

Almost-Polynomial Ratio ETH-Hardness of Approximating DENSEST k -SUBGRAPH

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Abstract

In the DENSEST k -SUBGRAPH (DkS) problem, given an undirected graph G and an integer k , the goal is to find a subgraph of G on k vertices that contains maximum number of edges. Even though Bhaskara et al.'s state-of-the-art algorithm for the problem achieves only $O(n^{1/4+\epsilon})$ approximation ratio, previous attempts at proving hardness of approximation, including those under average case assumptions, fail to achieve a polynomial ratio; the best ratios ruled out under any worst case assumption and any average case assumption are only any constant (Raghavendra and Steurer) and $2^{O(\log^{2/3} n)}$ (Alon et al.) respectively.

In this work, we show, assuming the exponential time hypothesis (ETH), that there is no polynomial-time algorithm that approximates DkS to within $n^{1/(\log \log n)^c}$ factor of the optimum, where $c > 0$ is a universal constant independent of n . In addition, our result has *perfect completeness*, meaning that we prove that it is ETH-hard to even distinguish between the case in which G contains a k -clique and the case in which every induced k -subgraph of G has density at most $1/n^{-1/(\log \log n)^c}$ in polynomial time.

Moreover, if we make a stronger assumption that there is some constant $\epsilon > 0$ such that no subexponential-time algorithm can distinguish between a satisfiable 3SAT formula and one which is only $(1 - \epsilon)$ -satisfiable (also known as Gap-ETH), then the ratio above can be improved to $n^{f(n)}$ for any function f whose limit is zero as n goes to infinity (i.e. $f \in o(1)$).

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1 Introduction

In the DENSEST k -SUBGRAPH (DkS) problem, we are given an undirected graph G on n vertices and a positive integer $k \leq n$. The goal is to find a set S of k vertices such that the induced subgraph on S has maximum number of edges. Since the size of S is fixed, the problem can be equivalently stated as finding a k -subgraph (i.e. subgraph on k vertices) with maximum density where density¹ of the subgraph induced on S is $|E(S)|/\binom{|S|}{2}$ and $E(S)$ denotes the set of all edges among the vertices in S .

DENSEST k -SUBGRAPH, a natural generalization of k -CLIQUE [Kar72], was first formulated and studied by Kortsarz and Peleg [KP93] in the early 90s. Since then, it has been the subject of intense study in the context of approximation algorithm and hardness of approximation [FS97, SW98, FL01, FKP01, AHI02, Fei02, Kho06, GL09, RS10, BCC+10, AAM+11, BCV+12, Bar15, BKRW17]. Despite this, its approximability still remains wide open and is considered by some to be an important open question in approximation algorithms [BCC+10, BCV+12, BKRW17].

On the approximation algorithm front, Kortsarz and Peleg [KP93], in the same work that introduced the problem, gave a polynomial-time $\tilde{O}(n^{0.3885})$ -approximation algorithm for DkS. Feige, Kortsarz and Peleg [FKP01] later provided an $O(n^{1/3-\delta})$ -approximation for the problem for some constant $\delta \approx 1/60$. This approximation ratio was the best known for almost a decade² until Bhaskara et al. [BCC+10] invented a log-density based approach which yielded an $O(n^{1/4+\varepsilon})$ -approximation for any constant $\varepsilon > 0$. This remains the state-of-the-art approximation algorithm for DkS.

While the above algorithms demonstrate the main progresses of approximations of DkS in general case over the years, many special cases have also been studied. Most relevant to our work is the case where the optimal k -subgraph has high density, in which better approximations are known [FS97, ST08, MM15, Bar15]. The first and most representative algorithm of this kind is that of Feige and Seltser [FS97], which provides the following guarantee: when the input graph contains a k -clique, the algorithm can find an $(1 - \varepsilon)$ -dense k -subgraph in $n^{O(\log n/\varepsilon)}$ time. We will refer to this problem of finding densest k -subgraph when the input graph is promised to have a k -clique DENSEST k -SUBGRAPH *with perfect completeness*.

Although many algorithms have been devised for DkS, relatively little is known regarding its hardness of approximation. While it is commonly believed that the problem is hard to approximate to within some polynomial ratio [AAM+11, BCV+12], not even a constant factor NP-hardness of approximation is known. To circumvent this, Feige [Fei02] came up with a hypothesis that a random 3SAT formula is hard to refute in polynomial time and proved that, assuming this hypothesis, DkS is hard to approximate to within some constant factor.

Alon et al. [AAM+11] later used a similar conjecture regarding random k -AND to rule out polynomial-time algorithms for DkS with any constant approximation ratio. Moreover, they proved hardnesses of approximation of DkS under the following *Planted Clique Hypothesis* [Jer92, Kuc95]: there is no polynomial-time algorithm that can distinguish between a typical Erdős–Rényi random graph $\mathcal{G}(n, 1/2)$ and one in which a clique of size polynomial in n (e.g. $n^{1/3}$) is planted. Assuming this hypothesis, Alon et al. proved that no polynomial-time algorithm approximates DkS to within any constant factor. They also showed that, when the hypothesis is strengthened to rule out not only polynomial-time but also super-polynomial time algorithms for the Planted Clique problem, their inapproximability guarantee for DkS can be improved. In particular, if no $n^{O(\sqrt{\log n})}$ -time algorithm solves the Planted Clique problem, then $2^{O(\log^{2/3} n)}$ -approximation for DkS cannot be achieved in polynomial time.

There are also several inapproximability results of DkS based on worst-case assumptions. Khot [Kho06] showed, assuming $\text{NP} \not\subseteq \text{BPTIME}(2^{n^\varepsilon})$ for some constant $\varepsilon > 0$, that no polynomial-time algorithm can approximate DkS to within $(1 + \delta)$ factor where $\delta > 0$ is a constant depending only on ε ; the proof is based on a construction of a “quasi-random” PCP, which is then used in place of a random 3SAT in a reduction similar to that from [Fei02].

¹It is worth noting that sometimes density is defined as $|E(S)|/|S|$. For DkS, both definitions of density result in the same objective since $|S| = k$ is fixed. However, our notion is more convenient to deal with as it always lies in $[0, 1]$.

