Multilinear Formulas, Maximal-Partition Discrepancy and Mixed-Sources Extractors

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Abstract

We study multilinear formulas, monotone arithmetic circuits, maximal-partition discrepancy, best-partition communication complexity and extractors constructions.

We start by proving lower bounds for an explicit polynomial for the following three subclasses of syntactically multilinear arithmetic formulas over the field \( \mathbb{C} \) and the set of variables \( \{x_1, \ldots, x_n\} \):

1. **Noise-resistant.** A syntactically multilinear formula computing a polynomial \( h \) is \( \varepsilon \)-noise-resistant, if it approximates \( h \) even when each of its edges is multiplied by an arbitrary value that is \( \varepsilon \) close to 1 (we think of this value as noise). Any formula is 0-noise-resistant, and, more generally, the smaller \( \varepsilon \) is the less restricted an \( \varepsilon \)-noise-resistant formula is. We prove an \( \Omega(n/k) \) lower bound for the depth of \( 2^{-k} \)-noise-resistant syntactically multilinear formulas, for every \( k \in \mathbb{N} \).

2. **Non-cancelling.** A syntactically multilinear formula is \( \tau \)-non-cancelling, if for every sum gate \( v \) in \( \Phi \), the norm of the polynomial computed by \( v \) is at least \( \tau \) times the norm of the polynomial computed by both children of \( v \). Any formula is 0-noise-resistant, and, more generally, the smaller \( \tau \) is the less restricted a \( \tau \)-non-cancelling formula is. We prove an \( \Omega(n/k) \) lower bound for the depth of \( 2^{-k} \)-non-cancelling syntactically multilinear formulas, for every \( k \in \mathbb{N} \).
3. **Orthogonal.** A syntactically multilinear arithmetic formula is orthogonal, if for every sum gate $v$ in $\Phi$, the two polynomials computed by the children of $v$ are orthogonal (as vectors). Orthogonal syntactically multilinear formulas were first defined by Aaronson in connection to a certain type of quantum computation. We prove a tight $2^{\Omega(n)}$ lower bound for the size of orthogonal syntactically multilinear formulas.

We also prove a tight $2^{\Omega(n)}$ lower bound for the size of (not necessarily multilinear) monotone arithmetic circuits. To the best of our knowledge the best lower bounds previously known for the monotone model are $2^{\Omega(\sqrt{n})}$.

One ingredient of our proof is an explicit map $f : \{0,1\}^n \to \{0,1\}$ that has exponentially small discrepancy for every partition of $\{1,\ldots,n\}$ into two sets of roughly the same size. More precisely, for every partition of $\{1,\ldots,n\}$ into two sets of size at least $n/3$ each, the matrix of $f$ that corresponds to that partition has exponentially small discrepancy (the discrepancy of a matrix is the maximal difference between the number of 1’s and 0’s in a sub-matrix divided by the size of the matrix). We give two additional applications of this property:

1. **Communication Complexity.** The best-partition communication complexity of a map $h : \{0,1\}^n \to \{0,1\}$ is defined as the minimal communication complexity of $h$, where the minimum is taken over all partitions of $\{1,\ldots,n\}$ to two sets $A$ and $B$ of equal size (where Alice gets the bits in $A$ and Bob gets the bits in $B$). We prove a tight $\Omega(n)$ lower bound for the probabilistic best-partition communication complexity of $f$. To the best of our knowledge the best lower bound previously known for this model is $\Omega(\sqrt{n})$.

2. **Mixed-2-source Extractors.** A mixed-2-source is a source of randomness whose bits arrive from two independent sources (of size $n/2$ each), but they arrive in a fixed but unknown order. Using the small maximal-partition discrepancy of $f$ we are able to extract one almost perfect random bit from a mixed-2-source of min-entropy $(1-\delta)n$ (for some constant $\delta > 0$). We then show how to use the same methods in order to extract a linear number of almost perfect random bits from such sources.

1 **Introduction**

In this paper we study three subclasses of syntactically multilinear arithmetic formulas, as well as monotone arithmetic circuits, maximal-partition discrepancy, best-partition communication complexity and extractors constructions.

We prove lower bounds for the following three subclasses of syntactically multilinear arithmetic formulas over the field $\mathbb{C}$ and the set of variables $\{x_1,\ldots,x_n\}$ (the formal definitions are in Sections 1.1.3 and 1.1.2):
1. **Noise-resistant formulas**, that are formulas that approximate the polynomials that they compute even when a small noise (of size at most $\varepsilon$) occurs in the edges.

2. **Non-cancelling formulas**, that are formulas that are not allowed to subtract two polynomials $f_1$ and $f_2$ that are almost the same (where by almost the same we mean that $\|f_1 - f_2\|$ is smaller than $\tau \cdot \min(\|f_1\|, \|f_2\|)$).

3. **Orthogonal formulas**, that are formulas that are allowed to add only orthogonal polynomials (thinking of a polynomial as the vector of its coefficients). Orthogonal syntactically multilinear formulas were first defined and studied by Aaronson [A], who proved lower bounds for a subclass of orthogonal syntactically multilinear formulas.

We prove an $\Omega(n^\alpha)$ (for a constant $0 < \alpha \leq 1$) lower bounds for the depth of syntactically multilinear noise-resistant formulas and syntactically multilinear non-cancelling formulas. These lower bounds hold even for exponentially small $\varepsilon$ and $\tau$. We note that the smaller $\varepsilon$ and $\tau$ are the better the lower bounds are (in the sense that they hold in a more general model). We also prove a $2^{\Omega(n)}$ lower bound for the size of orthogonal syntactically multilinear formulas.

Furthermore, we show how to use these ideas in order to obtain a lower bound of $2^{\Omega(n)}$ for the size of (not necessarily multilinear) monotone arithmetic circuits (that are circuits that do not use subtractions). To the best of our knowledge the best lower bounds previously known for the monotone model are $2^{\Omega(\sqrt{n})}$.

The lower bound for orthogonal syntactically multilinear formulas is tight in the sense that for every multilinear polynomial there is an orthogonal syntactically multilinear formula of size $2^{\Omega(n)}$ computing it. Similarly, the lower bound for monotone circuits is tight in the sense that for every monotone multilinear polynomial there is a monotone formula of size $2^{\Omega(n)}$ computing it.

One important ingredient of our proof is an explicit map $f : \{0, 1\}^n \rightarrow \{0, 1\}$ that has exponentially small maximal-partition discrepancy. We will now give a short definition of maximal-partition discrepancy. Let $A$ be a subset of $\{1, \ldots, n\}$ of size $k$ (we think of $A$ as a partition of $\{1, \ldots, n\}$ into $A$ and $\{1, \ldots, n\} \setminus A$). For $y \in \{0, 1\}^k$ and $z \in \{0, 1\}^{n-k}$, define $f_A$ to be the $2^k \times 2^{n-k}$ matrix whose $(y, z)$ entry is $f((y, z)_A)$, where $(y, z)_A$ is the unique vector in $\{0, 1\}^n$ whose restriction to the entries in $A$ is $y$ and restriction to the entries not in $A$ is $z$. The maximal-partition discrepancy of $f$ is the maximal discrepancy of $f_A$ among all sets $A$ of size $n/3 \leq |A| \leq 2n/3$ (the discrepancy of a matrix is the maximal difference between the number of 1’s and 0’s in a sub-matrix divided by the size of the matrix). We will now survey two additional applications of small maximal-partition discrepancy (one to communication complexity and one to extractors construction).
The best-partition communication complexity of a map $h : \{0, 1\}^n \rightarrow \{0, 1\}$ is defined as the minimal communication complexity of $h$, where the minimum is taken over all partitions of $\{1, \ldots, n\}$ into two sets $A$ and $B$ of equal size (where Alice gets the bits in $A$ and Bob gets the bits in $B$). We show that the probabilistic best-partition communication complexity of $f$ is $\Omega(n)$. To the best of our knowledge the best lower bound previously known for this model is $\Omega(\sqrt{n})$ [J].

A mixed-2-source is a source of randomness whose bits arrive from two independent sources (of size $n/2$ each), but they arrive in a fixed but unknown order. So, mixed-2-sources are more general than the extensively studied 2-sources. Using the small maximal-partition discrepancy of $f$ we are able to extract one almost perfect random bit from a mixed-2-source of min-entropy $(1-\delta)n$ (for some constant $\delta > 0$). We then show how to use the same methods in order to extract a linear number of almost perfect random bits from such sources.

### 1.1 Multilinear Formulas and Monotone Circuits

An arithmetic circuit $\Phi$ over the field of complex numbers $\mathbb{C}$ and over the set of variables $X = \{x_1, \ldots, x_n\}$ is a directed acyclic graph as follows: Every vertex of in-degree 0 is labelled by either a field element or a variable. Every other vertex is of in-degree 2, and is labelled by either $+$ or $\times$. There is a unique vertex in $\Phi$ of out-degree 0. An arithmetic formula is an arithmetic circuit whose underlying graph is a binary tree (whose edges are directed from the leaves to the root).

The size of $\Phi$ is the number of vertices in $\Phi$. We denote the size of $\Phi$ by $|\Phi|$. The depth of a vertex $v$ in $\Phi$ is the length of the longest directed path reaching $v$. We denote the depth of $v$ by $\text{depth}(v)$. The depth of $\Phi$ is the maximal depth of a gate in $\Phi$.

The vertices of $\Phi$ are also called gates. Gates of in-degree 0 are also called input gates. Gates labelled by $+$ are called sum gates, and gates labelled by $\times$ are called product gates. The gate of out-degree 0 is called the output gate. If there is a directed edge from a gate $v$ to a gate $u$, then $v$ is called a child of $u$. An arithmetic circuit computes a polynomial in a natural way. An input gate computes the polynomial it is labelled by (i.e., the variable or the field element). A sum gate computes the sum of the two polynomials computed by its two children. A product gate computes the product of the two polynomials computed by its two children. For a gate $v$ in $\Phi$, denote by $\Phi_v$ the sub-circuit of $\Phi$ rooted at $v$. Denote by $X_v$ the set of variables that occur in $\Phi_v$. Denote by $\hat{\Phi}_v$ the polynomial in $\mathbb{C}[X_v]$ computed by $v$ in $\Phi$. Denote by $\hat{\Phi}$ the polynomial computed by the output gate of $\Phi$.

A polynomial $f \in \mathbb{C}[X]$ is called multilinear, if the degree of every variable in $f$ is at most 1. We say that an arithmetic circuit is multilinear, if the polynomial computed by each of its gates is multilinear. We
say that an arithmetic circuit is *syntactically multilinear*, if for every product gate \( v \) in it with children \( v_1 \) and \( v_2 \), the two sets \( X_{v_1} \) and \( X_{v_2} \) are disjoint.

A polynomial \( f \in \mathbb{R}[X] \) is called *monotone*, if the coefficients of all the monomials in \( f \) are non-negative. An arithmetic circuit is called *monotone*, if all the field elements labeling its input gates are positive real numbers.

### 1.1.1 Vectors and Polynomials

Let \( n \in \mathbb{N} \) be an integer. We denote \( [n] = \{1, \ldots, n\} \). For the rest of this paper, we will sometimes interchange between subsets of \([n]\), subsets of \( X = \{x_1, \ldots, x_n\} \) and monic multilinear monomials in the variables \( X \) (a monic monomial is a monomial whose coefficient is 1). For example, a set \( T \subseteq [n] \) is also the set \( \{x_i : i \in T\} \) as well as the monomial \( \prod_{i \in T} x_i \).

We will focus on the following two vector spaces over the field \( \mathbb{C} \).

1. The vector space of multilinear polynomials in \( \mathbb{C}[X'] \), where \( X' \subseteq X \) (thinking of a polynomial as the vector of its coefficients). For example, for a gate \( v \) in a multilinear formula \( \Phi \) over the field \( \mathbb{C} \) and over the set of variables \( X \), we think of the polynomial \( \hat{\Phi}_v \) also as a vector.

2. The vector space of maps from \( \{1, -1\}^T \) to \( \mathbb{C} \), where \( T \subseteq [n] \).

For two vectors \( w, w' \) (as above), the *inner product* of \( w \) and \( w' \) is

\[
\langle w, w' \rangle = \sum_t w(t)\overline{w'(t)},
\]

where the sum is over all the coordinates \( t \) of the vectors (and for \( \alpha \in \mathbb{C} \), we denote by \( \overline{\alpha} \) the complex conjugate of \( \alpha \)). Define the *correlation* of \( w \) and \( w' \) as

\[
\text{cor}(w, w') = |\langle w, w' \rangle|.
\]

The vectors \( w \) and \( w' \) are called *orthogonal*, if \( \text{cor}(w, w') = 0 \). The *norm* of the vector \( w \) is

\[
\|w\| = \sqrt{\langle w, w \rangle}.
\]
1.1.2 The Non-cancelling and the Orthogonal Models

For $\tau > 0$, we say that a sum gate $v$ in an arithmetic formula $\Phi$ is $\tau$-non-cancelling, if
\[
\|\hat{\Phi}_v\| \geq \tau \cdot \max(\|\hat{\Phi}_{v_1}\|, \|\hat{\Phi}_{v_2}\|),
\]
where $v_1$ and $v_2$ are the two children of $v$. Stated differently, $v$ is non-cancelling, if it does not subtract two polynomials that are ‘almost’ the same. We say that $\Phi$ is $\tau$-non-cancelling, if every sum gate in $\Phi$ is $\tau$-non-cancelling.

