# ENTROPY OF OPERATORS OR WHY MATRIX MULTIPLICATION IS HARD FOR DEPTH-TWO CIRCUITS 

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#### Abstract

We consider unbounded fanin depth-2 circuits with arbitrary boolean functions as gates. We define the entropy of an operator $f:\{0,1\}^{n} \rightarrow\{0,1\}^{m}$ as the logarithm of the maximum number of vectors distinguishable by at least one special subfunction of $f$.

Our main result is that every depth- 2 circuit for $f$ requires at least entropy $(f)$ wires. This gives an information-theoretic explanation of why some operators require many wires We use this to prove a tight estimate $\Theta\left(n^{3}\right)$ of the smallest number of wires in any depth-2 circuit computing the product of two $n$ by $n$ matrices over any finite field. Previously known lower bound for this operator was $\Omega\left(n^{2} \log n\right)$.


## 1. Introduction

One of the challenges in circuit complexity is to prove a nonlinear lower bound for logdepth circuits computing an explicitly given boolean operator $f:\{0,1\}^{n} \rightarrow\{0,1\}^{n}$. This corresponds to simultaneous computation of the sequence of boolean functions $f_{j}:\{0,1\}^{n} \rightarrow$ $\{0,1\}$, where $f_{j}(\mathbf{x})$ is the $j$-th coordinate of the vector $f(\mathbf{x})$. An important result of Valiant [20] reduces this problem to proving a lower bound $\Omega\left(n^{1+\epsilon}\right)$ on the number of wires in a depth2 circuit computing a linear operator $y=A \mathrm{x}$ over $G F_{2}$, where we allow arbitrary boolean functions as gates. Note that in this case the phenomenon which causes complexity of circuits is information transfer instead of information processing in the case of single functions. It is therefore important to understand what properties of operators do force high information transfer in their depth-2 circuits.

A depth-2 circuit for $f:\{0,1\}^{n} \rightarrow\{0,1\}^{m}$ is a directed acyclic graph with $n$ input nodes $x_{1}, \ldots, x_{n}$, and $m$ output nodes $z_{1}, \ldots, z_{m}$. Every noninput node computes an arbitrary boolean function of its inputs, and there is no bound on the fanin or on the fanout. The size of a circuit is the total number of wires in it. Without loss of generality, we may assume that there are no direct wires from inputs to outputs: this can be easily achieved by adding at most $n$ new wires.

Let $s_{2}(f)$ denote the minimum size of a depth- 2 circuit computing $f$. Note that $s_{2}(f) \leq n^{2}$ for every operator $f:\{0,1\}^{n} \rightarrow\{0,1\}^{n}$.

Superlinear lower bounds of the form $s_{2}(f)=\Omega(n \log n)$ were obtained using graphtheoretic arguments by analyzing some superconcentration properties of the circuit as a graph $[6,9,12,11,15]$. Unfortunately, the approach based on superconcentrators cannot lead to

[^0]lower bounds for depth -2 circuits larger than $\Omega\left(n \log ^{2} n\right)$, since there are depth- 2 superconcentrators with $O\left(n \log ^{2} n\right)$ [10], and even $O\left(n \log ^{2} n / \log \log n\right)$ [14] edges.

The (numerical) limitation of the graph-theoretic lower bounds comes from their power: they show much more than that the number of wires must be large - they also provide an information about the structure of the underlying graphs. It is therefore natural to expect to prove larger lower bounds, if we only care about the number of wires in a circuit, not about its structure. Such a direct approach has already led Cherukhin [5] to the highest known lower bound $s_{2}(f)=\Omega\left(n^{3 / 2}\right)$ for an explicit boolean operator $f$-cyclic convolution computing $n$ special bilinear forms $\mathbf{x}^{\top} A \mathbf{y}$ over $G F_{2}$. (Recall that such a bound for a linear operator $A \mathbf{x}$ would already imply nonlinear lower bound for log-depth circuits.)

In this paper we prove a general lower bound $s_{2}(f) \geq$ entropy $(f)$, where the entropy of $f:\{0,1\}^{n} \rightarrow\{0,1\}^{m}$ is just the logarithm of the maximum number of vectors distinguishable by at least one special subfunction of $f$. This gives a simple explanation of what operators and, more importantly, why require many wires. The bound itself is reminiscent of a classical lower bound of Nechiporuk [8] on the formula size of a boolean function as the logarithm of the number of its subfunctions.

