Domain Reduction for Monotonicity Testing:  
A $o(d)$ Tester for Boolean Functions on Hypergrids

Hadley Black∗  Deeparnab Chakrabarty†  C. Seshadhri‡

Abstract

Testing monotonicity of Boolean functions over the hypergrid, $f : [n]^d \rightarrow \{0, 1\}$, is a classic problem in property testing. When the range is real-valued, there are $\Theta(d \log n)$-query testers and this is tight. In contrast, the Boolean range qualitatively differs in two ways:

- **Independence of $n$:** There are testers with query complexity independent of $n$ [Dodis et al. (RANDOM 1999); Berman et al. (STOC 2014)], with linear dependence on $d$.
- **Sublinear in $d$:** For the $n = 2$ hypercube case, there are testers with $o(d)$ query complexity [Chakrabarty, Seshadhri (STOC 2013); Khot et al. (FOCS 2015)].

It was open whether one could obtain both properties simultaneously. This paper answers this question in the affirmative. We describe a $O(d^{5/6})$-query monotonicity tester for $f : [n]^d \rightarrow \{0, 1\}$.

Our main technical result is a **domain reduction theorem** for monotonicity. For any function $f$, let $\varepsilon_f$ be its distance to monotonicity. Consider the restriction $\hat{f}$ of the function on a random $[k]^d$ sub-hypergrid of the original domain. We show that for $k = \text{poly}(d/\varepsilon)$, the expected distance of the restriction $E[\varepsilon_{\hat{f}}] = \Omega(\varepsilon_f)$. Therefore, for monotonicity testing in $d$ dimensions, we can restrict to testing over $[n]^d$, where $n = \text{poly}(d/\varepsilon)$. Our result follows by applying the $d^{5/6} \cdot \text{poly}(1/\varepsilon, \log n, \log d)$-query hypergrid tester of Black-Chakrabarty-Seshadhri (SODA 2018).

---

∗Department of Computer Science, University of California, Los Angeles. Email: habilack@cs.ucla.edu. Part of this work was done while the author was at University of California, Santa Cruz.
†Department of Computer Science, Dartmouth College. Email: deeparnab@dartmouth.edu. Supported by NSF CCF-1813165.
‡Department of Computer Science, University of California, Santa Cruz. Email: sesh@ucsc.edu. Supported by NSF TRIPods CCF-1740850, CCF-1813165.
1 Introduction

Monotonicity testing over hypergrid domains is a fundamental problem in property testing. Consider the hypergrid $[n]^d$, where $\prec$ denotes the coordinate-wise partial ordering. Let $R$ be a total order. A function $f : [n]^d \to R$ is monotone if $f(x) \leq f(y)$ for any $x \prec y$. The distance of a function $f$ to monotonicity is the Hamming distance to the nearest monotone function, that is, $\varepsilon_f := \min_{g \in \mathcal{M}} d(f, g)$, where $d(f, g) = n^{-d} \cdot |\{x \in [n]^d : f(x) \neq g(x)\}|$, and $\mathcal{M}$ is the set of all monotone functions. A monotonicity tester is a randomized algorithm that makes queries to $f$ and accepts with probability $\geq n^3$. By simply applying the best known monotonicity tester to a random hypercube and then checking whether $f$ is monotone, we obtain a $\tilde{O}(d/\varepsilon)$ tester. Although the dependence on $n$ requires $\Omega(\log n)$ queries [EKK+00, Fis04]. Recently, Black, Chakrabarty, and Seshadhri [BCS18] gave a $\tilde{O}(d^{1/6} \log^{1/3} n \varepsilon^{-4/3})$-query tester. Although the dependence on $d$ was sublinear, there was a dependence on $n$. The following question remained open:

> Is there a monotonicity tester for functions $f : [n]^d \to \{0, 1\}$, whose query complexity is independent of $n$ and sublinear in $d$?

The main outcome of this paper is an affirmative answer to this question.

Theorem 1.1 (Informal). There is a one-sided, non-adaptive $\tilde{O}(d^{5/6} \varepsilon^{-7/3})$-query monotonicity tester for Boolean functions $f : [n]^d \to \{0, 1\}$.

1.1 Domain Reduction

A natural approach, at least in hindsight, to tackle Boolean monotonicity testing over the hypergrid is to try reducing it to Boolean monotonicity testing over the hypercube. For a function $f$ over $[n]^d$, consider the restriction $\hat{f}$ to a random hypercube in this hypergrid. More precisely, for each dimension $i \in [d]$, sample two independent u.a.r values $a_i < b_i$ in $[n]$ and let $\hat{f}$ be the restriction of $f$ on the hypercube formed by the Cartesian product $\prod_{i=1}^d \{a_i, b_i\}$. If the expectation of $\varepsilon_{\hat{f}}$ is $\Omega(\varepsilon_f)$, then we obtain a hypergrid tester by first reducing our domain to a random hypercube and then simply applying the best known monotonicity tester on the hypercube. However, we show that this does not work. In §5, we describe a function $f : [n]^d \to \{0, 1\}$ such that $\varepsilon_{\hat{f}} = \Omega(1)$, but the restriction of $f$ on a random hypercube is monotone with probability $1 - \Theta(1/d)$ (see Theorem 5.1).

1Throughout the paper $\tilde{O}$ hides $\log(d/\varepsilon)$ factors.
Nonetheless, one can consider the question of reducing the domain to a \([k]^d\) hypergrid, for some parameter \(k \ll n\). For each \(i \in [d]\), consider sampling a subset \(T_i \subset [n]\) by taking \(k\) i.i.d. uniform samples from \([n]\). Let \(T = \prod_{i=1}^{d} T_i\) and \(f_T\) be the restriction of \(f\) to \(T\). For \(k\) independent of \(n\), can we lower bound \(E_T[f_T]\)? We refer to this as the problem of domain reduction with \(k\) samples. Our main technical result is a domain reduction theorem with \(k = \text{poly}(d/\varepsilon_f)\).

**Theorem 1.2 (Informal).** The expected distance to monotonicity of \(f\) restricted to a random \([k]^d\) hypergrid with \(k = \Theta((d/\varepsilon_f)^2)\), is \(\Omega(\varepsilon_f)\).

The construction of §5 actually shows that such a theorem is impossible for \(k = o(\sqrt{d})\), and thus, domain reduction requires \(k\) to be polynomial in \(d\).

