

PPSZ on CSP Instances with Multiple Solutions

Dominik Scheder

October 31, 2018

Abstract

We study the success probability of the PPSZ algorithm on (d, k) -CSP formulas. We greatly simplify the analysis of Hertli, Hurbain, Millius, Moser, Szedlák, and myself for the notoriously difficult case that the input formula has more than one satisfying assignment.

1 Introduction

A (d, k) -CSP formula F over a variable set V is a bunch of constraints $C_1 \wedge \dots \wedge C_m$, where each C_i is an arbitrary constraint on k variables from V . Each variable takes on a value from $[d] := \{1, \dots, d\}$, and F is *satisfied* if all constraints are satisfied. We assume that d and k are constants, so each C_i can be represented explicitly, by its truth table, for example. We are interested in the decision problem (d, k) -CSP, which asks whether a given (d, k) -CSP formula is satisfiable. For $d = 2$, this is the well-known k -SAT problem. Note that $(d, 2)$ -CSP contains d -colorability as a special case. The problem is NP-complete except for the trivial cases $k = 1$ or $d = 1$ and the non-trivial case of $(2, 2)$ -CSP, which is 2-SAT and has a polynomial-time algorithm.

All other cases are NP-complete, and much effort has been invested into finding *moderately exponential* algorithms, that is, algorithms solving (d, k) -CSP in time c^n for some $c < d$. For example, Schöning's famous random walk algorithm [11] runs in time $O\left(\left(\frac{d(k-1)}{k}\right)^n \cdot \text{poly}(n)\right)$, or more precisely runs in polynomial time and returns a satisfying assignment, if there is one, with probability at least $O\left(\left(\frac{d(k-1)}{k}\right)^{-n} / \text{poly}(n)\right)$. Another example is PPZ [8], named after its authors Paturi, Pudlák, and Zane. Originally stated only

for k -SAT, it runs in polynomial time and has success probability at least $2^{-n+n/k}$. It has a straightforward generalization to (d, k) -CSP. For $(d, 2)$ -CSP, it has been analyzed by Feder and Motwani [2]. For general (d, k) -CSP, Li, Li, Liu, and Xu [6] give a sub-optimal analysis, which has later been improved by myself [9].

Concerning (conditional) lower bounds, Patrick Traxler [12] showed that under the Exponential Time Hypothesis [5], $(d, 2)$ -CSP takes time at least d^{cn} , for some $c > 0$. That is, an algorithm of running time $f(d) \cdot 100^n$ solving $(d, 2)$ -CSP for all d is impossible under ETH. This stands in contrast to d -colorability, which is a special case of $(d, 2)$ -CSP and can be solved in $O(2^n \text{poly}(n))$ by a clever application of the Exclusion-Inclusion technique [1].

In this paper, we study the famous PPSZ algorithm [7] by Paturi, Pudlák, Saks, and Zane. Originally, this algorithm has been designed for k -SAT. Hertli, Hurbain, Millius, Moser, Szedlák, and myself give a version for (d, k) -CSP and analyze its success probability. Here, we greatly simplify their analysis for the notoriously difficult case that the input formula has more than one satisfying assignment. This is itself a generalization of a recent paper by Steinberger and myself [10], who simplify Timon Hertli’s breakthrough analysis of PPSZ for k -CNF formulas (i.e., $d = 2$) that have more than one satisfying assignment.

1.1 The Algorithm

The algorithm PPSZ, named after its inventors Paturi, Pudlák, Saks, and Zane [7], is the currently fastest algorithm for solving k -SAT. It is a randomized algorithm, and analyzing its success probability is famously difficult. However, it is very easy to state informally. Let us sketch the algorithm when applied to a (d, k) -CSP formula F :

PPSZ Algorithm, Informally. Process the variables of F in random order; when processing variable x , check for each color $c \in [d]$ whether $F|_{x=c}$ is “obviously unsatisfiable”. If so, remove it from $[d]$. Let $P_x(F)$ be the remaining set of colors, i.e., those $c \in [d]$ for which $F|_{x=c}$ is not obviously unsatisfiable. Select $c \in P_x(F)$ uniformly at random and set $F := F|_{x=c}$. Then iterate.

Of course, to make this a formal algorithm, we have to state what it means to be “obviously unsatisfiable”. First of all, let $S_x(F)$ be the set of all $c \in [d]$ such that $F|_{x=c}$ is satisfiable. Obviously $1 \leq |S_x(F)| \leq d$ if F is a satisfiable (d, k) -CSP formula. Second, suppose the algorithm has access to a proof

heuristic P which, for every (d, k) -CSP formula F and variable x , outputs a set $P_x(F)$ with $S_x(F) \subseteq P_x(F) \subseteq [d]$. Note that P is *sound*, meaning that $c \notin P_x(F)$ implies that $F|_{x=c}$ is unsatisfiable. It might, however, be *incomplete*, namely if $S_x(F) \subsetneq P_x(F)$. We call $S_x(F)$ the set of *satisfiable colors* and $P_x(F)$ the set of *plausible colors*.