²Around the same time as Bhaskara et al.’s work [BCC+10], Goldstein and Langberg [GL09] presented an algorithm with approximation ratio $O(n^{0.3159})$, which is slightly better than [FKP01] but is worse than [BCC+10].

While no inapproximability of DkS is known under the Unique Games Conjecture, Raghavendra and Steurer [RS10] showed that a strengthened version of it, in which the constraint graph is required to satisfy a “small-set expansion” property, implies that DkS is hard to approximate to within any constant ratio.

Recently, Braverman et al. [BKRW17], showed, under the exponential time hypothesis (ETH), which will be stated shortly, that, for some constant $\varepsilon > 0$, no $n^{\tilde{O}(\log n)}$ -time algorithm can approximate DENSEST k -SUBGRAPH with perfect completeness to within $(1 + \varepsilon)$ factor. It is worth noting here that their result matches almost exactly with the previously mentioned Feige-Seltser algorithm [FS97].

Since none of these inapproximability results achieve a polynomial ratio, there have been efforts to prove better lower bounds for more restricted classes of algorithms. For example, Bhaskara et al. [BCV⁺12] provided polynomial ratio lower bounds against strong SDP relaxations of DkS. Specifically, for the Sum-of-Squares hierarchy, they showed integrality gaps of $n^{2/53-\varepsilon}$ and n^ε against $n^{\Omega(\varepsilon)}$ and $n^{1-O(\varepsilon)}$ levels of the hierarchy respectively. (See also [Man15, CMMV17] in which $2/53$ in the exponent was improved to $1/14$.) Unfortunately, it is unlikely that these lower bounds can be translated to inapproximability results and the question of whether any polynomial-time algorithm can achieve subpolynomial approximation ratio for DkS remains an intriguing open question.

1.1 Our Results

In this work, we rule out, under the exponential time hypothesis (i.e. no subexponential time algorithm can solve 3SAT; see Hypothesis 4), polynomial-time approximation algorithms for DkS (even with perfect completeness) with slightly subpolynomial ratio:

Theorem 1 *There is a constant $c > 0$ such that, assuming ETH, no polynomial-time algorithm can, given a graph G on n vertices and a positive integer $k \leq n$, distinguish between the following two cases:*

- *There exist k vertices of G that induce a k -clique.*
- *Every k -subgraph of G has density at most $n^{-1/(\log \log n)^c}$.*

If we assume a stronger assumption that it takes exponential time to even distinguish between a satisfiable 3SAT formula and one which is only $(1 - \varepsilon)$ -satisfiable for some constant $\varepsilon > 0$ (aka Gap-ETH; see Hypothesis 5), the ratio can be improved to $n^{f(n)}$ for any ³ $f \in o(1)$:

Theorem 2 *For every function $f \in o(1)$, assuming Gap-ETH, no polynomial-time algorithm can, given a graph G on n vertices and a positive integer $k \leq n$, distinguish between the following two cases:*

- *There exist k vertices of G that induce a k -clique.*
- *Every k -subgraph of G has density at most $n^{-f(n)}$.*

We remark that, for DkS with perfect completeness, the aforementioned Feige-Seltser algorithm achieves⁴ an n^ε -approximation in time $n^{O(1/\varepsilon)}$ for every $\varepsilon > 0$ [FS97]. Hence, the ratios in our theorems cannot be improved to some fixed polynomial and the ratio in Theorem 2 is tight in this sense.

Comparison to Previous Results. In terms of inapproximability ratios, the ratios ruled out in this work are almost polynomial and provides a vast improvement over previous results. Prior to our result, the best known ratio ruled out under any worst case assumption is only any constant [RS10] and the best ratio ruled out under any average case assumption is only $2^{O(\log^{2/3} n)}$ [AAM⁺11]. In addition, our results also have perfect completeness, which was only achieved in [BKRW17] under ETH and in [AAM⁺11] under the Planted Clique Hypothesis but not in [Kho06, Fei02, RS10].

Regarding the assumptions our results are based upon, the average case assumptions used in [Fei02, AAM⁺11] are incomparable to ours. The assumption $\text{NP} \not\subseteq \text{BPTIME}(2^{n^\varepsilon})$ used in [Kho06] is also incomparable to ours since, while not stated explicitly, ETH and Gap-ETH by default focus only on deterministic algorithms and our reductions are also deterministic. The strengthened Unique Games Conjecture used in [RS10] is again incomparable to ours as it is a statement that a specific problem is NP-hard. Finally, although Braverman

³Recall that $f \in o(1)$ if and only if $\lim_{n \rightarrow \infty} f(n) = 0$.

⁴This guarantee was not stated explicitly in [FS97] but it can be easily achieved by changing the degree threshold in their algorithm **DenseSubgraph** from $(1 - \varepsilon)n$ to n^ε .

et al.’s result [BKRW17] also relies on ETH, its relation to our results is more subtle. Specifically, their reduction time is only $2^{\tilde{O}(\sqrt{m})}$ where m is the number of clauses, meaning that they only need to assume that $3SAT \notin DTIME(2^{\tilde{O}(\sqrt{m})})$ to rule out a constant ratio polynomial-time approximation for DkS. However, as we will see in Theorem 8, even to achieve a constant gap, our reduction time is $2^{\tilde{\Omega}(m^{3/4})}$. Hence, if $3SAT$ somehow ends up in $DTIME(2^{\tilde{O}(m^{3/4})})$ but outside of $DTIME(2^{\tilde{O}(\sqrt{m})})$, their result will still hold whereas ours will not even imply constant ratio inapproximability for DkS.