We can invoke [BCS18] to prove Theorem 1.1. Sample a random \([k]^d\) hypergrid denoted \(T\) and apply the tester of [BCS18] on \(f_T\). The final query complexity is \(\tilde{O}(d^{5/6}) \cdot \text{poly} \log k\). Setting \(k = \text{poly}(d/\varepsilon)\), one gets a purely sublinear-in-\(d\) tester (see §1.5 for a formal proof).

An obvious question is whether the dependence on \(d\) can be brought down to \(\sqrt{d}\) as in the hypercube case. Theorem 1.2 allows us to assume that \(n = \text{poly}(d)\). Therefore if one could design a \(\sqrt{d}\cdot \text{poly} \log n\) query monotonicity tester for the domain \([n]^d\), then Theorem 1.2 can be used as a black box to achieve an \(\tilde{O}(\sqrt{d})\) monotonicity tester.

**Implication for Other Notions of Distance:** Berman, Raskhodnikova, and Yaroslavtsev [BRY14a] introduce the notion of \(L_p\) testing, where \(f : [n]^d \to [0,1]\) and the distance between functions is measured in terms of \(L_p\)-norms. They prove that monotonicity testing with \(L_p\) distances can be reduced to (non-adaptive, one-sided) Boolean monotonicity testing. Thus, Theorem 1.1 implies an \(L_p\)-test for monotonicity over hypergrids, with the same query complexity.

Previous work has also considered distance under product distributions [HK08, CDJS15]. Let \(D\) be a product distribution over \([n]^d\), and define \(d(f,g) = \Pr_{x \sim D}[f(x) \neq g(x)]\). Chakraborty et al. [CDJS15] observed that monotonicity testing of \(f : [n]^d \to R\) over product distributions can be reduced to monotonicity testing of \(f : [N]^d \to R\) over the uniform distribution (standard distance). Here, \(N\) is potentially much larger than \(n\), and depends on the probabilities in \(D\). By this observation, for the Boolean range case \(R = \{0,1\}\), the query complexity of Theorem 1.1 holds for distances measured according to any product distribution. Note that the independence of \(n\) is necessary in the reduction to get a query complexity independent of the distribution \(D\).

**Domain Reduction for Variance:** Recent works [CS14a, KMS15, BCS18] have shown that certain isoperimetric theorems for the undirected hypercube have directed analogues where the variance is replaced by the distance to monotonicity. Interestingly, for the case of domain reduction, the variance and distance to monotonicity behave differently. While domain reduction for the distance to monotonicity requires \(k \geq \sqrt{d}\) (Theorem 5.1), we show that the expected variance of a restriction of \(f\) to a random hypercube \((k = 2)\) is at least half the variance of \(f\) (see Theorem A.1). This statement may be of independent interest. We were unable to find a reference to such a statement and provide a proof in §A.

### 1.2 The Formal Result

Fix a function \(f : [n]^d \to \{0,1\}\). We construct \(d\) random (multi-) sets \(T_1, \ldots, T_d \subseteq [n]\), each formed by taking \(k\) i.i.d. uniform samples from \([n]\) with replacement. We define \(T := T_1 \times \cdots \times T_d\) and let \(f_T\) denote \(f\) restricted to \(T\). We treat duplicate elements of a multi-set as being distinct copies of that element, which are then treated as immediate neighbors in the total order. The function value of \(f_T\) is the same on these distinct copies. In our applications \(k \ll n\) and so we can assume that \(T_i\) contains a duplicate with negligible probability. Nonetheless, sampling with replacement allows for no conditions on \(k\).
Then E[k] for some T \times f monotonicity violation with high probability, and thus the restriction of domain reduction for d (Domain Reduction Lemma) Lemma 1.4 is the heart of our result and we give an overview of its proof in §1.3. The theorem is a direct corollary of the following lemma, applied to each dimension. This lemma C > k where ε = ε/7 where C > 0 is a universal constant.

In particular, k = O((d/ε)^7) samples in each dimension is sufficient to preserve the distance to monotonicity. The theorem is a direct corollary of the following lemma, applied to each dimension. This lemma is the heart of our result and we give an overview of its proof in §1.3.

Lemma 1.4 (Domain Reduction Lemma). Let f : [n] × (Π_{i=2}^d [n_i]) \to \{0, 1\} be any function over a rectangular hypergrid for some n, n_2, \ldots, n_d \in \mathbb{Z}^+ and let k \in \mathbb{Z}^+. Choose T to be a (multi-) set formed by taking k i.i.d. samples from the uniform distribution on [n] and let f_T denote f restricted to T \times (Π_{i=2}^d [n_i]). Then E_{f_T} [f - f_T] \leq C \frac{C}{k^{1/7}} where C > 0 is a universal constant.

1.3 Proving the Domain Reduction Lemma : Overview

Let us start with the simple case of d = 1 (the line). Monotonicity testers for the line immediately imply domain reduction for d = 1 [DGL+99, BRY14a]. A u.a.r sample of \tilde{O}(1/ε_f) points in [n] contains a monotonicity violation with high probability, and thus the restriction of f to the sample has distance \Omega(ε_f). We note that these arguments typically get a lower bound of ε_f/2. Therefore, even if we could generalize this argument to the setting of Lemma 1.4, we would need to apply it d times to get the full domain reduction (Theorem 1.3). That would imply a final lower bound of ε_f/2^d, which has little value towards proving a sublinear-in-d bound.

Indeed, the first baby step towards Lemma 1.4 is to get a stronger domain reduction just for the line. We prove that if one samples Θ(d^2/ε^2_f) points, then the expected distance of the restricted function is at least ε_f(1 − 1/d). Numerically speaking, this is encouraging news, since we could at least hope to iterate this argument d times. Of course, this result for the line alone is not enough to deal with the structure of general hypergrids, but forms a part of our final proof.

Let us go to the general case of Lemma 1.4. For brevity, we let D := [n] × (Π_{i=2}^d [n_i]) and D_T := T \times (Π_{i=2}^d [n_i]) denote the original and reduced domains, respectively. Note that |D_T| = \frac{k}{n}|D|.

The violation graph of f has vertex set D and an edge (x, y) iff x < y and f(x) = 1, f(y) = 0. A theorem of [FLN+02] states that any maximum cardinality matching in M in the violation graph satisfies |M| = ε_f|D|. Fix such a matching M. For a fixed sample T, we let M_T denote a maximum cardinality matching in the violation graph of f_T. To argue about ε_{f_T}, we need to to lower bound the expected size |M_T|. To do so, we lower bound the expected number of endpoints of M that can still be matched in the violation graph of f_T.