Algorithm 1 Generic PPSZ Procedure for Fixed Permutation

```

1: procedure ppsz_fixed( $F, P, \pi$ )
2:    $\beta :=$  the empty assignment on  $V$ 
3:   for  $x \in V$  in the order of  $\pi$  do
4:     Select  $c \in P_x(F|_\beta)$  uniformly at random
5:      $\beta(x) := c$ 
6:   end for
7:   return  $\beta$ 
8: end procedure

```

Algorithm 2 Generic PPSZ Procedure

```

1: procedure ppsz( $F, P$ )
2:    $\pi :=$  a uniformly random permutation of  $\text{var}(F)$ 
3:   return ppsz_fixed( $F, P, \pi$ )
4: end procedure

```

It is understood that `ppsz_fixed` returns `failure` if the set $P(F|_\beta, x)$ is empty at any point in Line 4, or if β does not satisfy F . Let $\text{var}(F)$ denote the set of variables in F and $\text{sat}(F)$ the set of satisfying assignments. Let π a permutation of $\text{var}(F)$, $x \in \text{var}(F)$, and $\alpha \in \text{sat}(F)$. We write $F|_{\pi, x, \alpha}$ to denote the formula that arises if we fix y to $\alpha(y)$ for all variables y that appear before x in π . Write $S_x(F, \pi, \alpha) := S_x(F|_{\pi, x, \alpha})$ and $P_x(F, \pi, \alpha) := P_x(F|_{\pi, x, \alpha})$. If F is understood, we might write $S_x(\pi, \alpha)$ and $P_x(\pi, \alpha)$ for brevity. We can give an exact formula for the success probability of PPSZ in terms of these expressions:

Observation 1. *Let α be a satisfying assignment of F . The probability that `ppsz_fixed`(F, P, π) returns α is $\prod_{x \in \text{var}(F)} \frac{1}{|P_x(F, \pi, \alpha)|}$.*

Using this observation, one calculates:

$$\begin{aligned}
\Pr[\text{ppsz}(F, P) = \alpha] &= \mathbb{E}_{\pi} \left[\prod_{x \in \text{var}(F)} \frac{1}{|P_x(F, \pi, \alpha)|} \right] \\
&= \mathbb{E}_{\pi} \left[2^{-\sum_{x \in \text{var}(F)} \log |P_x(F, \pi, \alpha)|} \right] \\
&\geq 2^{-\sum_{x \in \text{var}(F)} \mathbb{E}_{\pi} [\log |P_x(F, \pi, \alpha)|]} .
\end{aligned} \tag{1}$$

Next, we define a way to gauge the power of P .

Definition 2. *Let P be a proof heuristic. We say P has error rate at most γ against (d, k) -CSP formulas if $\mathbb{E}_{\pi} [\log |P_x(F, \pi, \alpha)|] \leq \gamma$ for all (d, k) -CSP formulas F , all $\alpha \in \text{sat}(F)$, and all $x \in \text{var}(F)$ for which $|S_x(F)| = 1$.*

We need the condition $|S_x(F)| = 1$ since otherwise we cannot state anything useful about $P_x(F, \pi, \alpha)$. For example, it might simply be that $S_x(F) = [d]$ and $P_x(F, \pi, \alpha) = [d]$ for all π and α . Of course, one might be able to bound $\mathbb{E}_{\pi} [\log |P_x(F, \pi, \alpha)|]$ if $|S_x(F)| = 2$, say. However, we do not know how to use such a bound.

Observation 3. *If F is a (d, k) -CSP formula with a unique satisfying assignment α , and P has error rate at most γ against (d, k) -CSP formulas, then $\Pr[\text{ppsz}(F, P) = \alpha] \geq 2^{-\gamma n}$.*

XXX move to top: This follows from (1) since $|S_x(F)| = |\{\alpha(x)\}| = 1$ for all variables x .