Implications of Our Results. One of the reasons that DkS has received significant attention in the approximation algorithm community is due to its connections to many other problems. Most relevant to our work are the problems to which there are reductions from DkS that preserve approximation ratios to within some polynomial⁵. These problems include DENSEST AT-MOST- k -SUBGRAPH [AC09], SMALLEST m -EDGE SUBGRAPH [CDK12], STEINER k -FOREST [HJ06] and QUADRATIC KNAPSACK [Pis07]. For brevity, we do not define these problems here. We refer interested readers to cited sources for their definitions and reductions from DkS to respective problems. We also note that this list is by no means exhaustive and there are indeed numerous other problems with similar known connections to DkS (see e.g. [HJL⁺06, KS07, KMNT11, CHK11, HIM11, LNV14, CLLR15, CL15, CZ15, SFL15, TV15, CDK⁺16, CMVZ15, Lee16]). Our results also imply hardness of approximation results with similar ratios to DkS for such problems:

Corollary 3 *For some constant $c > 0$, assuming ETH, there is no polynomial-time $n^{1/(\log \log n)^c}$ -approximation algorithm for DENSEST AT-MOST- k -SUBGRAPH, SMALLEST m -EDGE SUBGRAPH, STEINER k -FOREST, QUADRATIC KNAPSACK. Moreover, for any function $f \in o(1)$, there is no polynomial-time $n^{f(n)}$ -approximation algorithm for any of these problems, unless Gap-ETH is false.*

2 Preliminaries and Notations

We use $\exp(x)$ and $\log(x)$ to denote e^x and $\log_2(x)$ respectively. $\text{polylog } n$ is used as a shorthand for $O(\log^c n)$ for some constant c . For any set S , $\mathcal{P}(S) := \{T \mid T \subseteq S\}$ denotes the power set of S . For any non-negative integer $t \leq |S|$, we use $\binom{S}{t} := \{T \in \mathcal{P}(S) \mid |T| = t\}$ to denote the collection of all subsets of S of size t .

Throughout this work, we only concern with simple unweighted undirected graphs. Recall that the density of a graph $G = (V, E)$ on $N \geq 2$ vertices is $|E|/\binom{N}{2}$. We say that a graph is α -dense if its density is α . Moreover, for every $t \in \mathbb{N}$, we view each element of V^t as a t -size ordered multiset of V . $(L, R) \in V^t \times V^t$ is said to be a *labelled copy of a t -biclique* (or $K_{t,t}$) in G if, for every $u \in L$ and $v \in R$, $u \neq v$ and $(u, v) \in E$. The number of labelled copies of $K_{t,t}$ in G is the number of all such (L, R) ’s.

2.1 Exponential Time Hypotheses

One of our results is based on the exponential time hypothesis (ETH), a conjecture proposed by Impagliazzo and Paturi [IP01] which asserts that $3SAT$ cannot be solved in subexponential time:

Hypothesis 4 (ETH [IP01]) *No $2^{o(m)}$ -time algorithm can decide whether any $3SAT$ formula with m clauses⁶ is satisfiable.*

Another hypothesis used in this work is Gap-ETH, a strengthened version of the ETH, which essentially states that even approximating $3SAT$ to some constant ratio takes exponential time:

Hypothesis 5 (Gap-ETH [Din16, MR16]) *There exists a constant $\varepsilon > 0$ such that no $2^{o(m)}$ -time algorithm can, given a $3SAT$ formula ϕ with m clauses⁷, distinguish between the case where ϕ is satisfiable and the case where $\text{val}(\phi) \leq 1 - \varepsilon$. Here $\text{val}(\phi)$ denote the maximum fraction of clauses of ϕ satisfied by any assignment.*

⁵These are problems whose $O(\rho)$ -approximation gives an $O(\rho^c)$ -approximation for DkS for some constant c .

⁶In its original form, the running time lower bound is exponential in the number of variables not the number of clauses; however, thanks to the sparsification lemma of Impagliazzo et al. [IPZ01], both versions are equivalent.

⁷As noted by Dinur [Din16], a subsampling argument can be used to make the number of clauses linear in the number of variables, meaning that the conjecture remains the same even when m denotes the number of variables.

2.2 Nearly-Linear Size PCPs and Subexponential Time Reductions

The celebrated PCP Theorem [AS98, ALM⁺98], which lies at the heart of virtually all known NP-hardness of approximation results, can be viewed as a polynomial-time reduction from 3SAT to a gap version of 3SAT, as stated below. While this perspective is a rather narrow viewpoint of the theorem that leaves out the fascinating relations between parameters of PCPs, it will be the most convenient for our purpose.

Theorem 6 (PCP Theorem [AS98, ALM⁺98]) *For some constant $\varepsilon > 0$, there exists a polynomial-time reduction that takes a 3SAT formula φ and produces a 3SAT formula ϕ such that*

- (Completeness) *if φ is satisfiable, then ϕ is satisfiable, and,*
- (Soundness) *if φ is unsatisfiable, then $\text{val}(\phi) \leq 1 - \varepsilon$.*

Following the first proofs of the PCP Theorem, considerable efforts have been made to improve the trade-offs between the parameters in the theorem. One such direction is to try to reduce the size of the PCP, which, in the above formulation, translates to reducing the size of ϕ relative to φ . On this front, it is known that the size of ϕ can be made nearly-linear in the size of φ [Din07, MR08, BSS08]. For our purpose, we will use Dinur’s PCP Theorem [Din07], which has a blow-up of only polylogarithmic in the size of ϕ :

Theorem 7 (Dinur’s PCP Theorem [Din07]) *For some constant $\varepsilon, d > 0$, there exists a polynomial-time reduction that takes a 3SAT formula φ with m clauses and produces another 3SAT formula ϕ with $m' = O(m \text{ polylog } m)$ clauses such that*

- (Completeness) *if φ is satisfiable, then ϕ is satisfiable, and,*
- (Soundness) *if φ is unsatisfiable, then $\text{val}(\phi) \leq 1 - \varepsilon$, and,*
- (Bounded Degree) *each variable of ϕ appears in $\leq d$ clauses.*

Note that Dinur’s PCP, combined with ETH, implies a lower bound of $2^{\Omega(m/\text{polylog } m)}$ on the running time of algorithms that solve the gap version of 3SAT, which is only a factor of $O(\text{polylog } m)$ in the exponent off from Gap-ETH. Putting it differently, Gap-ETH is closely related to the question of whether a linear size PCP, one where the size blow-up is only constant instead of polylogarithmic, exists; its existence would mean that Gap-ETH is implied by ETH.

Under the exponential time hypothesis, nearly-linear size PCPs allow us to start with an instance ϕ of the gap version of 3SAT and reduce, in subexponential time, to another problem. As long as the time spent in the reduction is $2^{o(m/\text{polylog } m)}$, we arrive at a lower bound for the problem. Arguably, Aaronson et al. [AIM14] popularized this method, under the name *birthday repetition*, by using such a reduction of size $2^{\tilde{O}(\sqrt{m})}$ to prove ETH-hardness for free games and dense CSPs. Without going into any detail now, let us mention that the name birthday repetition comes from the use of the birthday paradox in their proof and, since its publication, their work has inspired many inapproximability results [BKW15, Rub15, BPR16, MR16, Rub16b, DFS16, BKRW17]. Our result too is inspired by this line of work and, as we will see soon, part of our proof also contains a birthday-type paradox.