Since entropy $(f)$ is relatively easy to compute, this gives us a handy tool to prove large lower bounds for a whole string of explicit operators. We demonstrate this by a tight estimate $\Theta\left(n^{3}\right)$ of the smallest number of wires in any depth- 2 circuit computing the product of two $n$ by $n$ matrices over any finite field. This improves the highest previously known lower bound $s_{2}(f)=\Omega\left(n^{2} \log n\right)$ for this operator derived in [15] using a technical lemma from [11] and graph-theoretic arguments.

## 2. Results

In this section we first introduce the notion of entropy of operators, and state some its basic properties. Then we prove our main result-a general lower bound on the number of wires in depth-2 circuits in terms of the entropy (Lemma 3 and Theorem 4).
2.1. Entropy of function sets. Let $F=\left\{f_{1}, \ldots, f_{m}\right\}$ be a set of functions $f_{j}:\{0,1\}^{n} \rightarrow$ $\{0,1\}$ on the same set of variables $x_{1}, \ldots, x_{n}$. Say that a set of vectors $A \subseteq\{0,1\}^{n}$ is separated by $F$, if for every pair of vectors $a \neq b \in A$ there is a function $f \in F$ with $f(a) \neq f(b)$, that is, if the corresponding to $F$ operator in injective on $A$. Define

$$
\operatorname{entropy}(F)=\max \left\{\log _{2}|A|: A \subseteq\{0,1\}^{n} \text { and } F \text { separates } A\right\}
$$

Say that a function $f$ can be computed from a set of functions $G$ if there exists a boolean function $\varphi$ such that $f=\varphi\left(g_{1}, \ldots, g_{k}\right)$ for some functions $g_{1}, \ldots, g_{k}$ in $G$. We write $F \leq G$ if every function in $F$ can be computed from the functions in $G$. Note that, in any circuit with arbitrary boolean functions as gates, every function is computed from the set of functions computed at its inputs. In particular, every set of functions $F$ on variables $x_{1}, \ldots, x_{n}$ is computatble from $G=\left\{x_{1}, \ldots, x_{n}\right\}$.

Proposition 1. Let $F$ and $G$ be some finite sets of boolean functions in $n$ variables.
(i) Upper bound: $\operatorname{entropy}(F) \leq \min \{n,|F|\}$.
(ii) Lower bound: if $F$ contains $r$ single variables, then entropy $(F) \geq r$.
(iii) Main connection: if $F \leq G$ then entropy $(F) \leq \operatorname{entropy}(G) \leq|G|$.

Proof. (i) The set $F=\left\{f_{1}, \ldots, f_{m}\right\}$ defines a natural encoding of vectors $a \in\{0,1\}^{n}$ by vectors $F(a)=\left(f_{1}(a), \ldots, f_{m}(a)\right)$ in $\{0,1\}^{m}$. If a set $A \subseteq\{0,1\}^{n}$ is separated by $F$, then
each vector in $A$ must receive its own code, implying that $|A| \leq 2^{m}=2^{|F|}$, and hence, $\log _{2}|A| \leq|F|$.
(ii) Suppose that $F$ contains $r$ single variables $x_{1}, \ldots, x_{r}$. Let $A \subseteq\{0,1\}^{n}$ be an arbitrary set of $|A|=2^{r}$ vectors having the same values on all remaining $n-r$ variables. Since any pair of vectors $a \neq b \in A$ must differ in at least one of the first $r$ coordinates, each such pair is separated by at least one of the variables $x_{1}, \ldots, x_{r}$.
(iii) Just observe that then $G(a)=G(b)$ implies $F(a)=F(b)$. Hence, any set separated by $F$ must be also separated by $G$, implying that entropy $(F) \leq$ entropy $(G) \leq|G|$, where the last inequality follows from (i).
2.2. Entropy of subfunctions and the number of wires. Let $F$ and $G$ be two sets of boolean functions. We can think of $F$ as a set of functions computed by some circuit at its output nodes, and $G$ as a set of functions computed at some intermediate nodes. Fix some set $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)$ of variables, and call them main variables. Let $\mathbf{y}=\left(y_{1}, \ldots, y_{r}\right)$ be the set of the remaining auxiliary variables.

