

# On isoperimetric profiles and computational complexity

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#### Abstract

The isoperimetric profile of a graph is a function that measures, for an integer k, the size of the smallest edge boundary over all sets of vertices of size k. We observe a connection between isoperimetric profiles and computational complexity. We illustrate this connection by an example from communication complexity, but our main result is in algebraic complexity.

We prove a sharp super-polynomial separation between monotone arithmetic circuits and monotone arithmetic branching programs. This shows that the classical simulation of arithmetic circuits by arithmetic branching programs by Valiant, Skyum, Berkowitz, and Rackoff (1983) cannot be improved, as long as it preserves monotonicity.

A key ingredient in the proof is an accurate analysis of the isoperimetric profile of finite full binary trees. We show that the isoperimetric profile of a full binary tree constantly fluctuates between one and almost the depth of the tree.

## 1 Introduction

Computational complexity theory is about understanding the amount of resources required to compute a given function. One general framework for analyzing the limitations of a given computational device is to partition it to two or more parts and study the interactions between them (see [11, 2] and references within). This framework is directly related to communication complexity [23, 14], and appears in the study of branching programs (e.g. [4]), in algebraic complexity theory (e.g. [16, 9]), and more.

In this work, we observe the following phenomenon: the *exact* sizes of the parts in the partition matter. Some functions are "easy" to compute when the sizes can be chosen flexibly, but are "difficult" to compute when the sizes are chosen adversarially. The

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simplest illustration of this phenomenon comes from communication complexity, and is discussed below. Our most convincing application, however, comes from arithmetic circuit complexity, and forms the bulk of this paper.

#### **1.1** Isoperimetric profile of graphs

The aforementioned phenomenon is related to expansion properties of graphs. For a graph G = (V(G), E(G)) and  $U \subseteq V(G)$ , the size of the edge boundary of U is

 $e_G(U) = |\{\{u, v\} \in E(G) : u \in U, v \in V(G) \setminus U\}|.$ 

The edge isoperimetric profile of G is the function

$$\operatorname{eip}_{G}(k) = \min\{e_{G}(U) : U \subseteq V(G), |U| = k\}.$$

For example, G is connected if and only if  $eip(k) \ge 1$  for every non trivial k. Analyzing the isoperimetric profile of a graph is not a simple task. In fact, even understanding simple properties of the isoperimetric profile in manifolds is difficult (see [15] are references within).

The high-level connection is as follows. Consider functions defined over some graph G. The vertices are labelled by variables, and the edges represent interactions between them. A partitioning of the variables into two parts yields a partition of the vertices of G. Intuitively, the size of the edge boundary represents the amount of interaction between the parts, and so a large boundary implies high complexity.

## **1.2** Communication complexity

Communication complexity studies the amount of communication two or more parties need to exchange in order to achieve a common goal. It was initiated by Yao in [23] in the context of distributed computing. For simplicity of the presentation, here we focus on the best-case deterministic two player model that was introduced by Papadimitriou and Sipser [17], and applied to study of very-large-scale integration (for more background and details, see the textbook [14]).

The deterministic communication complexity D(f) of a boolean function  $f : \{0, 1\}^A \times \{0, 1\}^B \to \{0, 1\}$  is the minimum number of bits two players need to exchange in order to determine the value of f(x, y), where one player sees  $x \in \{0, 1\}^A$  and the other sees  $y \in \{0, 1\}^B$ . Let  $F : \{0, 1\}^V \to \{0, 1\}$ . Given a partition of V to two sets A, B, we can define a function  $F_{A,B} : \{0, 1\}^A \times \{0, 1\}^B \to \{0, 1\}$  by  $F_{A,B}(x, y) = F(z)$  where  $z|_A = x$ and  $z|_B = y$ . The best-case deterministic communication complexity with partition-size k of F, denoted  $D_k^{\text{best}}(F)$ , is the minimum of  $D(F_{A,B})$  over all partitions of V to two sets A, B with |A| = k.

We observe the following connection between the best-case communication complexity and the edge isoperimetric profile for certain functions. Let G = (V, E) be an undirected graph with n vertices and maximum degree  $\Delta$ . Consider, e.g., the function  $F: \{0,1\}^V \to \{0,1\}$  defined via G as<sup>1</sup>

$$F(z) = \bigoplus_{\{u,v\}\in E} z_u \wedge z_v,$$

where  $\oplus$  is addition modulo two. Then, for every  $1 \le k \le n$ , it holds that<sup>2</sup>

$$\Omega(\operatorname{eip}_G(k)/\Delta) \le D_k^{\operatorname{best}}(F) \le O(\operatorname{eip}_G(k))$$

The upper bound is obtained by partitioning the variables according to the minimizer of the edge boundary, noting that the players need only to exchange inputs that appear on edges of the boundary. The lower bound holds for the following reason. For every partition A, B of the inputs with |A| = k, the edge boundary of A contains an induced matching of size  $m \ge \Omega(\operatorname{eip}_G(k)/\Delta)$ . Setting the variables not participating in the matching to zero, the lower bound follows from standard lower bounds on the inner product function,  $\bigoplus_{i \in [m]} x_i \wedge y_i$ .

In other words, the best-case communication complexity of F is determined by the isoperimetric profile of G, as long as G has constant degree. So, for example, if the isoperimetric profile of G changes dramatically with k, then so does  $D_k^{\text{best}}(F)$ . In particular, some values of k may yield low communication complexity whereas some yield very high complexity.