1.2 Which Error Rates Are Possible

In [4], Hertli, Hurbain, Millius, Moser, Szeglák, and myself have analyzed the “usual” proof heuristic P_D : it checks whether there is a set $G \subseteq F$ of D constraints for which $G|_{x=c}$ is unsatisfiable (and includes c into $P_x(F)$ if this is not the case). The parameter D is usually taken to be some slowly increasing function $D(n)$, slowly enough so that P_D can be implemented to run in time $2^{o(n)}$. It was shown in [4] that P_D has error rate at most $\gamma_{d,k} + o_D(1)$. Here, $\gamma_{d,k}$ can be defined by the following random experiment (next paragraph copied almost literally from [4]):

Let T be an infinite rooted tree in which every even-level vertex (this includes the root, which has level 0) has $k - 1$ children, and every odd-level vertex has $d - 1$ children (there are no leaves). Take $d - 1$ disjoint copies of T , choose a value $p \in [0, 1]$ uniformly

at random, and delete each odd-level vertex of the $d - 1$ trees with probability p , independently. Let Y be the number of trees in which this deletion still leaves an infinite path starting at the root. Obviously, Y is a random variable and $0 \leq Y \leq d - 1$. Define $\gamma_{d,k} := \mathbb{E}[\log(1 + Y)]$.

Lemma 4 (Lemma 2.5 from [4]). P_D has error rate at most $\gamma_{d,k} + o(1)$ against (d, k) -CSP formulas.

Observation 3 immediately implies the following theorem:

Theorem 5 (Theorem 1.1 from [4]). *Let F be a (d, k) -CSP formula over n variables. If F has a unique satisfying assignment, then PPSZ outputs it with probability at least $2^{-\gamma_{d,k}n - o(n)}$.*

The theorem, as stated, raises the obvious question whether we can remove the condition that F have a unique satisfying assignment. For $d = 2$ (the Boolean case, k -SAT), and $k \geq 5$, this has already been proved by Paturi, Pudlák, Saks, and Zane [7]. Unfortunately, their proof ceases to work for $k = 3, 4$ and has to look inside P_D in great detail. In a breakthrough paper, Hertli [3] gave a more abstract proof that also works for $d = 3, 4$, and works for almost any proof heuristic P . Still, his proof is very technical and somewhat obscure. Also, it only works provided that P is “not too strong”, i.e., only as long as its error rate γ is at least $1 - \frac{\log(e)}{2}$. Since this holds for the concrete heuristic P_D , this is a purely hypothetical limitation to his proof. We simply don’t know of any proof heuristic that runs in subexponential time and has an error rate less than $1 - \frac{\log(e)}{2}$. In [4], Hertli, Hurbain, Millius, Moser, Szegedy, and myself generalize Hertli’s result to (d, k) -CSP problems:

Definition 6. *A proof heuristic P is monotone if $P_x(F|_{y=c}) \subseteq P_x(F)$, for all formulas F , variables $x \neq y$, and colors c .*

Intuitively, this very mild condition states that adding information can never hurt the heuristic. The reader is welcome to verify that P_D is monotone.

Theorem 7 (Theorem 1.2 from [4]). *Let F be a satisfiable (d, k) -CSP and P a monotone proof heuristic of error rate at most γ against (d, k) -CSP formulas. Then $\text{ppsz}(F, P)$ finds a satisfying assignment of F with probability at least $2^{-\gamma'n - o(n)}$, where $\gamma' = \max(\gamma, \theta_d)$ and $\theta_d := \log(d) - \frac{\log(e)}{2}$.*

Lemma 1.3 of [4] states that for $k \geq 4$ it holds that $\gamma_{d,k} \geq \theta_d$, and thus the bound of Theorem 7 matches that of Theorem 5, when using P_D as proof heuristic. The same is true for $d = 2$ (the Boolean case). However, if $k = 2$ and $d \geq 3$ or if $k = 3$ and $d \geq 6$, it happens that $\gamma_{d,k} < \theta_d$, and thus Hertli’s hypothetical limitation of too strong a proof heuristic suddenly becomes real.

1.3 Our Contribution

In this paper, we reprove Theorem 7, giving a proof that is simpler, shorter, and more accessible than the original one from [4]. This builds upon work from Steinberger and myself [10], who simplified Hertli's proof for $d = 2$. However, the non-Boolean case $d \geq 3$ comes with additional subtleties that need to be addressed. Our proof also highlights where the mysterious θ_d comes from.

1.4 Open Questions

We suspect that Theorem 7 holds true when we replace γ' by γ . That is, the limitation $\gamma \geq \theta_d$ is simply an artifact of the proof. However, we currently cannot prove this, not even for the Boolean case $d = 2$.