We say that a main variable $x_{i}$ is critical for a function $g(\mathbf{x}, \mathbf{y})$ if $g\left(\mathbf{e}_{i}, \mathbf{y}\right) \neq g(\mathbf{0}, \mathbf{y})$, where $\mathbf{e}_{i}=(0, \ldots, 0,1,0, \ldots, 0)$ is the vector of length $n$ with precisely one 1 in the $i$-th coordinate.

Given a subset $X \subseteq\left\{x_{1}, \ldots, x_{n}\right\}$ of main variables, let $X(g)$ denote the set of all variables $x_{i} \in X$ which are critical for $g$. The number of variables in $X(g)$ is the weight of $g$ with respect to the set of variables $X$. The weight of a set $G$ of functions, denoted by weight ${ }_{X}(G)$, is the sum of weights of all its functions. We will see soon (Lemma 3) that, in depth- 2 circuits, weight $_{X}(G)$ lower bounds to the number of wires leaving the inputs in $X$.

Remark. Recall that a function $g(\mathbf{x}, \mathbf{y})$ depends on a variable $x_{i}$ if $g\left(\mathbf{a} \oplus \mathbf{e}_{i}, \mathbf{y}\right) \neq g(\mathbf{a}, \mathbf{y})$ for at least one vector $\mathbf{a} \in\{0,1\}^{n}$. Hence, in general, the number $|X(g)|$ of variables in $X$ that are critical for $g$ may be much smaller than the total number of variables in $X$ on which the function $g$ depends. If, for example, $g(\mathbf{x}, \mathbf{y})=x_{1} x_{2} \oplus y$ and $X=\left\{x_{1}, x_{2}\right\}$, then $g(1,0,1)=g(0,1,1)=1 \neq 0=g(1,1,1)$, implying that $g$ depends on both variables $x_{1}$ and $x_{2}$. But $g(1,0, y)=g(0,1, y)=g(0,0, y)=y$ implies that $X(g)=\emptyset$.

If every function in $F$ can be computed from the functions in $G$, then Proposition 1(iii) implies $|G| \geq$ entropy $(F)$. To get a similar (entropic) lower bound on weight ${ }_{X}(G)$ we consider the following set $F_{X}$ of subfunctions of the functions in $F$.

We define the set $F_{X}$ of subfunctions of $F$ with respect to $X$ to be the set of all boolean functions in variables $Y$ that can be obtained from some function $f \in F$ by setting some variable $x_{i} \in X$ to 1 and all the remaining main variables to 0 . That is,

$$
F_{X}=\left\{f\left(\mathbf{e}_{i}, \mathbf{y}\right): f \in F, x_{i} \in X\right\}
$$

Note that $F_{X}$ may contain up to $|X| \cdot|F|$ different functions.
Lemma 2 (Entropy and weight). If every function in $F$ can be computed from the functions in $G$, then

$$
\operatorname{weight}_{X}(G) \geq \operatorname{entropy}\left(F_{X}\right)-|G| .
$$

Proof. Since the functions in $F$ can be computed from the functions in $G$, the subfunctions in $F_{X}$ can be computed from the subfunctions in $G_{X}$, as well. By Proposition 1(iii), we have entropy $\left(F_{X}\right) \leq \operatorname{entropy}\left(G_{X}\right)$. By Proposition 1(i), it remains to show that $\left|G_{X}\right| \leq$ weight $_{X}(G)+|G|$.

To show this, recall that $G_{X}$ consists of all boolean functions $g\left(\mathbf{e}_{i}, \mathbf{y}\right)$ obtained from some function $g \in G$ by setting some variable $x_{i} \in X$ to 1 and the remaining main variables to 0 . If
$x_{i} \notin X(g)$, then $g\left(\mathbf{e}_{i}, \mathbf{y}\right)=g(\mathbf{0}, \mathbf{y})$. Hence, for each $g \in G$, the set $\left\{g\left(\mathbf{e}_{i}, \mathbf{y}\right): x_{i} \in X\right\}$ consist of at most $|X(g)|$ functions $g\left(\mathbf{e}_{i}, \mathbf{y}\right)$ with $x_{i} \in X(g)$ and just one additional function $g(\mathbf{0}, \mathbf{y})$. Summing over all $g \in G$, we obtain that $\left|G_{X}\right| \leq|G|+\sum_{g \in G}|X(g)|=|G|+$ weight $_{X}(G)$.