We say that an arithmetic formula $\Phi$ is orthogonal, if for every sum gate $v$ in $\Phi$ with children $v_1$ and $v_2$,
\[
\text{cor}(\hat{\Phi}_{v_1}, \hat{\Phi}_{v_2}) = 0;
\]
that is, the polynomials $\hat{\Phi}_{v_1}$ and $\hat{\Phi}_{v_2}$ are orthogonal (as vectors of coefficients). So, an orthogonal arithmetic formula is, in particular, 1-non-cancelling.

Remark 1.1. We note that for every two vectors $f$ and $g$, since
\[
\|f + g\| \geq \|f\| - \|g\|,
\]
it holds that for $\tau \leq 1$
\[
\|f + g\| \geq \tau \cdot \min(\|f\|, \|g\|) \Rightarrow \|f + g\| \geq \frac{\tau}{2} \cdot \max(\|f\|, \|g\|).
\]
So, using minimum instead of maximum in (1.1) is the same, up to a factor of 2.

1.1.3 The Noise-Resistant Model

Given an input $t$, say in $\{1, -1\}^n$, an arithmetic formula $\Phi$ gives a natural way for computing the value of the polynomial $\hat{\Phi}$ on $t$. Upon realizing this computation of $\hat{\Phi}(t)$ in the ‘real world’, it seems reasonable to assume that some noise will occur. A natural model for this noise is that each edge in the formula introduces a small noise into the computation. Given $\Phi$ we will think of a noisy version of $\Phi$ as the same as $\Phi$, except that each edge of the noisy version is multiplied by a value that is close to 1 (that we think of as noise).

We note that, since we are proving lower bounds, if we assume a weaker noise model, our results become stronger. Hence, we want the noise model to be as weak as possible. We hence assume that the noise have
the following two restrictions: only sum gates introduce noise, and the noise is a positive real number that is independent of the input.

We now turn to the formal definition of the noise model. For a gate \( v \) in an arithmetic formula \( \Phi \), and for \( 0 \leq \epsilon \leq 1 \), we will define below \( N_\epsilon(\Phi_v) \) to be the set of maps from \( \{1, -1\}^{X_v} \) to \( \mathbb{C} \) that are the outputs of all the noisy versions of \( \Phi_v \) on inputs in \( \{1, -1\}^{X_v} \). Elements of \( N_\epsilon(\Phi_v) \) will be called \( \epsilon \)-noisy values of \( \Phi_v \). Before the definition, we make the following remark.

**Remark 1.2.** The polynomial \( \hat{\Phi}_v \) naturally defines a map \( \phi_v \) from \( \{1, -1\}^{X_v} \) to \( \mathbb{C} \). For \( t \in \{1, -1\}^n \), the value of \( \phi_v(t) \) is the value of the polynomial \( \hat{\Phi}_v \) after substituting \( x_i = t_i \). Since only variables in \( X_v \) occur in \( \hat{\Phi}_v \), the map \( \phi_v \) is indeed from \( \{1, -1\}^{X_v} \) to \( \mathbb{C} \).

The definition of \( N_\epsilon(\Phi_v) \) is inductively as follows.

- If \( v \) is an input gate,
  \[
  N_\epsilon(\Phi_v) = \{ \phi_v \},
  \]
  where \( \phi_v \) is the map from \( \{1, -1\}^{X_v} \) to \( \mathbb{C} \) defined by \( \hat{\Phi}_v \) – see Remark 1.2 (and so there is no noise in input gates). For example, if \( \Phi_v = x_i \), then \( \phi_v(1) = 1 \) and \( \phi_v(-1) = -1 \).

Otherwise, \( v \) has two children \( v_1 \) and \( v_2 \). We note that although \( \phi_{v_i} \) is a map from \( \{1, -1\}^{X_{v_i}} \) to \( \mathbb{C} \) we can naturally think of it as a map from \( \{1, -1\}^{X_v} \) to \( \mathbb{C} \) (for every \( t \in \{1, -1\}^{X_v} \), set \( \phi_{v_i}(t) \) to be \( \phi_{v_i}(t') \), where \( t' \) is the restriction of \( t \) to the entries in \( X_{v_i} \)), and so the following is well defined.

- If \( v \) is a product gate,
  \[
  N_\epsilon(\Phi_v) = \{ \phi_{v_1} \cdot \phi_{v_2} : \phi_{v_1} \in N_\epsilon(\Phi_{v_1}), \phi_{v_2} \in N_\epsilon(\Phi_{v_2}) \},
  \]
  (and so there is no noise in edges going into product gates).

- If \( v \) is a sum gate,
  \[
  N_\epsilon(\Phi_v) = \{ (1 + \alpha_1) \cdot \phi_{v_1} + (1 + \alpha_2) \cdot \phi_{v_2} : \phi_{v_1} \in N_\epsilon(\Phi_{v_1}), \phi_{v_2} \in N_\epsilon(\Phi_{v_2}) \},
  \]
  where \( \alpha_1, \alpha_2 \) are arbitrary real values such that
  \[
  0 \leq \alpha_1 \leq \epsilon \quad \text{and} \quad 0 \leq \alpha_2 \leq \epsilon
  \]
  (and so the edges going into sum gates introduce a noise of ‘magnitude’ at most \( \epsilon \)).
For a map \( g : \{1, -1\}^n \rightarrow \mathbb{C} \), we say that \( \Phi \) is \( \varepsilon \)-noise-resistant to computing \( g \), if every \( \varepsilon \)-noisy value of \( \Phi \) is ‘correlated’ with \( g \); that is, for every \( \phi \in N_\varepsilon(\Phi) \),

\[
\text{cor}(\phi, g) \geq \varepsilon \cdot \|\phi\| \cdot \|g\| \tag{1.2}
\]

(where we think of \( \phi \) and \( g \) as maps from \( \{1, -1\}^n \) to \( \mathbb{C} \)). So, for \( \Phi \) to be noise-resistant to computing \( g \), we only require all noisy values of \( \Phi \) to be weakly correlated with \( g \). We note that we could have introduced a new parameter (other than \( \varepsilon \), that could, perhaps, be closer to 1) to bound the correlation in (1.2). We do not do so for simplicity of notation (and, once again, this only makes the lower bounds stronger).

Reading the definition above the reader may ask herself whether noise-resistant formulas exist. One example of a formula that is noise-resistant is a formula that is a sum of monomial – Every two different multilinear monomials \( m \) and \( m' \) in the variables \( X \) admit \( \text{cor}(\phi_m, \phi_{m'}) = 0 \), where \( \phi_m \) and \( \phi_{m'} \) are the maps from \( \{1, -1\}^n \) to \( \mathbb{C} \) defined by \( m \) and \( m' \) respectively – see Remark 1.2. Thus, a polynomial of the form \( \sum_i c_i m_i \) is not very sensitive to small changes in the \( c_i \)’s (where the \( m_i \)’s are distinct monic monomials and the \( c_i \)’s are their coefficients).

### 1.2 Maximal-Partition Discrepancy

We will first recall the definition of the discrepancy of a matrix. Let \( M \) be an \( N \times N' \) matrix with entries in \( \{0, 1\} \). A rectangle \( R \) in \( M \) is a set of the form \( R = Y \times Z \subseteq [N] \times [N'] \). The discrepancy of a rectangle \( R \) in \( M \) is the difference between the number of 1’s and the number of 0’s in \( R \) divided by the size of \( M \); that is,

\[
\text{DISC}_R(M) = \frac{1}{N \cdot N'} \left| \sum_{(y,z) \in R} (-1)^{M(y,z)} \right|.
\]

The discrepancy of \( M \) is

\[
\text{DISC}(M) = \max_R \text{DISC}_R(M),
\]

where the maximum is over all rectangles \( R \) in \( M \).

We will now define maximal-partition discrepancy. Let \( f \) be a map from \( \{0, 1\}^n \) to \( \{1, -1\} \), and let \( A \) be a subset of \( \{1, \ldots, n\} \) of size \( k \) (we think of \( A \) as a partition of \( \{1, \ldots, n\} \) into \( A \) and \( \{1, \ldots, n\} \setminus A \)). For \( y \in \{0, 1\}^k \) and \( z \in \{0, 1\}^{n-k} \), define \( f_A \) to be the \( 2^k \times 2^{n-k} \) matrix whose \( (y, z) \) entry is \( f((y, z)_A) \), where \( (y, z)_A \) is the unique vector in \( \{0, 1\}^n \) whose restriction to the entries in \( A \) is \( y \) and restriction to the entries not in \( A \) is \( z \). The maximal-partition discrepancy of \( f \) is the maximal discrepancy of \( f_A \) among all sets \( A \) of size \( n/3 \leq |A| \leq 2n/3 \).
1.3 Best-Partition Communication Complexity

We will now define the framework of probabilistic best-partition communication complexity. There are two players, Alice and Bob, that share a public random string of bits. There is a fixed boolean function $g : \{0,1\}^n \rightarrow \{0,1\}$ that they both know (and assume that $n$ is even). Let $A$ and $B$ be a partition of $[n]$ into two sets of equal size. Given an input $x \in \{0,1\}^n$, Alice gets $x_A \in \{0,1\}^{n/2}$ and Bob gets $x_B \in \{0,1\}^{n/2}$ (where $x_A$ is $x$ restricted to the entries in $A$ and $x_B$ is $x$ restricted to the entries in $B$). Alice does not know $x_B$ and Bob does not know $x_A$. Their common goal is to compute $g(x)$.

The probabilistic communication complexity of $g$ with respect to $A$ and $B$ is the number of bits Alice and Bob need to exchange in order to compute $g$ (as above) with a two-sided error (a two-sided error means that they need to output the correct answer with probability at least $2/3$). The probabilistic best-partition communication complexity of $g$ is the minimal probabilistic communication complexity of $g$ with respect to $A$ and $B$, among all partitions of $[n]$ to two sets $A$ and $B$ of equal size.

1.4 Mixed-2-Source Extractors

We start with a few preliminary definitions and notation. Let $\mu$ be a distribution on $\{0,1\}^n$, and denote by $t \sim \mu$ an element distributed by $\mu$. The min-entropy of $\mu$ is

$$H_\infty(\mu) = \min_{t \in \{0,1\}^n} \log \left( \frac{1}{\mu(t)} \right);$$

that is, the min-entropy of $\mu$ is $k > 0$, if the most probable element in $\mu$ has probability $2^{-k}$. We denote by $U_n$ the uniform distribution on $\{0,1\}^n$. The statistical distance between $\mu$ and the uniform distribution $U_n$ is

$$\|\mu - U_n\|_1 = \sum_{t \in \{0,1\}^n} |\mu(x) - U_n(x)|.$$

For two vectors $t$ and $t'$ in $\{0,1\}^n$, denote by $t \circ t' \in \{0,1\}^{2n}$ the concatenation of $t$ and $t'$. For a one-to-one map $\pi$ from $[2n]$ to $[2n]$, denote by $(t \circ t')_\pi \in \{0,1\}^{2n}$ the reordering of $t \circ t'$ according to $\pi$; that is, for every $i \in [2n]$, the $i$'th entry in $(t \circ t')_\pi$ is $(t \circ t')_{\pi(i)}$.

We now give the definition of a mixed-2-source extractor. For $n, m \in \mathbb{N}$ and $k, \varepsilon > 0$, a map $\text{EXT} : \{0,1\}^{2n} \rightarrow \{0,1\}^m$ is called a mixed-2-source extractor with $k$ min-entropy requirement and error $\varepsilon$, if for every $\mu$ and $\mu'$, two independent distributions on $\{0,1\}^n$ such that

$$H_\infty(\mu) + H_\infty(\mu') \geq k,$$
and for every one-to-one map $\pi$ from $[2n]$ to $[2n],$

$$||\text{Ext}((t \circ t')_\pi) - U_m||_1 \leq \varepsilon,$$

where $t \sim \mu$ and $t' \sim \mu'$.

A mixed-2-source extractor is stronger than a 2-source extractor. More specifically, a 2-source extractor is promised to extract random bits only when $\pi$ is the identity map. We note that we think of $\pi$ as being a fixed (but unknown) order in which the bits from the two random sources arrive.

1.5 Background and Motivation

1.5.1 Multilinear Arithmetic Formulas

Multilinear polynomials are common (e.g., determinant, and permanent). The natural way to compute a multilinear polynomial is via a multilinear computation, as the use of high powers during the computation requires non-intuitive cancellations. The multilinear model was first studied by Nisan and Wigderson [NW]. Later [R04a] proved a super-polynomial lower bound for the size of multilinear arithmetic formulas for the determinant and the permanent. Furthermore, [R04b] proved a super-polynomial separation between the size of multilinear arithmetic circuits and formulas. The proof of this separation was later simplified in [RY], which also showed that syntactically multilinear arithmetic circuits of size poly$(n)$ are (without loss of generality) of depth $O(\log^2(n))$ ([RY] following [VSBR]).

Proving super-polynomial lower bounds for the size of multilinear arithmetic circuits is an open problem (the best lower bound known for syntactically multilinear arithmetic circuits is $\Omega(n^{4/3}/\log^2(n))$ [RSY]).

