Finding a Heaviest Triangle is not Harder than Matrix Multiplication

Artur Czumaj  
Department of Computer Science  
New Jersey Institute of Technology  
aczumaj@acm.org

Andrzej Lingas  
Department of Computer Science  
Lund University  
Andrzej.Lingas@cs.lth.se

Abstract

We show that for any $\epsilon > 0$, a maximum-weight triangle in an undirected graph with $n$ vertices and real weights assigned to vertices can be found in time $O(n^\omega + n^{2+\epsilon})$, where $\omega$ is the exponent of fastest matrix multiplication algorithm. By the currently best bound on $\omega$, the running time of our algorithm is $O(n^{2.376})$. Our algorithm substantially improves the previous time-bounds for this problem recently established by Vassilevska et al. (STOC 2006, $O(n^{2.688})$) and (ICALP 2006, $O(n^{2.575})$). Its asymptotic time complexity matches that of the fastest known algorithm for finding a triangle (not necessarily a maximum-weight one) in a graph.

By applying or extending our algorithm, we can also improve the upper bounds on finding a maximum-weight triangle in a sparse graph and on finding a maximum-weight subgraph isomorphic to a fixed graph established in the papers by Vassilevska et al. For example, we can find a maximum-weight triangle in a vertex-weighted graph with $m$ edges in asymptotic time required by the fastest algorithm for finding any triangle in a graph with $m$ edges, i.e., in time $O(m^{1.41})$.

*Research supported in part by NSF ITR grant CCR-0313219 and by VR grant 621-2005-4085.
1 Introduction

We consider a classical graph problem of finding a fixed subgraph in a graph. The most basic version of that problem, that of finding a triangle (a cycle of length three), is related to the shortest path problem. It is well known that the asymptotic time complexity of finding a triangle in a graph does not exceed that of matrix multiplication (cf. [10]), that is, $O(n^\omega)$, where $\omega < 2.376$ is the exponent of the fastest matrix multiplication algorithm [4] (see also [2]).

The more general problem of finding a maximum-weight triangle in a graph with vertex or edge weights has been widely open for long time. The first substantially sub-cubic upper time-bound for vertex weighted graphs has been established only recently by Vassilevska et al. in [12]. It has been later improved by Vassilevska et al. [13], who observed that the problem of finding a maximum weight triangle in a vertex-weighted graph immediately reduces to the problem of finding the so-called maximum witnesses of Boolean matrix product studied in [7, 11]. Hence, by the upper time-bound $O(n^{2.616})$ for the latter problem established in [11] (improved to $O(n^{2.575})$ by rectangular matrix multiplication in [6, 7]), they could obtain the same upper time-bounds for finding a maximum-weight triangle in a vertex weighted graph.

In this paper, we present a new algorithm for finding a maximum-weight triangle in a vertex weighted graph. It does not rely on computing maximum witnesses of Boolean matrix product and on contrary, it strongly utilizes the fact that the output to the problem is a single triangle. By applying a recursive elimination scheme and fast matrix multiplication algorithm, we obtain an algorithm whose running time is $O(n^{\omega^*}) = O(n^{2.376})$, where $\omega^* = \max\{\omega, 2 + \epsilon\}$ and $\epsilon$ can be chosen an arbitrarily small positive constant. (Observe that the running time is $O(n^\omega)$ assuming that $\omega - 2$ is a positive constant.) The running time of our algorithm matches that of the fastest algorithm for finding a triangle (not necessarily one with the maximum-weight) in a graph.

Next, we study the same problem for sparse graphs with $m$ edges (with the running time being a function of $m$). Previously, Vassilevska et al. [13] designed an algorithm that finds a maximum-weight triangle in time $O(m^{18/13}) = O(m^{1.45})$. We use our $O(n^{\omega^*})$-time algorithm for finding a maximum-weight triangle to design an algorithm running in time $O(m^{2/3 + \omega^*}) = O(m^{1.41})$. The running time of this algorithm matches that of the fastest algorithm for finding any triangle in a graph, due to Alon et al. [1].

The problems of finding fixed cliques and more generally subgraphs isomorphic to fixed graph are natural generalizations of the problem of finding a triangle in a graph. In [12, 13], Vassilevska et al. considered the vertex-weighted variants of these problems, where the task is to find a maximum (or, equivalently minimum) weight subgraph isomorphic to a fixed graph. The weight of a subgraph is defined as the total weight of its vertices. Vassilevska et al. obtained non-trivial upper time bounds for these variants by applying their algorithm for a maximum-weight triangle in [13]. We improve these bounds by using or extending our algorithm for a maximum-weight triangle. And so, our algorithm for finding a maximum-weight triangle can be easily extended to find a maximum-weight clique $K_{3k}$ (or, in general, to find a maximum-weight fixed subgraph (either induced or not) with $3k$ vertices) in time $O(n^{\omega^* k}) = O(n^{2.376} k)$, for any constant $k$. For other values of the size of the graphs, we design two algorithms. The first algorithm finds a maximum-weight clique $K_h$ (or, in general, any fixed subgraph with $h$ vertices) in time $O(n^{\lfloor h/3 \rfloor \omega^* + (h \mod 3)})$. This algorithm
improves the running time upon the fastest previously existing algorithms (see [13]) for all values of \( h \geq 6 \). Our second algorithm uses fast rectangular matrix multiplication (instead of that for square matrices) and improves the running time even further (for values \( h \mod 3 \neq 0 \)). And so, if \( h = 3f + 1 \), then the second algorithm runs in time \( O(n^{f+1-\omega}(1+\epsilon)}\), where \( \omega(1, r, 1) \) is the exponent of the multiplication of an \( n \times n^r \) matrix by an \( n^r \times n \) matrix. For \( h = 3f + 2 \), the running time is \( O(n^{f+1}(1+\omega) \cdot n^{f+1}(2+\omega)}\). By known result about \( \omega(1, r, 1) \) [3, 4, 9], this yields in particular running times of \( O(n^{2.376f}) \) for \( h = 3f \), \( O(n^{2.376f+1}) \) for \( h = 3f + 1 \), and \( O(n^{2.376f+1.844}) \) for \( h = 3f + 2 \).