## 1.3 Algebraic complexity

Algebraic complexity theory studies the complexity of computing polynomials over a field. For more background and details, see [7, 5, 20] and references within. We start by outlining definitions of the models we consider.

The most general model of computation in this area is that of *arithmetic circuit*. An arithmetic circuit is a directed acyclic graph with fan-in either zero or two. Vertices of fan-in zero are labelled by a field element or a variable. Vertices of fan-in two are labelled by either + or  $\times$ . Every vertex in an arithmetic circuit computes a polynomial in the obvious way. A weaker model is an *arithmetic formula*: it is a circuit whose underlying graph is a tree. Another model is the *algebraic branching program*, ABP. An ABP is a directed acyclic graphs with two special vertices  $v_{\text{start}}$ ,  $v_{\text{end}}$ . Each edge e in it is labelled by L(e) which is a variable times a field element. The program computes f, which is the following sum over all directed paths  $\gamma$  from  $v_{\text{start}}$  to  $v_{\text{end}}$ :

$$f = \sum_{\gamma: v_{\text{start}} \to v_{\text{end}}} \prod_{e \in \gamma} L(e).$$

The computation performed by ABPs correspond to the iterated multiplication of matrices. The size parameter in each of the three models is the number of edges in the underlying graph.

<sup>&</sup>lt;sup>1</sup>The definition of F is inspired by a private communication with Avi Wigderson following [18].

<sup>&</sup>lt;sup>2</sup>In this text, big O and  $\Omega$  notation means "up to a constant multiplicative factor".

We now discuss reductions between these models. Formulas can be losslessly simulated by an ABP, which in turn can be losslessly simulated by a circuit. In the opposite direction, Hyafil [10] showed that every circuit of size s computing a polynomial of degree r can be simulated by a formula of size  $2^{O(\log(s)\log(r))}$ . Valiant, Skyum, Berkowitz and Rackoff [22] significantly strengthened this result. In their seminal work, they showed that an arithmetic circuit of size s computing a polynomial of degree r can be simulated by a circuit of size s computing a polynomial of degree r can be simulated by a circuit of size poly(r, s) and depth  $O(\log(r)\log(s))$ . This was result was later used in a sequence of works — Agrawal and Vinay [1], Koiran [12], and Tavenas [21] — to prove non-trivial simulations of circuits by circuits of depth four (and unbounded fan-in). This depth reductions sprung a long sequence of works on lower bounds for constant depth circuits (see [8, 13, 6] are references within).

An intriguing question is whether the simulations discussed above are sharp. It is possible they can be significantly improved. However, since we do not have strong enough methods for proving lower bounds for these models of computation, proving that the reductions are sharp is currently beyond us.

We therefore address this question in the restricted setting of monotone computations. A monotone arithmetic computation is a computation over the real numbers that uses only non-negative numbers. The aforementioned reductions of Hyafil and Valiant et al. transform a monotone device to a monotone device. We call such reductions monotone.

Since we know how to prove lower bounds for monotone computation, we can in fact show that in the category of monotone reductions the reductions above are indeed sharp. Indeed, the reduction between ABPs and formulas is sharp since Shamir and Snir [19] proved that in order to multiply d matrices of size  $n \times n$ , we need a monotone formula of size  $n^{\Omega(\log d)}$ , but on the other hand this can be done via a monotone ABP of size poly(n, d). The reduction from circuits to ABPs was not previously studied. In this paper, we prove:

**Theorem 1.** There is a multilinear n-variate polynomial f with zero-one coefficients so that the following hold:

- (i). The polynomial f can be computed by a monotone arithmetic circuit of size poly(n).
- (ii). Every monotone ABP computing f has size at least  $2^{\Omega(\log^2(n))}$ .

The simulation of [22] shows that the lower bound in the theorem is tight, up to a constant in the exponent. Stated differently, the theorem shows that any monotone reduction from circuits to ABPs must incur a super-polynomial blowup. Prior to this work, it was conceivable that the monotone construction of [22] or other monotone variants of it can simulate a circuit by an ABP with only a polynomial increase in size.

We now briefly discuss the proof. All lower bounds we know of for monotone algebraic computation are based on combinatorial problems that are related to counting monomials. The lower bounds for circuits use the following structure, which is standard by now (see e.g. [19, 20, 9]). We denote by  $\deg(f)$  the total degree of f. **Lemma 2.** If f is a homogeneous polynomial of degree r that can be computed by a monotone circuit of size s, then for every integer  $2 \le k \le r$ , we can write

$$f = \sum_{i=1}^{s} h_i g_i \tag{1}$$

where for each *i*, both  $h_i, g_i$  are homogeneous, monotone, and of degrees  $k/3 \le deg(h_i) < 2k/3$  and  $deg(g_i) = r - deg(h_i)$ .

A typical monotone lower bound proceeds by showing that the number of monomials in each  $h_i g_i$  is small and so s must be large. To separate monotone circuits from ABPs, we must find a polynomial that has a small circuit and use some other property of ABPs. We use the following.

**Lemma 3.** If f is a homogeneous polynomial of degree r that can be computed by a monotone ABP of size s, then for every integer  $0 \le k \le r$ , we can write

$$f = \sum_{i=1}^{s} h_i g_i \tag{2}$$

where for each *i*, both  $h_i, g_i$  are homogeneous, monotone, and of degrees  $deg(h_i) = k$  and  $deg(g_i) = r - k$ .