We note that, since syntactically multilinear arithmetic circuits can be balanced, proving $\omega(\log^2(n))$ lower bounds for the depth of syntactically multilinear arithmetic formulas will give a super-polynomial lower bound for the size of syntactically multilinear arithmetic circuits (we mention again that depth lower bounds for formulas imply depth lower bounds for circuits). This motivates proving depth lower bounds for sub-classes of syntactically multilinear formulas.

We note that we could have altered the definitions of the non-cancelling model and the noise-resistant model so that our proofs would work for multilinear formulas as well. We chose not to do so for the simplicity of the definitions and since for every multilinear formula there is a syntactically multilinear formula of the same size and depth computing the same polynomial [R04a].
1.5.2 The Noise-Resistant Model

Our main motivation for the noise model is that it seems natural to assume that in any ‘real’ implementation of an arithmetic formula over $\mathbb{C}$ noise will occur. In fact, it seems that there are two ways to implement an arithmetic computation over the field of complex numbers: either by an analog circuit, which bound to have some noise in it, or by a digital circuit, which yields the finite representation of complex numbers (floating point, for instance). Both of these ways seem to have an intrinsic noise in them. So, in order to compute (or even approximate) a map $g : \{1, -1\}^n \to \mathbb{C}$ in a way that will be resilient to the noise introduced by practical implementations, we want to find an arithmetic formula that is noise-resistant to computing $g$.

Moreover, it seems natural to think that if the noise is much smaller than the size of the formula, then the formula computes almost the same polynomial even when noise occurs. Thus, one could expect that a polynomial size formula is always noise-resistant for exponentially small noise. Indeed, natural polynomial size formulas are usually noise-resistant for exponentially small noise. Here we prove lower bounds for formulas that are noise-resistant for exponentially small noise.

Finally, we note that in other computation models defined over $\mathbb{C}$ (such as quantum circuits) a noise model was studied, and various interesting results were obtained.

1.5.3 The Non-cancelling and the Orthogonal Models

We will first give some intuition for the non-cancelling model. Every sum gate $v$ in an arithmetic formula $\Phi$ sums two polynomials, say $f_1$ and $f_2$. Roughly, the non-cancelling condition says that the norm of $f_1 + f_2$ is not much smaller than the norms of both $f_1$ and $f_2$. What does this mean? Well, in the case where the norms of $f_1 + f_2$ is much smaller than the norm of both $f_1$ and $f_2$, the two polynomials are ‘almost’ the same (with opposite signs), except for a ‘small’ part in which they differ (unless $f_1 + f_2 = 0$, in which case $v$ is ‘not needed’). Loosely speaking, this condition could be interpreted as a ‘deep’ understanding $\Phi$ (or the designer of $\Phi$) has about the computation of $\hat{\Phi}$.

Every minimal size arithmetic formula is $\tau$-non-cancelling, for some $\tau > 0$. So, every arithmetic formula ‘fits’ to the non-cancelling model. However, in the case where $\tau \leq 2^{-\Omega(n)}$ the lower bounds we prove become trivial (i.e., $\Omega(1)$). Nevertheless, our lower bounds are non-trivial even for $\tau = 2^{-n^{1-\delta}}$, for a small constant $\delta > 0$ (in which case our lower bounds for the depth of such formulas are $\Omega(n^\delta)$).

The fact that we succeed in proving polynomial lower bounds for the depth of non-cancelling syntactically multilinear arithmetic formulas shows that (perhaps) in order to prove better lower bounds for
syntactically multilinear circuits we need to understand the cancellations of monomials better.

As mentioned before, we also study orthogonal syntactically multilinear formulas. Orthogonal syntactically multilinear formulas were first suggested and motivated by Aaronson [A], who showed a connection between syntactically multilinear arithmetic formulas and a certain type of quantum computations. Aaronson studied the orthogonal model and proved lower bounds for a weaker model than the orthogonal syntactically multilinear model (which he calls manifestly orthogonal).

1.5.4 Monotone Arithmetic Circuits

The non-cancelling model is more general than the monotone model (in which there are no cancellations at all). In particular, a monotone arithmetic formula is 1-non-cancelling.

The model of monotone circuits has been studied in many papers, and exponential lower bounds for the size of monotone circuits are well known. This is true for the arithmetic case as well as the Boolean case. In particular, \(2^{\Omega(\sqrt{n})}\) lower bounds are known for the size of monotone arithmetic circuits and formulas, e.g., [SS, JS] (in fact, Valiant showed that one ‘negation’ gate is exponentially powerful [V]). Here we show how to prove a tight \(2^{\Omega(n)}\) lower bound for the size of monotone arithmetic circuits.

We also note that a monotone arithmetic circuit computing a multilinear polynomial is also a syntactically multilinear circuit. This helps us to prove a lower bound for general monotone circuits using a lower bound for syntactically multilinear formulas.

1.5.5 Maximal-Partition Discrepancy

The discrepancy of a matrix is a well known and useful property, since it measures (in some sense) the amount of pseudo-randomness in a matrix. In computer science, it is connected to probabilistic communication complexity, extractors construction, and more. In combinatorics, it is connected to Ramsey theory.

The notion of maximal-partition discrepancy is a stricter measure of pseudo-randomness. We use known ideas to show that maximal-partition discrepancy is connected to communication complexity and extractors construction. Furthermore, we show a new connection between maximal-partition discrepancy and proving lower bounds for subclasses of arithmetic formulas.
1.5.6 Communication Complexity

Communication complexity was defined by Yao [Y], and has been studied extensively since. Different models of communications complexity are related to various areas in computer science. In particular, best-partition communication complexity is related to time/space tradeoffs for Very Large Scale Integration Circuits and to the width of branching programs (see [J]). We prove a tight $\Omega(n)$ lower bound for the probabilistic best-partition communication complexity of an explicit function. Previously, Jukna [J] proved an $\Omega(\sqrt{n})$ lower bound for the probabilistic best-partition communication complexity of a function (Jukna proved a lower bound for a function that has some additional properties).

1.5.7 Mixed-2-Source Extractors

Chor and Goldreich were the first to consider weak sources of randomness, which are sources with min-entropy $k$ [CG]. Extracting randomness from one weak source is impossible (as long as $k \leq n - 1$). So, other sources of randomness were considered, such as two independent weak sources, and a few independent sources. We note that the study of extracting randomness from a few independent sources has advanced significantly lately [BIW, BKSSW, BRSW, R05, R] due to the well known sum-product theorem [BKT].

We focus on mixed-2-sources that are a generalization of two independent sources. Given two independent sources of size $n/2$ each and total min-entropy $k$, [CG] showed that the Hadamard matrix gives efficient extraction of one random bit for $k > n/2$ (we omit the dependency on the error term). The state of the art, due to Bourgain [Bo+], is a 2-source extractor that gives a linear number of almost perfect bits for $k > n(1 - \delta)/2$ (for some constant $\delta > 0$). Here we give an explicit mixed-2-source extractor for $k > n(1 - \delta')$ (for some constant $\delta' > 0$) that gives a linear number of almost perfect random bits.

One way of thinking of a mixed-2-source extractor is as an extractor that works also when the bits of the two random sources arrive in a fixed but unknown order. This seems to be a natural relaxation of the well known notion of 2-source extractors, although, as far as we know, it has not been considered before. We also note that the Hadamard matrix does not give a mixed-2-source extractor even for $k = n - 4$ (in fact, the Hadamard extractor can be made constant for such a $k$).

1.6 Results and Methods

In all the following theorems, $n = 12sp$ is an integer, where $p \in \mathbb{N}$ is prime and $s \in \mathbb{N}$ is a large enough constant (given in Theorem 6.1), and $f$ is the multilinear polynomial over the set of variables
\[ X = \{x_1, \ldots, x_n\} \text{ with coefficients in } \{1, -1\} \text{ defined below in Section 5.2. We will also use the map } g \text{ from } \{1, -1\}^n \text{ to } \{1, -1\} \text{ defined by} \]
\[
\forall t \in \{1, -1\}^n \quad g(t) \text{ is the coefficient of the monomial } \prod_{i \in [n]: t_i = -1} x_i \text{ in } f. \quad (1.3)
\]

We note that \( g \) can be computed in polynomial time, and hence \( f \) is in VNP, which is Valiant’s algebraic analog of NP.

### 1.6.1 Non-cancelling, Orthogonal and Noise-resistant Formulas

The following theorem gives a tradeoff between the depth and the “amount of non-cancelling” for a syntactically multilinear arithmetic formula computing \( f \). E.g., a \( 2^{-\sqrt{n}} \)-non-cancelling syntactically multilinear arithmetic formula that is at least \( 2^{-\sqrt{n}} \) correlated with \( f \) is of depth \( \Omega(\sqrt{n}) \).

**Theorem 1.3.** Let \( \tau, c > 0 \), and let \( \Phi \) be a \( \tau \)-non-cancelling syntactically multilinear arithmetic formula of depth \( d \in \mathbb{N} \) over the field \( \mathbb{C} \) and over the set of variables \( X \) such that
\[
\text{cor}(\hat{\Phi}, f) \geq c \cdot \|\hat{\Phi}\| \cdot \|f\|,
\]
where \( f \) is the polynomial defined in Section 5.2, and we think of \( \hat{\Phi} \) and \( f \) as vectors of coefficients. Then,
\[
|\Phi| \cdot \tau^{-d} \geq c \cdot 2^{\Omega(n)}.
\]

In particular, if \( \tau < 2 \) and \( c \geq 1/2 \),
\[
d = \Omega\left(\frac{n}{\log(2/\tau)}\right),
\]
and if \( \tau \geq 1 \) and \( c \geq 1/2 \),
\[
|\Phi| = 2^{\Omega(n)}.
\]

Since we do not know how to balance arithmetic formulas in the non-cancelling model, Theorem 1.3 does not imply an exponential lower bound for the size (for small \( \tau \)). However, since every orthogonal arithmetic formula is 1-non-cancelling, we have the following exponential lower bound for the size of orthogonal syntactically multilinear arithmetic formulas computing \( f \).

**Corollary 1.4.** Let \( \Phi \) be an orthogonal syntactically multilinear arithmetic formula over the field \( \mathbb{C} \) and over the set of variables \( X \) computing \( f \), where \( f \) is the polynomial defined in Section 5.2. Then,
\[
|\Phi| = 2^{\Omega(n)}.
\]
(a similar lower bound holds for the monotone model).

A similar trade-off holds for a noise-resistant computation of \( f \). For example, a syntactically multilinear arithmetic formula that is \( 2^{-\sqrt{n}} \)-noise-resistant to computing \( g \) is of depth \( \Omega(\sqrt{n}) \).

**Theorem 1.5.** Let \( 0 < \varepsilon < 1 \), and let \( \Phi \) be a syntactically multilinear arithmetic formula of depth \( d \in \mathbb{N} \) over the field \( \mathbb{C} \) and over the set of variables \( X \) that is \( \varepsilon \)-noise-resistant to computing \( g \), where \( g \) is defined in (1.3). Then,

\[
    d = \Omega \left( \frac{n}{\log(2/\varepsilon)} \right).
\]

The proof of all the theorems given in this section are in Section 4. The proofs also use Theorem 3.1 that shows that syntactically multilinear formulas have a special structure.

### 1.6.2 Monotone Arithmetic Circuits

The previous lower bounds are for formulas computing \( f \), the polynomial defined in Section 5.2. The polynomial \( f \) has negative coefficients, and so it cannot be computed by a monotone circuit. However, we can use \( f \) to define a new polynomial \( F \in \mathbb{C}[X] \) with coefficients in \( \{0, 1\} \), for which we will also be able to prove lower bounds. The polynomial \( F \) is defined as follows: for a monic monomial \( m \) in the variables \( X \), the coefficient of \( m \) in \( F \) is

\[
    \frac{f_m + 1}{2} \in \{0, 1\},
\]

where \( f_m \) is the coefficient of \( m \) in \( f \).

The following theorem gives a tight lower bound for the size of monotone arithmetic circuits for \( F \).

**Theorem 1.6.** Let \( \Phi \) be a monotone arithmetic circuit over the field \( \mathbb{R} \) and over the set of variables \( X \) computing the polynomial \( F \) defined above. Then,

\[
    |\Phi| = 2^{\Omega(n)}.
\]

The proof of Theorem 1.6 is in Section 7.
1.6.3 Maximal-Partition Discrepancy

The property of $f$ that we use is given by the following theorem. A multilinear polynomial $f' \in \mathbb{C}[X]$ is called *big*, if there exist two disjoint sets $X_1, X_2 \subseteq X$ of size at least $n/3$ each, and two polynomials $f_1 \in \mathbb{C}[X_1]$ and $f_2 \in \mathbb{C}[X_2]$ such that

$$f' = f_1 \cdot f_2$$  \hspace{1cm} (1.4)

(see Section 2.1 for more details).

**Theorem 1.7.** Every big multilinear polynomial $f' \in \mathbb{C}[X]$ admits

$$\text{cor}(f, f') \leq 2^{-\Omega(n)} \|f\| \|f'\|,$$

where $f$ is the polynomial defined in Section 5.2, and we think of $f$ and $f'$ as vectors of coefficients.

The proof of Theorem 1.7 is in Section 6. A key ingredient in the proof is an exponential sum estimate of Bourgain, Glibichuk and Konyagin [BoGK]. A corollary of Theorem 1.7 is that $g$ has small maximal-partition discrepancy.

**Corollary 1.8.** The maximal-partition discrepancy of $g$ is $2^{-\Omega(n)}$, where $g$ is the map defined in (1.3).

1.6.4 Best-Partition Communication Complexity

The following theorem lower bounds the probabilistic best-partition communication complexity of $g$.