These bounds subsume the corresponding ones from [13] (see Table 2, page 12).

## 2 Finding a maximum-weight triangle in \( O(n^{\omega^*}) \) time

In this section, we present our key algorithm \( HT_\xi(G, I, K, J) \) for finding a maximum-weight triangle in \( O(n^{\omega^*}) \) time. It uses a matrix decomposition method together with fast matrix multiplication algorithm to recursively reduce the number of possible triangle configurations one has to consider. The principal algorithm begins with the set of all \( n^3 \) potential triplets to be considered for the maximum-weight triangle, and in each recursive call it reduces the number of triplets to \( O(\xi^3) \) sets of \( (n/\xi)^3 \) triplets, where \( \xi \) is a parameter for the algorithm. By choosing \( \xi \) to be an appropriate constant, the running time of our algorithm is \( O(n^{\omega^*}) \).
procedure $HT_\xi(G, I, K, J)$

Input: A graph $G = (V, E)$ with vertex weights ($G$ is given as adjacency matrix)
vertices are numbered in non-decreasing weight order from 1 to $n$
subintervals $I$, $K$, and $J$ of $[1, \ldots, n]$, of the same length $\kappa$ assumed to be a power of $\xi$

Output: Maximum-weight triangle $(i, j, k)$, if any, such that $i \in I$, $j \in J$, and $k \in K$

if $\kappa = 1$ then
  if $(i_0 + 1, j_0 + 1, k_0 + 1)$ is a (non-degenerate) triangle in $G$ then return $(i_0 + 1, j_0 + 1, k_0 + 1)$;
stop
let $i_0$, $j_0$, and $k_0$ be such that
$I = [i_0 + 1, i_0 + \kappa]$, $K = [k_0 + 1, k_0 + \kappa]$, and $J = [j_0 + 1, j_0 + \kappa]$
$\ell = \kappa/\xi$
for all $p, r = 1, \ldots, \xi$ do
  form an $\ell \times \ell$ Boolean matrix $A_{pr}$ such that for every $1 \leq i' \leq \ell$ and $1 \leq k' \leq \ell$:
  $$A_{pr}[i', k'] = \begin{cases} 
1 & \text{if } (i_0 + (p - 1)\ell + i', k_0 + (r - 1)\ell + k') \in E \\
0 & \text{otherwise.} 
\end{cases}$$
for all $r, q = 1, \ldots, \xi$ do
  form an $\ell \times \ell$ Boolean matrix $B_{rq}$ such that for every $1 \leq k' \leq \ell$ and $1 \leq j' \leq \ell$:
  $$B_{rq}[k', j'] = \begin{cases} 
1 & \text{if } (k_0 + (r - 1)\ell + k', j_0 + (q - 1)\ell + j') \in E \\
0 & \text{otherwise.} 
\end{cases}$$
for all $p, r, q = 1, \ldots, \xi$ do
  compute $C_{pq}^r = A_{pr} \times B_{rq}$ (using the fast Boolean matrix multiplication algorithm)
$T = \emptyset$
for all $p, r, q = 1, \ldots, \xi$ do
  for all $i', j' = 1, \ldots, \ell$ do
    if $C_{pq}^r(i', j') = 1$ and $(i_0 + (p - 1)\ell + i', j_0 + (q - 1)\ell + j') \in E$ then
      $T = T \cup \{(p, r, q)\}$
  { Observation 1: $(p, r, q) \in T$ iff there is a triangle $(i, j, k)$ with $i \in [i_0 + (p - 1)\ell + 1, i_0 + p\ell]$, $k \in [k_0 + (r - 1)\ell + 1, k_0 + r\ell]$, and $j \in [j_0 + (q - 1)\ell + 1, j_0 + q\ell]$ }
for every $(p, r, q) \in T$ do
  if there is a $(p', r', q') \in T$ with $p < p'$, $r < r'$, $q < q'$ then
    remove $(p, r, q)$ from $T$
  { Observation 2: $(p, r, q)$ is removed from $T$ iff there is a $(p', r', q') \in T$ with $p < p'$, $r < r'$, $q < q'$.
for every $(p, r, q) \in T$ do
  call $HT_\xi(G, [i_0 + (p - 1)\ell + 1, i_0 + p\ell], [k_0 + (r - 1)\ell + 1, k_0 + r\ell], [j_0 + (q - 1)\ell + 1, j_0 + q\ell])$
Return the maximum-weight triangle among the triangles returned by these calls

Lemma 1 The procedure $HT_\xi$ is correct, that is, it returns a maximum-weight triangle $(i, j, k)$, if any, such that $i \in I$, $j \in J$, and $k \in K$.

Proof. The correctness of the algorithm follows from the two following observations:
1. just before pruning $T$, $(p, r, q) \in T$ if and only if there is a triangle $(i, k, j)$ with $i \in [i_0 + (p - 1)\ell + 1, i_0 + p\ell], k \in [k_0 + (r - 1)\ell + 1, k_0 + r\ell], j \in [j_0 + (q - 1)\ell + 1, j_0 + q\ell]$;

2. $(p, r, q)$ is then removed from $T$ if and only if there is a $(p', r', q') \in T$ with $p < p', r < r', q < q'$.