We use the following standard notions of lines and slices in D, with respect to the first dimension. Below, for x \in D, the vector x_{-1} is used to denote (x_2, x_3, \ldots, x_d).

- (Lines in D) L := \{\ell_z : z ∈ [Π_{i=2}^d [n_i]]\} where \ell_z := \{x ∈ D : x_{-1} = z\}.
- (Slices in D) S := \{S_i : i ∈ [n]\} where S_i := \{x ∈ D : x_1 = i\}. 
We partition $M$ into a collection of “local” matchings for each line:

- (Line Decomposition of $M$) For each $\ell \in \mathcal{L}$: $M^{(\ell)} := \{(x, y) \in M : x \in \ell\}$.

We find a large matching in the violation graph of $f_T$ by doing a line-by-line analysis. In particular, we define the following matching $M^{(\ell)}_T$.

- (The matching $M^{(\ell)}_T$) For each $\ell \in \mathcal{L}$, let $M^{(\ell)}_T$ be any maximum cardinality violation matching with respect to $f_T$ on the set of vertices that (a) are matched by $M^{(\ell)}$, and (b) lie in some slice $S_i$ where $i \in T$.

We stress that $M^{(\ell)}_T$ is not a subset of $M^{(\ell)}$; the endpoints of the pairs in $M^{(\ell)}_T$ are a subset of the endpoints of the pairs in $M^{(\ell)}$, but the actual pairs can be different. The above definition implies that the union of $M^{(\ell)}_T$ over all $\ell \in \mathcal{L}$ is a valid matching $M_T$ in the violation graph of $f_T$ and that $M^{(\ell)}_T \cap M^{(\ell')}_T = \emptyset$ for all $\ell \neq \ell' \in \mathcal{L}$. We will lower bound the size of this matching, $M_T$.

Fix some $\ell \in \mathcal{L}$ and notice that by definition, the lower-endpoints of $M^{(\ell)}$ all lie on $\ell$, and thus are all comparable. Thus, let $M^{(\ell)} = \{(x_1, y_1), \ldots, (x_m, y_m)\}$ where $x_1 < \cdots < x_m$ and observe this implies that, for any $j \in [m], x_1, \ldots, x_j < y_j, \ldots, y_m$. Combining this with the fact that the function is Boolean, we see that any $x \in \{x_1, \ldots, x_j\}$ forms a violation to monotonicity with any $y \in \{y_j, \ldots, y_m\}$, and therefore these vertices can be matched in $M^{(\ell)}_T$, if their 1-coordinates are sampled by $T$.

Since all the $x_i$’s lie on the same line $\ell$, their 1-coordinates are distinct. Suppose that the 1-coordinates of all the $y_i$’s were also distinct and distinct from those of the $x_i$’s too. Under this assumption we can project all the violations onto $\ell$, and the analysis becomes identical to the one-dimensional case. As alluded to above, the one-dimensional case can be handled without much difficulty (Lemma 1.6). However, the assumption that the $y_i$’s have distinct 1-coordinates is problematic. For instance, it could also be the case that all the $y_i$’s have the same 1-coordinate. That is, they all lie in the same slice $S_a$, for some $a \in [n]$. In this case, with probability $(1 - k/n)$ we would have the size of $M^{(\ell)}_T$ be 0 (if $a \notin T$), which in turn implies that $E_T \left[ |M^{(\ell)}_T| \right]$ could be as small as $(k/n)^2 \cdot |M^{(\ell)}|$. This would disprove the lemma if such a “collision of $y$’s 1-coordinates” happened all the time. Unfortunately, there are examples of violation matchings where this happens. Consider Example 1, and the left part of Fig. 1. For the lowest line, all the corresponding $y_i$’s in $M^{(\ell)}$ have the same coordinate. Indeed, this example is extremely pathological for our approach.

The only hope is to discover a different violation matching that does not have such a problem. Indeed, our main insight is that there always exists a violation matching $M$ where the problem above does not arise (too often). This motivates the key definition of stacks; the stacks are what determine the “shape” of a matching. Formally, for any $\ell \in \mathcal{L}$ and $S \in \mathcal{S}$, the $(\ell, S)$-stack is the set of pairs $(x, y) \in M$, where $x \in \ell$ and $y \in S$.

- (Stacks) $M^{(\ell, S)} := \{(x, y) \in M^{(\ell)} : y \in S\} = \{(x, y) \in M : x \in \ell, y \in S\}$.

Often, we will use the notation “size of a stack $(\ell, S)$” to denote $|M^{(\ell, S)}|$. To summarize the above discussion, small stacks are good news while big stacks are bad news. This is formalized in Lemma 1.6.

Intuitively, if there is a maximum cardinality matching $M$ in the violation graph of $f$ such that all stacks had size at most 1, then the one-dimensional argument can be directly applied (Lemma 1.6 would be enough to prove Lemma 1.4). Even if their sizes were at most a constant, this would suffice as well. Unfortunately, we do not know if this is possible. One reason for this difficulty may be that there can be various maximum cardinality matchings in the violation graph that have vastly different stack sizes (shape of the matching);
again consider Example 1. Nevertheless, we can show that for any \( \lambda \geq 2 \), there is a matching \( M \) where the total number of vertices participating in stacks of size at least \( \lambda \) is at most \( |D|/\text{poly}(\lambda) \).

**Lemma 1.5 (Stack Bound).** For any integer \( \lambda \geq 2 \), there exists a maximum cardinality matching \( M \) in the violation graph of \( f \), where \( \sum_{(\ell,S):|M(\ell,S)| \geq \lambda} |M(\ell,S)| \leq \frac{6}{\lambda} \cdot |D| \).

The main creativity to prove this lemma lies in the choice of \( M \). Given a matching, we define the vector \( \Lambda(M) \) which enumerates all the stack sizes in non-decreasing order. We show that the maximum cardinality matching \( M \) which has the lexicographically largest \( \Lambda(M) \) suffices. That is, we choose \( M \) which maximizes the minimum stack size, and then subject to this maximizes the second minimum, and so on. It may seem a bit counter-intuitive that we want a matching with small stack sizes, and yet our potential function wishes to maximize the minimum. The explanation is that the sum of the stack sizes is \( |M| \), which is fixed, and so in a sense maximizing the minimum also balances out the \( \Lambda(M) \) vector. Of course, this is purely at an intuition level. The proof uses a matching rewiring argument to show that any large stack must be “adjacent” to many moderate size stacks. Essentially, if two stacks are appropriately aligned, one could change the matching to move points from one stack to the other. If a large stack was thus aligned with a small stack, one could rewire to get a lexicographically larger \( \Lambda(\cdot) \) vector. Thus, large stacks can only potentially rewire with other large stacks. But since the function is Boolean one can show that there are many opportunities for rewiring the violation matching. One can then apply some technical charging arguments to bound the total number of points in large stacks. The full proof can be found in §3.