**Theorem 1.9.** The probabilistic best-partition communication complexity of $g$ is $\Omega(n)$, where $g$ is the map defined in (1.3).

The proof of Theorem 1.9 follows using standard methods in communication complexity and using the exponentially small maximal-partition discrepancy of $g$.

1.6.5 Mixed-2-Source Extractors

The following theorem gives an efficient map that extracts a linear number of almost perfect random bits from a mixed-2-source of randomness of high min-entropy.
Theorem 1.10. There exists a constant \( \beta > 0 \) such that the following holds. Let \( n = 12sp \) be an even integer, where \( p \in \mathbb{N} \) is prime and \( s \in \mathbb{N} \) is the constant given in Theorem 6.1. Then, there exists an explicit mixed-2-source extractor \( \text{Ext} \) : \( \{0,1\}^n \rightarrow \{0,1\}^m \) with \( m = \lfloor \beta n \rfloor \), that is computable in deterministic polynomial time with \((n - 3m)\) min-entropy requirement and error \( 2^{-2m} \).

The proof of Theorem 1.10 is in Section 8.

2 Preliminaries for Multilinear Arithmetic Formulas

2.1 Big Polynomials

Let \( n \geq 3 \) be an integer, and let \( X = \{x_1, \ldots, x_n\} \). We say that a multilinear polynomial \( f \in \mathbb{C}[X] \) is big, if there exist two disjoint sets \( X_1, X_2 \subseteq X \) of size at least \( n/3 \) each, and two polynomials \( f_1 \in \mathbb{C}[X_1] \) and \( f_2 \in \mathbb{C}[X_2] \) such that

\[
f = f_1 \cdot f_2
\]

We say that a variable \( x \in X \) occurs in a polynomial \( f \in \mathbb{C}[X] \), if the degree of \( x \) in \( f \) is at least 1.

We will use the following claim.

Claim 2.1. Let \( n \geq 3 \) be an integer, and let \( X = \{x_1, \ldots, x_n\} \). Let \( f \in \mathbb{C}[X] \) be a big polynomial. Let \( T \subseteq X \) be such that \( |T| \leq n/3 \). Let \( g \in \mathbb{C}[T] \) be a polynomial such that \( f \cdot g \) is multilinear. Then, the polynomial \( f \cdot g \) is big as well.

Proof. Let \( X', X'' \subseteq X \) be the two disjoint sets given by the fact that \( f \) is big, and let \( f' \in \mathbb{C}[X'] \) and \( f'' \in \mathbb{C}[X''] \) be the two polynomials given by the fact that \( f \) is big. Let \( T' \subseteq X' \) be the set of variables in \( X' \) that occur in \( f' \), and let \( T'' \subseteq X'' \) be the set of variables in \( X'' \) that occur in \( f'' \). So, \( f' \) is in \( \mathbb{C}[T'] \) and \( f'' \) is in \( \mathbb{C}[T''] \). Assume without loss of generality that \( |T'| \geq |T''| \). Since \( f' \cdot f'' \cdot g \) is multilinear, the sets \( T', T'' \) and \( T \) are pairwise disjoint. Consider two cases:

1. \( |T''| \geq n/3 \) (and hence \( |T'| \geq n/3 \)). Thus, \( f \cdot g = f' \cdot (f'' \cdot g) \) is big (with the sets \( T' \) and \( T'' \cup T \)).
2. \( |T''| < n/3 \). Thus, \( |T'' \cup T| < 2n/3 \). Since \( f \) is big, \( |T'| \leq 2n/3 \). So, let \( S'' \) be a subset of \( X \setminus T' \) of size at least \( n/3 \) and at most \( 2n/3 \), such that \( T'' \cup T \subseteq S'' \), and let \( S' = X \setminus S'' \). Thus, \( f \cdot g = f' \cdot (f'' \cdot g) \) is big (with the sets \( S' \) and \( S'' \)).

\( \square \)
2.2 Norm of Product of Polynomials

The following claim shows that the norm is multiplicative (in a certain case).

Claim 2.2. Let \( f \) and \( g \) be two polynomials in \( \mathbb{C}[X] \) such that \( f \cdot g \) is multilinear. Then,
\[
\|f \cdot g\| = \|f\| \cdot \|g\|.
\]

Proof. For a polynomial \( F \) and a monomial \( m \), we denote by \( F_m \) the coefficient of \( m \) in \( F \). Denote by \( A \) the set of variables that occur in \( f \), and denote by \( B \) the set of variables that occur in \( g \). Since \( f \cdot g \) is multilinear, the sets \( A \) and \( B \) are disjoint. Furthermore,
\[
\|f \cdot g\|^2 = \sum_{a,b} |(f \cdot g)_{a-b}|^2 = \sum_{a,b} |f_a \cdot g_b|^2 = \left( \sum_a |f_a|^2 \right) \left( \sum_b |g_b|^2 \right) = \|f\|^2 \cdot \|g\|^2,
\]
where the sums are over all multilinear monomials \( a \) in the variables \( A \), and all multilinear monomials \( b \) in the variables \( B \).

3 Sum Trees

In this section we define and study sum trees. We first show that every syntactically multilinear arithmetic formula can be thought of as a sum tree with certain properties. We then show that sum trees do not increase the correlation with a given polynomial during their computation. This will enable us to bound the correlation between the polynomials computed by non-cancelling or noise-resistant syntactically multilinear arithmetic formulas and a certain family of polynomials. In the next section we will use this bound on the correlation to prove lower bounds for non-cancelling and noise-resistant arithmetic formulas.

3.1 Definition

A sum tree \( \Psi \) over the field \( \mathbb{C} \) and over the set of variables \( X = \{x_1, \ldots, x_n\} \) is a directed binary tree (whose edges are directed from the leaves to the root) as follows: Every leaf in \( \Psi \) is labelled by a polynomial in \( \mathbb{C}[X] \). All vertices of in-degree 2 in \( \Psi \) are labelled by +.

The notation and definitions of sum trees are the same as of arithmetic formulas. We will now give a few examples. Every gate \( v \) in a sum tree computes a polynomial \( \hat{\Psi}_v \) in \( \mathbb{C}[X_v] \) (where leaves compute
the polynomials they are labelled by). A sum tree $\Psi$ is $\tau$-non-cancelling if every sum gate $v$ with two children $v_1$ and $v_2$ in it (these are all the inner gates of $\Psi$) admits
\[ \|\Psi_v\| \geq \tau \cdot \max(\|\Psi_{v_1}\|, \|\Psi_{v_2}\|). \]

The set of noisy values of a sum tree $N_\varepsilon(\Psi_v)$ is defined the same as for formulas. We note that in the case of sum tree an input gate $u$ computes an arbitrary polynomials $\widehat{\Phi}_u$, and so the set of noisy values of $u$ is composed of a single element which is the map from $\{1, -1\}^X_u$ to $\mathbb{C}$ defined by $\widehat{\Phi}_u$ (see Remark 1.2).

### 3.2 Multilinear Arithmetic Formulas as Sum Trees

We now show that every syntactically multilinear arithmetic formula can be transformed to a sum tree in which the input gates are labelled by big polynomials (for the definition of a big polynomial see Section 2.1). We note that for every polynomial, there is a sum tree $\Psi$ of size 1 computing it. However, the input gate of $\Psi$ is not (necessarily) labelled by a big polynomial.

**Theorem 3.1.** Let $n \geq 3$ be an integer, and let $\tau, \varepsilon > 0$. Let $\Phi$ be a $\tau$-non-cancelling syntactically multilinear arithmetic formula over the field $\mathbb{C}$ and over the set of variables $X = \{x_1, \ldots, x_n\}$. Then, there exists a $\tau$-non-cancelling sum tree $\Psi$ of size at most $|\Phi|$ and of depth at most the depth of $\Phi$ over the field $\mathbb{C}$ and over the set of variables $X$ computing $\widehat{\Phi}$ such that every input gate in $\Psi$ is labelled by a big polynomial. Furthermore,
\[ N_\varepsilon(\Psi) \subseteq N_\varepsilon(\Phi). \]

**Proof.** We will in fact prove the following claim. Let $v$ be a gate in $\Phi$. Then, there exists a $\tau$-non-cancelling sum tree $\Psi_v$ of size at most $|\Phi_v|$ and of depth at most depth$(v)$ over the field $\mathbb{C}$ and over the set of variables $X_v$ computing $\widehat{\Phi}_v$ such that every input gate in $\Psi_v$ is labelled by a big polynomial. Furthermore,
\[ N_\varepsilon(\Psi_v) \subseteq N_\varepsilon(\Phi_v). \]

The proof will follow by induction on the size of $\Phi_v$. Consider the following four cases:

**Case one:** $v$ is an input gate. Set $\Psi_v$ to be an input gate labelled $\widehat{\Phi}_v$. So, $\Psi_v$ is a sum tree of size 1 and of depth 0 over the set of variables $X_v$ computing $\widehat{\Phi}_v$ such that (since $n \geq 3$) the input gate of $\Psi_v$ is labelled by a big polynomial. Since $\Psi_v$ has no sum gates, it is $\tau$-non-cancelling. Furthermore, since there is no noise in input gates, $N_\varepsilon(\Psi_v) \subseteq N_\varepsilon(\Phi_v)$. 19
Case two: \( v \) is a sum gate with children \( v_1 \) and \( v_2 \). By induction, there exist two sum trees \( \Psi_{v_1} \) and \( \Psi_{v_2} \) with the above properties. Set \( \Psi_v = \Psi_{v_1} + \Psi_{v_2} \). By induction,

\[
\hat{\Psi}_v = \hat{\Psi}_{v_1} + \hat{\Psi}_{v_2} = \hat{\Phi}_{v_1} + \hat{\Phi}_{v_2} = \hat{\Phi}_v.
\]

Furthermore, since \( \Phi \) is \( \tau \)-non-cancelling,

\[
\|\hat{\Psi}_v\| \geq \tau \cdot \max(\|\hat{\Psi}_{v_1}\|, \|\hat{\Psi}_{v_2}\|).
\]

So, by induction, \( \Psi_v \) is a \( \tau \)-non-cancelling sum tree of size at most \( |\Phi_v| \) and of depth at most \( \text{depth}(v) \) over the set of variables \( X_v \) computing \( \hat{\Phi}_v \) such that the input gates of \( \Psi_v \) are labelled by big polynomials. Furthermore, let \( \psi_v \in N_\varepsilon(\Psi_v) \). Thus, there exist \( \alpha_1, \alpha_2 \in \mathbb{R} \) that admit \( 0 \leq \alpha_1 \leq \varepsilon \) and \( 0 \leq \alpha_2 \leq \varepsilon \) such that

\[
\psi_v = (1 + \alpha_1) \cdot \psi_{v_1} + (1 + \alpha_2) \cdot \psi_{v_2},
\]

where \( \psi_{v_1} \in N_\varepsilon(\Psi_{v_1}) \) and \( \psi_{v_2} \in N_\varepsilon(\Psi_{v_2}) \). By induction, \( \psi_{v_1} \in N_\varepsilon(\Phi_{v_1}) \) and \( \psi_{v_2} \in N_\varepsilon(\Phi_{v_2}) \), and so \( \psi_v \in N_\varepsilon(\Phi_v) \). Thus, \( N_\varepsilon(\Psi_v) \subseteq N_\varepsilon(\Phi_v) \).

Case three: \( v \) is a product gate with children \( v_1 \) and \( v_2 \) such that the sets \( X_{v_1} \) and \( X_{v_2} \) are of size at least \( n/3 \) each. Since \( \Phi \) is syntactically multilinear, \( X_{v_1} \cap X_{v_2} = \emptyset \). So, the polynomial \( \hat{\Phi}_v = \hat{\Phi}_{v_1} \cdot \hat{\Phi}_{v_2} \) is big. Set \( \Psi_v \) to be an input gate labelled by \( \hat{\Phi}_v \). So, \( \Psi_v \) is a sum tree of size 1 and of depth 0 over the set of variables \( X_v \) computing \( \hat{\Phi}_v \) such that the input gate of \( \Psi_v \) is labelled by a big polynomial. Since \( \Psi_v \) has no sum gates, it is \( \tau \)-non-cancelling. Furthermore, since there is no noise in input gates, \( N_\varepsilon(\Psi_v) \subseteq N_\varepsilon(\Phi_v) \).