Indeed, the latter property implies that if there is a triangle $(i, k, j)$ with $i \in [i_0 + (p - 1)\ell + 1, i_0 + p\ell], k \in [k_0 + (r - 1)\ell + 1, k_0 + r\ell], j \in [j_0 + (q - 1)\ell + 1, j_0 + q\ell]$, then the triple $(p, q, r)$ representing such triangles $(i, k, j)$ is removed from $T$ only if there is another triangle $(i', k', j')$ such that for some $(p', r', q') \in T$ with $p < p', r < r', q < q'$, we have $i' \in [i_0 + (p' - 1)\ell + 1, i_0 + p'\ell], k' \in [k_0 + (r' - 1)\ell + 1, k_0 + r'\ell], j' \in [j_0 + (q' - 1)\ell + 1, j_0 + q'\ell]$. It follows by the properties of the initial vertex numbering that then such a triangle $(i, k, j)$ cannot be any maximum-weight triangle.

To estimate the running time of the procedure $HT_\xi$ we shall use the following lemma.

**Lemma 2** Let $\xi$ be any positive integer. Let $X$ be any subset of $\{1, 2, \ldots, \xi\}^3$ which does not contain any two $t, t'$ such that $t'$ has each coordinate greater than the corresponding one in $t$. The cardinality of $X$ is at most $3(\xi - 1)^2 - 3(\xi - 1) + 1$.

**Proof.** Define the relation $\prec$ such that $(i, k, j) \prec (i', k', j')$ iff $i < i', k < k'$, and $j < j'$. The relation $\prec$ defines a partial order on $\{1, 2, \ldots, \xi\}^3$. For each $(t_1, t_2, t_3) \in \{1, 2, \ldots, \xi\}^3$ that has at least one coordinate equal to 1 define $\text{chain}((t_1, t_2, t_3))$ to be the set of all triples in $\{1, 2, \ldots, \xi\}^3$ of the form $(t_1 + i, t_2 + i, t_3 + i)$ for $i = 0, 1, \ldots$. Observe that $\text{chain}(t)$ is indeed a chain in the poset $\{1, 2, \ldots, \xi\}^3, \prec$ and the chains $\text{chain}(t)$ cover all the elements in $\{1, 2, \ldots, \xi\}^3$. It follows now from Dilworth’s lemma [8] that the cardinality of the largest anti-chain in the aforementioned poset does not exceed the number of the triples with at least one coordinate equal to 1, which in turn, is at most $\xi^3 - (\xi - 1)^3 = 3(\xi - 1)^2 - 3(\xi - 1) + 1$.

**Lemma 3** The running time of $HT_\xi$ satisfies the recurrence

$$
\tau(\kappa) \leq (3(\xi - 1)^2 - 3(\xi - 1) + 1) \cdot \tau(\kappa/\xi) + O(\xi^3 - \omega \cdot \kappa^\omega + \xi^6).
$$

**Proof.** Forming the Boolean matrices $A_{pr}$ and $B_{rq}$, computing their products $C_{pr}$ and computing $T$, take time $O(\xi^2 \cdot \ell^2), \xi^3 \cdot O(\ell^2)$ and $O(\xi^3 \cdot \ell^2 + \xi^6)$, respectively. By Lemma 2, the final size of $T$ is at most $3(\xi - 1)^2 - 3(\xi - 1) + 1$. Hence, we obtain the following recurrence for the running time of $HT_\xi$:

$$
\tau(\kappa) \leq O(\xi^2 \cdot \ell^2) + \xi^3 \cdot O(\ell^2) + O(\xi^3 \cdot \ell^2 + \xi^6) + (3(\xi - 1)^2 - 3(\xi - 1) + 1) \cdot \tau(\ell)
= O(\xi^3 - \omega \cdot \kappa^\omega + \xi^6) + (3(\xi - 1)^2 - 3(\xi - 1) + 1) \cdot \tau(\kappa/\xi).
$$

As an immediate corollary, for a sufficiently large constant $\xi$, we obtain our main result.

---

1Here, let us observe that $\log_\xi(3(\xi - 1)^2 - 3(\xi - 1) + 1) \leq \log_\xi(3\xi^2) = \frac{\log 3 + 2 \log \xi}{\log \xi} \xrightarrow{\xi \to \infty} 2$.  

**Theorem 4** A maximum-weight triangle in a vertex weighted graph on $n$ vertices can be found in time $O(n^{\omega^*}) < O(n^{2.376})$.

**Proof.** This result follows from Lemma 3 by solving the recurrence for the running time of $HT_\xi$.

Let us first assume that $\omega > 2 + \epsilon$ for some constant $0 < \epsilon \leq 0.1$. Then, let us choose $\xi$ large enough, e.g., $\xi \geq 9^{1/\epsilon}$, and solve the recurrence (1) using the Master Theorem (see, e.g., [5, Chapter 4.3]) to obtain $\tau(\kappa) \leq O(\kappa^{\omega})$. Indeed, by the Master Theorem, we have to choose $\xi$ large enough so that (1) $\kappa^{\omega} \leq O(\kappa^{\omega-\epsilon/2})$ and that (2) $(3(\xi-1)^2 - 3(\xi-1)+1)(\kappa/\xi)^\omega \leq c'\kappa^\omega$ for some constant $c' < 1$ and for large enough $\kappa$.