With the stack bound in hand, we need to generalize the one-dimensional argument to account for bounded stack sizes. This is precisely what the following lemma achieves. Thus, we can bound \( |M_T(\ell)| \) for all \( \ell \), and get the final lower bound on the distance \( \varepsilon_f \).

**Lemma 1.6 (Line Sampling).** Suppose that \( M \) is a matching in the violation graph of \( f \) such that for \( \lambda \in \mathbb{Z}^+ \), \( |M(\ell,S)| \leq \lambda \) for all \( \ell \in \mathcal{L} \) and \( S \in \mathcal{S} \). Then, for any \( \ell \in \mathcal{L} \),

\[
\mathbb{E}_T \left[ |M_T(\ell)| \right] \geq \frac{k}{n} \cdot |M(\ell)| - 3\lambda \sqrt{k \ln k}.
\]

Note that in the one dimensional case, we have only one line \( \ell \) and each slice is a singleton. Thus, any stack has at most one point and so we can set \( \lambda = 1 \). Therefore, setting \( k = \omega \left( \frac{1}{\varepsilon^2 \ln(1/\varepsilon)} \right) \) we get that the function restricted to this random set has expected distance to monotonicity \( \varepsilon_f(1 - o(1)) \). To see this, note that \( \varepsilon_f = |M|/n = |M(\ell)|/n \) and \( \varepsilon_{f_T} \geq |M_T|/k = |M_T(\ell)|/k \).

The proof technique is a careful generalization of the argument that we alluded to in the beginning of this section, which shows that \( \tilde{O}(1/\varepsilon^2) \) random points contain a violation with high probability. We show that one can control the size of the maximum matching \( M_T(\ell) \) by analyzing the discrepancy of a random subsequence of a sequence of 1s and 0s.

**Example 1 (A Two Dimensional Example).** Consider the anti-majority function on two dimensions. More precisely, \( f : [n]^2 \to \{0, 1\} \) defined as \( f(x, y) = 1 \) if \( x + y \leq n \), and \( f(x, y) = 0 \) otherwise. We describe two maximum cardinality matchings with vastly different stack sizes. The first matching \( R \) matches a point \((x, y)\) with \( x + y \leq n \) to the point \((n - y + 1, n - x + 1)\). For an illustration, see the left red matching in Fig. 1 for the case \( n = 5 \). Observe that whenever \( x + y \leq n \), we have \((n - y + 1) + (n - x + 1) > n \). The second matching \( B \) matches a point \((x, y)\) with \( x + y \leq n \) to the point \((x + y, n - x + 1)\). Again, observe that \((x + y) + (n - x + 1) > n \). For an illustration, see the right blue matching in Fig. 1 for the case \( n = 5 \). Note that the stack sizes for the matching \( R \) are large; in particular, they are \( n - 1, n - 2, \ldots, 2, 1 \) for \( n - 1 \) stacks and 0 for the rest. On the other hand, any stack in \( B \) is of size \( \leq 1 \).
Figure 1: Accompanying illustration for Example 1 showing two different maximum cardinality violation matchings for the anti-majority function \( f : \{5\}^2 \rightarrow \{0,1\} \) which have very different stack sizes. Black (white, resp.) circles represent vertices where \( f = 1 \) (\( f = 0 \), resp.) and connecting lines represent pairs of the matching. Observe that for the left matching, the bottom line and the right-most slice form a stack of size 4 while the right matching has stack sizes all \( \leq 1 \).

1.4 Related Work

Monotonicity testing has been extensively studied in the past two decades [EKK+00, GGL+00, DGL+99, LR01, FLN+02, HK03, AC06, HK08, ACCL07, Fis04, SS06, Bha08, BCSM12, FR10, BBM12, RRSW11, BGJ+12, CS13, CS14a, CST14, BRY14a, BRY14b, CDST15, CDJS15, KMS15, BB16, CWX17].

We give a short summary of Boolean monotonicity testing over the hypercube. The problem was introduced by Goldreich et al [GGL+00] (refer to Raskhodnikova’s thesis [Ras99]), with an \( O(d/\varepsilon) \)-query tester. The first improvement over that bound was the \( \tilde{O}(d^{7/8}) \) tester of Chakrabarty and Seshadhri [CS14a], achieved via a directed analogue of Margulis’ isoperimetric theorem. Chen-Servedio-Tan improved the analysis to get an \( \tilde{O}(d^{5/6}) \) bound [CST14]. A breakthrough result of Khot-Minzer-Safra gave an \( \tilde{O}(\sqrt{d}) \) tester [KMS15]. All these testers are non-adaptive and one-sided. Fischer et al. had proved a (nearly) matching lower bound of \( \Omega(\sqrt{d}) \) for this case [FLN+02]. The first polynomial two-sided lower bound was given by Chen-Servedio-Tan, subsequently improved to \( \Omega(d^{1/2-\delta}) \) by Chen et al. [CDST15]. The first polynomial lower bound of \( \Omega(d^{1/4}) \) for adaptive testers was given recently by Belovs-Blais [BB16], and was improved to \( \Omega(d^{1/3}) \) by Chen-Waingarten-Xie [CWX17].

For Boolean monotonicity testing over general hypergrids, Dodis et al. gave a non-adaptive, one-sided \( O((d/\varepsilon) \log^2(d/\varepsilon)) \)-query tester [DGL+99]. This was improved to \( O((d/\varepsilon) \log(d/\varepsilon)) \) by Berman-Raskhodnikova-Yaroslavtsev [BRY14a]. They also prove an \( \Omega(\log(1/\varepsilon)) \) separation between adaptive and non-adaptive monotonicity testers for \( f : [n]^2 \rightarrow \{0,1\} \). They show an \( O(1/\varepsilon) \) adaptive tester (for any constant \( d \)), and an \( \Omega(\log(1/\varepsilon)/\varepsilon) \) lower bound for non-adaptive monotonicity testers. Previous work by the authors give a monotonicity tester with query complexity \( \tilde{O}(d^{5/6} \log n) \) via directed isoperimetric inequalities for augmented hypergrids [BCS18].