Notice the similarities between the two lemmas. The only difference between circuits and ABPs is that circuits are slightly more flexible about the degrees of  $h_i, g_i$  in (1), whereas ABPs are not. We exploit this weakness to prove the separation. Motivated by Section 1.2, the polynomial f in Theorem 1 will be defined over an underlying graph G. The setting will be such that for each k, large  $eip_G(k)$  implies a super-polynomial lower bound on s in (2), and hence gives a lower bound on the ABP-size. On the other hand, the graph must be chosen so that f is easy to compute via a monotone circuit. If Gis too complex, such as an expander graph, then we do not expect to prove meaningful upper bounds. In fact, in order to circumvent the lower bound implied by (1), the value of  $eip_G(k)$  must be small for many integers k. It turns out that the right graph to choose is the full binary tree, which we discuss next.

#### **1.4** Full binary trees

We analyze the isoperimetric profile of full finite binary trees. The case of the infinite binary tree was previously studied by Bharadwaj, Chandran and Das in [3], where it was shown to be related to meta-Fibonacci sequences and signed almost binary partitions.

For an integer  $d \ge 0$ , denote by  $T_d$  the full binary tree of depth d. It has precisely  $2^d$  leaves and  $2^{d+1} - 1$  vertices. It is clear that there are many values  $k \le |V(T_d)|$  for which  $\operatorname{eip}_{T_d}(k) = 1$ . It is more surprising that for some k, the value of  $\operatorname{eip}_{T_d}(k)$  can be fairly large, almost as large as the depth of  $T_d$ . This is the content of the first theorem:

**Theorem 4.** Let  $mip(T_d)$  be the maximum of  $eip_{T_d}(k)$  over all  $0 \le k \le |V(T_d)|$ . Then

$$\frac{d}{2} - O(\log d) \le \min(T_d) \le \frac{d}{2} + O(1).$$

In order to analyze the isoperimetric profile of  $T_d$ , we relate it to the binary representation of k. For an integer  $k \ge 0$ , denote the binary representation of k by

$$B(k) = (B_0(k), B_1(k), B_2(k), \ldots) \in \{0, 1\}^{\mathbb{N}}.$$

I.e.,  $k = \sum_{i=0}^{\infty} B_i(k) 2^i$ . Denote by drops(k) the number of drops in B(k):

$$drops(k) = |\{i \ge 0 : B_i(k) > B_{i+1}(k)\}|.$$

The number of drops is a quantity that is relatively easy to understand, and as the following theorem shows, it captures the isoperimetric profile of binary trees.

**Theorem 5.** For every  $d \ge 0$  and  $0 \le k < |V(T_d)|$ ,

$$\frac{\mathrm{drops}(k)}{2} \le \operatorname{eip}_{T_d}(k) \le 2\mathrm{drops}(k) \,.$$

Moreover, the lower bound can be improved to drops(k) - O(log(drops(k)))).

The theorem provides an almost optimal description of the isoperimetric profile  $\operatorname{eip}_{T_d}(k)$  of  $T_d$ . It implies that although  $\operatorname{eip}_{T_d}(k) = 1$  for many values of k, for most values of k we have  $\operatorname{eip}_{T_d}(k) \geq \Omega(d)$ .

Figure 1 is a plot of the graph of drops(k) as a function of k. Theorem 5 shows that, up to constant factors, the edge isoperimetric profile of the full binary tree has the same graph, which indicates how irregular it is. The plot also shows that if we want to choose an integer that forces the largest possible edge boundary for depth d = 14, then we should consider 21,845, whose binary representation starts with one and then alternates.

We get an explicit choice of k for which eip(k) is large. For even  $d \ge 0$ , define

$$\sigma_d = 1 + 4 + 16 + \ldots + 2^d \approx \frac{2}{3} 2^{d+1},\tag{3}$$

and for odd d define  $\sigma_d = \sigma_{d-1}$ . The number of drops in  $B(\sigma_d)$  is at least d/2. The number  $\sigma_d$  can be thought of as the truncation of the binary expansion of 2/3.

**Corollary 6.** For every  $d \ge 0$ , we have  $\operatorname{eip}_{T_d}(\sigma_d) \ge d/2 - O(\log d) \ge d/4$ .



Figure 1: The graph of drops(k) for  $k = 1, 2, \ldots, 2^{15}$ .

## 2 Binary trees

In order to prove the lower bounds in Theorems 4 and Theorem 5, we will introduce the quantity sbl(k) which, roughly speaking, measures how far k is from powers of 2. We then relate  $eip_{T_d}(k)$  and sbl(k), and later estimate sbl(k) in terms of drops(k). The upper bounds will be proved separately, in Lemma 10.

We say that k is a signed power of two if it is of the form  $\pm 2^j$  for some integer  $j \ge 0$ . For  $k \in \mathbb{Z}$ , the signed binary length of k, denoted  $\operatorname{sbl}(k)$ , is the minimum b so that there exist b signed powers of two  $k_1, \ldots, k_b$  so that  $k = \sum_{i=1}^b k_i$ , where repetitions are a priori allowed. For example,  $\operatorname{sbl}(0) = 0$  and if  $d \ge 1$  then

$$\operatorname{sbl}(1+2+4+\ldots+2^d) = \operatorname{sbl}(2^{d+1}-1) = 2.$$

The following lemma gives a lower bound on  $eip_{T_d}(k)$  in terms of sbl(k).