3 The Reduction and Proofs of The Main Theorems

The reduction from the gap version of 3SAT to DkS is simple. Given a 3SAT formula ϕ on n variables x_1, \dots, x_n and an integer $1 \leq \ell \leq n$, we construct a graph⁸ $G_{\phi, \ell} = (V_{\phi, \ell}, E_{\phi, \ell})$ as follows:

- Its vertex set $V_{\phi, \ell}$ contains all partial assignments to ℓ variables, i.e., each vertex is $\{(x_{i_1}, b_{i_1}), \dots, (x_{i_\ell}, b_{i_\ell})\}$ where $x_{i_1}, \dots, x_{i_\ell}$ are ℓ distinct variables and $b_{i_1}, \dots, b_{i_\ell} \in \{0, 1\}$ are the bits assigned to them.
- We connect two vertices $\{(x_{i_1}, b_{i_1}), \dots, (x_{i_\ell}, b_{i_\ell})\}$ and $\{(x_{i'_1}, b_{i'_1}), \dots, (x_{i'_\ell}, b_{i'_\ell})\}$ by an edge iff the two partial assignments are consistent (i.e. no variable is assigned 0 in one vertex and 1 in another), and, every clause in ϕ all of whose variables are from $x_{i_1}, \dots, x_{i_\ell}, x_{i'_1}, \dots, x_{i'_\ell}$ is satisfied by the partial assignment induced by the two vertices.

⁸For interested readers, we note that our graph is not the same as the FGLSS graph [FGL⁺91] of the PCP in which the verifier reads ℓ random variables and accepts if no clause is violated; while this graph has the same vertex set as ours, the edges are different since we check that no clause between the two vertices is violated, which is not checked in the FGLSS graph. It is possible to modify our proof to make it work for this FGLSS graph. However, the soundness guarantee for the FGLSS graph is worse.

Clearly, if $\text{val}(\phi) = 1$, the $\binom{n}{\ell}$ vertices corresponding to a satisfying assignment induce a clique. Our main technical contribution is proving that, when $\text{val}(\phi) \leq 1 - \varepsilon$, every $\binom{n}{\ell}$ -subgraph is sparse:

Theorem 8 *For any $d, \varepsilon > 0$, there exists $\delta > 0$ such that, for any 3SAT formula ϕ on n variables such that $\text{val}(\phi) \leq 1 - \varepsilon$ and each variable appears in at most d clauses and for any integer $\ell \in [n^{3/4}/\delta, n/2]$, any $\binom{n}{\ell}$ -subgraph of $G_{\phi, \ell}$ has density $\leq 2^{-\delta \ell^4/n^3}$.*

We remark that there is nothing special about 3SAT; we can start with any boolean CSP and end up with a similar result, albeit the soundness deteriorates as the arity of the CSP grows. However, it is crucial that the variables are boolean; in fact, Braverman et al. [BKRW17] considered a graph similar to ours for 2CSPs but they were unable to achieve subconstant soundness since their variables were not boolean⁹. Specifically, there is a non-boolean 2CSP with low value which results in the graph having a biclique of size $\geq \binom{n}{\ell}$ (Appendix A), i.e., one cannot get an inapproximability ratio more than two starting from a non-boolean CSP.

Once we have Theorem 8, the inapproximability results of DkS (Theorem 1 and 2) can be easily proved by applying the theorem with appropriate choices of ℓ . We defer these proofs to Subsection 3.2. For now, let us turn our attention to the proof of Theorem 8. To prove the theorem, we resort to the following lemma due to Alon [Alo02], which states that every dense graph contains many labelled copies of bicliques:

Lemma 9 ([Alo02, Lemma 2.1]¹⁰) *Any α -dense graph G on $N \geq 2$ vertices has at least $(\alpha/2)^{t^2} N^{2t}$ labelled copies of $K_{t,t}$ for all $t \in \mathbb{N}$.*

Equipped with Lemma 9, our proof strategy is to bound the number of labelled copies of $K_{t,t}$ in $G_{\phi, \ell}$ where t is to be chosen later. To argue this, we will need some additional notations:

- First, let $A_\phi := \{(x_1, 0), (x_1, 1), \dots, (x_n, 0), (x_n, 1)\}$ be the set of all single-variable partial assignments. Observe that $V_{\phi, \ell} \subseteq \binom{A_\phi}{\ell}$, i.e., each $u \in V_{\phi, \ell}$ is a subset of A_ϕ of size ℓ .
- Let $\mathcal{A} : (V_{\phi, \ell})^t \rightarrow \mathcal{P}(A_\phi)$ be a “flattening” function that, on input $T \in (V_{\phi, \ell})^t$, outputs the set of all single-variable partial assignments that appear in at least one vertex in T . In other words, when each vertex u is viewed as a subset of A_ϕ , we can write $\mathcal{A}(T)$ simply as $\bigcup_{u \in T} u$.
- Let $\mathcal{K}_{t,t} := \{(L, R) \in (V_{\phi, \ell})^t \times (V_{\phi, \ell})^t \mid \forall u \in L, \forall v \in R, u \neq v \wedge (u, v) \in E_{\phi, \ell}\}$ denote the set of all labelled copies of $K_{t,t}$ in $G_{\phi, \ell}$ and, for each $A, B \subseteq A_\phi$, let $\mathcal{K}_{t,t}(A, B) := \{(L, R) \in \mathcal{K}_{t,t} \mid \mathcal{A}(L) = A, \mathcal{A}(R) = B\}$ denote the set of all $(L, R) \in \mathcal{K}_{t,t}$ with $\mathcal{A}(L) = A$ and $\mathcal{A}(R) = B$.

The number of labelled copies of $K_{t,t}$ in $G_{\phi, \ell}$ can be written as

$$|\mathcal{K}_{t,t}| = \sum_{A, B \subseteq A_\phi} |\mathcal{K}_{t,t}(A, B)|. \quad (1)$$

To bound $|\mathcal{K}_{t,t}|$, we will prove the following bound on $|\mathcal{K}_{t,t}(A, B)|$.