Let now $f=\left(f_{1}, \ldots, f_{m}\right)$ be an operator and $F \subseteq\left\{f_{1}, \ldots, f_{m}\right\}$. Let also $X \subseteq\left\{x_{1}, \ldots, x_{n}\right\}$ be a subset of main variables. Lemma 2 yields the following basic relation between the entropy and the number of wires.

Lemma 3 (Entropy and depth-2 complexity). In any depth-2 circuit computing $f$, the number of wires leaving the inputs in $X$ or entering the outputs in $F$ must be at least entropy $\left(F_{X}\right)$.

Proof. Let $M$ be the set of all nodes on the middle layer joined by a wire with at least one output in $F$. Then $F$ must be computable from the set $G=\left\{g_{v}: v \in M\right\}$ of boolean functions computed at the nodes $v \in M$. Since we have $|M| \geq|G|$ wires entering the outputs in $J$, it remains, by Lemma 3, to show that at least weight ${ }_{X}(G)$ wires must leave the inputs in $X$.

Each node $v \in M$ must be connected by a wire with each input $x_{i} \in X$ of which the function $g_{v}$ depends. Hence, at least $\left|X\left(g_{v}\right)\right|$ wires must go from $X$ to the node $v$. Since no wire can go to more than one node, the total number of wires from $X$ to $M$ must be at least $\sum_{v \in M}\left|X\left(g_{v}\right)\right|=$ weight $_{X}(G)$.

Define the entropy of an $(n, m)$-operator $f=\left(f_{1}, \ldots, f_{m}\right)$ as

$$
\begin{equation*}
\operatorname{entropy}(f)=\max \sum_{t=1}^{p} \operatorname{entropy}\left(\left\{f_{j}\left(\mathbf{e}_{i}, \mathbf{y}\right): i \in I_{t}, j \in J_{t}\right\}\right) \tag{2.1}
\end{equation*}
$$

where the maximum is over all partitions $I_{1}, \ldots, I_{p}$ of inputs $[n]$ and all partitions $J_{1}, \ldots, J_{p}$ of outputs $[m]$. Since the total number of wires in a depth- 2 circuit is just the number of wires incident to its input or output nodes, Lemma 2 directly yields the following

Theorem 4. For every operator $f$, we have $s_{2}(f) \geq \operatorname{entropy}(f)$.
Remark. Theorem 4 can be readily extended to sequences of functions $f: D^{n} \rightarrow D$ for any finite set $D$. For this, it is enough to take the logarithm to the basis $|D|$ in Definition ?? of the entropy. The rest is the same.

Remark. Taking partitions of inputs and outputs in the definition of entropy $(f)$ is not crucial. For each natural number $k$, we can define entropy $_{k}(f)$ as the maximum (2.1) over all subsets $I_{1}, \ldots, I_{p}$ of inputs and all subsets $J_{1}, \ldots, J_{p}$ of outputs such that no element belongs to more than $k$ of these sets. Hence, taking partitions corresponds to $k=1$. Now, if $d(i)$ is the number of wires leaving the input $i$, then the sum

$$
\sum_{t=1}^{p} \sum_{i \in I_{t}} d(i)=\sum_{i=1}^{n} \sum_{t: i \in I_{t}} d(i) \leq k \sum_{i=1}^{n} d(i)
$$

is at most $k$ times larger than the total number $\sum_{i=1}^{n} d(i)$ of wires leaving the inputs. Since the same also holds for the number of wires entering the output nodes, Lemma 2 implies

$$
s_{2}(f) \geq \max _{k \geq 1} \frac{1}{k} \cdot \operatorname{entropy}_{k}(f)
$$