1.5 The Monotonicity Tester: Proof of Theorem 1.1

We use the following theorem of [BCS18] on monotonicity testing for Boolean functions on \([n]^d\).

Theorem 1.7 (Theorem 1.1 of [BCS18]). Given a function \( f : [n]^d \rightarrow \{0,1\} \) and a parameter \( \varepsilon \in (0,1) \), there is a randomized algorithm that makes \( O \left( d^{5/6} \cdot \log^{3/2} d \cdot (\log n + \log d)^{4/3} \cdot \varepsilon^{-4/3} \right) \) non-adaptive
queries and (a) returns YES with probability 1 if the function is monotone, and (b) returns NO with probability > 2/3 if the function is \( \varepsilon \)-far from being monotone.

We refer to the tester of Theorem 1.7 as the grid-path-tester. Using this result along with our domain reduction theorem (Theorem 1.3), we design the following improved tester. Let \( C \) denote the universal constant from Theorem 1.3.

**Algorithm 1** Improved Monotonicity Tester for \( f : [n]^d \to \{0, 1\} \) \((f, \varepsilon, n)\)

1: if \( n \leq (2C \cdot \frac{d}{\varepsilon})^7 \): return grid-path-tester\((f, \varepsilon, n)\).
2: else:
3: repeat \(256/\varepsilon\) times:
4: Sample \( T = T_1 \times \cdots \times T_d \) as in Theorem 1.3 with \( k = (2C \cdot \frac{d}{\varepsilon})^7 \).
5: if grid-path-tester\((f_T, \varepsilon/4, k)\) returns NO, then return NO.
6: return YES.

**Proof of Theorem 1.1**: The result is a corollary of Theorem 1.3 and Theorem 1.7. If \( n \leq (2C \cdot \frac{d}{\varepsilon})^7 \), then the tester of Theorem 1.7 (grid-path-tester\((f, \varepsilon, n)\)) already achieves the stated guarantees. On the other hand if \( n > (2C \cdot \frac{d}{\varepsilon})^7 \), then we set \( k := (2C \cdot \frac{d}{\varepsilon})^7 \) and sample a sub-hypergrid \( T := T_1 \times \cdots \times T_d \), where each \( T_i \) is formed by taking \( k \) i.i.d. draws from the uniform distribution on \([n]\). By Theorem 1.3, \( \mathbb{E}_T[\varepsilon_{f_T}] \geq \varepsilon - \frac{C_d}{k^{1/7}} = \varepsilon/2 \). Thus, by Markov’s inequality, \( \Pr_T[\varepsilon_{f_T} \geq \varepsilon/4] \geq \varepsilon/4 \). Thus, at least one of the iterations of Step 4 in Alg. 1 returns \( T \) satisfying \( \varepsilon_{f_T} \geq \varepsilon/4 \) with probability \( \geq 1 - (1 - \varepsilon/4)^{256/\varepsilon} \geq 1 - \left(1 - (1/4)^{1/4}\right)^4 \geq 1 - (1/4)^4 \geq 15/16 \).

Thus, if \( f \) is \( \varepsilon \)-far from monotone, then Alg. 1 returns NO with probability \( \geq 15/16 \cdot \frac{2}{3} = 5/8 \). On the other hand, if \( f \) is monotone, then Alg. 1 clearly returns YES. For the query complexity, Alg. 1 runs grid-path-tester at most \( 256/\varepsilon \) times with parameters \( \varepsilon/4 \) and \( k = (2C \cdot \frac{d}{\varepsilon})^7 \). Thus, substituting these values in place of \( \varepsilon \) and \( n \) in the query complexity of Theorem 1.7 and multiplying by \( 256/\varepsilon \) completes the proof of Theorem 1.1.

## 2 Domain Reduction: Proof of Lemma 1.4

In this section, we use Lemma 1.5 and Lemma 1.6 to prove Lemma 1.4. Recall that \( D := [n] \times \left( \prod_{i=2}^d [n_i] \right) \) and \( D_T := T \times \left( \prod_{i=2}^d [n_i] \right) \) denote the original and reduced domains, respectively. Note that \( |D_T| = \frac{k}{n} |D| \).

Let \( M \) be the matching given by Lemma 1.5 with \( \lambda := \left\lceil 36k^{2/7} \right\rceil \).

By Lemma 1.5, we have \( \left| \bigcup_{(\ell,S) : |M(\ell,S)| \geq 40k^{2/7}} M(\ell,S) \right| \leq \frac{6}{\sqrt{\lambda}} \cdot |D| \leq \frac{|D|}{k^{1/7}} \). Let

\[
\widehat{M} := M \setminus \left( \bigcup_{(\ell,S) : |M(\ell,S)| \geq 40k^{2/7}} M(\ell,S) \right)
\]

denote the set of pairs in \( M \) which do not belong to stacks larger than \( 40k^{2/7} \); we therefore have

\[
\sum_{\ell \in L} |\widehat{M}(\ell)| = |\widehat{M}| \geq |M| - \frac{|D|}{k^{1/7}},
\]

(1)
In this proof, our goal is to construct a matching $M_T$ in the violation graph of $f_T$ whose cardinality is sufficiently large. We measure $E_T[|M_T|]$ by summing over all lines in $L$ and applying Lemma 1.6 to each. Notice that $\hat{M}$ is a matching in the violation graph of $f$ which satisfies $|\hat{M}(\ell,S)| \leq 40k^{2/7}$ for all $\ell \in L$ and $S \in S$. Thus by Lemma 1.6, for any $\ell \in L$,

$$E_T[|M^T_{\ell}|] \geq \frac{k}{n} \cdot |\hat{M}(\ell)| - 3 \cdot (40k^{2/7}) \cdot \sqrt{k \ln k} \geq \frac{k}{n} \cdot |\hat{M}(\ell)| - 120k^{5/6} \tag{2}$$

where we have used $\sqrt{k \ln k} < k^{1/3 - 2/7}$. Now, using (1) and (2), we can calculate $E_T[|M_T|]$. We use the fact that $\{\hat{M}(\ell)\}_{\ell \in L}$ is a partition of $\hat{M}$, apply linearity of expectation and use Lemma 1.6 to measure $E_T[|M^T_{\ell}|]$ for each $\ell$. Also note that the number of lines is $|L| = |D|/n$.