**Lemma 7.** For every  $d \ge 0$  and  $0 \le k \le |V(T_d)|$ ,

$$\operatorname{eip}_{T_d}(k) \ge \operatorname{sbl}(k) - O(\log(\operatorname{sbl}(k))).$$

In addition, if  $k < |V(T_d)|$  then  $\operatorname{eip}_{T_d}(k) \ge \operatorname{sbl}(k)/2$ .

*Proof.* For an integer k, let st(k) denote the smallest b such that there exist non-negative integers  $j_1, \ldots, j_b$  and  $\epsilon_1, \ldots, \epsilon_b \in \{-1, 1\}$  with<sup>3</sup>

$$k = \sum_{j=1}^{b} \epsilon_j \cdot (2^j - 1) \,. \tag{4}$$

<sup>&</sup>lt;sup>3</sup>This quantity has previously appeared in [3].

Recall that if j > 0, then  $2^j - 1$  is the number of vertices in  $T_{j-1}$ . We will prove the following:

**Claim 8.** For every  $U \subseteq V(T_d)$  not containing the root of  $T_d$ , we have  $st(|U|) \leq e_{T_d}(U)$ .

Claim 8 implies that for every  $U \subseteq V(T_d)$ ,

$$\operatorname{st}(|U|) \le e_{T_d}(U) + 1.$$
(5)

Indeed, if U contains the root of  $T_d$ , then apply Claim 8 to the complement  $\overline{U} = V(T_d) \setminus U$ . Then  $\overline{U}$  does not contain the root of  $T_d$  and  $e_{T_d}(U) = e_{T_d}(\overline{U}) \ge \operatorname{st}(|\overline{U}|)$ . But  $|U| = |V(T_d)| - |\overline{U}|$  gives  $\operatorname{st}(|U|) \le \operatorname{st}(|\overline{U}|) + 1$ .

Proof of Claim 8. The proof is by induction on d. The claim holds for d = 0 as st(0) = 0. Assume d > 0. Let  $v_d$  be the root of  $T_d$  and for a node v, let T(v) be the full subtree of  $T_d$  with root v. Let  $U \subseteq V(T_d)$  be so that  $v_d \notin U$ . Let M be the subset of maximal vertices in U. That is, a vertex v is in M if  $v \in U$  and the shortest path from v to  $v_d$ does not contain a vertex from U. For  $v \in M$ , let  $U(v) = U \cap V(T(v))$ . Hence,

$$e_{T_d}(U) = |M| + \sum_{v \in M} e_{T(v)}(U(v)).$$

Since  $|U| = \sum_{v \in M} |U(v)|$ ,

$$\operatorname{st}(|U|) \le \sum_{v \in M} \operatorname{st}(|U(v)|).$$

For every  $v \in M$ , the inductive assumption and (5) show that

$$st(|U(v)|) \le e_{T(v)}(U(v)) + 1.$$

Overall,

$$st(|U|) \le \sum_{v \in M} (1 + e_{T(v)}(U(v))) = |M| + \sum_{v \in M} e_{T(v)}(U(v)) = e_{T_d}(U).$$

To prove the lemma, it remains to estimate sbl(k) in terms of st(k). If k is written as in (4) with b = st(k), we have

$$\operatorname{sbl}(k) \le \operatorname{sbl}(\sum_{j=1}^{b} \epsilon_j 2^j) + \operatorname{sbl}(\sum_{j=1}^{b} \epsilon_j) \le \operatorname{st}(k) + \log_2(\operatorname{st}(k) + 1)$$

This gives  $st(k) \ge sbl(k) - O(\log(sbl(k)))$  and so (5) gives

$$\operatorname{eip}_{T_d}(k) \ge \operatorname{sbl}(k) - O(\log(\operatorname{sbl}(k))),$$

as required.

Finally, assume that  $U \neq V(T_d)$ . If U does not contain the root, apply Claim 8 and the estimate  $\operatorname{sbl}(k) \leq 2\operatorname{st}(k)$ , to obtain  $e_{T_d}(U) \geq \operatorname{sbl}(|U|)/2$ . If U does contain the root, apply Claim 8 to  $\overline{U} = V(T_d) \setminus U$  and note that  $\operatorname{sbl}(|U|) \leq 2\operatorname{st}(|\overline{U}|)$  whenever  $\overline{U} \neq \emptyset$ .  $\Box$  The next lemma shows that, up to a constant factor, sbl(k) and drops(k) are the same.

**Lemma 9.** For every  $k \ge 0$ , we have drops $(k) \le sbl(k) \le 2drops(k)$ .

*Proof.* We start by showing that  $sbl(k) \leq 2drops(k)$ . First, note that k can be written as

$$k = \sum_{i=1}^{t} \sum_{r_i \le j \le \ell_i} 2^j , \qquad (6)$$

where  $t \leq \operatorname{drops}(k)$  and  $r_1 \leq \ell_1 < r_2 \leq \ell_2 < \cdots < r_t \leq \ell_t$  are non-negative integers. Second, note that each sum  $\sum_{r_i \leq j \leq \ell_i} 2^j$  can be expressed in terms of at most two signed powers of 2.

