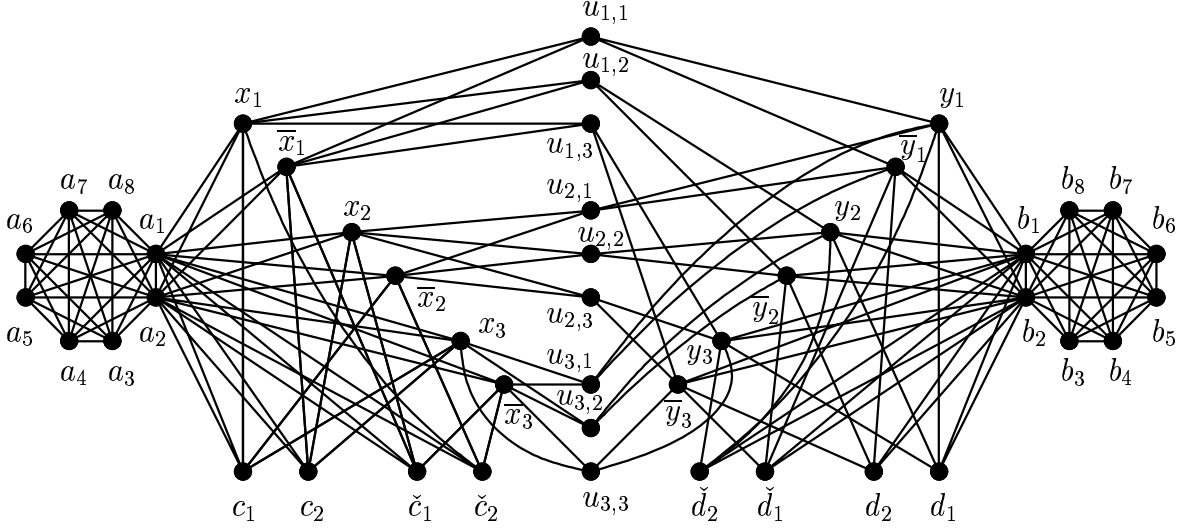


Figure 4: Graph $G = f(H_1, H_2)$ showing that $\text{Exact-}(3, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ is DP-complete.

V_3 , and V_4 as follows:

$$\begin{aligned}
V_1 &= \hat{C} \cup \check{C} \cup \{a_5, a_6\} \cup \{b_1, b_3\} \cup \{x \mid x \text{ is a literal over } X \text{ and } t(x) = \text{true}\}, \\
V_2 &= \{u_{i,j} \mid (1 \leq i \leq n-1 \wedge j = 1) \vee (i = n \wedge 2 \leq j \leq r)\} \cup \{a_7, a_8\} \cup \{b_2, b_4\} \\
&\quad \cup \{x \mid x \text{ is a literal over } X \text{ and } t(x) = \text{false}\}, \\
V_3 &= \hat{D} \cup \check{D} \cup \{a_1, a_3\} \cup \{b_5, b_6\} \cup \{y \mid y \text{ is a literal over } Y \text{ and } \tilde{t}(y) = \text{true}\}, \\
V_4 &= \{u_{i,j} \mid (i = n \wedge j = r) \vee (1 \leq i \leq n-1 \wedge 2 \leq j \leq r)\} \cup \{a_2, a_4\} \cup \{b_7, b_8\} \\
&\quad \cup \{y \mid y \text{ is a literal over } Y \text{ and } \tilde{t}(y) = \text{false}\}.
\end{aligned}$$

Thus, $\gamma(G) \geq 4$. Since $\gamma(G) \leq 4$, it follows that $\gamma(G) = 4$ in this case.