Case four: \( v \) is a product gate with two children \( v_1 \) and \( v_2 \) such that (without loss of generality) \( |X_{v_2}| < n/3 \). By induction, there exists a sum tree \( \Psi' = \Psi_{v_1} \) satisfying the above properties with respect to \( v_1 \). Recall that for a gate \( u \) in \( \Psi' \), we defined \( \hat{\Psi}'_u \) to be the polynomial in \( \mathbb{C}[X_{v_1}] \) that \( u \) computes in \( \Psi' \). Set \( \Psi = \Psi_v \) (we denote \( \Psi_v \) by \( \Psi \), for simplicity of notation) to be the same as \( \Psi' \), except that each input gate \( u \) in \( \Psi' \) is labelled in \( \Psi \) by

\[
\hat{\Psi}'_u \cdot \hat{\Phi}_{v_2}.
\]

There is a one-to-one correspondence between gates in \( \Psi' \) and gates in \( \Psi \). We think of a gate \( u \) both as a gate in \( \Psi' \) and as a gate in \( \Psi \). It follows by induction (on the structure of \( \Psi \)) that each gate \( u \) admits

\[
\hat{\Psi}_u = \hat{\Psi}'_u \cdot \hat{\Phi}_{v_2}.
\]

So, if \( u_1 \) and \( u_2 \) are the children of \( u \), using Claim 2.2, since \( X_{v_1} \cap X_{v_2} = \emptyset \), and since \( \Psi' \) is \( \tau \)-non-cancelling,

\[
\|\hat{\Psi}_u\| = \|\hat{\Psi}'_u\| \cdot \|\hat{\Phi}_{v_2}\| \geq \tau \cdot \max(\|\hat{\Psi}_u_1\|, \|\hat{\Psi}_u_2\|).
\]
So, $\Psi$ is $\tau$-non-cancelling. By induction, $\hat{\Psi}' = \hat{\Phi}_{v_1}$, which implies $\hat{\Psi} = \hat{\Phi}_v$. For every input gate $u$ in $\Psi$, since $\hat{\Psi}_u'$ is a big polynomial in $C[X_{v_1}]$, since $X_{v_1} \cap X_{v_2} = \emptyset$, and since $|X_{v_2}| < n/3$, using Claim 2.1, it follows that $\hat{\Psi}_u = \hat{\Psi}_u' \cdot \hat{\Phi}_{v_2}$ is a big polynomial. So, $\Psi$ is a sum tree of size at most $|\Phi_v|$ and of depth at most depth($v$) over the set of variables $X_v$ computing $\hat{\Phi}_v$ such that the input gates of $\Psi$ are labelled by big polynomials.

Furthermore, let $\psi \in N_\varepsilon(\Psi)$, and let $\phi_{v_2} \in N_\varepsilon(\Phi_{v_2})$ be the map defined by $\hat{\Phi}_{v_2}$. It follows by induction (on the structure of $\Psi$) that there exists $\psi' \in N_\varepsilon(\Psi')$ such that

$$\psi = \psi' \cdot \phi_{v_2}.$$ 

By induction, $\psi' \in N_\varepsilon(\Phi_{v_1})$, and so $\psi \in N_\varepsilon(\Phi_v)$. Thus, $N_\varepsilon(\Psi) \subseteq N_\varepsilon(\Phi_v)$.

### 3.3 Sum Trees Do Not Increase Correlation

In the previous section we have shown that without loss of generality every syntactically multilinear arithmetic formula is a sum tree, whose input gates are labelled by big polynomials. We now bound the correlation between a polynomial computed by a sum tree and a given polynomial, using the correlations in the input gates.

**Theorem 3.2.** Let $n \in \mathbb{N}$ be an integer, let $\tau > 0$ and let $0 < \varepsilon \leq 1$. Let $\Psi$ be a $\tau$-non-cancelling sum tree of depth $d$ over the field $C$ and over the set of variables $X = \{x_1, \ldots, x_n\}$. Let $\delta > 0$, and let $f$ be a polynomial in $C[X]$ such that for every input gate $u$ in $\Psi$,

$$\text{cor}(\hat{\Psi}_u, f) \leq \delta \cdot \|\hat{\Psi}_u\| \cdot \|f\|.$$ 

Then,

$$\text{cor}(\hat{\Psi}, f) \leq \delta \cdot \|\hat{\Psi}\| \cdot \|f\| \cdot |\Psi| \cdot \tau^{-d}.$$ 

Furthermore, let $g$ be a map from $\{1, -1\}^n$ to $C$ such that for every input gate $u$ in $\Psi$,

$$\text{cor}(\psi_u, g) \leq \delta \cdot \|\psi_u\| \cdot \|g\|,$$

where $\psi_u : \{1, -1\}^n \rightarrow C$ is the unique element of $N_\varepsilon(\Psi_u)$ (recall that $\psi_u$ is the map defined by the polynomial $\hat{\Psi}_u$ – see Remark 1.2). Then, there exists $\psi \in N_\varepsilon(\Psi)$ such that

$$\text{cor}(\psi, g) \leq \delta \cdot \|\psi\| \cdot \|g\| \cdot (\varepsilon/6)^{-d}.$$ 

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Proof. The proof follows by induction on the size of $\Psi$. Let $v$ be the root of $\Psi$, and consider the following two cases:

**Case one:** $v$ is an input gate.
Since $|\Psi| = 1$ and since $d = 0$,
\[
\text{cor}(\hat{\Psi}, f) \leq \delta \cdot \|\hat{\Psi}\| \cdot \|f\| = \delta \cdot \|\hat{\Psi}\| \cdot \|f\| \cdot |\Psi| \cdot \tau^{-d},
\]
and
\[
\text{cor}(\psi, g) \leq \delta \cdot \|\psi\| \cdot \|g\| \cdot (\varepsilon/6)^{-d},
\]
where $\psi \in N_\varepsilon(\Psi)$.

**Case two:** $v$ is a sum gate with children $v_1$ and $v_2$.
By induction,
\[
\text{cor}(\hat{\Psi}_{v_1}, f) \leq \delta \cdot \|\hat{\Psi}_{v_1}\| \cdot \|f\| \cdot |\Psi_{v_1}| \cdot \tau^{-d+1},
\]
and
\[
\text{cor}(\hat{\Psi}_{v_2}, f) \leq \delta \cdot \|\hat{\Psi}_{v_2}\| \cdot \|f\| \cdot |\Psi_{v_2}| \cdot \tau^{-d+1}.
\]
So,
\[
\text{cor}(\hat{\Psi}, f) = \text{cor}(\hat{\Psi}_{v_1} + \hat{\Psi}_{v_2}, f) \leq \text{cor}(\hat{\Psi}_{v_1}, f) + \text{cor}(\hat{\Psi}_{v_2}, f)
\leq \delta \cdot \max(\|\hat{\Psi}_{v_1}\|, \|\hat{\Psi}_{v_2}\|) \cdot \|f\| \cdot (|\Psi_{v_1}| + |\Psi_{v_2}|) \cdot \tau^{-d+1}.
\]
Since $\Psi$ is $\tau$-non-cancelling,
\[
\max(\|\hat{\Psi}_{v_1}\|, \|\hat{\Psi}_{v_2}\|) \leq \tau^{-1} \|\hat{\Psi}\|.
\]
So, since $|\Psi_{v_1}| + |\Psi_{v_2}| \leq |\Psi|$,
\[
\text{cor}(\hat{\Psi}, f) \leq \delta \cdot \|f\| \cdot \|\hat{\Psi}\| \cdot |\Psi| \cdot \tau^{-d}.
\]
Similarly, there exist $\psi_{v_1} \in N_\varepsilon(\Psi_{v_1})$ and $\psi_{v_2} \in N_\varepsilon(\Psi_{v_2})$ such that
\[
\text{cor}(\psi_{v_1}, g) \leq \delta \cdot \|\psi_{v_1}\| \cdot \|g\| \cdot (\varepsilon/6)^{-d+1},
\]
and
\[
\text{cor}(\psi_{v_2}, g) \leq \delta \cdot \|\psi_{v_2}\| \cdot \|g\| \cdot (\varepsilon/6)^{-d+1}.
\]
Assume without loss of generality that $\|\psi_{v_1}\| \geq \|\psi_{v_2}\|$. There are two possibilities:
1. \[ \|\psi_{v_1} + \psi_{v_2}\| \geq \frac{\varepsilon}{2} \cdot \|\psi_{v_1}\|. \]

Then, we set \( \psi = \psi_{v_1} + \psi_{v_2} \), and so \( \psi \in N_{\varepsilon}(\Psi) \). Thus,
\[ \|\psi\| \geq \varepsilon \cdot \|\psi_{v_1}\|. \]

2. \[ \|\psi_{v_1} + \psi_{v_2}\| < \frac{\varepsilon}{2} \cdot \|\psi_{v_1}\|. \]

Then, we set \( \psi = (1 + \varepsilon)\psi_{v_1} + \psi_{v_2} \), and so \( \psi \in N_{\varepsilon}(\Psi) \). Thus,
\[ \|\psi\| \geq \varepsilon \cdot \|\psi_{v_1}\| - \|\psi_{v_1} + \psi_{v_2}\| > \frac{\varepsilon}{2} \cdot \|\psi_{v_1}\|. \]

So, since \( \varepsilon \leq 1 \),

\[ \text{cor}(\psi, g) \leq (1 + \varepsilon) \cdot \text{cor}(\psi_{v_1}, g) + \text{cor}(\psi_{v_2}, g) \leq 3\delta \cdot \|\psi_{v_1}\| \cdot \|g\| \cdot (\varepsilon/6)^{-d+1} \leq \delta \cdot \|\psi\| \cdot \|g\| \cdot (\varepsilon/6)^{-d}. \]

\[ \square \]

4 Lower Bounds for Non-Cancelling and Noise-Resistant Formulas

In this section we prove the two lower bounds for non-cancelling and for noise-resistant syntactically multilinear arithmetic formulas.

4.1 Proof of Theorem 1.3

By Theorem 3.1, there exists a \( \tau \)-non-cancelling sum tree \( \Psi \) of size at most \( |\Phi| \) and of depth at most \( d \) over the field \( \mathbb{C} \) and over the set of variables \( X \) computing \( \hat{\Phi} \) such that every input gate in \( \Psi \) is labelled by a big multilinear polynomial. So, by Theorem 1.7, every input gate \( u \) in \( \Psi \) admits

\[ \text{cor}(\hat{\Psi}_u, f) \leq 2^{-\Omega(n)} \cdot \|\hat{\Psi}_u\| \cdot \|f\|. \]

So, by Theorem 3.2, since \( \hat{\Psi} = \hat{\Phi} \),

\[ c \cdot \|\hat{\Psi}\| \cdot \|f\| \leq \text{cor}(\hat{\Psi}, f) \leq 2^{-\Omega(n)} \cdot \|\hat{\Psi}\| \cdot \|f\| \cdot |\Psi| \cdot \tau^{-d}. \]
Thus, since $|\Psi| \leq |\Phi|$, 

$$|\Phi| \cdot \tau^{-d} \geq c \cdot 2^\Omega(n).$$

Furthermore, since $|\Phi| \leq 2^d$, setting $c = 1/2$ and assuming $\tau < 2$, 

$$d = \Omega\left(\frac{n}{\log(2/\tau)}\right).$$

\[\square\]

### 4.2 Proof of Theorem 1.5

By Theorem 3.1, there exists a sum tree $\Psi$ of size at most $|\Phi|$ and of depth at most $d$ over the field $\mathbb{C}$ and over the set of variables $X$ such that every input gate in $\Psi$ is labelled by a big polynomial, and such that $N_\varepsilon(\Psi) \subseteq N_\varepsilon(\Phi)$.

Let $u$ be an input gate in $\Psi$, and let $\psi_u$ be the unique element of $N_\varepsilon(\Psi_u)$ (recall that $\psi_u$ is the map defined by the polynomial $\hat{\Psi}_u$ – see Remark 1.2). Since $\hat{\Psi}_u$ is a big polynomial, $\psi_u$ is the vector of coefficients of a big polynomial (different than $\hat{\Psi}_u$). So, by Theorem 1.7, and by the definition of $g$, 

$$\text{cor}(\psi_u, g) \leq 2^{-\Omega(n)} \cdot \|\psi_u\| \cdot \|g\|.$$ 

So, since $\Phi$ is $\varepsilon$-noise-resistant to computing $g$, and by Theorem 3.2, there exists $\psi \in N_\varepsilon(\Psi)$ such that 

$$\varepsilon \cdot \|\psi\| \cdot \|g\| \leq \text{cor}(\psi, g) \leq 2^{-\Omega(n)} \cdot \|\psi\| \cdot \|g\| \cdot (\varepsilon/6)^{-d}.$$ 

So, 

$$d = \Omega\left(\frac{n}{\log(2/\varepsilon)}\right).$$ 

\[\square\]

### 5 The Explicit Construction

In this section we construct a multilinear polynomial $f$ that is 'uncorrelated' with any big polynomial (for the definition of a big polynomial see Section 2.1). That is, every big multilinear polynomial $f' \in \mathbb{C}[X]$ admits 

$$\text{cor}(f, f') \leq 2^{-\Omega(n)} \|f\| \cdot \|f'\|$$
(see Theorem 1.7). The definition of \( f \) requires some preliminaries, so we defer it to Section 5.2. We note that the coefficients of monomials in \( f \) are either 1 or \( -1 \). We also note that the coefficients of monomials in \( f \) can be computed efficiently, and so \( f \) is in VNP, which is Valiant’s algebraic analog of NP.

5.1 Preliminaries

5.1.1 Additive Characters

Let \( p \in \mathbb{N} \) be a prime integer, and let \( \mathbb{F} = \text{GF}(2^p) \) be the field of size \( 2^p \). Every \( y \in \mathbb{F} \) can be thought of as a vector \((y_1, \ldots, y_p) \in \{0,1\}^p\). The inner product of two field elements \( y = (y_1, \ldots, y_p) \) and \( z = (z_1, \ldots, z_p) \) is defined as
\[
\langle y, z \rangle = \sum_{i \in [p]} y_iz_i \in \{0,1\}
\]
(where the sum is modulo 2). For \( z \in \mathbb{F} \), define the map \( \psi_z : \mathbb{F} \to \mathbb{C} \) as
\[
\forall y \in \mathbb{F} \quad \psi_z(y) = (-1)^{\langle z,y \rangle}.
\]
So, every \( y \) and \( y' \) in \( \mathbb{F} \) admit
\[
\psi_z(y + y') = \psi_z(y) \cdot \psi_z(y').
\]
(5.1)
The map \( \psi_z \) is called an additive character of \( \mathbb{F} \). If \( z \) is non-zero, then \( \psi_z \) is called a non-trivial additive character of \( \mathbb{F} \). So, the image of a non-trivial character is \( \{1, -1\} \).