2 Proof of Theorem 7

For a CSP formula F and $x \in \text{var}(F)$, recall that $S_x(F)$ denotes the set of satisfying colors, i.e., the set of all $c \in [d]$ such that $F|_{x=c}$ is satisfiable. Let $S(F)$ be the set $\{(x, c) \in \text{var}(F) \times [d] \mid c \in S_x(F)\}$. If F is unsatisfiable then $S(F)$ is obviously empty. Otherwise, $|S(F)|$ is at least n and at most dn . Recall that $F|_{\pi, x, \alpha}$ denotes the formula that arises if we fix y to $\alpha(y)$ for all variables y that appear before x in π , and $S_x(F, \pi, \alpha) := S_x(F|_{\pi, x, \alpha})$ and $P_x(F, \pi, \alpha) := P_x(F|_{\pi, x, \alpha})$. If F is understood, we might write $S_x(\pi, \alpha)$ and $P_x(\pi, \alpha)$ for brevity.

For a satisfiable formula F , consider the following process R_F : Start with $F' := F$. Sample a pair $(x, c) \in S(F)$ uniformly at random and set $F' := F'|_{x=c}$. Then continue until all variables have been set. Let π denote the order in which the variables have been chosen and let α denote the resulting satisfying assignment. This defines a probability distribution R_F , or simply R , if F is understood.

Observation 8. $R(\pi, \alpha) = \prod_{x \in \text{var}(F)} \frac{1}{|S_x(F|_{\pi, x, \alpha})|}$.

As an aside, suppose we call $\text{ppsz}(F, S)$, i.e., we give it access to a complete proof heuristic (which is computationally intractable, of course). Since S is complete, it will never output **failure**. Denote by $Q(\pi, \alpha)$ the probability that PPSZ chooses π and outputs α . One checks that $Q(\pi, \alpha) = \frac{1}{n!} \cdot \prod_{x \in \text{var}(F)} \frac{1}{|S_x(\pi, \alpha)|}$. The reader is invited to check three things: first, Q and R are indeed different probability distributions. Second, and less obviously, Q and R induce the same marginal distribution on $\text{sat}(F)$ if $d = 2$,

i.e., in the Boolean case. This is mentioned, without proof, in Scheder and Steinberger [10]. Third, once $d \geq 3$, however, those marginal distributions are not the same in general.

One of the difficulties in proving Theorem 7 is that, if F is multiple satisfying assignments, the bound in (1) can be exponentially smaller than $2^{-\gamma n}$. In fact, it can be exponentially small even for the complete proof heuristic ($\gamma = 0$). Steinberger and myself [10] exhibit a CNF formula with this behavior. This problem disappears once we do not apply Jensen's inequality to the uniform distribution over π (as in the derivation of (1), but "skew" that distribution using the R defined above. In what follows, we treat $P_x(\pi, \alpha)$ and $S_x(\pi, \alpha)$ as random variables over the probability space $\text{Sym}(\text{var}(F)) \times \text{sat}(F)$ and sometimes drop the argument, i.e., write P_x and S_x if π, α are understood from the context.

$$\begin{aligned} \Pr[\text{success}] &= \sum_{\alpha} \mathbb{E}_{\pi} \left[\prod_x \frac{1}{|P_x(\pi, \alpha)|} \right] = \sum_{\pi, \alpha} \frac{1}{n!} \prod_x \frac{1}{|P_x|} \\ &= \mathbb{E}_{(\pi, \alpha) \sim R} \left[\frac{1}{n! R(\pi, \alpha)} \prod_x \frac{1}{|P_x|} \right] \\ &\geq 2^{-\mathbb{E}_R[\log(n! R(\pi, \alpha))] - \sum_x \mathbb{E}_R[\log |P_x|]}. \end{aligned} \tag{2}$$

To complete the proof, it suffices to prove the following lemma.

Lemma 9. $\mathbb{E}_R[\log(n! R(\pi, \alpha))] + \sum_x \mathbb{E}_R[\log |P_x|] \leq \gamma' n$.

Proof. Recall that $S_x = S_x(\pi, \alpha)$ is the set of satisfying colors for x at the point in time when x is processed. Let L_x be the indicator variable that is 1 if $|S_x| \geq 2$ and 0 otherwise. We call x *frozen in F* if $|S_x(F)| = 1$, and *liquid* otherwise. Thus, L_x is the indicator variable of x being liquid. Recall that P has error rate at most γ , and $\gamma' := \max\left(\gamma, \log(d) - \frac{\log(e)}{2}\right)$. Let $\epsilon := \log(d) - \gamma' = \min\left(\log(d) - \gamma, \frac{\log(e)}{2}\right)$.

Lemma 10. $\mathbb{E}_R[\log |P_x|] \leq \gamma' + \mathbb{E}_R[\epsilon L_x]$.