Case 2: $H_1 \in \text{NAE-3-SAT}$ and $H_2 \notin \text{NAE-3-SAT}$. Let t be a truth assignment satisfying H_1 . We can partition G into three $(\mathbb{N}^+, \mathbb{N}^+)\text{-sets}$ V_1, V_2 , and V_3 as follows:

$$\begin{aligned}
V_1 &= \hat{C} \cup \check{C} \cup \{a_5, a_6\} \cup \{b_1, b_3\} \cup \{x \mid x \text{ is a literal over } X \text{ and } t(x) = \text{true}\}, \\
V_2 &= \{u_{i,j} \mid 1 \leq i \leq n \wedge 1 \leq j \leq r\} \cup \{a_7, a_8\} \cup \{b_2, b_4\} \\
&\quad \cup \{x \mid x \text{ is a literal over } X \text{ and } t(x) = \text{false}\}, \\
V_3 &= \hat{D} \cup \check{D} \cup \{a_1, a_2, a_3, a_4\} \cup \{b_5, b_6, b_7, b_8\} \cup \{y \mid y \text{ is a literal over } Y\}.
\end{aligned}$$

Thus, $3 \leq \gamma(G) \leq 4$. For a contradiction, suppose that $\gamma(G) = 4$, with a partition of G into four $(\mathbb{N}^+, \mathbb{N}^+)\text{-sets}$, say U_1, U_2, U_3 , and U_4 . Vertex $u_{1,1}$ is adjacent to exactly four vertices, namely to x_1, \bar{x}_1, y_1 and \bar{y}_1 . These four vertices must then be in four distinct sets of the

partition. Without loss of generality, suppose that $x_1 \in U_1$, $\bar{x}_1 \in U_2$, $y_1 \in U_3$, and $\bar{y}_1 \in U_4$. For each j with $2 \leq j \leq r$, the vertices y_j and \bar{y}_j are connected to x_1 and \bar{x}_1 via vertex $u_{1,j}$, so it follows that either $y_j \in U_3$ and $\bar{y}_j \in U_4$, or $y_j \in U_4$ and $\bar{y}_j \in U_3$.

Every clause vertex d_j , $1 \leq j \leq r$, is connected only to the vertices representing its literals and to the vertices b_1 and b_2 , which therefore must be in the sets U_1 and U_2 , respectively. Thus, every clause vertex d_j is connected to at least one literal vertex in U_3 and to at least one literal vertex in U_4 . This describes a valid truth assignment for H_2 in the not-all-equal sense. This is a contradiction to the case assumption $H_2 \notin \text{NAE-3-SAT}$.

Case 3: $H_1 \notin \text{NAE-3-SAT}$ and $H_2 \in \text{NAE-3-SAT}$. This case is a contradiction to our assumption that $H_2 \in \text{NAE-3-SAT}$ implies $H_1 \in \text{NAE-3-SAT}$, and therefore it cannot occur.

Case 4: $H_1 \notin \text{NAE-3-SAT}$ and $H_2 \notin \text{NAE-3-SAT}$. A valid partition of G into two $(\mathbb{N}^+, \mathbb{N}^+)$ -sets is:

$$\begin{aligned} V_1 &= \{u_{i,j} \mid 1 \leq i \leq n \wedge 1 \leq j \leq r\} \cup \{x_i \mid 1 \leq i \leq n\} \cup \{y_j \mid 1 \leq j \leq r\} \\ &\quad \cup \{a_1, a_3, a_5, a_7\} \cup \{b_1, b_3, b_5, b_7\}, \\ V_2 &= \hat{C} \cup \check{C} \cup \hat{D} \cup \check{D} \cup \{\bar{x}_i \mid 1 \leq i \leq n\} \cup \{\bar{y}_j \mid 1 \leq j \leq r\} \\ &\quad \cup \{a_2, a_4, a_6, a_8\} \cup \{b_2, b_4, b_6, b_8\}. \end{aligned}$$

Thus, $2 \leq \gamma(G) \leq 4$. By the same argument as in Case 2, $\gamma(G) \neq 4$. For a contradiction, suppose that $\gamma(G) = 3$, with a partition of G into three $(\mathbb{N}^+, \mathbb{N}^+)$ -sets, say U_1 , U_2 , and U_3 . Without loss of generality, assume that x_1 and \bar{x}_1 belong to distinct U_i sets,² say $x_1 \in U_1$ and $\bar{x}_1 \in U_2$.