5.1.2 Monomials as Field Elements

Let \( n = 12sp \) be an integer, where \( p \in \mathbb{N} \) is prime and \( s \in \mathbb{N} \) is the constant given in Theorem 6.1. Let \( X = \{x_1, \ldots, x_n\} \) be a set of variables, and let \( \mathbb{F} \) be the field of size \( 2^p \). Recall that we think of field elements in \( \mathbb{F} \) also as vectors in \( \{0,1\}^p \). For a multilinear monomial \( m \) over the set of variables \( X \) and for \( i \in [12s] \), we denote by \( y_i = y_i(m) \in \mathbb{F} \) the field element defined as
\[
\forall j \in [p] \quad (y_i)_j = \text{the degree of } x_{p(i-1)+j} \text{ in } m.
\]
5.2 Definition of $f$

Let $n = 12sp$ be an integer, where $p \in \mathbb{N}$ is prime and $s \in \mathbb{N}$ is the constant given in Theorem 6.1. Let $X = \{x_1, \ldots, x_n\}$ be a set of variables, and let $F$ be the field of size $2^p$. Let $\psi$ be an arbitrary non-trivial additive character of $F$ (we note that the fact that $\psi$ is arbitrary will be used in Section 8 in the proof that the extractor works).

We define the multilinear polynomial $f \in \mathbb{C}[X]$ by defining the coefficients of the monomials in $f$. Let $m$ be a monic multilinear monomial over the set of variables $X$. For every $i \in [12s]$, let $y_i = y_i(m) \in F$ be the field element defined in Section 5.1.2. Define the coefficient of $m$ in $f$ to be $\psi(y_1 \cdot y_2 \cdot \cdots y_{12s}) \in \{1, -1\}$.

6 The Explicit Construction Works

In this section we prove Theorem 1.7; i.e., that $f$ is uncorrelated with any big polynomial.

6.1 An Exponential Sum Estimate

We will use the following exponential sum estimate of [BoGK] (see also [Bo]). We state a weaker result than the result of [BoGK].

**Theorem 6.1.** There exist two constants, an integer $s \in \mathbb{N}$ and $\beta > 0$, such that for every prime $p \in \mathbb{N}$, for every family of sets $A_1, \ldots, A_s \subseteq GF(2^p)$ of size at least $2^{p/4}$ each, for every non-zero field element $z \in GF(2^p)$, and for every non-trivial additive character $\psi$ of $GF(2^p)$,

$$\left| \sum_{y_1 \in A_1, \ldots, y_s \in A_s} \psi(z \cdot y_1 \cdot y_2 \cdot \cdots y_s) \right| \leq 2^{-\beta p} \cdot |A_1| \cdot |A_2| \cdots |A_s|.$$

6.2 Preliminaries

We recall the Cauchy-Schwarz inequality: for every $N \in \mathbb{N}$ and for every two vectors $(w_1, \ldots, w_N)$ and $(t_1, \ldots, t_N)$ in $\mathbb{C}^N$,

$$\left| \sum_{\ell \in [N]} w_\ell t_\ell \right|^2 \leq \left( \sum_{\ell \in [N]} |w_\ell|^2 \right) \left( \sum_{\ell \in [N]} |t_\ell|^2 \right).$$
In this proof we use the following notation. For a multilinear polynomial \( F \) in \( \mathbb{C}[X] \) and for a multilinear monomial \( m \) in the variables \( X \), we denote by \( F(m) \in \mathbb{C} \) the coefficient of \( m \) in \( F \). This may be misleading, as \( F \) is also a function, but we do so for simplicity of notation. We note that in this section we will think of a polynomial always as a vector of coefficients, and not as a function.

6.3 Proof of Theorem 1.7

Let \( f' \in \mathbb{C}[X] \) be a big multilinear polynomial. Thus, there exists a partition of \( X \) into two sets \( A \) and \( B \) (i.e., \( A \cup B = X \) and \( A \cap B = \emptyset \)) of size at least \( n/3 \) each, and two multilinear polynomials \( g \in \mathbb{C}[A] \) and \( h \in \mathbb{C}[B] \) such that

\[ f' = gh. \]

The proof continues as follows. We will identify two sets \( A_1 \subseteq A \) and \( B_1 \subseteq B \) that will enable us to use the exponential sum estimate of [BoGK] to bound the correlation between \( f \) and \( f' \). We will then give some notation, and finally we will bound the correlation between \( f \) and \( f' \).

6.3.1 Identifying \( A_1 \) and \( B_1 \)

For \( i \in [12s] \), set

\[ X(i) = \{ x_{(i-1)p+j} : j \in [p] \}, \]

and set

\[ A(i) = A \cap X(i) \text{ and } B(i) = B \cap X(i). \]

The following proposition will give \( A_1 \) and \( B_1 \) (see (6.1) and (6.2) below).

Proposition 6.2. There exists a set \( I \subseteq [12s] \) of size \( s \) such that for every \( i \in I \),

\[ |A(i)| \geq p/4. \]

Proof. Let \( I' \) be the set of \( i \in [12s] \) such that \( |A(i)| \geq p/4 \). Since \( |A| \geq n/3 \), we have

\[ 4sp \leq |A| \leq |I'| \cdot p + (12s - |I'|) \cdot p/4, \]

which implies \( |I'| > s \). Set \( I \) to be a subset of \( I' \) of size \( s \). \( \square \)

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Let $I \subseteq \{12s\}$ be the set given by Proposition 6.2, and let $J = \{12s\} \setminus I$. Set
\[
A_1 = \bigcup_{i \in I} A(i) \quad \text{and} \quad A_2 = A \setminus A_1,
\]
and set
\[
B_1 = \bigcup_{i \in J} B(i) \quad \text{and} \quad B_2 = B \setminus B_1.
\]
So, since $|B| \geq n/3$, since every $i \in I$ admits $|B(i)| \leq p$ and since $|I| = s$, we have
\[
|B_1| \geq |B| - sp \geq 3sp.
\]

### 6.3.2 Notation

For a set of variables $T \subseteq X$, we write $t$ (or $t'$) when $t$ (or $t'$) is a monic multilinear monomial in the variables $T$. For example, $b_1$ (or $b'_1$) is a monic multilinear monomial in the variables $B_1$. Recall that $f(m) \in \mathbb{C}$ is the coefficient of the monomial $m$ in $f$, and recall that for $i \in \{12s\}$, the field element $y_i = y_i(m) \in \mathbb{F}$ is defined as
\[
\forall j \in [p] \quad (y_i)_j = \text{the degree of } x_{p(i-1)+j} \text{ in } m.
\]

For a monomial $a_2$ over the set of variables $A_2$, and for two monomials $b_1$ and $b'_1$ over the set of variables $B_1$, we denote
\[
Z(a_2, b_1, b'_1) = \prod_{i \in J} y_i(a_2b_1) - \prod_{i \in J} y_i(a_2b'_1) \in \mathbb{F}.
\]

Denote by $S(a_2)$ the set of pairs $(b_1, b'_1)$ such that $Z(a_2, b_1, b'_1) = 0$. Denote
\[
S_1 = \left\{ a_2 : |S(a_2)| > 2^{2|B_1|-p/12} \right\},
\]
and denote
\[
S_2 = \left\{ a_2 : |S(a_2)| \leq 2^{2|B_1|-p/12} \right\}
\]
(the compliment set of $S_1$).
6.3.3 Bounding the Correlation Between $f$ and $f'$

Recall that
\[
\text{cor}(f, f') = \text{cor}(f, gh) = \left| \sum_{a_1, a_2, b_1, b_2} f(a_1 a_2 b_1 b_2) g(a_1 a_2) h(b_1 b_2) \right|,
\]
where the sum is over all monomials $a_1$ in the variables $A_1$, all monomials $a_2$ in the variables $A_2$, all monomials $b_1$ in the variables $B_1$ and all monomials $b_2$ in the variables $B_2$.

Denote
\[
C_1 = \left| \sum_{a_2 \in S_1} \sum_{a_1, b_1, b_2} f(a_1 a_2 b_1 b_2) g(a_1 a_2) h(b_1 b_2) \right|,
\]
and
\[
C_2 = \left| \sum_{a_2 \in S_2} \sum_{a_1, b_1, b_2} f(a_1 a_2 b_1 b_2) g(a_1 a_2) h(b_1 b_2) \right|.
\]

Therefore,
\[
\text{cor}(f, f') \leq C_1 + C_2.
\]

We bound the correlation between $f$ and $f'$ by bounding $C_1$ and $C_2$.

**Proposition 6.3.** There exists a constant $\beta_1 > 0$ such that
\[
C_1 \leq 2^{-\beta_1 p} \|f\| \|f'\|.
\]

**Proposition 6.4.** There exists a constant $\beta_2 > 0$ such that
\[
C_2 \leq 2^{-\beta_2 p} \|f\| \|f'\|.
\]

We defer the proof of Proposition 6.3 to Section 6.3.4, and the proof of Proposition 6.4 to Section 6.3.5.

Using Propositions 6.3 and 6.4, since $p = \Omega(n)$, we have
\[
\text{cor}(f, f') \leq 2^{-\Omega(n)} \|f\| \|f'\|,
\]
which completes the proof of Theorem 1.7.
6.3.4 Proof of Proposition 6.3

Recall that we want to bound from above

\[ C_1 = \left| \sum_{a_2 \in S_1} \sum_{a_1, b_1, b_2} f(a_1a_2b_1b_2)g(a_1a_2)h(b_1b_2) \right|, \]

where

\[ S_1 = \{ a_2 : |S(a_2)| > 2^{2|B_1|-p/12} \}. \]

First, we will bound the size of \( S_1 \) from above. We denote by \( S \) the set of triplets \((a_2, b_1, b'_1)\) such that \( Z(a_2, b_1, b'_1) = 0 \). To bound the size of \( S_1 \) we bound the size of \( S \).

**Claim 6.5.** For every large enough \( p \),

\[ |S| \leq 2^{2|B_1|+|A_2|-p/6}. \]

**Proof.** We will first bound the number of triplets \((a_2, b_1, b'_1)\) such that

\[ \prod_{i \in J} y_i(a_2b'_1) = 0. \quad (6.3) \]

Since

\[ A_2 \cup B_1 = \bigcup_{i \in J} X(i), \]

and since \(|J| = 11s\), all the monomials of the form \( a_2b'_1 \) are all the \( 2^{11s}p \) monomials in the variables \( \bigcup_{i \in J} X(i) \). Note that for every monomial \( a_2b'_1 \),

\[ \forall i \in J \ y_i(a_2b'_1) \neq 0 \iff \prod_{i \in J} y_i(a_2b'_1) \neq 0, \]

and that for every \( i \in J \), the number of pairs \((a_2, b'_1)\) for which \( y_i(a_2b'_1) = 0 \) is \( 2^{|B_1|+|A_2|-p} \). So, by the union bound, the number of pairs \((a_2, b'_1)\) for which (6.3) holds is at most

\[ |J|2^{|B_1|+|A_2|-p} = 11s2^{|B_1|+|A_2|-p}. \]

Hence, the number of triplets \((a_2, b_1, b'_1)\) for which (6.3) holds is at most

\[ 2^{|B_1|} \cdot 11s2^{|B_1|+|A_2|-p} = 11s2^{|B_1|+|A_2|-p}. \]

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We will now bound the number of triplets in $S$ for which (6.3) does not hold. Since $|B_1| \geq 3sp$, there exists $j \in J$ such that

$$|B(j)| \geq \frac{p}{4}.$$ 

The number of triplets in $S$ for which (6.3) does not hold is at most the number of triplets $(a_2, b_1, b'_1)$ in $S$ such that

$$y_j(a_2b'_1) = \prod_{i \in J} y_i(a_2b_1) \prod_{i \in J \setminus \{j\}} y_i(a_2b'_1)$$

(note that $\prod_{i \in J \setminus \{j\}} y_i(a_2b'_1)$ is non-zero). So, the number of triplets in $S$ for which (6.3) does not hold is at most

$$2^{2|B_1|+|A_2|-p/4}.$$ 

We conclude that, for large enough $p$,

$$|S| \leq 11s2^{2|B_1|+|A_2|-p} + 2^{2|B_1|+|A_2|-p/4} \leq 2^{2|B_1|+|A_2|-p/6}.$$

The following corollary bounds the size of $S_1$.