For the first bound, it is easy to see that it is enough to have $\xi$ such that $\xi \geq 3^{2}/\epsilon$; indeed, we have $\kappa^{\omega} \leq O(m^{\omega-\epsilon/2})$ if $3(\xi-1)^2 - 3(\xi-1)+1 \leq \xi^{\omega-\epsilon/2}$. Next, $3(\xi-1)^2 - 3(\xi-1)+1 \leq 3\xi^2$ and $\xi^{\omega} \leq \xi^{\omega-\epsilon/2}$. Hence, if $\xi \geq 3^2/\epsilon$, then $\kappa^{\omega} \leq O(\kappa^{\omega-\epsilon/2})$. To see the second bound, we note that (2) holds if we set $3\xi^2-\omega \leq c$. Hence, we can choose any $\xi \geq 6^{1/\epsilon}$ in order to obtain $3\xi^2-\omega \leq \frac{1}{2}$.

Next, let us consider the case when $\omega \leq 2 + \epsilon$. Then similarly as in the other case, one can choose $\xi$ to solve the recurrence (1) (e.g., using the Master Theorem) to obtain $\tau(\kappa) \leq O(\kappa^{2+4\epsilon})$.

Let us set $\xi = 2^{1/(2\epsilon)}$. Then, since $\epsilon \leq 0.1$, we have that $\xi \geq 9$, and thus $3(\xi-1)^2 - 3(\xi-1)+1 = 3\xi^2 - 9\xi + 7 \geq 2\xi^2$. With this bound and using the inequality $\omega \leq 2 + \epsilon$, we obtain that $\xi^{\omega+\epsilon} \leq 2^{\epsilon^2+2\epsilon} \leq 2\xi^2 \leq 3(\xi-1)^2 - 3(\xi-1)+1$. Hence, we get $\omega \leq \log_\xi (3(\xi-1)^2 - 3(\xi-1)+1)$. Therefore, $\kappa^\omega = O(\kappa^{\omega} \log_\xi (3(\xi-1)^2 - 3(\xi-1)+1))$, where, by the Master Theorem (see, e.g., Case 1 in [5, Theorem 4.1]), yields $\tau(\kappa) = O(\kappa^{\omega} \log_\xi (3(\xi-1)^2 - 3(\xi-1)+1))$. Finally, we observe that $\log_\xi (3(\xi-1)^2 - 3(\xi-1)+1) \leq \log_\xi (3\xi^2) = \log_\xi (2 \log_2 \xi + \log_2 3) \leq 2 + \frac{2}{\log_2 \xi} = 2 + \frac{2}{1/(2\epsilon)} = 2 + 4\epsilon$.

Therefore, $\tau(\kappa) = O(\kappa^{2+4\epsilon})$.

Summarizing, we obtain the running time $\max\{O(n^{2+\epsilon}), O(n^\omega)\} = O(n^{\omega^*})$ for an arbitrarily small fixed $\epsilon > 0$.

\[\Box\]

### 3 Improved bounds for sparse graphs

By arguing analogously as in the proof of Theorem 2 in [13], we can refine the upper bound from Theorem 4 in the case of sparse graphs as follows.

**Corollary 5** A maximum-weight triangle in a vertex weighted graph with $m$ edges and no isolated vertices can be found in time $O(m^{2.376}) < O(m^{1.41})$.

**Proof.** Let $G = (V, E)$ be the input graph and let $X$ be the set of all vertices in $V$ of degree at most $\delta$. It follows that $|V \setminus X| \leq 2m/\delta$. In time $O(m\delta)$, we can enumerate all triangles in $G$ that contain a vertex in $X$ and find a maximum-weight one among them. On the other hand, a maximum-weight triangle in $G$ that has all vertices in $V \setminus X$ can be found in time $O((m/\delta)^{\omega^*})$ by Theorem 4. By setting $\delta = m^{\omega^* - 1}$, we obtain the corollary. \[\Box\]
4 Finding a maximum-weight clique $K_h$ and $H$-subgraphs

In this section, we present a construction that extends the algorithm for finding a maximum-weight triangle to include finding a maximum-weight clique or any maximum-weight subgraph isomorphic to a given graph.

**Theorem 6** A maximum-weight clique $K_h$ in a vertex weighted graph on $n$ vertices can be found in time
\[ O(n^{\lfloor h/3 \rfloor} \cdot \omega^* + (h \mod 3)). \]

**Proof.** Let $f = \lfloor h/3 \rfloor$. Suppose first that $h = 3f$. Form a new graph $G'$ in which each vertex corresponds one to one to a $K_f$ in the original graph $G$ and the weight of such a vertex equals the total weight of the vertices in this $K_f$. Two vertices in $G'$ are connected by an edge if and only if the corresponding cliques form an $K_{2f}$ clique in $G$. Observe that $G'$ has $O(n^f)$ vertices and it can be constructed in time $O(n^f)$. Furthermore, a maximum-weight triangle in $G'$ corresponds to a maximum-weight $K_h$ clique in $G$. Therefore, by using Theorem 4 to find a maximum-weight triangle in $G'$, we can find a maximum-weight clique in $G$ in time $O(n^f \cdot \omega^*)$.

Next, let us consider the case $h = 3f + 2$. Find all cliques $K_f$ and $K_{f+1}$ that are subgraphs of $G$. Divide the $K_{f+1}$ subgraphs into $O(n)$ groups of size $O(n^f)$. For each such two groups $a$ and $b$ ($a$ can be equal to $b$) and the $K_f$ subgraphs form a tripartite graph $G_{a,b}$ whose vertices in the first part, second part and the third part are in one to one correspondence with: the $K_{f+1}$ subgraphs in the first group, the $K_{f+1}$ subgraphs in the second group, and the $K_f$ subgraphs of $G$, respectively. The weights of the vertices in $G_{a,b}$ are equal to the total weights of the corresponding cliques in $G$. There is an edge between two vertices in $G_{a,b}$ if the corresponding cliques are disjoint and induce the clique in $G$ whose size equals the sum of their sizes. Observe that all the constructions can be easily done in total time $O(n^{2f+2})$. Now note that a maximum-weight triangle among the maximum-weight triangles in the graphs $G_{a,b}$ yields a maximum-weight $K_h$ in $G$. By Theorem 4, it takes time $O(n^f \cdot (n^f)^{\omega^*})$.