It follows that for each j with $1 \leq j \leq r$, at least one of y_j or \bar{y}_j has to be in U_3 . If both vertices are in U_3 , then we have:

$$(\forall i : 1 \leq i \leq n) \quad [\text{either } x_i \in U_1 \text{ and } \bar{x}_i \in U_2, \text{ or } x_i \in U_2 \text{ and } \bar{x}_i \in U_1]. \quad (4.8)$$

Since $H_1 \notin \text{NAE-3-SAT}$, for each truth assignment t for H_1 , there exists a clause $c_i \in \hat{C}$ such that $c_i = (x \vee y \vee z)$ and the literals x , y , and z are either simultaneously true or simultaneously false under t . Note that for the corresponding clause $\check{c}_i \in \check{C}$, which contains the negations of x , y , and z , the truth value of its literals is flipped under t . That is, $t(\bar{x}) = 1 - t(x)$, $t(\bar{y}) = 1 - t(y)$, and $t(\bar{z}) = 1 - t(z)$. Since the corresponding clause vertex c_i is adjacent to x , y , z , a_1 , and a_2 , it follows that x , y , and z are in the same set of the partition, say in U_1 . Hence, either $a_1 \in U_2$ and $a_2 \in U_3$, or $a_1 \in U_3$ and $a_2 \in U_2$. Similarly, since the clause vertex \check{c}_i is adjacent to \bar{x} , \bar{y} , \bar{z} , a_1 , and a_2 , the vertices \bar{x} , \bar{y} , \bar{z} are in the same set of the partition that must be distinct from U_1 . Let U_2 , say, be that set. It follows that either $a_1 \in U_1$ and $a_2 \in U_3$, or $a_1 \in U_3$ and $a_2 \in U_1$, which is a contradiction.

Each of the remaining subcases can be reduced to (4.8), and the above contradiction follows. Hence, $\gamma(G) = 2$.

²If x_1 and \bar{x}_1 both belong to the same set U_i , then each y_j and \bar{y}_j must belong to distinct sets U_k and U_ℓ , $k \neq \ell$, since $u_{1,j}$ is connected with x_1 , \bar{x}_1 , y_j , and \bar{y}_j . Thus, a symmetric argument works for y_j and \bar{y}_j in this case.

Thus, we obtain:

$$\begin{aligned} \|\{i \mid H_i \in \text{NAE-3-SAT}\}\| \text{ is odd} &\iff H_1 \in \text{NAE-3-SAT} \wedge H_2 \notin \text{NAE-3-SAT} \\ &\iff \gamma(G) = 3, \end{aligned}$$

which proves Equation (4.7). Thus, Equation (2.1) of Lemma 4 is fulfilled, and it follows that **Exact**-(3, \mathbb{N}^+ , \mathbb{N}^+)-**Partition** is DP-complete.

2. **Exact**-(1, \mathbb{N}^+ , \mathbb{N}^+)-**Partition** is in coNP, since **Exact**-(1, \mathbb{N}^+ , \mathbb{N}^+)-**Partition** = $A \cap \overline{B}$ with $A = (1, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ being in P and $B = (2, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ being in NP. Note that the coNP-hardness of **Exact**-(1, \mathbb{N}^+ , \mathbb{N}^+)-**Partition** follows immediately via the original reduction from **NAE-3-SAT** to $(2, \mathbb{N}^+, \mathbb{N}^+)\text{-Partition}$ presented in [HT98]. \blacksquare

	ρ	\mathbb{N}	\mathbb{N}^+
σ			
\mathbb{N}		∞	5*
\mathbb{N}^+		∞	3*
{1}		5*	–
{0, 1}		5*	–
{0}		4	–