Lemma 10 *Let ϕ, n, ℓ, d and ε be as in Theorem 8. There exists $\lambda > 0$ depending only on d and ε such that, for any $t \in \mathbb{N}$ and any $A, B \subseteq A_\phi$, $|\mathcal{K}_{t,t}(A, B)| \leq \left(2^{-\lambda \ell^2/n} \binom{n}{\ell}\right)^{2t}$.*

Before we prove the above lemma, let us see how Lemma 9 and Lemma 10 imply Theorem 8.

Proof of Theorem 8. Assume w.l.o.g. that $\lambda \leq 1$. Pick $\delta = \lambda^2/8$ and $t = (4/\lambda)(n^2/\ell^2)$. From Lemma 10 and (1), we have

$$|\mathcal{K}_{t,t}| \leq 2^{4n} \cdot \left(2^{-\lambda \ell^2/n} \binom{n}{\ell}\right)^{2t} \leq (2^{-\lambda \ell^2/n})^t \cdot \binom{n}{\ell}^{2t}$$

where the second inequality comes from our choice of t ; note that t is chosen so that the 2^{4n} factor is consumed by $2^{-\lambda \ell^2/n}$ from Lemma 10. Finally, consider any $\binom{n}{\ell}$ -subgraph of $G_{\phi, \ell}$. By the above bound, it contains at

⁹Any satisfiable boolean 2CSP is solvable in polynomial time so one cannot start with a boolean 2CSP either.

¹⁰The lemma is stated slightly differently in [Alo02]. Namely, it was stated there that any graph G with $\geq \varepsilon N^2$ edges contains at least $(2\varepsilon)^{t^2} N^{2t}$ labelled copies of $K_{t,t}$. The formulation here follows from the fact that α -dense graph on $N \geq 2$ vertices contains at least $(\alpha/4)N^2$ edges.

most $(2^{-\lambda\ell^2/n})^t \cdot \binom{n}{\ell}^{2t}$ labelled copies of $K_{t,t}$. Thus, from Lemma 9 and from $\ell \geq n^{3/4}/\delta$, its density is at most $2 \cdot 2^{-\lambda\ell^2/(nt)} = 2 \cdot 2^{-2\delta\ell^4/n^3} \leq 2^{-\delta\ell^4/n^3}$ as desired. \square

We now move on to the proof of Lemma 10.

Proof of Lemma 10. First, notice that if (x, b) appears in A and $(x, -b)$ appears in B for some variable x and bit b , then $\mathcal{K}_{t,t}(A, B) = \emptyset$; this is because, for any L with $\mathcal{A}(L) = A$ and R with $\mathcal{A}(R) = B$, there exist $u \in L$ and $v \in R$ that contain (x, b) and $(x, -b)$ respectively, meaning that there is no edge between u and v and, thus, $(L, R) \notin \mathcal{K}_{t,t}(A, B)$. Hence, from now on, we can assume that, if (x, b) appears in one of A, B , then the other does not contain $(x, -b)$. Observe that this implies that, for each variable x , its assignments can appear in A and B at most two times¹¹ in total. This in turn implies that $|A| + |B| \leq 2n$.

Let us now argue that $|\mathcal{K}_{t,t}(A, B)| \leq \binom{n}{\ell}^{2t}$; while this is not the bound we are looking for yet, it will serve as a basis for our argument later. For every $(L, R) \in \mathcal{K}_{t,t}(A, B)$, observe that, since $\mathcal{A}(L) = A$ and $\mathcal{A}(R) = B$, we have $L \in \binom{A}{\ell}^t$ and $R \in \binom{B}{\ell}^t$. This implies that $\mathcal{K}_{t,t}(A, B) \subseteq \binom{A}{\ell}^t \times \binom{B}{\ell}^t$. Hence,

$$|\mathcal{K}_{t,t}(A, B)| \leq \binom{|A|}{\ell}^t \binom{|B|}{\ell}^t. \quad (2)$$

Moreover, $\binom{|A|}{\ell} \binom{|B|}{\ell}$ can be further bounded as

$$\binom{|A|}{\ell} \binom{|B|}{\ell} = \frac{1}{(\ell!)^2} \prod_{i=0}^{\ell-1} (|A| - i)(|B| - i) \leq \frac{1}{(\ell!)^2} \prod_{i=0}^{\ell-1} \left(\frac{|A| + |B|}{2} - i \right)^2 \leq \binom{n}{\ell}^2 \quad (3)$$

where the inequalities come from the AM-GM Inequality and from $|A| + |B| \leq 2n$ respectively. Combining (2) and (3) indeed yields $|\mathcal{K}_{t,t}(A, B)| \leq \binom{n}{\ell}^{2t}$.

Inequality (2) is very crude; we include all elements of $\binom{A}{\ell}$ and $\binom{B}{\ell}$ as candidates for vertices in L and R respectively. However, as we will see soon, only tiny fraction of elements of $\binom{A}{\ell}, \binom{B}{\ell}$ can actually appear in L, R when $(L, R) \in \mathcal{K}_{t,t}(A, B)$. To argue this, let us categorize the variables into three groups:

- x is *terrible* iff its assignments appear at most once in total in A and B (i.e. $|\{(x, 0), (x, 1)\} \cap A| + |\{(x, 0), (x, 1)\} \cap B| \leq 1$).
- x is *good* iff, for some $b \in \{0, 1\}$, $(x, b) \in A \cap B$. Note that this implies that $(x, -b) \notin A \cup B$.
- x is *bad* iff either $\{(x, 0), (x, 1)\} \subseteq A$ or $\{(x, 0), (x, 1)\} \subseteq B$.