In order to prove the other inequality, we first note that for every  $k, j \ge 0$ 

$$\left|\operatorname{drops}(k+2^{j}) - \operatorname{drops}(k)\right| \le 1.$$
(7)

To see (7), assume first that  $B_j(k) = 0$ . Then adding  $2^j$  can introduce one drop if  $B_{j+1}(k) = 0$  and delete one drop if j > 0 and  $B_{j-1}(k) = 1$ . If  $B_j(k) = 1$ , let  $\ell$  be the smallest integer with  $B_\ell(k) = 0$  and  $\ell > j$ . The binary representations of k and  $k + 2^j$  are the same, except that  $B_\ell(k+2^j) = 1$  and  $B_i(k+2^j) = 0$  for every  $j \leq i < \ell$ . The number of drops in  $k + 2^j$  can increase only if  $B_{j-1}(k) = 1$  and j > 0, and increases at most by one. It can decrease only if  $B_{\ell+1}(k) = 1$ , and again at most by one.

By induction on  $\operatorname{sbl}(k)$ , we now prove that for every  $k \ge 0$ ,  $\operatorname{drops}(k) \le \operatorname{sbl}(k)$ . If  $\operatorname{sbl}(k) = 0$ , the statement holds. Otherwise, let  $k_1, \ldots, k_b$ , with  $b = \operatorname{sbl}(k)$ , be signed powers of two that sum to k. Choose  $k_i$  so that  $k - k_i$  is non-negative. Hence, (7) shows that  $\operatorname{drops}(k - k_i) \ge \operatorname{drops}(k) - 1$ . Furthermore, we have  $\operatorname{sbl}(k - k_i) = \operatorname{sbl}(k) - 1$ . By the inductive assumption,  $\operatorname{sbl}(k - k_i) \ge \operatorname{drops}(k - k_i)$ . Altogether,  $\operatorname{sbl}(k) = \operatorname{sbl}(k - k_i) + 1 \ge (\operatorname{drops}(k) - 1) + 1 = \operatorname{drops}(k)$ , completing the proof.

The last lemma gives our upper bounds on  $eip_{T_d}(k)$ .

**Lemma 10.** For every  $d \ge 0$  and  $0 \le k \le |V(T_d)|$ ,

 $\operatorname{eip}_{T_d}(k) \le \min\{2\operatorname{drops}(k), d/2 + O(1)\}.$ 

*Proof.* We view  $T_d$  as ordered: for every vertex with two children, there is the left child and there is the right child. Let  $v_0$  be the leftmost leaf in  $T_d$  and let  $v_0, v_1, \ldots v_d$  be the shortest path from  $v_0$  to the root  $v_d$ . For  $j \in \{1, \ldots, d\}$ , let  $R_j$  be the full subtree rooted at the right child of  $v_j$  and let  $U_j = V(R_j) \cup \{v_j\}$ . Furthermore, let  $U_0 = \{v_0\}$ . Each  $R_j$ is a full binary tree of depth j - 1, and hence  $|U_j| = 2^j$  for every  $j \in \{0, \ldots, d\}$ .

We first prove that  $\operatorname{eip}_{T_d}(k) \leq 2\operatorname{drops}(k)$ . Write k as in (6). For every  $i \in [t]$ , define

$$U^{(i)} := \bigcup_{j \in [r_i, \ell_i]} U_i$$
 and  $U := \bigcup_{i \in [t]} U^{(i)}$ .

Hence, |U| = k. Finally, notice that for every  $i \in [t]$ , the size of the edge boundary of  $U^{(i)}$  is of size at most 2; the possible edges in the boundary are the edge from  $v_{r_i}$  to its left child and the edge from  $v_{\ell_i}$  to its parent.

We now prove that  $\operatorname{eip}_{T_d}(k) \leq d/2 + 2$ . For a tree T with root v and  $U \subseteq V(T)$ , define

$$r_T(U) := \begin{cases} 1 & \text{if } v \in U, \\ 0 & \text{if } v \notin U. \end{cases}$$

It is sufficient to prove the following claim: if  $0 \le k \le V(T_d)$  then there exists a subset U of  $V(T_d)$  of size k such that

$$e_{T_d}(U) \le \frac{d}{2} + 2 - r_{T_d}(U)$$
.

The proof is by induction on d. If  $d \in \{0, 1\}$ , the statement holds. Assume that  $d \geq 2$  and  $0 \leq k \leq |V(T_d)|$ . Recall the trees  $R_d$ ,  $R_{d-1}$ , and let L be the full subtree with root  $v_{d-2}$ . Hence,  $R_d$  has depth d-1, whereas  $R_{d-1}$  and L have depth d-2. In addition,

$$V(T_d) = V(R_d) \cup V(R_{d-1}) \cup V(L) \cup \{v_d, v_{d-1}\}.$$

Define  $S_1 := V(R_d)$  if  $k \ge |V(R_d)|$  and  $S_1 := \emptyset$  otherwise. Similarly, define  $S_2 := V(R_{d-1})$  if  $k - |S_1| \ge |V(R_{d-1})|$  and  $S_2 := \emptyset$  otherwise. Define

$$k_0 := k - |S_1| - |S_2|.$$

If  $k_0 \ge |V(T_{d-2})| + 1$  then  $k \ge |V(T_d)| - 1$ . Hence  $\operatorname{eip}_{T_d}(k) \le 1$  and the claim holds. Otherwise, if  $k_0 \le 1$  set  $U := S_1 \cup S_2 \cup U'$  where U' is a subset of leaves of L of size  $k_0$ . This gives  $e_{T_d}(U) \le 3$  and the claim holds since the root of  $T_d$  is not in U.