Table 2: DP-completeness values for **Exact**-(k, σ, ρ)-**Partition**

The numbers in Table 2 indicate the best DP-completeness results currently known for the exact versions of generalized dominatic set problems, where the results from this paper are marked with an asterisk.³ That is, they give the best value of k for which the problem **Exact**-(k, σ, ρ)-**Partition** is known to be DP-complete. In many cases this value is not yet optimal. For example, **Exact**-(5, \mathbb{N}, \mathbb{N}^+)-**Partition** is known to be DP-complete and **Exact**-(2, \mathbb{N}, \mathbb{N}^+)-**Partition** is known to be coNP-complete. What about **Exact**-(3, \mathbb{N}, \mathbb{N}^+)-**Partition** and **Exact**-(4, \mathbb{N}, \mathbb{N}^+)-**Partition**? Only the DP-completeness of **Exact**-(4, {0}, \mathbb{N})-**Partition** is known to be optimal [Rot03].

5 The Exact Conveyor Flow Shop Problem

The conveyor flow shop problem is a minimization problem arising in real-world applications in the wholesale business, where warehouses are supplied with goods from a central storehouse. Suppose you are given m machines, P_1, P_2, \dots, P_m , and n jobs, J_1, J_2, \dots, J_n . Conveyor belt systems are used to convey jobs from machine to machine at which they are to be processed in a “permutation flow shop” manner. That is, the jobs visit the machines in the fixed order P_1, P_2, \dots, P_m , and the machines process the jobs in the fixed order J_1, J_2, \dots, J_n . An $(n \times m)$ task matrix $\mathcal{M} = (\mu_{j,p})_{j,p}$ with $\mu_{j,p} \in \{0, 1\}$ provides the information which job has to be processed at which machine:

³Again, a value of ∞ in Table 2 means that this problem is efficiently solvable for all values of k .

$\mu_{j,p} = 1$ if job J_j is to be processed at machine P_p , and $\mu_{j,p} = 0$ otherwise. Every machine can process at most one job at a time. There is one worker supervising the system. Every machine can process a job only if the worker is present, which means that the worker occasionally has to move from one machine to another. If the worker is currently not present at some machine, jobs can be queued in a buffer at this machine. The objective is to minimize the movement of the worker, where we assume the “unit distance” between any two machines, i.e., to measure the worker’s movement, we simply count how many times he has switched machines until the complete task matrix has been processed.⁴ Let $\Delta_{\min}(\mathcal{M})$ denote the minimum number of machine switches needed for the worker to completely process a given task matrix \mathcal{M} , where the minimum is taken over all possible orders in which the tasks in \mathcal{M} can be processed. Define the decision version of the conveyor flow shop problem by:

$$\text{CFSP} = \{ \langle \mathcal{M}, k \rangle \mid \mathcal{M} \text{ is a task matrix and } k \text{ is a positive integer such that } \Delta_{\min}(\mathcal{M}) \leq k \}.$$

Espelage and Wanke [EW00,Esp01,EW01,EW03] introduced and studied the problem CFSP, and variations thereof, extensively. We are interested in the complexity of the exact version of CFSP.

Definition 22 *Define the exact version of the conveyor flow shop problem by:*

$$\text{Exact-}k\text{-CFSP} = \left\{ \langle \mathcal{M}, S_k \rangle \mid \begin{array}{l} \mathcal{M} \text{ is a task matrix and } S_k \subseteq \mathbb{N} \text{ is a set of } k \\ \text{noncontiguous integers with } \Delta_{\min}(\mathcal{M}) \in S_k \end{array} \right\}.$$

To show that CFSP is NP-complete, Espelage [Esp01, pp. 27–44] provided, in a rather involved 17 pages proof, a reduction g from the 3-SAT problem to CFSP, via the intermediate problem of finding a “minimum valid block cover” of a given task matrix \mathcal{M} . In particular, finding a minimum block cover of \mathcal{M} directly yields a minimum number of machine switches. Espelage’s reduction can easily be modified so as to have certain useful properties, which we state in the following lemma. The details of this modification can be found in [Rie02]; in particular, prior to the Espelage reduction, a reduction from the (unrestricted) satisfiability problem to 3-SAT is used that has the properties stated as Equations (5.9) and (5.10) below.