**Corollary 6.6.** For every large enough $p$, 

$$|S_1| \leq 2^{|A_2|}-p/12.$$

**Proof.** Using Claim 6.5, for every large enough $p$,

$$2^{2|B_1|+|A_2|-p/6} \geq |S| = \sum_{a_2} |S(a_2)| > |S_1| \cdot 2^{2|B_1|-p/12}.$$ 

So, for large enough $p$,

$$|S_1| \leq 2^{|A_2|}-p/12.$$ 

Back to the proof of Proposition 6.3. Recall that

$$C_1 = \left| \sum_{a_2 \in S_1} \sum_{a_1, b_1, b_2} f(a_1a_2b_1b_2)f'(a_1a_2b_1b_2) \right|.$$
By the Cauchy-Schwarz inequality,
\[
C_1 \leq \sqrt{\sum_{a_2 \in S_1} \sum_{a_1, b_1, b_2} |f(a_1 a_2 b_1 b_2)|^2} \sqrt{\sum_{a_2 \in S_1} \sum_{a_1, b_1, b_2} |f'(a_1 a_2 b_1 b_2)|^2}.
\]
Since the coefficients of \( f \) are in \( \{1, -1\} \) and since the sum is only over \( a_2 \in S_1 \),
\[
C_1 \leq \sqrt{|S_1| 2^{|A_1| + |B_1| + |B_2|} \|f'\|}.
\]
By Corollary 6.6, for every large enough \( p \),
\[
C_1 \leq 2^{|A_1| + |A_2| + |B_1| + |B_2|/2 - p/21} \|f'\|.
\]
Thus, since \( \|f\| = 2^{n/2} \) and since \( |A_1| + |A_2| + |B_1| + |B_2| = n \), there exists a constant \( \beta_1 > 0 \) such that
\[
C_1 \leq 2^{-\beta_1 p} \|f\| \|f'\|,
\]
which completes the proof of the proposition.

\[\square\]

6.3.5 Proof of Proposition 6.4

Recall that we want to bound from above
\[
C_2 = \left| \sum_{a_2 \in S_2} \sum_{a_1, b_1, b_2} f(a_1 a_2 b_1 b_2) g(a_1 a_2) h(b_1 b_2) \right|,
\]
where
\[
S_2 = \{ a_2 : |S(a_2)| \leq 2^{|B_1| - p/12} \}.
\]
We first prove the following claim.

Claim 6.7. There exists a constant \( \beta_3 > 0 \) such that for every multilinear monomial \( a_2 \) over the set of variables \( A_2 \), and for every multilinear monomial \( b_2 \) over the set of variables \( B_2 \),
\[
\sum_{b_1, b_2} \left| \sum_{a_1} f(a_1 a_2 b_1 b_2) \overline{f(a_1 a_2 b_1 b_2)} \right|^2 \leq 2^{|A_1|} \left( |S(a_2)| + 2^{|B_1| - \beta_3 p} \right).
\]
Proof. Let $a_2$ be a multilinear monomial over the set of variables $A_2$, and let $b_2$ be a multilinear monomial over the set of variables $B_2$. For every $i \in J$, we have that $y_i$ does not depend on the variables in either $A_1$ or $B_2$. Similarly, for every $i \in I$, we have that $y_i$ does not depend on the variables in either $A_2$ or $B_1$. Let $a_1$ be a multilinear monomial over the set of variables $A_1$, and let $b_1$ and $b_1'$ be two multilinear monomials over the set of variables $B_1$. Thus,

$$\prod_{i \in [2s]} y_i(a_1a_2b_1b_2) - \prod_{i \in [2s]} y_i(a_1a_2b'_1b_2) = \prod_{i \in I} y_i(a_1b_2) \prod_{i \in J} y_i(a_2b_1) - \prod_{i \in I} y_i(a_1b_2) \prod_{i \in J} y_i(a_2b'_1)$$

$$= \prod_{i \in I} y_i(a_1b_2) \left( \prod_{i \in J} y_i(a_2b_1) - \prod_{i \in J} y_i(a_2b'_1) \right)$$

$$= Z(a_2, b_1, b'_1) \prod_{i \in I} y_i(a_1b_2)$$

(by the definition of $Z(a_2, b_1, b'_1)$). Recall that

$$Z(a_2, b_1, b'_1) = 0 \iff (b_1, b'_1) \in S(a_2). \quad (6.4)$$

Thus, by the definition of $f$, since $\psi$ is an additive character of $\mathbb{F}$ (using (5.1)),

$$\left| \sum_{a_1} f(a_1a_2b_1b_2)f(a_1a_2b'_1b_2) \right| = \left| \sum_{a_1} \psi \left( Z(a_2, b_1, b'_1) \prod_{i \in I} y_i(a_1b_2) \right) \right|.$$

Denote by $i_1, \ldots, i_s$ the elements of $I$. For all $j \in [s]$, denote

$$A_1(j) = A_1 \cap X(i_j).$$

So, $A_1(1), \ldots, A_1(s)$ is a partition of $A_1$. In the following sums $a_1(j)$ is a monomial in the variables $A_1(j)$. By Proposition 6.2, for all $j \in [s],

$$|A_1(j)| \geq \frac{p}{4}.$$

Therefore, if $(b_1, b'_1) \not\in S(a_2)$, then, by (6.4) and by Theorem 6.1, there exists a constant $\alpha > 0$ such that

$$\left| \sum_{a_1} f(a_1a_2b_1b_2)f(a_1a_2b'_1b_2) \right| \leq \left| \sum_{a_{1(1)}, \ldots, a_{1(s)}} \psi \left( Z(a_2, b_1, b'_1) \prod_{i \in I} y_i(a_1b_2) \right) \right| < 2^{-\alpha p + |A_1(1)| + \ldots + |A_1(s)|} = 2^{-\alpha p + |A_1|}. \quad 33$$
Also if \((b_1, b_1') \in S(a_2)\), then
\[
\left| \sum_{a_1} f(a_1 a_2 b_1 b_2) f(a_1 a_2 b_1' b_2') \right| \leq 2^{|A_1|}.
\]
Therefore,
\[
\sum_{b_1, b_1'} \left| \sum_{a_1} f(a_1 a_2 b_1 b_2) f(a_1 a_2 b_1' b_2') \right|^2 \leq |S(a_2)| 2^{|A_1|} + 2^{2|B_1|} 2^{-2\alpha p + 2|A_1|}.
\]
So, there exists a constant \(\beta_3 > 0\) such that
\[
\sum_{b_1, b_1'} \left| \sum_{a_1} f(a_1 a_2 b_1 b_2) f(a_1 a_2 b_1' b_2') \right|^2 \leq 2^{|A_1|} \left( |S(a_2)| + 2^{2|B_1| - \beta_3 p} \right).
\]
\(\square\)

We will use the following corollary.

**Corollary 6.8.** There exists a constant \(\beta_4 > 0\) such that
\[
\sum_{a_2 \in S_2 \ b_2} \left| \sum_{a_1, b_1} f(a_1 a_2 b_1 b_2) g(a_1 a_2) h(b_1 b_2) \right|^2 \leq 2^{|A_1| + |B_1| - \beta_4 p} \|g\|^2 \|h\|^2.
\]

**Proof.** Denote
\[
R = \sum_{a_2 \in S_2 \ b_2} \left| \sum_{a_1, b_1} f(a_1 a_2 b_1 b_2) g(a_1 a_2) h(b_1 b_2) \right|^2.
\]
So,
\[
R = \sum_{a_2 \in S_2 \ b_2} \left| \sum_{a_1} g(a_1 a_2) \sum_{b_1} f(a_1 a_2 b_1 b_2) h(b_1 b_2) \right|^2.
\]
Using the Cauchy-Schwarz inequality,
\[
R \leq \sum_{a_2 \in S_2 \ b_2} \left( \sum_{a_1} |g(a_1 a_2)|^2 \right) \left( \sum_{a_1} \left| \sum_{b_1} f(a_1 a_2 b_1 b_2) h(b_1 b_2) \right|^2 \right)
\]
\[
= \sum_{a_2 \in S_2 \ b_2} \left( \sum_{a_1} |g(a_1 a_2)|^2 \right) \left( \sum_{b_1, b_1'} \sum_{a_1} f(a_1 a_2 b_1 b_2) f(a_1 a_2 b_1' b_2') h(b_1 b_2) h(b_1' b_2') \right)
\]
\[
= \sum_{a_2 \in S_2 \ b_2} \left( \sum_{a_1} |g(a_1 a_2)|^2 \right) \left( \sum_{b_1, b_1'} h(b_1 b_2) h(b_1' b_2') \sum_{a_1} f(a_1 a_2 b_1 b_2) f(a_1 a_2 b_1' b_2') \right).
\]
Again, using the Cauchy-Schwarz inequality,

\[ R \leq \sum_{a_2 \in S_2} \sum_{b_2} \left( \sum_{a_1} |g(a_1a_2)|^2 \right) \sqrt{\sum_{b_1,b_1'} |h(b_1b_2)h(b_1'b_2)|^2} \mathbf{\sqrt{\sum_{a_1} f(a_1a_2b_1b_2)f(a_1a_2b_1'b_2)^2}}. \]

So, using Claim 6.7,

\[ R \leq \sum_{a_2 \in S_2} \sum_{b_2} \left( \sum_{a_1} |g(a_1a_2)|^2 \right) \mathbf{\sqrt{\sum_{b_1} |h(b_1b_2)|^2} \sqrt{2^{2|A_1|} (|S(a_2)| + 2^{2|B_1| - \beta_4 p})}}. \]

So, by the definition of \( S_2 \), for large enough \( p \), there exists a constant \( \beta_4 > 0 \) such that

\[ R \leq \sum_{a_2 \in S_2} \sum_{b_2} \left( \sum_{a_1} |g(a_1a_2)|^2 \right) \left( \sum_{b_1} |h(b_1b_2)|^2 \right) \mathbf{\sqrt{2^{2|A_1|} (2^{2|B_1| - p/12} + 2^{2|B_1| - \beta_4 p})}} \]

\[ \leq 2^{2|A_1| + |B_1| - \beta_4 p} \|g\| \|h\|^2. \]

Back to the proof of Proposition 6.4. Recall that

\[ C_2 = \left| \sum_{a_2 \in S_2} \sum_{b_2} \sum_{a_1,b_1} f(a_1a_2b_1b_2)g(a_1a_2)h(b_1b_2) \right|. \]

So, using Corollary 6.8 and the Cauchy-Schwarz inequality,

\[ C_2 \leq \sqrt{\sum_{a_2 \in S_2} \sum_{b_2} \left( \sum_{a_1,b_1} f(a_1a_2b_1b_2)g(a_1a_2)h(b_1b_2) \right)^2} \leq 2^{2|A_1|/2 + |B_1|/2} |A_1|^{1/2 + |B_1|/2 - \beta_4 p/2} \|g\| \|h\|. \]

By Claim 2.2, we have \( \|f'\| = \|g\| \|h\| \). Thus, since \( \|f\| = 2^{n/2} \) and since \( |A_1| + |A_2| + |B_1| + |B_2| = n \), there exists a constant \( \beta_2 > 0 \) such that

\[ C_2 \leq 2^{-\beta_2 p} \|f\| \|f'\|, \]

which completes the proof of the proposition.
7 Monotone Arithmetic Circuits

In this section we prove Theorem 1.6 that gives a tight lower bound for the size of monotone arithmetic circuits.

7.1 The Structure of Monotone Circuits

In this section we prove the following lemma about the structure of monotone syntactically multilinear circuits.

Lemma 7.1. Let \( n \geq 3 \) be an integer. Let \( \Phi \) be a monotone syntactically multilinear arithmetic circuit with \( s \in \mathbb{N} \) edges over the field \( \mathbb{R} \) and over the set of variables \( X = \{x_1, \ldots, x_n\} \). Then, there exist \( s + 1 \) monotone big polynomials \( g_1, \ldots, g_{s+1} \in \mathbb{R}[X] \) such that

\[
\hat{\Phi} = \sum_{i \in [s+1]} g_i
\]

(the definition of a big polynomial is in Section 2.1).

Proof. The proof follows by induction on the number of edges in \( \Phi \).

Assume without loss of generality that \( \Phi \) has a unique output gate \( v \) computing \( \hat{\Phi} \).

Induction Base: The gate \( v \) is an input gate.

Since \( n \geq 3 \), the polynomial \( \hat{\Phi} \) is big. Thus, the lemma follows with \( g_1 = \hat{\Phi} \) (since \( s \geq 0 \)).

Induction Step: The gate \( v \) is not an input gate.

If \( |X_v| \leq 2n/3 \), then \( \hat{\Phi} \) is a big polynomial, and the lemma follows with \( g_1 = \hat{\Phi} \) (since \( s \geq 0 \)).

Assume that \( |X_v| > 2n/3 \). Every gate \( u \) in \( \Phi \) with children \( u_1 \) and \( u_2 \) admits \( |X_u| \leq |X_{u_1}| + |X_{u_2}| \). Thus, there exists a gate \( u \) in \( \Phi \) such that

\[
n/3 \leq |X_u| \leq 2n/3
\]

(\( u \) is the first gate that satisfies the above, going down in \( \Phi \) from \( v \), when each step is to the child with the maximal number of variables).
Let $\Psi$ be the circuit $\Phi$ after substituting a new variable $y$ instead of $u$. Since $\Phi$ is monotone and syntactically multilinear, there exists a monotone multilinear polynomial $h_1$ in the set of variables $X \setminus X_u$ such that

$$\hat{\Psi} = h_1 \cdot y + h_2,$$

where $h_2$ is the polynomial computed by $\Psi$ after substituting $y = 0$. By the definition of $\Psi$,

$$\hat{\Phi} = h_1 \cdot \hat{\Phi}_u + h_2.$$

Since $\hat{\Phi}_u$ is monotone and since $n/3 \leq |X_u| \leq 2n/3$, the polynomial $h_1 \cdot \hat{\Phi}_u$ is both monotone and big.