$$E_T[|M_T|] = E_T\left[\sum_{\ell \in L} |M^T_{\ell}|\right] = \sum_{\ell \in L} E_T[|M^T_{\ell}|] \geq \sum_{\ell \in L} \left(\frac{k}{n} \cdot |\hat{M}(\ell)| - 120k^{5/6}\right) \text{ (by (2))}$$

$$= \left(\frac{k}{n} \cdot \sum_{\ell \in L} |\hat{M}(\ell)|\right) - \left(120k^{5/6} \cdot \frac{|D|}{n}\right) \geq \frac{k}{n} \cdot \left(\frac{|M|}{k^{1/7}} - \frac{|D|}{k^{1/6}}\right) - \left(120k^{5/6} \cdot \frac{|D|}{n}\right) \text{ (by (1))}$$

$$= \frac{k}{n} \cdot \left(|M| - \frac{|D|}{k^{1/7}} - \frac{120k^{5/6}}{k^{1/6}}\right) \geq \frac{k}{n} \cdot \left(|M| - \frac{C \cdot |D|}{k^{1/7}}\right) \tag{3}$$

for a constant $C > 0$, since $\frac{1}{k^{1/7}}$ dominates $\frac{1}{k^{1/6}}$. (3) gives the expected cardinality of our matching after sampling. To recover the distance to monotonicity we simply normalize by the size of the domain. Dividing by $|D_T| = \frac{k}{n} |D|$, we get $E_T[|f_T|] \geq \frac{|M|}{|D|} - \frac{C}{k^{1/7}} = \varepsilon_f - \frac{C}{k^{1/7}}$. This completes the proof of Lemma 1.4. ■

### 3 Stack Bound: Proof of Lemma 1.5

We are given a positive integer $\lambda \geq 2$ and a Boolean function $f : D \to \{0, 1\}$ where $D = [n] \times \left(\prod_{i=2}^{d} [n_i]\right)$ is a rectangular hypergrid for some $n, n_2, \ldots, n_d \in \mathbb{Z}^+$. Lemma 1.5 asserts there is a maximum cardinality matching $M$ such that $\sum_{(\ell,S) : |M^T_{\ell,S}| \geq \lambda} |M^T_{\ell,S}| \leq \frac{6}{\sqrt{\lambda}} \cdot |D|$.

Given a matching $M$, we consider the vector (or technically, list) $\Lambda(M)$ indexed by stacks $(\ell, S)$ with $\Lambda_{\ell,S} := |M^T_{\ell,S}|$, and list these in non-decreasing order. Consider the maximum cardinality matching $M$ in the violation graph of $f$ which has the lexicographically largest $\Lambda(M)$. That is, the minimum entry of $\Lambda(M)$ is maximized, and subject to that the second-minimum is maximized and so on. We claim that this matching serves as the matching we want. To prove this, we henceforth fix this matching $M$ and introduce the following notation.

- **(Low Stacks)** $L := \{(\ell, S) \in L \times S : |M^T_{\ell,S}| \leq \lambda - 2\}$.
- **(High Stacks)** $H := \{(\ell, S) \in L \times S : |M^T_{\ell,S}| \geq \lambda\}$.

Let $V(H)$ denote the set of vertices matched by $\bigcup_{(\ell,S) \in H} M^T_{\ell,S}$. Let $B$ (for blue) be the set of points in $V(H)$ with function value 0, and $R$ (for red) be the set of points in $V(H)$ with function value 1. $M$ induces a perfect matching between $B$ and $R$, and we wish to prove $|B| = |R| \leq \frac{6}{\sqrt{\lambda}} \cdot |D|$. Indeed, define $\delta$ to be such that $|B| = \delta |D|$. In the remainder of the proof, we will prove that $\delta < \frac{6}{\sqrt{\lambda}}$.

We make a simple observation that for any fixed line $\ell$, the number of stacks $(\ell, S)$ which are non-low cannot be “too many”.

8
Claim 3.1. For any line $\ell$, the number of non-low stacks $\ell$ participates in is at most $\frac{n}{\lambda - 1}$.

Proof. Fix any line $\ell$ and consider the set $\bigcup_{S: (\ell, S) \notin L} \{ x_1 : \exists (x, y) \in M(\ell, S) \}$. That is, the set of 1-coordinates that are used by some non-low stack involving $\ell$. The size of this set can’t be bigger than the length of $\ell$, which is $n$. Furthermore, each non-low stack contributes at least $\lambda - 1$ unique entries to this set. The uniqueness follows since the union $\bigcup_{S: (\ell, S) \notin L} M(\ell, S)$ is a matching.

We show that if the number of blue points $|B|$ is large ($> 6|\mathcal{D}| / \sqrt{\lambda}$), then we will find a line participating in more than $n/(\lambda - 1)$ non-low stacks. To do so, we need to “find” these non-low stacks. We need some more notation to proceed. For a vertex $z$, let $\ell_z$ ($S_z$, resp.) denote the unique line (slice, resp.) containing $z$. For each blue point $y \in B$, we define the following interval

$$\mathcal{I}_y := \{ z \in \ell_y : z_1 \in [x_1, y_1] \}$$

where $(x, y) \in M$.

Armed with this notation, we can find our non-low stacks. Our next claim, which is the heart of the proof and uses the potential function, shows that for every high stack $(\ell, S)$, we get a bunch of other “non-low” stacks participating with the line $\ell$.

Claim 3.2. Given $y \in B$, let $x := M^{-1}(y)$ and suppose $(\ell, S) \in H$ is such that $(x, y) \in M(\ell, S)$ (note that this stack, $(\ell, S)$, exists by definition of $B$). Then, for any $z \in \mathcal{I}_y \cap B$, $(\ell, S_z) \notin L$.

Proof. The claim is obviously true if $z = y$, since this implies $S_z = S$ (since $y \in S$) and $(\ell, S) \in H$ by assumption. Therefore, we may assume $z \neq y$, and we also assume, for contradiction’s sake, $(\ell, S_z) \in L$. Note that $x \in \ell$ and by definition of $\mathcal{I}_y$, we get $x < z < y$.