## 3. Application: matrix multiplication

Theorem 4 allows one to show that $s_{2}(f)$ must be super-linear for many operators $f=$ $\left(f_{1}, \ldots, f_{m}\right)$ on two sets of variables $X$ and $Y$. For this, it is enough that we can split the set $F=\left\{f_{1}, \ldots, f_{m}\right\}$ of functions computed by this operator into some number $p$ of disjoint sets $F_{1}, \ldots, F_{p}$ such that, for some partition $X_{1}, \ldots, X_{p}$ of the variables in $X$, and for each $t=1, \ldots, p$, we can obtain each single variable $y \in Y$ by taking some function $f \in F_{t}$ and fixing one its variable $x \in X_{t}$ to 1 and the rest of $X$ to 0 . (We say in this case that $f$ isolates the variable $y$.) Then, by Proposition 1(ii), the set of subfunctions in each $F_{t}$ with respect to the corresponding set of variables $X_{t}$ must have entropy at least $|Y|$. By Theorem 4 , we then have $s_{2}(f) \geq p|Y|$.

One of the most natural functions isolating all its single variables is a scalar product function $f(\mathbf{x}, \mathbf{y})=x_{1} y_{1}+x_{2} y_{2}+\cdots+x_{r} y_{r}$; then $f\left(\mathbf{e}_{i}, \mathbf{y}\right)=y_{i}$ for all $i=1, \ldots, r$. Hence, natural examples of operators of large entropy are sequences of particular scalar products. Many operators computing sequences of bilinear functions, including that of cyclic $n$-convolution considered in [5], fall in this general (scalar product) frame. We illustrate this with one important example - matrix product.

Given two $r \times r$ boolean matrices $X=\left(x_{i, j}\right)$ and $Y=\left(y_{i, j}\right)$ over a finite field $\mathbb{F}$, our goal is to compute their product $Z=X \cdot Y$ over $\mathbb{F}$. The corresponding operator $f=\operatorname{mult}_{n}(X, Y)$ has $n=2 r^{2}$ input variables, arranged in two matrices, and consists of $n=r^{2}$ scalar products $f_{i, j}=\sum_{k=1}^{r} x_{i, k} y_{k, j}$ corresponding to the entries of the product matrix $Z=\left(z_{i, j}\right)$. (This time indexes of variables as well as of computed functions are pairs of numbers.)

Since mult $_{n}$ is just a sequence of $r^{2}$ scalar products on $2 r$ variables, $(2 r) r^{2}=2 n^{3 / 2}$ is a trivial upper bound, even in depth-1. If we put no restrictions on the depth, then Strassen's algorithm [19], improved in [2], gives a circuit of size $O\left(n^{6 / 5}\right)$. The only know lower bound in the unrestricted case, however, is the lower bound $2.5 \cdot n$ proved in [4]. A lower bound $s_{2}\left(\right.$ mult $\left._{n}\right)=\Omega(n \log n)$ for depth- 2 , as well as nonlinear lower bounds for any constant depth, were proved in [15] using superconcentrators. For depth-2, entropy arguments yield a tight estimate $s_{2}\left(\right.$ mult $\left._{n}\right)=\Theta\left(n^{3 / 2}\right)$.

Lemma 5. entropy $\left(\right.$ mult $\left._{n}\right) \geq n^{3 / 2}$.
Proof. Let $f=$ mult $_{n}$, and let $\mathbf{e}_{i, k}$ be the boolean $r \times r$ matrix with precisely one 1 in the position $(i, k)$. Since $f_{i, j}=\sum_{k=1}^{r} x_{i, k} y_{k, j}$, we have that $f_{i, j}\left(\mathbf{e}_{i, k}, Y\right)=y_{k, j}$ for all $j=1, \ldots, r$. That is, for each $i, k \in[r]$, the $i$-th row $f_{i, 1}\left(\mathbf{e}_{i, k}, Y\right), \ldots, f_{i, r}\left(\mathbf{e}_{i, k}, Y\right)$ of the product matrix $\mathbf{e}_{i, k} \cdot Y$ is just the $k$-th row $y_{k, 1}, \ldots, y_{k, r}$ of $Y$.