Denote by $\Psi_0$ the circuit $\Psi$ after substituting $y = 0$. The circuit $\Psi_0$ is a monotone syntactically multilinear circuit for $h_2$ and it has at most $s - 1$ edges. By induction, there are $s$ monotone big polynomials $g_1, \ldots, g_s \in \mathbb{R}[X]$ such that

$$h_2 = \sum_{i \in [s]} g_i.$$

Thus, setting $g_{s+1} = h_1 \cdot \hat{\Phi}_u$, the lemma follows.

\[ \square \]

### 7.2 Proof of Theorem 1.6

For a monomial $m$ in the variables $X$ and a polynomial $h \in \mathbb{R}[X]$, we denote (in this section) by $h(m)$ the coefficient of $m$ in $h$ (this may be misleading, as $h$ is also a function, but we do so for simplicity of notation.) Let $f$ be the polynomial defined in Section 5.2, and let $F$ be the polynomial defined as

$$F(m) = \frac{f(m) + 1}{2} \in \{0, 1\},$$

for every monomial $m$ in the variables $X$. Let $\Phi$ be a monotone arithmetic circuit over the field $\mathbb{R}$ and over the set of variables $X$ computing $F$. Since $\Phi$ is monotone, we can assume without loss of generality that $\Phi$ is also syntactically multilinear. By Lemma 7.1, since the in-degree of $\Phi$ is at most 2, there exist at most $s = 2|\Phi| + 1$ monotone big polynomials $g_1, \ldots, g_s \in \mathbb{R}[X]$ such that

$$F = \sum_{i \in [s]} g_i.$$

By the definition of $F$, since

$$\sum_m f(m) \geq 0,$$

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where the sum is over all multilinear monomials in the variables $X$, we have (recall that $|f(m)| = 1$),

$$
\langle F, f \rangle = \sum_{m} \frac{f(m) + 1}{2} f(m) = \sum_{m} \frac{1}{2} + \sum_{m} \frac{f(m)}{2} \geq 2^{n-1}.
$$

Since the polynomials $g_1, \ldots, g_s$ are monotone, for every monomial $m$ the following holds.

- If $f(m) = -1$ (which implies $F(m) = 0$), then $g_i(m) = 0$, for every $i \in [s]$.
- If $f(m) = 1$ (which implies $F(m) = 1$), then $0 \leq g_i(m) \leq 1$, for every $i \in [s]$.

Thus, for every $i \in [s]$, we have $\langle g_i, f \rangle \geq 0$ and $\|g_i\| \leq \|f\|$. Hence, since

$$
\sum_{i \in [s]} \langle g_i, f \rangle = \langle F, f \rangle \geq 2^{n-1},
$$

there exists $j \in [s]$ such that

$$
\langle g_j, f \rangle \geq 2^{n-1}/s.
$$

Since $g_j$ is big and since $\|g_j\| \leq \|f\|$, using Theorem 1.7,

$$
\langle g_j, f \rangle \leq 2^{-\Omega(n)} \|g_j\| \|f\| \leq 2^{-\Omega(n)} \|f\|^2 = 2^{-\Omega(n)} 2^n.
$$

So, since $s \leq 2|\Phi| + 1$,

$$
|\Phi| = 2^{\Omega(n)},
$$

and the theorem follows.

\[\Box\]

8 Mixed-2-Source Extractors

In this section we construct a mixed-2-source extractor.

8.1 The Extractor

Let $n = 12sp$ be an integer, where $p \in \mathbb{N}$ is prime and $s \in \mathbb{N}$ is the constant given in Theorem 6.1. Let $\beta_0$ be the constant in the $\Omega(\cdot)$ in Corollary 1.8 and set

$$
\beta = \beta_0/8
$$

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Let \( m = \lfloor \beta \cdot n \rfloor \) and \( k = n - 3m \).

Recall that \( m \) is the length of the output of the extractor and that \( k \) is the min-entropy requirement.

We think of \( \{0, 1\}^p \) as the field \( \mathbb{F} \) of size 2\(^p\) (see Section 5.1.1). For \( t \in \{0, 1\}^n \) and \( i \in [12s] \), define \( y_i = y_i(t) \in \mathbb{F} \) as

\[
\forall \ j \in [p] \quad (y_i)_j = t_{p(i-1)+j}.
\]

Define the map \( F \) from \( \{0, 1\}^n \) to \( \mathbb{F} \) by

\[
F(t) = F(y_1, \ldots, y_{12s}) = y_1 \cdot y_2 \cdots y_{12s}.
\]

The extractor \( \text{Ext} : \{0, 1\}^n \to \{0, 1\}^m \) is defined as the \( m \) most significant bits of \( F(\cdot) \). That is,

\[
\text{Ext}(t) = (F_1(t), \ldots, F_m(t)),
\]

where \( F_i(\cdot) \) is the \( i \)th coordinate of \( F(\cdot) \), for every \( i \in [m] \). Note that \( \text{Ext}(\cdot) \) can be computed in deterministic polynomial time. Also note that \( m \) and \( k \) are as required by Theorem 1.10.

### 8.2 Proof of Theorem 1.10

The proof of the theorem follows by an argument known as Vazirani’s XOR lemma.

Let \( \mu_1 \) and \( \mu_2 \) be two independent distributions on \( \{0, 1\}^{n/2} \) (recall that \( n \) is even) such that

\[
H_\infty(\mu_1) = k_1 \quad H_\infty(\mu_2) = k_2 \quad \text{and} \quad k_1 + k_2 \geq k.
\]

Assume without loss of generality that \( \mu_1 \) is a uniform distribution on a set \( A_1 \subseteq \{0, 1\}^{n/2} \), that \( \mu_2 \) is a uniform distribution on a set \( A_2 \subseteq \{0, 1\}^{n/2} \), and that

\[
|A_1| \cdot |A_2| \geq (2^{k_1} - 1)(2^{k_2} - 1) \geq 2^{k-1},
\]

where the last inequality follows since both \( k_1 \) and \( k_2 \) are at most \( n/2 \) and since \( 6m + 4 \leq n \) (\( \mu_1 \) and \( \mu_2 \) can be written as a convex combination of such distributions - see Remark 8.1 below).

**Remark 8.1.** The set of distributions with min-entropy \( k' \) form a convex body. Thus, every distribution with min-entropy \( k' \) can be written as a convex combination of the extreme points of this body. In addition, if \( 2^{k'} \) is an integer, then the extreme points of this body are exactly the distributions that are uniform on a set of size \( 2^{k'} \).
Let \( t_1 \sim \mu_1 \) and let \( t_2 \sim \mu_2 \). Thus, \( t_1 \) is a uniform element of \( A_1 \) and \( t_2 \) is a uniform element of \( A_2 \). Let \( \pi \) be a one-to-one map from \([n] \) to \([n] \), and denote \( t = (t_1 \circ t_2)_\pi \). Thus, \( t \) is the input for the extractor.

Denote by \( W \) the random variable \( \text{Ext}(t) \). To prove Theorem 1.10 we need to show that \( W \) is close to uniform; i.e.,

\[
\|W - U_m\|_1 \leq 2^{-2m}
\]

\((W \) means the distribution on \([0,1]^m \) defined by \( W \)). The proof has three main steps. The first step is to show that every XOR of the bits of \( W \) is almost uniform. The second step is to use Parseval’s equality and conclude that the distance in 2-norm of \( W \) from uniform is small. The third step is to use Cauchy-Schwarz inequality to conclude that the statistical distance of \( W \) from uniform is small.

### 8.2.1 Every XOR of the Bits of \( W \) Is Almost Uniform

We will denote by \( W_S \) the XOR of all the entries of \( W \) that are in \( S \). Formally, for \( S \subseteq [m] \), denote

\[
F_S = \bigoplus_{i \in S} F_i,
\]

and denote

\[
W_S = F_S(t),
\]

where \( t = (t_1 \circ t_2)_\pi \), \( t_1 \sim \mu_1 \) and \( t_2 \sim \mu_2 \).

In this section we will prove that for every nonempty \( S \subseteq [m] \),

\[
\|W_S - U_1\|_1 \leq 2^{-3m}
\]

\((W_S \) means the distribution on \([0,1]^m \) defined by \( W_S \)). The proof will follow using the small maximal-partition discrepancy of \( f \) (see Section 1.2 for definitions).

The map \( \pi \) defines a partition of \([n] \) to two sets \( \pi^{-1}([1, \ldots, n/2]) \) and \( \pi^{-1}([n/2 + 1, \ldots, n]) \). This partition defines a \( 2^{n/2} \times 2^{n/2} \) matrix \( M \) whose \((r_1, r_2)\) entry is \( F_S((r_1 \circ r_2)_\pi) \), where \( r_1, r_2 \in \{0,1\}^{n/2} \).

Recall that \( f(\cdot) \) is defined as \( \psi(F(\cdot)) \), for an arbitrary non-trivial character \( \psi \), and note that \((-1)^{F_S(\cdot)} = \psi(F(\cdot)) \), where \( \psi(\cdot) \) is a non-trivial character of \( \mathbb{F} \). Thus, Corollary 1.8 in fact shows that the maximal-partition discrepancy of \( F_S \) is at most \( 2^{-\beta n} \), which implies that

\[
\text{Disc}(M) \leq 2^{-\beta n}.
\]
The sets $A_1$ and $A_2$ define a rectangle $R$ in $M$. The random variable $W_S$ is a uniform element of $R$. Thus,
\[
\|W_S - U_1\|_1 = \frac{2^n}{|A_1||A_2|} \text{DISC}_R(M) \leq 2^{n-(k-1) - \beta_0 n} \leq 2^{-3m},
\]
as claimed (where the last inequality follows since $6m + 1 \leq \beta_0 n$).

### 8.2.2 Distance of Ext from $U_m$ in 2-Norm is Small

By Parseval’s equality and by (8.1),
\[
\sum_{g \in \{0,1\}^m} (\Pr[W = g] - U_m(g))^2 = 2^{-m} \sum_{S \subseteq [m]:S \neq \emptyset} (\|W_S - U_1\|_1)^2 \leq 2^{-6m} \tag{8.2}
\]
(the following remark gives additional details, for completeness).

**Remark 8.2.** We recall some definitions regarding Fourier transform. We think of $G \defeq \{0,1\}^m$ as an abelian group (with addition of vectors over GF(2)). For every $S \subseteq [m]$, the map $\psi_S$ from $G$ to $\mathbb{C}$ defined as
\[
\forall g = (g_1, \ldots, g_m) \in G \quad \psi_S(g) = (-1)^{\sum_{i \in S} g_i}
\]
is a character of $G$. The set of characters of $G$, $\{\psi_S\}_{S \subseteq [m]}$, form an orthonormal basis for the vector space of maps from $G$ to $\mathbb{C}$ with respect to the inner product
\[
\langle \chi, \chi' \rangle = 2^{-m} \sum_{g \in G} \chi(g) \cdot \overline{\chi'(g)},
\]
where $\chi$ and $\chi'$ are maps from $G$ to $\mathbb{C}$. Thus, every map $\chi : G \to \mathbb{C}$ can be written as
\[
\chi = \sum_{S \subseteq [m]} \hat{\chi}(S) \cdot \psi_S,
\]
where
\[
\hat{\chi}(S) = \langle \chi, \psi_S \rangle
\]
(the map $\hat{\chi}(\cdot)$ is called the Fourier transform of $\chi$), and we have Parseval’s equality:
\[
\sum_{g \in G} |\chi(g)|^2 = 2^m \sum_{S \subseteq [m]} |\hat{\chi}(S)|^2.
\]
Denote by $U \overset{\text{def}}{=} U_m$ the uniform distribution on $G$. Since $U = 2^{-m} \cdot \psi_{\emptyset}$, for every $S \subseteq [m],$

$$\hat{U}(S) = \begin{cases} 
0 & S \neq \emptyset \\
2^{-m} & S = \emptyset 
\end{cases}$$

By Parseval’s equality,

$$\sum_{g \in G} (\Pr[W = g] - U(g))^2 = \sum_{g \in G} (|P - U|(g))^2 = 2^m \sum_{S \subseteq [m]} (|\hat{P} - \hat{U}|(S))^2,$$

where $P(g) = \Pr[W = g]$. Note that

$$\hat{P}(\emptyset) = 2^{-m}$$

and that

$$\hat{P}(S) = 2^{-m} \mathbb{E}[(-1)^{W_S}] = 2^{-m} \|W_S - U_1\|_1,$$

for every non-empty $S \subseteq [m]$. Thus, by linearity of Fourier transform,

$$\sum_{g \in G} (\Pr[W = g] - U(g))^2 = 2^m \sum_{S \subseteq [m]: S \neq \emptyset} (\hat{P}(S))^2 = 2^{-m} \sum_{S \subseteq [m]: S \neq \emptyset} (\|W_S - U_1\|_1)^2.$$

### 8.2.3 Completing the Proof

By Cauchy-Schwarz inequality, using (8.2),

$$\left( \sum_{g \in \{0,1\}^m} |\Pr[W = g] - U_m(g)| \right)^2 \leq 2^m \sum_{g \in \{0,1\}^m} (\Pr[W = g] - U_m(g))^2 \leq 2^{-5m}.$$ 

Thus,

$$\|W - U_m\|_1 \leq 2^{-2m},$$

which completes the proof.

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References