Proof. Let the R process run until one of two things happens: (1) x freezes, i.e., $|S_x(F')|$ drops to 1; (2) x is selected as the next variable in π . If (2) happens first, then $L_x = 1$. Since $|P_x| \leq d$ always, the left-hand side is at most $\log(d)$ and the right hand side is $\gamma' + \epsilon = \log(d)$. If (1) happens first, then $L_x = 0$. Let F' be the restricted formula after (1) has happened, and U the uniform distribution over permutations of $\text{var}(F')$. We know that $\mathbb{E}_{\pi \sim U}[\log |P_x(F', \pi, \alpha)|] \leq \gamma$, for every fixed $\alpha \in \text{sat}(F')$, since P has error

rate at most γ by assumption. However, this is not exactly what we need. We need to show that

$$\mathbb{E}_{(\pi, \alpha) \sim R} [\log |P_x(F, \pi \alpha)| \mid (1) \text{ and } F'] \leq \gamma ,$$

where the condition means that (1) happens first, and F' is the restricted formula just after (1) happens. Sampling from R conditioned on this specific past is basically the same as running the R -process, as defined above, on F' instead of F . That is, we have to show that

$$\mathbb{E}_{(\pi, \alpha) \sim R_{F'}} [\log |P_x(F', \pi, \alpha)|] \leq \gamma . \quad (3)$$

Note that F' is again a (d, k) -CSP formula, and thus it suffices to show the following lemma and apply it to F .

Lemma 11. *Let F be a satisfiable (d, k) -CSP formula and R the distribution over pairs (π, α) defined above. Then $\mathbb{E}_{(\pi, \alpha) \sim R} [\log |P_x(F, \pi, \alpha)|] \leq \gamma$.*

This lemma is non-obvious since we take the expectation over R , where both α and π are random, and π is typically not uniform, whereas in the definition of error rate, we take a fixed α and a uniform π . This lemma is, in a way, the heart of the overall proof, and also justifies the definition of R . We will prove it in the next section. To summarize, we have showed that if (2) happens first, then $L_x = 1$ and $\log |P_x| \leq \log d$ trivially, and the claimed bound holds. If (1) happens first, then $L_x = 0$, and by Lemma 11, $\mathbb{E}_R [\log |P_x| \mid (1)] \leq \gamma \leq \gamma'$. Thus, the claimed bound holds in both cases, which concludes the proof of Lemma 10, except for Lemma 11, a proof of which we give in the next section. \square

Plugging the bound of Lemma 10 into the left-hand side of Lemma 9, it suffices to show that

$$\mathbb{E}[\log(n!R(\pi, \alpha))] + \epsilon \sum_x \mathbb{E}[L_x] \leq 0 . \quad (4)$$

As an aside, note that the veracity of the above inequality depends solely on $\text{sat}(F)$ as a subset of $[d]^n$, and neither on the way this set is presented as a (d, k) -CSP formula nor on the proof heuristic P . Let us now change perspective. Rather than summing over individual variables x , let us sum / multiply over the steps taken by the R -process. Consider the i^{th} step, let F_i be the formula at the beginning of step i , let $n_i := n - i + 1$ be the number variables in F_i , let $s_i := |S(F_i)| = \sum_{x \in \text{var}(F_i)} |S_x(F_i)|$ be the number of satisfying literals. Let x_i be the variable chosen in step i and $L_i := L_{x_i}$

the indicator variable which is 1 if this variable is liquid and 0 if frozen. All of these are random variables with respect to the underlying probability distribution R (except n_i , of course, which is known beforehand). Note that $R(\pi, \alpha) = \prod_{i=1}^n \frac{1}{s_i}$. Indeed, there is, in every step, exactly one choice out of s_i many to produce the pair (π, α) . Consequently, $\log(n!R(\pi, \alpha)) = \sum_{i=1}^n \log\left(\frac{n_i}{s_i}\right)$, and (4) is equivalent to

$$\sum_{i=1}^n \mathbb{E} \left[\log\left(\frac{s_i}{n_i}\right) - \epsilon L_i \right] \geq 0. \quad (5)$$

In the next lemma, we will show that every summand is non-negative. This concludes the proof of Lemma 9. \square

Lemma 12. *For every $1 \leq i \leq n$, it holds that $\mathbb{E} \left[\log\left(\frac{s_i}{n_i}\right) - \epsilon L_i \right] \geq 0$.*

Proof. Let us imagine the R -process has already finished the first $i-1$ steps, and interpret \mathbb{E} as conditioned on this past. Then s_i becomes a constant. Let us write s and n instead of s_i and n_i , to simplify notation. Let f be the number of frozen variables in F_i . Note that $\mathbb{E}[L_i] = 1 - \frac{f}{s}$. Also, every liquid variable has at least 2 possible colors, thus $s \geq f + 2(n-f) = 2n - f$ and $f \geq 2n - s$. Therefore,

$$\mathbb{E}[L_i] = 1 - \frac{f}{s} \leq 1 - \frac{2n-s}{s} = \frac{2s-2n}{s}.$$

Note that this upper bound can easily be larger than 1, in which case it is of course trivial. Next, we will bound $\log\left(\frac{s}{n}\right)$ from below:

$$\begin{aligned} \log\left(\frac{s}{n}\right) &= -\log\left(\frac{n}{s}\right) = -\log\left(1 - \frac{s-n}{s}\right) \\ &= -\log(e) \ln\left(1 - \frac{s-n}{s}\right) \\ &\geq \log(e) \cdot \frac{s-n}{s}. \end{aligned}$$