Lemma 23 (Espelage and Riege; see pp. 27–44 of [Esp01] and pp. 37–42 of [Rie02])

There exists a polynomial-time many-one reduction g that witnesses $3\text{-SAT} \leq_{\text{m}}^{\text{p}} \text{CFSP}$ and satisfies, for each given boolean formula φ , the following properties:

1. $g(\varphi) = \langle \mathcal{M}_\varphi, z_\varphi \rangle$, where \mathcal{M}_φ is a task matrix and $z_\varphi \in \mathbb{N}$ is an odd number.
2. $\Delta_{\min}(\mathcal{M}_\varphi) = z_\varphi + u_\varphi$, where u_φ denotes the minimum number of clauses of φ not satisfied under assignment t , where the minimum is taken over all assignments t of φ . Moreover, $u_\varphi = 0$ if $\varphi \in 3\text{-SAT}$, and $u_\varphi = 1$ if $\varphi \notin 3\text{-SAT}$.

In particular, $\varphi \in 3\text{-SAT}$ if and only if $\Delta_{\min}(\mathcal{M}_\varphi)$ is odd.

Theorem 24 *For each $k \geq 1$, Exact- k -CFSP is $\text{BH}_{2k}(\text{NP})$ -complete. In particular, for $k = 1$, Exact-1-CFSP is DP-complete.*

⁴In this paper, we do not consider possible generalizations of the problem CFSP such as other distance functions, variable job sequences, more than one worker, etc. We refer to [Esp01] for results on such more general problems.

Proof. Analogously to the proof of Theorem 7, we can show that **Exact- k -CFSP** is in $\text{BH}_{2k}(\text{NP})$. To prove $\text{BH}_{2k}(\text{NP})$ -hardness of **Exact- k -CFSP**, we again apply Lemma 4, with some fixed NP-complete problem A and with **Exact- k -CFSP** being the problem B from this lemma. The reduction f satisfying Equation (2.1) from Lemma 4 is defined by using two polynomial-time many-one reductions, g and h .

We now define the reductions g and h . Fix the NP-complete problem A . Let x_1, x_2, \dots, x_{2k} be strings in Σ^* satisfying that $c_A(x_1) \geq c_A(x_2) \geq \dots \geq c_A(x_{2k})$, where c_A denotes the characteristic function of A , i.e., $c_A(x) = 1$ if $x \in A$, and $c_A(x) = 0$ if $x \notin A$. Wagner [Wag87] observed that the standard reduction (cf. [GJ79]) from the (unrestricted) satisfiability problem to 3-SAT can be easily modified so as to yield a reduction h from A to 3-SAT (via the intermediate satisfiability problem) such that, for each $x \in \Sigma^*$, the boolean formula $\varphi = h(x)$ satisfies the following properties:

$$x \in A \implies s_\varphi = m_\varphi; \quad (5.9)$$

$$x \notin A \implies s_\varphi = m_\varphi - 1, \quad (5.10)$$

where $s_\varphi = \max_t \{\ell \mid \ell \text{ clauses of } \varphi \text{ are satisfied under assignment } t\}$, and m_φ denotes the number of clauses of φ . Moreover, m_φ is always odd.

Let $\varphi_1, \varphi_2, \dots, \varphi_{2k}$ be the boolean formulas after applying reduction h to each given $x_i \in \Sigma^*$, i.e., $\varphi_i = h(x_i)$ for each i . For $i \in \{1, 2, \dots, 2k\}$, let $m_i = m_{\varphi_i}$ be the number of clauses in φ_i , and let $s_i = s_{\varphi_i}$ denote the maximum number of satisfiable clauses of φ_i , where the maximum is taken over all assignments of φ_i . For each i , apply the Lemma 23 reduction g from 3-SAT to CFSP to obtain $2k$ pairs $\langle \mathcal{M}_i, z_i \rangle = g(\varphi_i)$, where each $\mathcal{M}_i = \mathcal{M}_{\varphi_i}$ is a task matrix and each $z_i = z_{\varphi_i}$ is the odd number corresponding to φ_i according to Lemma 23. Use these $2k$ task matrices to form a new task matrix:

$$\mathcal{M} = \begin{pmatrix} \mathcal{M}_1 & 0 & \dots & 0 \\ 0 & \mathcal{M}_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \mathcal{M}_{2k} \end{pmatrix}.$$