The next and last step of the proof is where birthday-type paradoxes come in. Before we continue, let us briefly demonstrate the ideas behind this step by considering the following extreme cases:

- If all variables are terrible, then $|A| + |B| \leq n$ and (3) can be immediately tightened.
- If all variables are bad, assume w.l.o.g. that, for at least half of variables x 's, $\{(x, 0), (x, 1)\} \subseteq A$. Consider a random element u of $\binom{A}{\ell}$. Since u is a set of random ℓ distinct elements of A , there will, in expectation, be $\Omega(\ell^2/n)$ variables x 's with $(x, 0), (x, 1) \in u$. However, the presence of such x 's means that u is not a valid vertex. Moreover, it is not hard to turn this into the following probabilistic statement: with probability at most $2^{-\Omega(\ell^2/n)}$, u contains at most one of $(x, 0), (x, 1)$ for every variable x . In other words, only $2^{-\Omega(\ell^2/n)}$ fraction of elements of $\binom{A}{\ell}$ are valid vertices, which yields the desired bound on $|\mathcal{K}_{t,t}(A, B)|$.
- If all variables are good, then $A = B$ is simply an assignment to all the variables. Since $\text{val}(\phi) \leq 1 - \varepsilon$, at least εm clauses are unsatisfied by this assignment. As we will argue below, every element of $\binom{A}{\ell}$ that contains two variables from some unsatisfied clause cannot be in L for any $(L, R) \in \mathcal{K}_{t,t}(A, B)$. This means that there are $\Theta_\varepsilon(m) \geq \Omega_\varepsilon(n)$ prohibited pairs of variables that cannot appear together. Again, similar to the previous case, it is not hard to argue that only $2^{-\Omega_{\varepsilon, a}(\ell^2/n)}$ fraction of elements of $\binom{A}{\ell}$ can be candidates for vertices of L .

¹¹This is where we use the fact that the variables are boolean. For non-boolean CSPs, each variable x can appear more than two times in one of A or B alone, which can indeed be problematic (see Appendix A).

To turn this intuition into a bound on $|\mathcal{K}_{t,t}(A, B)|$, we need the following inequality. Its proof is straightforward and is deferred to Subsection 3.1.

Proposition 11 *Let U be any set and $P \subseteq \binom{U}{2}$ be any set of pairs of elements of U such that each element of U appears in at most q pairs. For any positive integer $2 \leq r \leq |U|$, the probability that a random element of $\binom{U}{r}$ does not contain both elements of any pair in P is at most $\exp\left(-\frac{|P|r^2}{4q|U|^2}\right)$.*

We are now ready to formalize the above intuition and finish the proof of Lemma 10. For the sake of convenience, denote the sets of good, bad and terrible variables by X_g, X_b and X_t respectively. Moreover, let $\beta := \varepsilon/(100d)$ and pick $\lambda = \min\{-\log(1 - \beta/2), \beta/64, \varepsilon/(384d)\}$. To refine the bound on the size of $\mathcal{K}_{t,t}(A, B)$, consider the following three cases:

1. $|X_t| \geq \beta n$. Since each $x \in X_t$ contributes at most one to $|A| + |B|$, $|A| + |B| \leq (1 - \beta/2)(2n)$. Hence, we can improve (3) to $\binom{|A|}{\ell} \binom{|B|}{\ell} \leq \binom{(1-\beta/2)n}{\ell}^2$. Thus, we have

$$|\mathcal{K}_{t,t}(A, B)| \stackrel{(2)}{\leq} \binom{|A|}{\ell}^t \binom{|B|}{\ell}^t \leq \binom{(1-\beta/2)n}{\ell}^{2t} \leq \left((1-\beta/2)^\ell \binom{n}{\ell}\right)^{2t} \leq \left(2^{-\lambda \ell^2/n} \binom{n}{\ell}\right)^{2t}$$

where the last inequality comes from $\lambda \leq -\log(1 - \beta/2)$ and $\ell > \ell^2/n$.

2. $|X_b| \geq \beta n$. Since each $x \in X_b$ appears either in A or B , one of A and B must contain assignments to at least $(\beta/2)n$ variables in X_b . Assume w.l.o.g. that A satisfies this property. Let X_b^L be the set of all $x \in X_b$ whose assignments appear in A . Note that $|X_b^L| \geq (\beta/2)n$. Observe that an element $u \in \binom{A}{\ell}$ is not a valid vertex if it contains both $(x, 0)$ and $(x, 1)$ for some $x \in X_b^L$. We invoke Proposition 11 with $U = A$, $P = \{(x, 0), (x, 1) \mid x \in X_b^L\}$, $q = 1$ and $r = \ell$, which implies that a random element of $\binom{A}{\ell}$ does not contain any prohibited pairs in P with probability at most $\exp\left(-\frac{|X_b^L|\ell^2}{4|A|^2}\right) \leq \exp\left(-\frac{(\beta/2)n\ell^2}{4(2n)^2}\right)$, which is at most $2^{-2\lambda \ell^2/n}$ because $\lambda \leq \beta/64$. In other words, at most $2^{-2\lambda \ell^2/n}$ fraction of elements of $\binom{A}{\ell}$ are valid vertices. This gives us the following bound:

$$|\mathcal{K}_{t,t}(A, B)| \leq \left(2^{-2\lambda \ell^2/n} \cdot \binom{|A|}{\ell}\right)^t \cdot \binom{|B|}{\ell}^t \stackrel{(3)}{\leq} \left(2^{-\lambda \ell^2/n} \binom{n}{\ell}\right)^{2t}.$$

3. $|X_t| < \beta n$ and $|X_b| < \beta n$. In this case, $|X_g| > (1 - 2\beta)n$. Let S denote the set of clauses whose variables all lie in X_g . Since each variable appears in at most d clauses, $|S| > m - (2\beta n)d \geq (1 - \varepsilon/2)m$ where the second inequality comes from our choice of β and from $m \geq n/3$.

Consider the partial assignment $f : X_g \rightarrow \{0, 1\}$ induced by A and B , i.e., $f(x) = b$ iff $(x, b) \in A, B$. Since $\text{val}(\phi) \leq 1 - \varepsilon$, the number of clauses in S satisfied by f is at most $(1 - \varepsilon)m$. Hence, at least $\varepsilon m/2$ clauses in S are unsatisfied by f . Denote the set of such clauses by S_{UNSAT} .

Fix a clause $C \in S_{\text{UNSAT}}$ and let x, y be two different variables in C . We claim that x, y cannot appear together in any vertex of L for any $(L, R) \in \mathcal{K}_{t,t}(A, B)$. Suppose for the sake of contradiction that $(x, f(x))$ and $(y, f(y))$ both appear in $u \in L$ for some $(L, R) \in \mathcal{K}_{t,t}(A, B)$. Let $z \in X_g$ be another variable¹² in C . Since $(z, f(z)) \in B$, some vertex $v \in R$ contains $(z, f(z))$. Thus, there is no edge between u and v in $G_{\phi, \ell}$, which contradicts with $(L, R) \in \mathcal{K}_{t,t}$.