Combining these two bounds, we obtain

$$\begin{aligned} \mathbb{E} \left[\log\left(\frac{s_i}{n_i}\right) - \epsilon L_i \right] &\geq \log(e) \cdot \frac{s-n}{s} - \epsilon \cdot \frac{2s-2n}{s} \\ &= \frac{s-n}{s} \cdot (\log(e) - 2\epsilon). \end{aligned}$$

Obviously $\frac{s-n}{s} \geq 0$. Note that $\log(e) - 2\epsilon$ is non-negative since $\epsilon \leq \frac{\log(e)}{2}$. \square

3 Bounding $\mathbb{E}_R[\log |P_x|]$ —Proof of Lemma 11

We have to show that $\mathbb{E}_{(\pi,\alpha)\sim R}[\log |P_x(F, \pi, \alpha)|] \leq \gamma$. For a fixed $\alpha \in \text{sat}(F)$, let $R_\alpha(\pi) := R(\pi|\alpha)$. So R_α is a distribution over permutations of variables. We can rewrite our expression as

$$\mathbb{E}_{(\pi,\alpha)\sim R}[\log |P_x|] = \mathbb{E}_{\alpha\sim R} \left[\mathbb{E}_{\pi\sim R_\alpha}[\log |P_x|] \right], \quad (6)$$

and we will show that this is at most γ by showing that

$$\mathbb{E}_{\pi\sim R_\alpha}[\log |P_x|] \leq \gamma, \text{ for every fixed } \alpha \in \text{sat}(F). \quad (7)$$

Since the R -process samples π and α in a very intertwined way, it is by no means clear how R_α behaves, and how (7) should be proved.

3.1 Informal Proof Outline

Let us first give an intuitive proof outline. Let π be some permutation and consider $\log |P_x|$. Suppose we move x towards the back of π , creating a new permutation π' . This can make P_x smaller. In fact, $P_x(\pi', \alpha) \subseteq P_x(\pi, \alpha)$. This should be clear: the later x is processed, the more information the heuristic P has about x , the more colors can be excluded as non-satisfying.

We claim that in $\pi \sim R_\alpha$, the variable x tends to come later than in a uniform permutation (in a sense we make precise soon). This means that P_x tends to be smaller under R_α than under the uniform distribution, thus $\mathbb{E}_{\pi\sim R_\alpha}[\log |P_x|] \leq \mathbb{E}_{\pi\sim \mathcal{U}}[\log |P_x|]$, and the latter expectation is at most γ by definition of the error rate of the proof heuristic.

What is an intuitive reason that x tends to come later under R_α ? When we remove the condition on α and only consider R , then a variable y is chosen first with probability $\frac{|S(F,y)|}{|S(F)|}$. Since x is frozen, we have $|S_x(F)| = 1$ and thus it is least likely to come first. The same argument applies to every step of the R -process. However, this is not what we want—we want to show x tends to come late under R_α , not R . Bayes' formula tells us that we have to correct $\frac{|S(F,y)|}{|S(F)|}$ by a factor that measures how the probability of α changes when conditioning on y being chosen first. A minute of thought shows that choosing y first changes α 's probability to something at least $\frac{1}{|S(F,y)|}$ times what it was before; furthermore, if y is frozen, it does not change it at all. That is, under R_α , x comes first with probability $\frac{1}{|S(F)|}$, while some other y comes first with probability at least $\frac{|S(F,y)|}{|S(F)|} \times \frac{1}{|S(F,y)|}$. So x is still least likely to come first.

3.2 The Formal Proof

For two strings σ, π , we write $\sigma \preceq \pi$ if σ is a prefix of π . A permutation π on set V of size n can be viewed as a string in V^n without repeated letters. A string $\sigma \in V^*$ without repeated letters is called a *partial permutation*. If D is a distribution over permutations on V and σ is a partial permutation, we write $D(\sigma) := \Pr_{\pi \sim D}(\sigma \preceq \pi) = \sum_{\pi: \sigma \preceq \pi} D(\pi)$.