The proof of case $h = 3f + 1$ is analogous. For each group $a$ of the $K_{f+1}$ subgraphs we form a tripartite graph $G_a$ whose vertices in the first part are in one to one correspondence with the $K_{f+1}$ subgraphs in $a$, whereas the vertices in each of the two remaining parts are in one to one correspondence with the $K_f$ subgraphs of $G$. The vertex weights and edges are specified analogously as in case of $G_{a,b}$ and all the constructions take time $O(n^{f+1} \cdot n^f)$. Analogously, a maximum-weight triangle among the maximum-weight triangles in the graphs $G_a$ yields a maximum-weight $K_h$ in $G$.

It is easy to extend the result from Theorem 6 to arbitrary induced subgraphs isomorphic to a given graph $H$ on $h$ vertices. We use an analogous construction to that in the proof of Theorem 6. We decompose $H$ into three induced subgraphs $H_i$ (possibly isomorphic), $i = 1, 2, 3$, and for each isomorphism between an induced subgraph of $G$ and $H_i$, we form a separate node in an auxiliary graph. Two such nodes are connected by an edge if the union of the corresponding isomorphisms yields an isomorphism between the subgraph induced by the vertices of the two underlying subgraphs and the subgraph of $H$ induced by the vertices of the $H_i$ images (required
to be different) of the two isomorphisms. (In case \( H = K_h \), it has not been necessary to have separate nodes for different isomorphisms between an induced subgraph of \( G \) and a clique which is a subgraph of \( K_h \) because of the symmetry between the vertices in the clique with respect to \( K_h \).

Furthermore, since any subgraph (not necessarily induced) of \( G \) on \( h \) vertices which is isomorphic to \( H \) is a subgraph of the induced subgraph of \( G \) on the same \( h \) vertices, finding (not necessarily induced) subgraphs reduces to finding induced subgraphs of the same size. The induced subgraphs correspond to all possible super-graphs of \( H \) on \( h \) vertices. This yields the following.

**Theorem 7** Let \( H \) be a fixed graph on \( h \) vertices. A maximum-weight induced subgraph of a vertex weighted graph on \( n \) vertices that is isomorphic to \( H \) can be found in time

\[
O(n^{\lfloor h/3 \rfloor \cdot \omega^* + (h \text{ mod } 3)})
\]

In asymptotically the same time complexity one can find a maximum-weight subgraph (not necessarily induced) isomorphic to \( H \).

## 5 Refinement by using fast rectangular matrix multiplication

The algorithms and the bounds from Theorems 6 and 7 can be improved for \( h \text{ mod } 3 \neq 0 \) if we use fast rectangular matrix multiplication algorithms (instead of fast square matrix multiplication).

Let \( \omega(1, \sigma, 1) \) denote the exponent of the multiplication of an \( n \times n^\sigma \) matrix by an \( n^\sigma \times n \) matrix. In order to improve Theorems 6 and 7 in terms of \( \omega(1, \sigma, 1) \), we need to generalize the procedure \( HT_\xi(G, I, K, J) \) to include the case where the sizes of the intervals \( I, K \) and \( J \) are not necessarily equal. We also relax the requirement that vertices are numbered in non-decreasing weight order by requiring solely that within each of the three input intervals \( I, K \) and \( J \), the numbering has this property.

For any \( \sigma, \frac{1}{2} \leq \sigma \leq 2 \), let \( HT_\xi^{(\sigma)}(G, I, K, J) \) denote such an analogous generalized procedure, where the sizes of \( I, K \), and \( J \) (besides being powers of \( \xi \)) satisfy \( |I| = |J| \) and \( |K| = |I|^{\sigma} \). The key difference in the body of \( HT_\xi^{(\sigma)} \) compared with that of \( HT_\xi \) is that since the matrices \( A_{pr} \) and \( B_{rq} \) are now of sizes \( \kappa/\xi \times (\kappa/\xi)^\sigma \) and \( (\kappa/\xi)^\sigma \times \kappa/\xi \), respectively, we use the fast rectangular Boolean matrix multiplication algorithm with the exponent \( \omega(1, \sigma, 1) \) instead of the fast square one with the exponent \( \omega \).
procedure $HT^{(\sigma)}_\xi(G, I, K, J)$

Input: A graph $G = (V, E)$ with vertex weights ($G$ is given as adjacency matrix)
    vertices are numbered in non-decreasing weight order from 1 to $n$
    subintervals $I$, $K$, and $J$ of $[1, \ldots, n]$, of the length $\kappa$, $\kappa^\sigma$, and $\kappa$, respectively,
    where $\kappa$, $\kappa^\sigma$, and $(\kappa/\xi)^\sigma$ are powers of $\xi$