We can now appeal to Proposition 11 with $U = A$, $q = 2d$, $r = \ell$ and P be the prohibited pairs described above. This implies that with probability at most $\exp\left(-\frac{|P|\ell^2}{8d|A|^2}\right) \leq \exp\left(-\frac{\varepsilon \ell^2}{192dn}\right)$, a random element of $\binom{A}{\ell}$ contains no prohibited pair from P . In other words, at most $\exp\left(-\frac{\varepsilon \ell^2}{192dn}\right)$ fraction of elements of $\binom{A}{\ell}$ can be candidates for each element of L for $(L, R) \in \mathcal{K}_{t,t}(A, B)$. This gives the following bound:

$$|\mathcal{K}_{t,t}(A, B)| \leq \left(\exp\left(-\frac{\varepsilon \ell^2}{192dn}\right) \cdot \binom{|A|}{\ell}\right)^t \cdot \binom{|B|}{\ell}^t \stackrel{(3)}{\leq} \left(2^{-\varepsilon \ell^2/(384dn)} \cdot \binom{n}{\ell}\right)^{2t}.$$

Since we picked $\lambda \leq \varepsilon/(384d)$, $|\mathcal{K}_{t,t}(A, B)|$ is once again bounded above by $\left(2^{-\lambda \ell^2/n} \binom{n}{\ell}\right)^{2t}$.

¹²If C contains two variables, let $z = x$. Note that we can assume w.l.o.g. that C contains at least two variables.

In all three cases, we have $|\mathcal{K}_{t,t}(A, B)| \leq \left(2^{-\lambda \ell^2/n} \binom{n}{\ell}\right)^{2t}$, completing the proof of Lemma 10. \square

3.1 Proof of Proposition 11

Proof of Proposition 11. We first construct $P' \subseteq P$ such that each element of U appears in at most one pair in P' as follows. Start out by marking every pair in P as active and, as long as there are active pairs left, include one in P' and mark every pair that shares an element of U with this pair as inactive. Since each element of U appears in at most q pairs in P , we mark at most $2q$ pairs as inactive per each inclusion. This implies that $|P'| \geq |P|/(2q)$.

Suppose that $P' = \{\{a_1, b_1\}, \dots, \{a_{|P'|}, b_{|P'|}\}\}$ where $a_1, b_1, \dots, a_{|P'|}, b_{|P'|}$ are distinct elements of U . Let u be a random element of $\binom{U}{r}$. For each $i = 1, \dots, |P'|$, we have

$$\begin{aligned} \Pr[\{a_i, b_i\} \not\subseteq u] &= 1 - \frac{\binom{|U|-2}{r-2}}{\binom{|U|}{r}} \\ &= 1 - \frac{r(r-1)}{|U|(|U|-1)} \\ (\text{Since } r-1 \geq r/2 \text{ for all } r \geq 2) &\leq 1 - \frac{r^2}{2|U|^2} \\ (\text{Since } 1-z \leq \exp(-z) \text{ for all } z \in \mathbb{R}) &\leq \exp\left(-\frac{r^2}{2|U|^2}\right). \end{aligned}$$

If u does not contain both elements of any pairs in P , it does not contain both elements of any pairs in P' . The probability of the latter can be written as

$$\Pr\left[\bigwedge_{i=1}^{|P'|} \{a_i, b_i\} \not\subseteq u\right] = \prod_{i=1}^{|P'|} \Pr\left[\{a_i, b_i\} \not\subseteq u \mid \bigwedge_{j=1}^{i-1} \{a_j, b_j\} \not\subseteq u\right].$$

In addition, since $a_1, b_1, \dots, a_{|P'|}, b_{|P'|}$ are distinct, it is not hard to see that $\Pr\left[\{a_i, b_i\} \not\subseteq u \mid \bigwedge_{j=1}^{i-1} \{a_j, b_j\} \not\subseteq u\right] \leq \Pr[\{a_i, b_i\} \not\subseteq u]$. Hence, we have

$$\Pr\left[\bigwedge_{i=1}^{|P'|} \{a_i, b_i\} \not\subseteq u\right] = \prod_{i=1}^{|P'|} \Pr[\{a_i, b_i\} \not\subseteq u] \leq \left(\exp\left(-\frac{r^2}{2|U|^2}\right)\right)^{|P'|} = \exp\left(-\frac{|P'|r^2}{2|U|^2}\right) \leq \exp\left(-\frac{|P|r^2}{4q|U|^2}\right),$$

completing the proof of Proposition 11. \square

3.2 Proofs of Inapproximability Results of DkS

In this subsection, we prove Theorem 1 and 2. The proof of Theorem 1 is simply by combining Dinur's PCP Theorem and Theorem 8 with $\ell = m/\text{polylog } m$, as stated below.

Proof of Theorem 1. For any 3SAT formula φ with m clauses, use Theorem 7 to produce ϕ with $m' = O(m \text{ polylog } m)$ clauses such that each variable appears in at most d clauses. Let ζ be a constant such that $m' = O(m \log^\zeta m)$ and let $\ell = m/\log^2 m$. Let us consider the graph $G_{\phi, \ell}$ with $k = \binom{n}{\ell}$ where n is the number of variables of ϕ . Let N be the number of vertices of $G_{\phi, \ell}$. Observe that $N = 2^\ell \binom{n}{\ell} \leq n^{2\ell} \leq (m')^{O(\ell)} = 2^{O(\ell \log m')} = 2^{o(m)}$.