Since $z \in B$, it is matched to some $w \in R$. Note $w < z < y$. Furthermore, the stack $(\ell_w, S_z) \in H$ (by definition of $B$). By assumption of the claim, $(\ell, S) \in H$. In particular, $x, w, z, y \in V(H)$. Now consider the new matching $N$ which deletes $(x, y)$ and $(w, z)$ and adds $(x, z)$ and $(w, y)$. Note that the cardinality of $M$ remains the same.

We now show that $\Lambda(N)$ is lexicographically bigger than $\Lambda(M)$. To see this, consider the stacks whose sizes have changed from $M$ to $N$. There are four of them (since we swap two pairs), namely the stacks $(\ell, S), (\ell_w, S_z), (\ell, S_z)$, and $(\ell_w, S)$. For brevity’s sake, let us denote their sizes in $M$ as $\lambda_1, \lambda_2, \lambda_3$, and $\lambda_4$, respectively. In $N$, their sizes become $\lambda_1 - 1, \lambda_2 - 1, \lambda_3 + 1$, and $\lambda_4 + 1$. Note that $\lambda_3 \leq \lambda - 2$ and both $\lambda_1$ and $\lambda_2$ are $\geq \lambda$. In particular, the “new” size of stack $(\ell, S_z)$ is still smaller than the “new” sizes of stacks $(\ell, S)$ and $(\ell_w, S)$. That is, the vector $\Lambda(N)$, even without the increase in $\lambda_4$, is lexicographically larger than $\Lambda(M)$. Since increasing the smallest coordinate (among some coordinates) increases the lexicographic order, we get a contradiction to the lexicographic maximality of $\Lambda(M)$.

The rest of the proof is a (slightly technical) averaging argument to prove that $|B|$ is small. We introduce some more notation to carry this through. For a blue point $y \in B$, let $\rho_y := \frac{|\mathcal{I}_y \cap B|}{|\mathcal{I}_y|}$ denote the fraction of blue points in $\mathcal{I}_y$. For $\alpha \in (0, 1)$, we say that $y \in B$ is $\alpha$-rich if $\rho_y \geq \alpha$. A point $x \in R$ is $\alpha$-rich if its blue partner $y \in B$ (i.e. $(x, y) \in M$) is $\alpha$-rich. We also call the pair $(x, y)$ an $\alpha$-rich pair.

Claim 3.3. If $|B| = \delta|\mathcal{D}|$, then at least $\delta|\mathcal{D}|/2$ of these points are $\delta/4$-rich.

Proof. Let $B^{(poor)} \subseteq B$ be the points with $\rho_y < \delta/4$. We show $|B^{(poor)}| \leq \delta|\mathcal{D}|/2$ which would prove the claim. To see this, first observe $B^{(poor)} \subseteq \bigcup_{y \in B^{(poor)}} (\mathcal{I}_y \cap B)$. Now consider the minimal subset $B^{(poor)} \subseteq B^{(poor)}$ such that $\bigcup_{y \in B^{(poor)}} \mathcal{I}_y = \bigcup_{y \in B^{(poor)}} \mathcal{I}_y$. That is, given a collection of intervals we are
vertices in $\bigcup S_n$ (Claim 3.2, we know that all these stacks are non-low, that is, denote the set of slices containing blue points from the collection of rich intervals, the cardinality of this set. 

Therefore, 

$$|B^{(poor)}| \leq \left| \bigcup_{y \in B^{(poor)}_\min} (I_y \cap B) \right| = \left| \bigcup_{y \in B^{(poor)}_\min} (I_y \cap B) \right| \leq \sum_{y \in B^{(poor)}_\min} |I_y \cap B|$$ 

$$\leq \frac{\delta}{4} \sum_{y \in B^{(poor)}_\min} |I_y| \leq \frac{\delta}{2} \cdot \left| \bigcup_{y \in B^{(poor)}_\min} I_y \right| \leq \frac{\delta}{2} |D|$$

The first equality follows from the definition of $B^{(poor)}_\min$ (taking intersection with $B$), and the third (strict) inequality follows from the fact that none of these points are $\delta/4$-rich. The fourth inequality is (4). This completes the proof. 

A corollary of Claim 3.3 is that there are at least $|D|/2$ red points which are $\delta/4$-rich. In particular, there must exist some line $\ell$ that contains $\geq \delta n/2$ red points in it which are $\delta/4$-rich. Let this line be $\ell$ and let $R_\ell \subseteq \ell$ be the set of rich red points. Let $B_\ell$ be their partners in $M$. Let $S^\ell = \{ S \in S : \exists z \in S \cap (\bigcup_{y \in B^\ell} I_y \cap B) \}$ denote the set of slices containing blue points from the collection of rich intervals, $\{I_y : y \in B^\ell\}$. By Claim 3.2, we know that all these stacks are non-low, that is, $(\ell, S) \notin L$ for all $S \in S^\ell$. We now lower bound the cardinality of this set. 

Consider the set of blue points in our union of rich intervals from $B^\ell, \bigcup_{y \in B^\ell} I_y \cap B$. There are precisely $n$ slices in total, and for a vertex $z \in D$, $S_z$ is the slice indexed by the 1-coordinate of $z$. Thus, we have $|S^\ell| = |\{z_1 : z \in \bigcup_{y \in B^\ell} I_y \cap B\}|$. That is, $|S^\ell|$ is exactly the number of unique 1-coordinates among vertices in $\bigcup_{y \in B^\ell} I_y \cap B$. 

Since we care about the number of unique 1-coordinates, we consider the “projections” of our sets of interest onto dimension 1. For a set $X \subseteq D$, let $\text{proj}_1(X) := \{ x_1 : x \in X \}$ be the set of 1-coordinates used by points in $X$. In particular, note that for $y \in B$, $\text{proj}_1(I_y) := [x_1, y_1] \subseteq [n]$, where $x := M^{-1}(y)$ and observe that $|S^\ell| = \left| \bigcup_{y \in B^\ell} \text{proj}_1(I_y \cap B) \right|$. Now, given that each interval from $\{I_y\}_{y \in B^\ell}$ is a $\frac{\delta}{4}$-fraction blue, the following claim says that at least a $\frac{\delta}{8}$-fraction of the union of intervals consists of blue points with unique 1-coordinates. 