Hence, if we take $X_{i}=\left\{x_{i, 1}, \ldots, x_{i, r}\right\}$ (the $i$-th row of $X$ ) and $F_{i}=\left\{f_{i, 1}, \ldots, f_{i, r}\right\}$ (the $i$-th row of the product matrix), then the corresponding set of subfunctions of $F_{i}$ with respect to the variables in $X_{i}$,

$$
\left\{\begin{array}{cccc}
f_{i, 1}\left(\mathbf{e}_{i, 1}, Y\right) & f_{i, 2}\left(\mathbf{e}_{i, 1}, Y\right) & \cdots & f_{i, r}\left(\mathbf{e}_{i, 1}, Y\right) \\
f_{i, 1}\left(\mathbf{e}_{i, 2}, Y\right) & f_{i, 2}\left(\mathbf{e}_{i, 2}, Y\right) & \cdots & f_{i, r}\left(\mathbf{e}_{i, 2}, Y\right) \\
\vdots & \vdots & & \vdots \\
f_{i, 1}\left(\mathbf{e}_{i, r}, Y\right) & f_{i, 2}\left(\mathbf{e}_{i, r}, Y\right) & \cdots & f_{i, r}\left(\mathbf{e}_{i, r}, Y\right)
\end{array}\right\}=\left\{\begin{array}{cccc}
y_{1,1} & y_{1,2} & \cdots & y_{1, r} \\
y_{2,1} & y_{2,2} & \cdots & y_{2, r} \\
\vdots & \vdots & & \vdots \\
y_{r, 1} & y_{r, 2} & \cdots & y_{r, r}
\end{array}\right\}
$$

contains all $r^{2}=n$ variables of $Y$. Together with Proposition 1(ii), this implies that, for each $i=1, \ldots, r$, the entropy of $F_{i}$ with respect to $X_{i}$ is at least $n$. By Theorem 4 , entropy $(f) \geq$ $r n=n^{3 / 2}$.

Remark (Limitations). How large can entropy of operators be? Recall that in the definition of entropy $(f)$ of an $(n, m)$-operator $f$, we first split the inputs into $p$ blocks $I_{1}, \ldots, I_{p}$ of some sizes $a_{1} \leq a_{2} \leq \ldots \leq a_{p}$, and the outputs into $p$ blocks $J_{1}, \ldots, J_{p}$ of some sizes $b_{1}, \ldots b_{p}$. Then we just take the sum of the entropies of the corresponding (to these blocks) sets of subfunctions. Say that a partition is balanced if $b_{1} \geq b_{2} \geq \ldots \geq b_{p}$. Note that the partition (into the rows) which we used for the matrix product is balanced - there all $b_{i}$ 's were even equal.

Since each of the sets $\left\{f_{j}\left(\mathbf{e}_{i}, \mathbf{y}\right): i \in I_{t}, j \in J_{t}\right\}$ can have at most $\left|I_{i} \times J_{i}\right|=a_{i} b_{i}$ functions, Proposition 1(i) implies that the entropy of this set cannot exceed $a_{i} b_{i}$. If the partition is balanced, then Chebyshev's inequality yields

$$
\operatorname{entropy}(f) \leq \sum_{i=1}^{p} a_{i} b_{i} \leq \frac{1}{p}\left(\sum_{i=1}^{p} a_{i}\right)\left(\sum_{i=1}^{p} b_{i}\right) \leq \frac{n m}{p} .
$$

On the other hand, we have a trivial upper bound entropy $(f) \leq p n$. Substituting $p \geq$ $\operatorname{entropy}(f) / n$ in the previous inequality, we obtain that entropy $(f) \leq n \sqrt{m}$. Thus, at least with respect to balanced partitions, the entropy of any $(n, m)$-operator does not exceed $n \sqrt{m}$. In particular, for such partitions, matrix multiplication has the largest possible entropy $\Theta\left(n^{3 / 2}\right)$ among all ( $n, n$ )-operators.