If φ is satisfiable, ϕ is also satisfiable and it is obvious that $G_{\phi, \ell}$ contains an induced k -clique. Otherwise, If φ is unsatisfiable, $\text{val}(\phi) \leq 1 - \varepsilon$. From Theorem 8, any k -subgraph of $G_{\phi, \ell}$ has density at most $2^{-\Omega(\ell^4/n^3)} \leq 2^{-\Omega(m/\log^{3\zeta+8} m)} = N^{-\Omega(1/(\log \log N)^{3\zeta+8})}$, which is at most $N^{-1/(\log \log N)^{3\zeta+9}}$ when m is sufficiently large. Hence, if there is a polynomial-time algorithm that can distinguish between the two cases in Theorem 1 when $c = 3\zeta + 9$, then there also exists an algorithm that solves 3SAT in time $2^{o(m)}$, contradicting with ETH. \square

The proof of Theorem 2 is even simpler since, under Gap-ETH, we have the gap version of 3SAT to begin with. Hence, we can directly apply Theorem 8 without going through Dinur’s PCP:

Proof of Theorem 2. Let ϕ be any 3SAT formula with m clauses such that each variable appears in $O(1)$ clauses¹³. Let $\ell = m^{\frac{5}{\sqrt{f(m)}}$ and consider the graph $G_{\phi,\ell}$ with $k = \binom{n}{\ell}$ where n is the number of variables of ϕ . The number of vertices N of $G_{\phi,\ell}$ is $2^\ell \binom{n}{\ell} \leq 2^\ell \left(\frac{en}{\ell}\right)^\ell \leq 2^{O(\ell \log(m/\ell))} = 2^{O(m^{\frac{5}{\sqrt{f(m)}}} \log(1/f(m)))} = 2^{o(m)}$ where the last inequality follows from $f \in o(1)$.

The completeness is again obvious. For the soundness, if $\text{val}(\phi) \leq 1 - \varepsilon$, from Theorem 8, any k -subgraph of $G_{\phi,\ell}$ has density at most $2^{-\Omega(\ell^4/n^3)} \leq 2^{-\Omega(mf(m)^{4/5})} \leq N^{-\Omega(f(m)^{4/5})}$, which is at most¹⁴ $N^{-f(N)}$ when m is sufficiently large. Hence, if there is a polynomial-time algorithm that can distinguish between the two cases in Theorem 2, then there also exists an algorithm that solves the gap version of 3SAT in time $2^{o(m)}$, contradicting with Gap-ETH. \square

4 Conclusion and Open Questions

In this work, we provide a subexponential time reduction from the gap version of 3SAT to DkS and prove that it establishes an almost-polynomial ratio hardness of approximation of the latter under ETH and Gap-ETH. Even with our results, however, approximability of DkS still remains wide open. Namely, it is still not known whether it is NP-hard to approximate DkS to within some constant factor, and, no polynomial ratio hardness of approximation is yet known.

Although our results appear to almost resolve the second question, it still seems out of reach with our current knowledge of hardness of approximation. In particular, to achieve a polynomial ratio hardness for DkS, it is plausible that one has to prove a long-standing conjecture called *the sliding scale conjecture (SSC)* [BGLR93]. In short, SSC essentially states that LABEL COVER, a problem used as starting points of almost all NP-hardness of approximation results, is NP-hard to approximate to within some polynomial ratio. Note here that polynomial ratio hardness for LABEL COVER is not even known under stronger assumptions such as ETH or Gap-ETH; we refer the readers to [Din16] for more detailed discussions on the topic.

Apart from the approximability of DkS, our results also prompt the following natural question: since previous techniques, such as Feige’s Random 3SAT Hypothesis [Fei02], Khot’s Quasi-Random PCP [Kho06], Unique Games with Small Set Expansion Conjecture [RS10] and the Planted Clique Hypothesis [Jer92, Kuč95], that were successful in showing inapproximability of DkS also gave rise to hardnesses of approximation of many problems that are not known to be APX-hard including SPARSEST CUT, MIN BISECTION, BALANCED SEPARATOR, MINIMUM LINEAR ARRANGEMENT and 2-CATALOG SEGMENTATION [AMS07, Sak10, RST12], is it possible to modify our construction to prove inapproximability for these problems as well? An evidence suggesting that this may be possible is the case of ε -approximate Nash Equilibrium with ε -optimal welfare, which was first proved to be hard under the Planted Clique Hypothesis by Hazan and Krauthgamer [HK11] before Braverman, Ko and Weinstein proved that the problem was also hard under ETH [BKW15].

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¹³We can assume w.l.o.g. that each variable appears in at most $O(1)$ clauses [MR16, p.21].

¹⁴Assume w.l.o.g. that f is decreasing; otherwise take $f'(m) = \sup_{m' \geq m} f(m')$ instead.

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A A Counterexample to Obtaining a Subconstant Soundness from Non-Boolean CSPs

Here we sketch an example due to Rubinfeld [Rub16a] of a non-boolean 2CSP ϕ with low value for which the graph $G_{\phi,\ell}$ contains a large biclique. For a non-boolean 2CSP, we define the graph $G_{\phi,\ell}$ similar to that of a 3SAT formula except that now the vertices contains all $\{(x_{i_1}, \sigma_{i_1}), \dots, (x_{i_\ell}, \sigma_{i_\ell})\}$ for all distinct variables $x_{i_1}, \dots, x_{i_\ell}$ and all $\sigma_{i_1}, \dots, \sigma_{i_\ell} \in \Sigma$ where Σ is the alphabet of the CSP.

Consider any non-boolean 2CSP instance ϕ on variables x_1, \dots, x_n such that there is no constraint between $X_1 := \{x_1, \dots, x_{n/2}\}$ and $X_2 = \{x_{n/2+1}, \dots, x_n\}$ and each variable appears in $\leq d$ constraints. Let L the set of all vertices u such that every variable in u belongs to X_1 and no constraint is contained in u . Define R

similarly for X_2 . Clearly, (L, R) forms a biclique and it is not hard to see that $|L|, |R| \geq |\Sigma|^\ell \binom{n/2 - (d+1)\ell}{\ell}$. Since $|\Sigma| \geq 3$, this value is $\geq \binom{n}{\ell}$ for all $\ell \leq \frac{n}{6(d+2)}$. Hence, for such ℓ , $G_{\phi, \ell}$ contains a biclique of size $\binom{n}{\ell}$.

Finally, note that there are several ways to define constraints within X_1 and X_2 so that $\text{val}(\phi)$ is bounded away from one. For instance, we can make each side a random 2-XOR formula, which results in $\text{val}(\phi) \leq 1/2 + O(1/d)$. Thus, if we start from a non-boolean CSP, the largest gap we can hope to get is only two.

Note that the instance above is rather extreme as it consists of two disconnected components. Hence, it is still possible that, if the starting CSP has more specific properties (e.g. expanding constraint graph), then one can arrive at a gap of more than two.