Output: Maximum-weight triangle $(i, j, k)$, if any, such that $i \in I$, $j \in J$, and $k \in K$

if $\kappa = 1$ then
    if $(i_0 + 1, j_0 + 1, k_0 + 1)$ is a (non-degenerate) triangle in $G$ then return $(i_0 + 1, j_0 + 1, k_0 + 1)$;
    stop

let $i_0$, $k_0$, and $j_0$ be such that
    $I = [i_0 + 1, i_0 + \kappa]$, $K = [k_0 + 1, k_0 + \kappa^\sigma]$, and $J = [j_0 + 1, j_0 + \kappa]$

for all $p = 1, \ldots, \xi$, $r = 1, \ldots, \xi^\sigma$ do
    form an $\frac{\xi}{\xi^\sigma} \times (\frac{\xi}{\xi^\sigma})^\sigma$ Boolean matrix $A_{pr}$ such that for every $1 \leq i' \leq \frac{\xi}{\xi^\sigma}$ and $1 \leq k' \leq (\frac{\xi}{\xi^\sigma})^\sigma$:
    $$A_{pr}[i', k'] = \begin{cases} 1 & \text{if } (i_0 + (p - 1)\frac{\xi}{\xi^\sigma} + i', k_0 + (r - 1)(\frac{\xi}{\xi^\sigma})^\sigma + k') \in E \\ 0 & \text{otherwise.} \end{cases}$$

for all $r = 1, \ldots, \xi^\sigma$, $q = 1, \ldots, \xi$ do
    form an $(\frac{\xi}{\xi^\sigma})^\sigma \times \frac{\xi}{\xi^\sigma}$ Boolean matrix $B_{rq}$ such that for every $1 \leq k' \leq (\frac{\xi}{\xi^\sigma})^\sigma$ and $1 \leq j' \leq \frac{\xi}{\xi^\sigma}$:
    $$B_{rq}[k', j'] = \begin{cases} 1 & \text{if } (k_0 + (r - 1)(\frac{\xi}{\xi^\sigma})^\sigma + k', j_0 + (q - 1)\frac{\xi}{\xi^\sigma} + j') \in E \\ 0 & \text{otherwise.} \end{cases}$$

for all $p, q = 1, \ldots, \xi$ and $r = 1, \ldots, \xi^\sigma$ do
    compute $C_{pq}^{\sigma} = A_{pr} \times B_{rq}$ (using the fast rectangular Boolean matrix multiplication algorithm)

$T = \emptyset$

for all $p, q = 1, \ldots, \xi$ and $r = 1, \ldots, \xi^\sigma$ do
    for all $i', j' = 1, \ldots, \frac{\xi}{\xi^\sigma}$ do
        if $C_{pq}^{\sigma}(i', j') = 1$ and $(i_0 + (p - 1)\frac{\xi}{\xi^\sigma} + i', j_0 + (q - 1)\frac{\xi}{\xi^\sigma} + j') \in E$ then
            $T = T \cup \{(p, r, q)\}$

{Observation 1: $(p, r, q) \in T$ iff there is a triangle $(i, k, j)$ with $i \in [i_0 + (p - 1)\frac{\xi}{\xi^\sigma} + 1, i_0 + p\frac{\xi}{\xi^\sigma}]$
    $k \in [k_0 + (r - 1)(\frac{\xi}{\xi^\sigma})^\sigma + 1, k_0 + r(\frac{\xi}{\xi^\sigma})^\sigma]$, and $j \in [j_0 + (q - 1)\frac{\xi}{\xi^\sigma} + 1, j_0 + q\frac{\xi}{\xi^\sigma}]$}

for every $(p, r, q) \in T$ do
    if there is a $(p', r', q') \in T$ with $p < p'$, $r < r'$, $q < q'$ then
        remove $(p, r, q)$ from $T$

{Observation 2: $(p, r, q)$ is removed from $T$ iff there is a $(p', r', q') \in T$ with $p < p'$, $r < r'$, $q < q'$.}

for every $(p, r, q) \in T$ do
    call $HT^{(\sigma)}_\xi(G, [i_0 + (p-1)\frac{\xi}{\xi^\sigma} + 1, i_0 + p\frac{\xi}{\xi^\sigma}], [k_0 + (r-1)\frac{\xi}{\xi^\sigma} + 1, k_0 + r\frac{\xi}{\xi^\sigma}], [j_0 + (\frac{q-1}{\xi^\sigma} + 1, j_0 + q\frac{\xi}{\xi^\sigma}])$

return the maximum-weight triangle among the triangles returned by these calls

By performing an analysis of $HT^{(\sigma)}_\xi$ analogous to that of $HT_\xi$, we obtain the following lemma.
Lemma 8 For any $\epsilon > 0$, there is a sufficiently large $\xi$ such that the procedure $HT^{(\sigma)}(I, K, J)$ returns a maximum-weight triangle $(i, j, k)$, if any, where $i \in I$, $j \in J$, and $k \in K$, in time $O(|I|^{\omega(1,\sigma,1)} + |I|^{2+\epsilon} + |I|^{1+\sigma+\epsilon})$.

Proof. We proceed as in the proof of Lemma 3, but this time to compute the matrices $C_{pq}^r$ we use fast rectangular matrix multiplication. Forming the Boolean matrices $A_{pr}$ and $B_{rq}$ takes time $O(\xi^{1+\sigma} \cdot \xi^2 \cdot (\frac{\xi}{\sigma})^\sigma) = O(\kappa^{1+\sigma})$, computing their products $C_{pq}^r$ takes time $O(\xi^{2+\sigma} \cdot (\kappa/\xi)^\omega(1,\sigma,1))$, and computing $T$ takes time $O(\xi^{\sigma} \cdot \kappa^2 + \xi^{2+2\sigma})$. Using the arguments from Lemma 2, the final size of $T$ is at most $\xi^{2+\sigma} - (\xi - 1)^2 (\xi^\sigma - 1) = 2\xi^{1+\sigma} + \xi^2 - 2\xi - \xi^\sigma + 1$. Since we consider $\xi \geq 1$, this is always bounded from above by $2\xi^{1+\sigma} + \xi^2$. Hence, we obtain the following recurrence for the running time of $HT^{(\sigma)}$:

$$
\tau(\kappa) \leq O(\kappa^{1+\sigma}) + O(\xi^{2+\sigma} \cdot (\kappa/\xi)^\omega(1,\sigma,1)) + O(\xi^\sigma \cdot \kappa^2 + \xi^{2+2\sigma}) + (2\xi^{1+\sigma} + \xi^2) \cdot \tau(\kappa/\xi)
$$

with the base case $\tau(1) = O(1)$.