## 4. Open problems

As mentioned in the introduction, a lower bound $\Omega\left(n^{1+\epsilon}\right)$ on the number of wires in a depth-2 circuit, computing an explicit linear operator $A$ x over $G F_{2}$, would yield a nonlinear lower bound for log-depth circuits. To approach this problem, it is natural to first prove such a bound for linear depth-2 circuits, where we only allow linear functions (sums mod 2) as gates. It is well known that matrices $A$ requiring $\Omega\left(n^{2} / \log n\right)$ wires in this restricted model exist. The situation with explicit bounds is, however, much worse. For circuits over the real field a lower bound $\Omega\left(n^{3 / 2}\right)$ was proved in [17]. However in their result it is essential that they use large integers in the matrix. It remains an open problem to prove such a bound for $0-1$ matrices. For $G F_{2}$ the largest bound is $\Omega\left(n \log ^{3 / 2} n\right)[1,11,13]$. In would be therefore interesting to extend the entropic approach to depth-2 circuits computing linear operators.

A less famous problem about depth-2 circuits, related to another old problem in circuit complexity (proving lower bounds for ACC circuits), is the following one.

A symmetric depth two circuit is a depth two circuit, where the gates on the middle layer compute ORs of their inputs, and each output gate computes the same symmetric function of its inputs. That is, each output gate gives the value 1 iff the number of 1 's in its input belongs to some specified (for the whole circuit) subset $S$ of natural numbers. We also assume that there are no direct wires from an input to an output node.

Say that a circuit computing a set $F=\left\{f_{1}, \ldots, f_{n}\right\}$ of boolean functions represents a given boolean $n \times n$ matrix $A=\left(a_{i j}\right)$ if, for every $i$ and $j, f_{i}\left(\mathbf{e}_{j}\right)=a_{i j}$. That is, the circuit is only required to be correct on inputs with precisely one 1 . Let $\operatorname{sym}_{2}(A)$ be the minimum number of nodes on the middle layer in a symmetric depth- 2 circuit representing $A$. That is, now we count nodes, not wires.

Remark. Note that the fact, that the circuit is allowed to output arbitrary values on inputs $\mathbf{x}$ with more than one 1 , is crucial. So, for example, every circuit computing the linear operator $A \mathbf{x}$ over $G F_{2}$ or a set $F=\left\{f_{1}, \ldots, f_{n}\right\}$ of boolean functions $f_{i}(\mathbf{x})=\bigvee_{j=1}^{n} a_{i j} x_{j}(\mathrm{a}(\wedge, \vee)$ boolean matrix-vector product $A \mathbf{x}$ ) represents the matrix $A$. By Proposition 1(iii), each such
circuit must have at least entropy $(F)$ nodes on the middle layer. Hence, already the identity matrix $A$ requires then $n$ nodes even if arbitrary boolean functions can be used as gates.

Simple counting shows that matrices with $\operatorname{sym}_{2}(A)=\Omega(n)$ exist. The problem, due to Yao [21], is to exhibit an explicit boolean matrix $A$ with large $\operatorname{sym}_{2}(A)$. In terms of set intersection representations of matrices, this problem was re-stated by Pudlák and Rödl in [13] (see Problem 10). To see the equivalence between $\operatorname{sym}_{2}(A)$ and their measure, just associate with each output node $i$ and each input node $j$ the sets $U_{i}$ and $V_{j}$ of all their neighbors on the middle layer. Then $a_{i j}=f_{i}\left(\mathbf{e}_{j}\right)=1$ iff $\left|U_{i} \cap V_{j}\right| \in S$.

What we need is an explicit boolean $n \times n$ matrix $A$ with $\operatorname{sym}_{2}(A)=2^{(\log \log n)^{\omega(1)}}$. Together with the results of Yao [21], and Beigel and Tarui [3], this would yield a super-polynomial lower bound for $A C C$ circuits. These are constant depth unbounded fanin circuits over a basis consisting of AND, OR and a finite number of modulo-counting functions: each such function gives the value 1 iff the number of 1 's in the input is not divisible by $p$. When $p$ is a prime, exponential lower bounds were proved by Razborov [16] and Smolensky [18]. However, the case of composite moduli $p$ (even when one moduli $p=6$ is allowed) remains widely open.

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[^0]:    1991 Mathematics Subject Classification. 68Q17, 94C10.
    Key words and phrases. Boolean circuits, bilinear forms, matrix multiplication, entropy.
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    Research supported by the DFG grant SCHN 503/4-1.