Every task of some matrix \mathcal{M}_i , where $1 \leq i \leq 2k$, can be processed only if all tasks of the matrices \mathcal{M}_j with $j < i$ have already been processed; see [Esp01,Rie02] for arguments as to why this is true. This implies that:

$$\Delta_{\min}(\mathcal{M}) = \sum_{i=1}^{2k} \Delta_{\min}(\mathcal{M}_i).$$

Let $z = \sum_{i=1}^{2k} z_i$; note that z is even. Define the set $S_k = \{z+1, z+3, \dots, z+2k-1\}$, and define the reduction f by $f(x_1, x_2, \dots, x_{2k}) = \langle \mathcal{M}, S_k \rangle$. Clearly, f is polynomial-time computable.

Let $u_i = u_{\varphi_i} = \min_t \{\ell \mid \ell \text{ clauses of } \varphi_i \text{ are not satisfied under assignment } t\}$. Equations (5.9) and (5.10) then imply that for each i :

$$u_i = m_i - s_i = \begin{cases} 0 & \text{if } x_i \in A \\ 1 & \text{if } x_i \notin A. \end{cases}$$

Recall that, by Lemma 23, we have $\Delta_{\min}(\mathcal{M}_i) = z_i + u_i$. Hence:

$|\{i \mid x_i \in A\}|$ is odd

$$\iff (\exists i : 1 \leq i \leq k) [x_1, \dots, x_{2i-1} \in A \text{ and } x_{2i}, \dots, x_{2k} \notin A]$$

$$\iff (\exists i : 1 \leq i \leq k) [s_1 = m_1, \dots, s_{2i-1} = m_{2i-1} \text{ and } s_{2i} = m_{2i} - 1, \dots, s_{2k} = m_{2k} - 1]$$

$$\iff (\exists i : 1 \leq i \leq k) [\Delta_{\min}(\mathcal{M}_1) = z_1, \dots, \Delta_{\min}(\mathcal{M}_{2i-1}) = z_{2i-1} \text{ and} \\ \Delta_{\min}(\mathcal{M}_{2i}) = z_{2i} + 1, \dots, \Delta_{\min}(\mathcal{M}_{2k}) = z_{2k} + 1]$$

$$\iff (\exists i : 1 \leq i \leq k) \left[\Delta_{\min}(\mathcal{M}) = \sum_{j=1}^{2k} \Delta_{\min}(\mathcal{M}_j) = \left(\sum_{j=1}^{2k} z_j \right) + 2k - 2i + 1 \right]$$

$$\iff \Delta_{\min}(\mathcal{M}) \in S_k = \{z + 1, z + 3, \dots, z + 2k - 1\}$$

$$\iff f(x_1, x_2, \dots, x_{2k}) = \langle \mathcal{M}, S_k \rangle \in \text{Exact-}k\text{-CFSP.}$$

Thus, f satisfies Equation (2.1). By Lemma 4, **Exact- k -CFSP** is $\text{BH}_{2k}(\text{NP})$ -complete. \blacksquare