Since we have assumed that $\frac{1}{2} \leq \sigma \leq 2$ and since $\xi$ is a parameter that we can set as an arbitrary integer constant, one can solve this recurrence analogously as in the proof of Theorem 4 to conclude that the running time of the algorithm is $\tau(\kappa) = O(\kappa^{\omega(1,\sigma,1)} + \kappa^{2+\epsilon} + \kappa^{1+\sigma+\epsilon})$.

Indeed, the recurrence for $\tau(\kappa)$ can be simplified to $\tau(\kappa) \leq O(\kappa^{\omega(1,\sigma,1)} + (2\xi^{1+\sigma} + \xi^2) \cdot \tau(\kappa/\xi))$. Furthermore, by using the Master Theorem and by setting the parameter $\xi$ appropriately, we can bound $\tau(\kappa)$ from above by the maximum of the bound coming from the first term, i.e., by $O(\kappa^{\omega(1,\sigma,1)})$, and the bound coming from the other term, i.e., $O(\kappa^{\log_\xi(2\xi^{1+\sigma} + \xi^2)})$, where $\xi$ is an arbitrary integer parameter. Next, let us simplify the latter bound. If $\sigma \leq 1$ then we have $O(\kappa^{\log_\xi(2\xi^{1+\sigma} + \xi^2)}) \leq O(\kappa^{\log_\xi(3\xi^2)}) = O(\kappa^{2+\log_\xi 3})$; otherwise, if $\sigma > 1$ then $O(\kappa^{\log_\xi(2\xi^{1+\sigma} + \xi^2)}) \leq O(\kappa^{\log_\xi(3\xi^{1+\sigma})}) = O(\kappa^{1+\sigma+\log_\xi 3})$ holds. Therefore, for any positive constant $\epsilon$, by setting $\xi$ to an appropriately large constant we have $O(\kappa^{\log_\xi(2\xi^{1+\sigma} + \xi^2)}) \leq O(\kappa^{2+\epsilon} + \kappa^{1+\sigma+\epsilon})$. This yields the lemma.

Equipped with Lemma 8, we can improve the bound form Theorem 6 for $h \neq 3f$ as follows.

Consider first the case when $h = 3f + 2$. Find all cliques $K_f$ and $K_{f+1}$ that are subgraphs of $G$. Next, form a new graph $G''$, where vertices are in one to one correspondence with the found cliques and their weight equals the total weight of the corresponding clique. Two vertices in $G''$ are adjacent if the corresponding cliques induce a clique in $G''$ whose size equals the sum of their sizes. Next, number the vertices of $G''$ such that the vertices corresponding to the $K_{f+1}$ cliques occur in a continuous interval in non-decreasing weight order as well as those corresponding to the $K_f$ cliques occur in a continuous interval in non-decreasing weight order.

Set $I$ and $J$ to the first of the aforementioned intervals and $K$ to the second one, and run the procedure $H^{(\sigma)}_\xi(I, K, J)$ for $G''$ and $\sigma = \log_{|I|}|K|$, where $\frac{1}{2} \leq \sigma < 1$.2 Observe that by Lemma 8 and by the definitions of $G''$, $I$, $K$ and $J$, the triangle returned by $H^{(\sigma)}_\xi(I, K, J)$, if any, corresponds

2The simplifying assumption about the sizes of the intervals being the power of $\xi$ can be achieved by increasing the sizes by a multiplicative factor less than $\xi$ via adding dummy vertices.
to a maximum-weight $K_h$ in $G$. By Lemma 8, monotonicity of the time taken by the multiplication of an $n \times n^\sigma$ matrix by an $n^\sigma \times n$ matrix with respect to $n$ and $\sigma$, and straightforward calculations, $H_{\xi}^{(\sigma)}(I, K, J)$ takes time $O((n^f+1)^{\omega(1, r/\ell+1)} + (n^f+1)^{2+\varepsilon})$ for sufficiently large constant $\xi$.

The proof in case $h = 3 f + 1$ is analogous with the exception that now $I$ and $J$ are set to the interval of vertices corresponding to $K_f$ cliques whereas $K$ is set to the interval of vertices corresponding to $K_{f+1}$ cliques. By analogous arguments, we conclude that in this case we can find a maximum-weight $K_h$ in time $O((n^f)^{\omega(1, r/\ell+1)} + n^f(2+\frac{1}{\ell}+\varepsilon))$.

By combining our improvements with Theorem 6, we obtain the following theorem.

**Theorem 9** Let $h$ be a positive integer, and let $f = \lfloor h/3 \rfloor$. A maximum-weight clique $K_h$ in a vertex weighted graph on $n$ vertices can be found in time $T_h(n)$, where

$$
T_h(n) = \begin{cases} 
O(n^f \omega^*) & \text{if } h \mod 3 \equiv 0 \\
O(n^f \omega(1, r/\ell+1)) + n^f(2+\frac{1}{\ell}+\varepsilon) & \text{if } h \mod 3 \equiv 1 \\
O(n^f(1+\omega(1, r/\ell+1)) + n^f(2+1+\varepsilon)) & \text{if } h \mod 3 \equiv 2.
\end{cases}
$$

Similarly as in the previous section, the results from Theorem 9 can be extended to finding a maximum-weight fixed graph.

**Theorem 10** For any fixed integer $h$, let $H$ be any graph on $n$ vertices. A maximum-weight induced subgraph of a vertex weighted graph on $n$ vertices that is isomorphic to $H$ can be found in time $T_h(n)$, where the function $T_h(n)$ is defined in Theorem 9.