Definition 13. *Let D be a distribution over permutations on V , and let $x \in V$. We say D delays x if for all $y \in V$ and all partial permutations σ not containing x or y , it holds that $D(\sigma x) \leq D(\sigma y)$.*

Lemma 11 will follow from the next two lemmas.

Lemma 14. *Let x be a frozen variable. Then the distribution R_α delays x*

Lemma 15 (Lemma 21 from [10]). *Let V be a finite set, $x \in V$, D a distribution over permutations of V that delays x , and $f : V \rightarrow \mathbb{R}$ a monotone function, meaning $f(U_1) \leq f(U_2)$ whenever $U_1 \subseteq U_2$. Denote by $W = W(\pi)$ the set of elements coming after x in π . Then*

$$\mathbb{E}_{\pi \sim D} [f(W)] \leq \mathbb{E}_{\pi \sim \mathcal{U}} [f(W)] ,$$

where \mathcal{U} is the uniform distribution over permutations.

To finish the proof of Lemma 11, let W be the set of variables occurring after x in π , and note that P_x indeed only depends on W : it depends on which variables have been set yet; the order in which they have been set is irrelevant. Also, it is monotone. The fewer variables come after x , the more information the heuristic P has about x , the more colors can be excluded as obviously non-satisfying, and the smaller P_x becomes. Thus, $f : W \mapsto \log |P_x|$ is monotone in the sense of Lemma 15. Lemma 11 now follows since R_α delays x and thus can play the role of D in Lemma 15.

Lemma 15 can be proved by a simple coupling argument. A full formal proof can be found in [10]. It remains to prove Lemma 14. The proof is similar to that of Lemma 21 in [10].

Proof of Lemma 14. Let x and y be variables and let σ be a partial permutation not containing x or y . We have to show that $R_\alpha(\sigma x) \leq R_\alpha(\sigma y)$. Multiplying both sides with $R(\alpha)$, this is equivalent to $R(\sigma x, \alpha) \leq R(\sigma y, \alpha)$. Note that $R(\sigma, \alpha)$ means $\sum_{\pi: \sigma \preceq \pi} R(\pi, \alpha)$. This is good, since we removed the hard-to-grasp conditioning on α .

We argue that it is enough to show this inequality for empty σ , i.e., $R(x, \alpha) \leq R(y, \alpha)$. Indeed, if σ is non-empty, one can imagine running the R -process according to α and σ for the first $|\sigma|$ steps, arriving at a formula F' , and then appeal to the case of empty prefix, for the new formula F' .

To prove $R(x, \alpha) \leq R(y, \alpha)$, we consider an alternative way to sample $(\pi, \alpha) \sim R$. First, recall that $S(F)$ is the set of all (v, c) such that $F|_{v=c}$ is satisfiable. Choose a random permutation on $S(F)$, namely $\tau = (v_1, c_1), (v_2, c_2), \dots, (v_s, c_s)$. Start with $F' = F$ and, for $i = 1, \dots, s$, check whether (1) v_i has not been set yet and (2) $F'|_{v_i=c_i}$ is satisfiable. If so, apply this assignment, i.e., set $F' := F'|_{v_i=c_i}$, and output (v_i, c_i) . Otherwise, do nothing. Proceed to $i + 1$. The output sequence has length n and defines a permutation π and a satisfying assignment α . We say τ *leads to* π and α . It is easy to see that (π, α) follows distribution R .

Let T be the set of all such sequences, i.e., $T = \text{Sym}(S(F))$. Let $T_{v,\alpha}$ be the set of all $\tau \in T$ leading to α and some π in which v comes first. With this notation, $R(v, \alpha) = \frac{|T_{v,\alpha}|}{|T|}$. Thus, we have to show that $|T_{x,\alpha}| \leq |T_{y,\alpha}|$. We show this by defining an injection from the former set into the latter as follows. Consider a sequence $\tau \in T_{x,\alpha}$. The first pair in τ must be $(x, \alpha(x))$, and the pair $(y, \alpha(y))$ must appear somewhere in τ . Let $\varphi(\tau)$ be the sequence arising from exchanging these two pairs. Clearly φ is injective, and we claim that $\varphi(\tau) \in T_{y,\alpha}$. Indeed, since τ leads to α , we can move the pair $(x, \alpha(x))$ to any position, and the new sequence still leads to α . This is because x is frozen, and thus $\alpha(x)$ is the only satisfying value for x anyway, and it does not matter when we actually apply the restriction $x = \alpha(x)$. So $\varphi(\tau)$ leads to α , as well, and its first pair is $(y, \alpha(y))$, so clearly y comes first in $\varphi(\tau)$, thus $\varphi(\tau) \in T_{y,\alpha}$. □