Hence, we can now assume that

$$2 \le k_0 \le |V(T_{d-2})|.$$

We will distinguish between two cases based on how many of  $S_1$  and  $S_2$  are empty or not.

Assume that at least one  $S_1, S_2$  is empty. Let U' be the subset of V(L) of size  $k_0$  guaranteed by the inductive assumption:

$$e_L(U') \le \frac{d-2}{2} + 2 - r_L(U') = \frac{d}{2} + 1 - r_L(U).$$

Define  $U := S_1 \cup S_2 \cup U'$ . Then U has size k and

$$e_{T_d}(U) \le 1 + e_{T_d}(U') = 1 + e_L(U') + r_L(U') \le \frac{d}{2} + 2.$$

Since the root of  $T_d$  is not in U, the claim holds.

Assume that both  $S_1$  and  $S_2$  are non-empty. Let  $k' = |V(T_d)| - k$ . Thus,

$$0 \le k' = |V(T_{d-2})| - k_0 + 2 \le |V(T_{d-2})|.$$

Let U' be the subset of L of size k' guaranteed by the inductive assumption. Hence,

$$e_{T_d}(U') = e_L(U') + r_L(U') \le \frac{d}{2} + 1$$

Set  $U := V(T_d) \setminus U'$ . Thus, |U| = k and  $e_{T_d}(U) = e_{T_d}(U')$ . Therefore,

$$e_{T_d}(U) \le \frac{d}{2} + 1 \le \frac{d}{2} + 2 - r_{T_d}(U)$$

as required. This concludes the proof of the claim.

Proof of Theorems 4 and 5. The lower bounds in both theorems follow from Lemmas 7 and 9, since drops( $\sigma_d$ ) = d/2 for  $\sigma_d$  as defined in (3). The upper bounds follow from Lemma 10.

## 2.1 Remarks

First, none of the bounds in Theorem 5 is tight for all k. For example, the 2drops(k) upper bound exceeds the upper bound from Theorem 4 for  $k = \sigma_d$  from (3). Furthermore, we do not know which of the bounds in Theorem 4 is more accurate.

Second, we have  $\operatorname{eip}_{T_d}(\sigma_d) \leq d/2 - \Omega(\log d)$ . Hence, the lower bound of drops $(k) - O(\log(\operatorname{drops}(k)))$  from Theorem 5 cannot be improved as a function of drops(k). A similar statement holds for Lemma 7 and  $\operatorname{sbl}(k)$ .

Third, the quantity  $\operatorname{st}(k)$  from Claim 8 characterizes eip almost exactly:  $\operatorname{st}(k) - 1 \leq \operatorname{eip}_{T_d}(k) \leq \operatorname{st}(k)$ . This can be deduced from Claim 8 and Theorem 2.3 from [3]. It also implies  $|\operatorname{eip}_{T_d}(k) - \operatorname{sbl}(k)| \leq O(\log k)$ .

Finally, we do not know of a simple procedure to compute  $\operatorname{eip}_{T_d}(k)$ , or to find a subset of size k that minimizes the boundary-size. The quantity  $\operatorname{sbl}(k)$ , however, can be computed exactly and quite easily, in time polynomial in  $\log k$ , which allows to efficiently approximate  $\operatorname{eip}_{T_d}(k)$  more accurately.

## 3 Algebraic complexity

In this section, we prove the separation between monotone circuits and ABPs stated in Theorem 1, and the structure of ABPs stated in Lemma 3.

#### 3.1 The tree function

We first describe a boolean function  $\mathcal{T}_{d,m}$  which is later used to prove our separation. Recall that  $T_d$  is the full binary tree of depth d, and let V be the set of its vertices. For

an integer m > 1, let  $\mathbb{Z}_m$  be the additive group of integers modulo m, and let  $\mathbb{Z}_m^V$  be the set of functions  $\gamma: V \to \mathbb{Z}_m$ .

A function  $\gamma \in \mathbb{Z}_m^V$  will be called *legal*, if for every vertex v which is not a leaf and its two children  $v_1, v_2$ , we have

$$\gamma(v) = \gamma(v_1) + \gamma(v_2) \,.$$

The tree function  $\mathcal{T}_{d,m}: \mathbb{Z}_m^V \to \{0,1\}$  takes  $\gamma \in \mathbb{Z}_m^V$  and accepts if  $\gamma$  is legal.

For a node  $v \in V$ , let T(v) be the full subtree of  $T_d$  rooted at v and let  $\ell(T(v))$  be the set of its leaves. Then  $\gamma$  is legal iff

$$\gamma(v) = \sum_{u \in \ell(T(v))} \gamma(u) \tag{8}$$

holds for every vertex v in T.

The following lemma depicts the key property of  $\mathcal{T}_{d,m}$  that we later use. For two functions f, g over the same domain, write  $f \leq g$  if  $f(x) \leq g(x)$  for all x. Denote by  $\sup(f)$  the set of inputs x so that f(x) = 1.