In asymptotically the same time complexity one can find a maximum-weight subgraph (not necessarily induced) isomorphic to $H$.

Coppersmith [3] and Huang and Pan [9] proved the following facts.

**Fact 11** [3, 9] Let $\omega = \omega(1, 1, 1) < 2.376$ and let $\alpha = \sup\{0 \leq r \leq 1 : \omega(1, r, 1) = 2 + o(1)\} > 0.294$. Then $\omega(1, r, 1) \leq \beta(r)$, where $\beta(r) = 2 + o(1)$ for $r \in [0, \alpha]$ and $\beta(r) = 2 + \frac{\omega-2}{1-\alpha} (r - \alpha) + o(1)$ for $r \in [\alpha, 1]$.

(Observe a useful fact, that if our goal is to compute $(f+1) \cdot \omega(1, \frac{2}{f+1}, 1)$, then the bounds in Fact 11 simplify it to $(f+1) \cdot \omega(1, \frac{2}{f+1}, 1) = (f+1) \cdot (2 + \frac{\omega-2}{1-\alpha} (\frac{2}{f+1} - \alpha) + o(1)) = 2 - \frac{(\omega-2)\alpha}{1-\alpha} + f \cdot \omega + o(f) < 1.844 + f \cdot \omega + o(f).$)

**Fact 12** [9, Section 8.1] $\omega(1, 2, 1) < 3.334$, and for every $r > 1$, we have $\omega(1, r, 1) \leq \omega + r - 1$.

(Section 8.1 in [9] contains some discussion about stronger bounds for $\omega(1, r, 1)$ for other values $r > 2$.)
Therefore, for example, by using the bounds from Facts 11 and 12, we have (see also Table 2):

\[
T_3(n) = O(n^{\omega}) < O(n^{2.376}),
\]
\[
T_4(n) = O(n^{\omega(1.2,1)} + n^{3+\epsilon}) < O(n^{3.334}),
\]
\[
T_5(n) = O(n^{2\omega(1.4,1)} + n^{4+\epsilon}) < O(n^{4.220}),
\]
\[
T_6(n) = O(n^{2\omega}) < O(n^{4.752}),
\]
\[
T_{3f}(n) = O(n^{f\omega}) < O(n^{2.376f}),
\]
\[
T_{3f+1}(n) = O(n^{f\omega+1}) < O(n^{2.376f+1}),
\]
\[
T_{3f+2}(n) = O(n^{f\omega+1.844}) < O(n^{2.376f+1.844}).
\]

Note that, for example, this bound subsumes the upper bound of Theorem 6 for $K_4$, $K_5$, and for $K_{3f+2}$ for every $f \geq 1$.

6 Conclusions

We have shown that finding a maximum-weight triangle is asymptotically not more difficult than matrix multiplication. Consequently, we could substantially improve prior upper time-bounds on finding a maximum-weight clique of size $O(1)$ and a maximum-weight subgraph isomorphic to a fixed graph.

A natural question arises whether or not our result for vertex weighted triangles is asymptotically optimal.

References


<table>
<thead>
<tr>
<th>Problem</th>
<th>Source</th>
<th>Running-time</th>
<th>Numerical runtime</th>
</tr>
</thead>
<tbody>
<tr>
<td>maximum-weight fixed subgraph with 4 vertices</td>
<td>this paper</td>
<td>$O(n^{3.376})$</td>
<td>$O(n^{3.334})$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with 5 vertices</td>
<td>this paper</td>
<td>$O(n^{4.220})$</td>
<td>$O(n^{4.376})$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with 6 vertices</td>
<td>this paper</td>
<td>$O(n^{5.232})$</td>
<td>$O(n^{4.752})$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with 7 vertices</td>
<td>this paper</td>
<td>$O(n^{5.848})$</td>
<td>$O(n^{5.752})$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with 8 vertices</td>
<td>this paper</td>
<td>$O(n^{6.752})$</td>
<td>$O(n^{6.596})$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with 9 vertices</td>
<td>this paper</td>
<td>$O(n^{7.752})$</td>
<td>$O(n^{7.128})$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with $3f$ vertices</td>
<td>[12] [13]</td>
<td>$O(n^{2.688}/f)$; randomized</td>
<td>$O(n^{2.575}/f)$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with $3f + 1$ vertices</td>
<td>this paper</td>
<td>$O(n^{2.376}/f)$</td>
<td>$O(n^{2.376}/f)$</td>
</tr>
<tr>
<td>maximum-weight fixed subgraph with $3f + 2$ vertices</td>
<td>this paper</td>
<td>$O(n^{2.376}/f+1)$</td>
<td>$O(n^{2.376}/f+1.844)$</td>
</tr>
</tbody>
</table>

Table 2: Summary of results for finding maximum-weight cliques of size greater than 3 and fixed induced subgraphs. In all results, $n$ denotes the number of vertices, $m$ number of edges, $B$ is the number of bits of precision of the input, $\omega < 2.376$ is the exponent of the fastest matrix multiplication algorithm [4], $\omega^* = \max\{\omega, 2 + \epsilon\}$, where $\epsilon$ can be chosen as an arbitrarily small positive constant (hence, $\omega^* < 2.376$), and $\omega(1, r, 1)$ is the exponent of the multiplication of an $n \times n^r$ matrix by an $n^r \times n$ matrix [3, 9].

[7] A. Czumaj, M. Kowaluk, and A. Lingas. Faster algorithms for finding lowest common ancestors in directed acyclic graphs. Invited and submitted to Theoretical Computer Science, special issue devoted to selected papers from the 32nd International Colloquium on Automata, Languages and Programming (ICALP’05). This paper is a result of merging [6] and [11].