4 Conclusion

We would like to find a proof that works for all monotone proof heuristics, for arbitrarily small error rates γ . More modestly, it would be nice if we could extend the proof of this paper to cover all values (d, k) for the concrete proof heuristic P_D , or at least more than it currently does. There are two points in the proof where we bound things too generously: first, in the proof of Lemma 11 we bound $\log |P_x| \leq \log(d)$, which is of course true. However, it is too pessimistic on expectation. For example, suppose $|S_x(F)| = 2$. Then $|P_x(\pi, \alpha)|$ should still be less than d , on expectation. Indeed, for any unsatisfiable color c , there is a certain chance that P_D “catches” it and thus

excludes it from $P_x(\pi, \alpha)$. This probability is not formalized in the definition of γ , the error rate. However, we surely can bound it for the concrete heuristic P_D . However, there are some difficulties: if $|S_x(F)| \geq 2$, then Lemma 14 does not apply anymore, and R_α quite possibly does not delay x . Thus, $\mathbb{E}_{\pi \sim R_\alpha}[\log |P_x(\pi, \alpha)|]$ might be significantly larger than under uniform π .

The other point in the proof where we possibly give away a lot is in the proof of Lemma 12. We argue that “every liquid variable has at least 2 possible colors. This might well be tight: $\text{sat}(F)$ might well be contained in the set $\{1, 2\}^n$, for example. However, this is an extreme case, and the pessimistic scenario that $|S_x(F)| \leq 2$ for all (or even most) x might turn out to be beneficial at some other point in the analysis.

References

- [1] A. Björklund and T. Husfeldt. Inclusion–exclusion algorithms for counting set partitions. In *47th Annual IEEE Symposium on Foundations of Computer Science (FOCS 2006), 21-24 October 2006, Berkeley, California, USA, Proceedings*, pages 575–582. IEEE Computer Society, 2006.
- [2] T. Feder and R. Motwani. Worst-case time bounds for coloring and satisfiability problems. *J. Algorithms*, 45(2):192–201, 2002.
- [3] T. Hertli. 3-SAT faster and simpler—unique-SAT bounds for PPSZ hold in general. In *2011 IEEE 52nd Annual Symposium on Foundations of Computer Science—FOCS 2011*, pages 277–284. IEEE Computer Soc., Los Alamitos, CA, 2011.
- [4] T. Hertli, I. Hurbain, S. Millius, R. A. Moser, D. Scheder, and M. Szédák. The PPSZ algorithm for constraint satisfaction problems on more than two colors. In M. Rueher, editor, *Principles and Practice of Constraint Programming - 22nd International Conference, CP 2016, Toulouse, France, September 5-9, 2016, Proceedings*, volume 9892 of *Lecture Notes in Computer Science*, pages 421–437. Springer, 2016.
- [5] R. Impagliazzo, R. Paturi, and F. Zane. Which problems have strongly exponential complexity. *J. Comput. System Sci.*, 63(4):512–530, 2001. Special issue on FOCS 98 (Palo Alto, CA).
- [6] L. Li, X. Li, T. Liu, and K. Xu. From k-sat to k-csp: Two generalized algorithms. *CoRR*, abs/0801.3147, 2008.
- [7] R. Paturi, P. Pudlák, M. E. Saks, and F. Zane. An improved exponential-time algorithm for k -SAT. *J. ACM*, 52(3):337–364 (electronic), 2005.

- [8] R. Paturi, P. Pudlák, and F. Zane. Satisfiability coding lemma. *Chicago J. Theoret. Comput. Sci.*, pages Article 11, 19 pp. (electronic), 1999.
- [9] D. Scheder. Ppz for more than two truth values - an algorithm for constraint satisfaction problems. *CoRR*, abs/1010.5717, 2010.
- [10] D. Scheder and J. P. Steinberger. PPSZ for General k-SAT - making Hertli's analysis simpler and 3-SAT faster. In R. O'Donnell, editor, *32nd Computational Complexity Conference, CCC 2017, July 6-9, 2017, Riga, Latvia*, volume 79 of *LIPICs*, pages 9:1–9:15. Schloss Dagstuhl - Leibniz-Zentrum fuer Informatik, 2017.
- [11] U. Schöning. A probabilistic algorithm for k -SAT and constraint satisfaction problems. In *Proceedings of the 40th Annual Symposium on Foundations of Computer Science*, pages 410–414. IEEE Computer Society, Los Alamitos, CA, 1999.
- [12] P. Traxler. The time complexity of constraint satisfaction. In M. Grohe and R. Niedermeier, editors, *Parameterized and Exact Computation, Third International Workshop, IWPEC 2008, Victoria, Canada, May 14-16, 2008. Proceedings*, volume 5018 of *Lecture Notes in Computer Science*, pages 190–201. Springer, 2008.