**Lemma 11.** Let  $V_0, V_1$  be a partition of V where  $|V_0| = \sigma_d$ , as defined in (3). If

$$h_0: \mathbb{Z}_m^{V_0} \to \{0, 1\}, \quad h_1: \mathbb{Z}_m^{V_1} \to \{0, 1\}, \quad h_0 \wedge h_1 \le \mathcal{T}_{d, m_2}$$

then

$$|\sup(h_0 \wedge h_1)| \le m^{-d/16} |\sup(\mathcal{T}_{d,m})|.$$

*Proof.* View  $T_d$  as directed from leaves to root. A directed path  $v_1, \ldots, v_k$  in  $T_d$  from  $v_1 \in \ell(T(v_k))$  to  $v_k$  will be called *pure* if  $v_1 \neq v_k$  and there exists  $i \in \{0, 1\}$  so that  $\{v_1, \ldots, v_k\} \cap V_i = \{v_k\}$ . A node will be called *pure* if it is the last node of some pure path. Let  $P \subset V$  be the set of pure nodes. Let E be the edge boundary of  $V_0$ .

To prove the lemma, we use the following two claims.

Claim 12.  $|P| \ge |E|/4$ .

Proof of Claim 12. Let S be the set of nodes  $v \in V$  so that the parent of v in  $T_d$  is pure. Since  $|S| \leq 2|P|$ , it is enough to show that  $|S| \geq |E|/2$ . Let T' be the minor of  $T_d$ obtained by contracting all the edges of  $T_d$  not in E. The tree T' is a (not necessarily binary) tree with |E| edges. For  $x \in V(T')$ , let  $[x] \subseteq V$  be the set of vertices that have been contracted to x. The root of T' is the vertex x so that the root of  $T_d$  is in [x]. View T' as directed from leaves to the root. For  $x \in V(T')$ , let  $v(x) \in V$  be the vertex in [x] that is closest to the root of  $T_d$ . This is well defined, since the set [x] connected in  $T_d$ . For every leaf  $x \in V(T')$ , we have  $v(x) \in S$ . For every  $x \in V(T')$  with in-degree one which is not the root of T', the vertex v(x) is also in S. Recall that T' can have at most |E|/2 vertices of in-degree at least two. Hence,  $|S| \geq (|E|+1) - (|E|/2+1)$ , as required.

For every pure node v, fix a leaf  $\tilde{v}$  such that the path from  $\tilde{v}$  to v is pure. Let  $P = \{\tilde{v} : v \in P\}$ . The sizes of P and P are the same.

**Claim 13.** Assume  $\sup(h_0) \neq \emptyset$ . Then every  $\beta \in \sup(h_1)$  is uniquely determined by its values on  $(\ell(T_d) \cap V_1) \setminus P$ .

*Proof of Claim 13.* Fix  $\alpha \in \sup(h_0)$ . For the sake of contradiction, assume that there are two distinct  $\beta_1, \beta_2 \in \sup(h_1)$  which agree on  $(\ell(T_d) \cap V_1) \setminus P$ . Since  $h_0 \wedge h_1 \leq \mathcal{T}_{d,m}$ , both  $\alpha \cup \beta_1$  and  $\alpha \cup \beta_2$  are legal maps satisfying (8). Hence,  $\beta_1$  and  $\beta_2$  differ on some leaf in  $V_1$ . They agree on leaves outside of  $\tilde{P}$  and so there exists a pure node  $v \in V_0$ such that  $\beta_1(\tilde{v}) \neq \beta_2(\tilde{v})$ . We can assume that v is minimal in that for every pure node  $u \in T(v) \cap V_0$  with  $u \neq v$ , we have  $\beta_1(\tilde{u}) = \beta_2(\tilde{u})$ . Since every pure path that starts in  $\ell(T(v)) \cap V_1$  must also end in T(v), we obtain that  $\beta_1(u) = \beta_2(u)$  for every leaf in  $T(v) \cap V_1$  with the sole exception of  $\tilde{v}$ . But this is impossible since (8) implies that for every  $i \in \{1, 2\}$ ,

$$\alpha(v) - \sum_{u \in \ell(T(v)) \cap V_0} \alpha(u) = \beta_i(\tilde{v}) + \sum_{u \in (\ell(T(v)) \cap V_1) \setminus \{\tilde{v}\}} \beta_i(u) ,$$

which gives  $\beta_1(\tilde{v}) = \beta_2(\tilde{v})$ .

To conclude the lemma, assume that  $\sup(h_0 \wedge h_1) \neq \emptyset$ , otherwise we are done. Claim 13 shows that

$$|\sup(h_0)| \le m^{|(\ell(T_d) \cap V_0) \setminus \hat{P}|}, \ |\sup(h_1)| \le m^{|(\ell(T_d) \cap V_1) \setminus \hat{P}|}.$$

Since  $|\sup(\mathcal{T}_{d,m})| = m^{|\ell(T_d)|}$ ,

$$|\sup(h_0)| \cdot |\sup(h_1)| \le m^{|\ell(T_d)| - |\tilde{P}|} = m^{-|\tilde{P}|} |\sup(\mathcal{T}_{d,m})|.$$

Finally, Claim 12 and Corollary 6 give  $|\tilde{P}| = |P| \ge |E|/4 \ge e_{T_d}(V_0)/4 \ge d/16$ .