6 Conclusions and Open Questions

In this paper, we have shown that the exact versions of the domatic number problem and of the conveyor flow shop problem are complete for the levels of the boolean hierarchy over NP. In particular, for $k = 1$ and for each given integer $i \geq 5$, it is DP-complete to determine whether or not $\delta(G) = i$ for a given graph G . In contrast, **Exact-2-DNP** is coNP-complete, and thus this problem cannot be DP-complete unless the boolean hierarchy collapses. For $i \in \{3, 4\}$, the question of whether or not the problems **Exact- i -DNP** are DP-complete remains an interesting open problem. As mentioned in the introduction, the corresponding gap for the exact chromatic number problem was recently closed by Rothe [Rot03]; see also [RSV02]. His reduction uses both the standard reduction from 3-SAT to 3-Colorability (cf. [GJ79]) and a very clever reduction found by Guruswami and Khanna [GK00]. The decisive property of the Guruswami–Khanna reduction is that it maps each satisfiable formula φ to a graph G with $\chi(G) = 3$, and it maps each unsatisfiable formula φ to a graph G with $\chi(G) = 5$. That is, the graphs they construct are never 4-colorable. To close the above-mentioned gap for the exact domatic number problem, one would have to find a reduction from some NP-complete problem to DNP with a similarly strong property: the reduction would have to yield graphs that never have a domatic number of 3.

In Section 4, we have studied the exact versions of generalized dominating set problems. Based on the uniform approach of Heggernes and Telle [HT98], we have considered problems of the form **Exact- (k, σ, ρ) -Partition**, where the parameters σ and ρ give the number of neighbors allowed for each vertex in the partition. We have obtained DP-completeness results for the minimization problems **Exact- $(5, \{0, 1\}, \mathbb{N})$ -Partition** and **Exact- $(5, \{1\}, \mathbb{N})$ -Partition**, and for the maximization problems **Exact- $(5, \mathbb{N}, \mathbb{N}^+)$ -Partition** and **Exact- $(3, \mathbb{N}^+, \mathbb{N}^+)$ -Partition**. These results are summarized in Table 2. Note that **Exact- $(k, \mathbb{N}, \mathbb{N}^+)$ -Partition** = **Exact- k -DNP**. Again, there arises the question of whether the value of $k = 3$ for $\sigma = \rho = \mathbb{N}^+$ and the value

of $k = 5$ in the other cases is optimal in all these results. We were only able to show these problems NP-complete or coNP-complete for the value of $k = 1$ if $\sigma = \rho = \mathbb{N}^+$ and for the value of $k = 2$ in the other cases, thus leaving a gap between DP-completeness and membership in NP or coNP.

Another interesting open question is whether one can obtain similar results for the minimization problems **Exact- $(k, \sigma, \{0, 1\})$ -Partition** for $\sigma \in \{\{0\}, \{0, 1\}, \{1\}\}$. It appears that the constructions that we used in Theorems 7, 16, 18, and 21 do not work here.

In Section 5, we studied the exact conveyor flow shop problem using similar techniques. We proved that **Exact-1-CFSP** is DP-complete and **Exact- k -CFSP** is $\text{BH}_{2k}(\text{NP})$ -complete. Note that in defining these problems, we do not specify a fixed set S_k with k fixed values as problem parameters; see Definition 22. Rather, only the cardinality k of such sets is given as a parameter, and S_k is part of the problem instance of **Exact- k -CFSP**. The reason is that the actual values of S_k depend on the input of the reduction f defined in the proof of Theorem 24. In particular, the number z_φ from Lemma 23, which is used to define the number $z = \sum_{i=1}^{2k} z_i$ in the proof of Theorem 24, has the following form (see [Esp01,Rie02]):

$$z_\varphi = 28n_K + 27n_{\overline{K}} + 8n_U + 90mt + 99m,$$

where t is the number of variables and m is the number of clauses of the given boolean formula φ , and n_K , $n_{\overline{K}}$, and n_U denote respectively the number of “coupling, inverting coupling, and interrupting elements” of the “minimum valid block cover” constructed in the Espelage reduction [Esp01] from 3-SAT to CFSP. It would be interesting to know whether one can obtain $\text{BH}_{2k}(\text{NP})$ -completeness of **Exact- k -CFSP** even if a set S_k of k fixed values is specified a priori.

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