#### 3.2The tree polynomial

We now describe the polynomial that separates monotone circuits from ABPs. Recall that  $T_d$  is the full binary tree of depth d and  $\mathcal{T}_{d,m} : \mathbb{Z}_m^V \to \{0,1\}$  is the tree function, where  $V = V(T_d)$ . For every  $v \in T_d$  and  $z \in \mathbb{Z}_m$ , introduce the variable  $x_{v,z}$ . For a partial function  $\gamma: V \to \mathbb{Z}_m$ , define the monomial  $x_{\gamma} = \prod_{v \in \operatorname{dom}(\gamma)} x_{v,\gamma(v)}$ . Define the tree polynomial as

$$\mathcal{P}_{d,m} = \sum_{\gamma \in \mathbb{Z}_m^V : \mathcal{T}_{d,m}(\gamma) = 1} x_{\gamma}$$

It is homogeneous of degree  $|V| = 2^{d+1} - 1$  and it has m|V| variables.

We now prove a generalization of Theorem 1.

**Proposition 14.** The polynomial  $\mathcal{P}_{d,m}$  can be computed by a monotone arithmetic circuit of size  $O(m^3 2^d)$ . However, every monotone ABP computing  $\mathcal{P}_{d,m}$  has size at least  $m^{\Omega(d)}$ .

Theorem 1 follows from Proposition 14 by setting  $m = 2^d$ .

Proof of Proposition 14. We first prove the lower bound. Assume that  $\mathcal{P}_{d,m}$  has a monotone ABP of size s. Let  $\sigma_d$  be as defined in (3). By Lemma 3, we can write

$$\mathcal{P}_{d,m} = \sum_{i=1}^s h_i g_i \,,$$

where  $h_i, g_i$  are homogeneous and monotone,  $h_i$  has degree  $\sigma_d$  and  $g_i$  has degree  $\deg(\mathcal{P}_{d,m}) - \sigma_d$ . We can assume  $h_i g_i \neq 0$  for every *i*. For a polynomial *f*, let mon(*f*) be the set of  $\gamma$ 's such that  $x_{\gamma}$  has a non-zero coefficient in *f*, and let  $f^*$  be the boolean function with  $\sup(f^*) = \min(f)$ . Monotonicity guarantees that for every  $i \in [s]$ , there exists  $V_i \subseteq V$  with  $|V_i| = \sigma_d$  such mon $(h_i) \subseteq \mathbb{Z}_m^{V_i}$  and mon $(g_i) \subseteq \mathbb{Z}_m^{V \setminus V_i}$ . Therefore,

$$\mathcal{P}_{d,m}^{\star} = \bigvee_{i=1}^{s} h_{i}^{\star} \wedge g_{i}^{\star} \,.$$

Since  $\mathcal{P}_{d,m}^{\star} = \mathcal{T}_{d,m}$ , Lemma 11 gives  $s \geq m^{d/16}$ .

For the upper bound, fix m and proceed by induction on d. For  $a \in \mathbb{Z}_m$ , let  $F_{a,d}$  be the polynomial defined as  $\mathcal{P}_{d,m}$ , except  $\gamma$  range over legal maps with  $\gamma(v_d) = a$ , where  $v_d$  is the root. Hence,  $\mathcal{T}_{d,m} = \sum_{a \in \mathbb{Z}_m} F_{a,d}$ .

We will show that  $F_{d,a}$ , for all  $a \in \mathbb{Z}_m$ , can be simultaneously computed by a circuit of size  $s(d) = O(m^3 2^d)$ . For d = 0, we have s(d) = O(m). Assume that d > 0. Let  $T_{\ell}$ be the left subtree of  $T_d$  of depth d - 1, and let  $T_r$  be the right subtree of depth d - 1. Let  $C_{\ell}, C_r$  be the two circuits guaranteed by induction on  $T_{\ell}, T_r$ . For  $a \in \mathbb{Z}_m$ , denote by  $f_{\ell,a}$  the polynomial computed in  $C_{\ell}$  so that the root of  $T_{\ell}$  is mapped to a, and similarly define  $f_{r,a}$ . To define the circuit for  $F_{d,a}$ , use the following:

$$F_{d,a} = \sum_{a_\ell, a_r, a \in \mathbb{Z}_m : a = a_\ell + a_r} f_{\ell, a_\ell} f_{r, a_r} x_{v_d, a},$$

Overall, we get the recursion

$$s(d) \le O(m^3) + 2 \cdot S(d-1)$$

showing that  $s(d) = O(m^3 2^d)$ .

#### 3.3 The structure of ABPs

We end this section by proving Lemma 3.

Proof of Lemma 3. Let P be an ABP computing a homogeneous polynomial f of degree r. For a vertex v in P, denote by  $h_v$  the polynomial

$$h_v = \sum_{\gamma: v_{\text{start}} \to v} \prod_{e \in \gamma} L_P(e)$$

and denote by  $g_v$  the polynomial

$$g_v = \sum_{\gamma: v \to v_{\text{end}}} \prod_{e \in \gamma} L_P(e).$$

Since the computation is monotone and f homogeneous, both  $h_v, g_v$  are homogeneous and the sum of their degrees is r. Denote by U the set of vertices v in P so that the degree of  $h_v$  is k. Every directed path from  $v_{\text{start}}$  to  $v_{\text{end}}$  in P passes through U exactly once. It follows that

$$f = \sum_{v \in U} h_v g_v,$$

as needed.

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