**Claim 3.4.** $\left| \bigcup_{y \in B^\ell} \text{proj}_1(I_y \cap B) \right| \geq \frac{\delta}{8} \left| \bigcup_{y \in B^\ell} \text{proj}_1(I_y) \right|$ 

*Proof:* As in the proof of Claim 3.2, let $B^{\ell}_{\min} \subseteq B^\ell$ be a minimal cardinality subset of $B^\ell$ such that $\bigcup_{y \in B^{\ell}_{\min}} \text{proj}_1(I_y) = \bigcup_{y \in B^\ell} \text{proj}_1(I_y)$. For any $y \in B$, $y$ belongs to at most two intervals from $B^{\ell}_{\min}$.
The line sampling lemma (Lemma 1.6) states that
\[
\left| \bigcup_{y \in B^l} \text{proj}_1(I_y \cap B) \right| = \left| \bigcup_{y \in B_{min}^l} \text{proj}_1(I_y \cap B) \right| \geq \frac{1}{2} \sum_{y \in B_{min}^l} \left| \text{proj}_1(I_y \cap B) \right| \geq \frac{\delta}{8} \sum_{y \in B_{min}^l} \left| \text{proj}_1(I_y) \right| \geq \frac{\delta}{8} \left| \bigcup_{y \in B^l} \text{proj}_1(I_y) \right|.
\]

Now importantly, \(\left| \text{proj}_1(R^l) \right| = \left| R^l \right| \geq \frac{\delta}{2} \cdot n\) since the 1-coordinates of elements of \(R^l\) are distinct (since \(R^l\) is contained on a single line). Moreover, by definition of \(I_y\), \(\text{proj}_1(R^l) \subseteq \bigcup_{y \in B^l} \text{proj}_1(I_y)\) and so \(\left| \bigcup_{y \in B^l} \text{proj}_1(I_y) \right| \geq \left| \text{proj}_1(R^l) \right| \geq \frac{\delta}{2} \cdot n\). Finally, combining this with Claim 3.4, we get
\[
\left| S^l \right| = \left| \bigcup_{y \in B^l} \text{proj}_1(I_y \cap B) \right| \geq \frac{\delta}{8} \left| \bigcup_{y \in B^l} \text{proj}_1(I_y) \right| \geq \frac{\delta^2}{16} \cdot n.
\]

Therefore, \(\ell\) participates in at least \(\frac{\delta^2}{16} \cdot n\) non-low stacks. Thus, using Claim 3.1, if \(\frac{\delta^2}{16} \cdot n > \frac{n}{x-1} \iff \delta > \frac{4}{\sqrt{x-1}}\), then we have a contradiction. Since \(\lambda \geq 2\), we conclude that \(\delta < 6/\sqrt{x}\). This concludes the proof of Lemma 1.5.

4 Line Sampling: Proof of Lemma 1.6

We recall the lemma for ease of reading. Given a line \(\ell \in \mathcal{L}\), we have defined \(M^{(\ell)} := \{(x, y) \in M : x \in \ell\}\). Given a stack \(S\), we have defined \(M^{(\ell, S)} := \{(x, y) \in M^{(\ell)} : y \in S\}\). Given a multi-set \(T \subseteq [n]\), recall \(M^{(\ell)}\) is the maximum cardinality matching of violations \((x, y)\) such that (a) \(x\) and \(y\) are both matched by \(M^{(\ell)}\), and (b) \(x_1\) and \(y_1\) both lie in \(T\). Given \(\lambda \in \mathbb{Z}^+\) such that \(|M^{(\ell, S)}| \leq \lambda\) for all \(\ell \in \mathcal{L}\) and \(S \in \mathcal{S}\), the line sampling lemma (Lemma 1.6) states
\[
\mathbb{E}_T \left[ |M_T^{(\ell)}| \right] \geq \frac{k}{n} \cdot |M^{(\ell)}| - 3\lambda \sqrt{k \ln k}.
\]

Consider an arbitrary, fixed line \(\ell \in \mathcal{L}\). We use the matching \(M^{(\ell)}\) to induce weights \(w^+(i), w^-(i)\) on \([n]\) as follows. Initially \(w^+(i) = 0\) for all \(i \in [n]\). For each \((x, y) \in M^{(\ell)}\) if \(x \in S_i\) then we increase \(w^+(i)\) by 1, and if \(y \in S_j\) then we increase \(w^-(j)\) by 1. We let \(V^+ := \{i : w^+(i) > 0\}\) and \(V^- := \{j : w^-(j) > 0\}\).

Claim 4.1. We make a few observations.

1. For any \(i \in [n]\), \(w^+(i) \leq 1\).
2. For any \(i \in [n]\), \(w^-(i) \leq \lambda\).
3. For any \(t \in [n]\), \(\sum_{s \leq t} \left( w^-(s) - w^+(s) \right) \leq 0\).

Proof. The first observation follows since the lower endpoints of \(M^{(\ell)}\) all lie on \(\ell\), and thus have distinct 1-coordinates. The second observation follows from the assumption that \(|M^{(\ell, S)}| \leq \lambda\) for all \((\ell, S) \in \mathcal{L} \times \mathcal{S}\). The third observation follows by noting that whenever \(w^-(j)\) is increased for some \(j\), we also increase \(w^+(i)\) for some \(i < j\).
Given a multiset $T \subseteq [n]$, denote $V^+_T := V^+ \cap T$ and $V^-_T := V^- \cap T$. Also, define the bipartite graph $G_T := (V^+_T, V^-_T, E_T)$ where $(i, j) \in E_T$ if $i \leq j$. A $w$-matching $A$ in $G_T$ is a subset of edges of $E_T$ such that every vertex $i \in V^+_T$ has at most $w^+(i)$ edges of $A$ incident on it, and every vertex $j \in V^-_T$ has at most $w^-(j)$ edges of $A$ incident on it. Let $\nu(G_T)$ denote the size of the largest $w$-matching in $G_T$.

**Lemma 4.2.** For any multiset $T \subseteq [n]$ and any $w$-matching $A \subseteq E_T$ in $G_T$, we have $|M^{(0)}_T| \geq |A|$. In particular, $E_T \left[ |M^{(0)}_T| \right] \geq E_T [\nu(G_T)]$.

**Proof.** Consider any $w$-matching $A \subseteq E_T$. For any vertex $i \in V^+_T$, there are at most $w^+(i)$ edges in $A$ incident on it. Each increase of $w^+(i)$ is due to an edge $(x, y) \in M^{(0)}$ where $x_1 = i$. Thus, we can charge each of these edges of $A$ (arbitrarily, but uniquely) to $w^+(i)$ different $x \in \ell$. Similarly, for any vertex $j \in V^-_T$, there are at most $w^-(j)$ edges in $A$ incident on it. Each increase of $w^-(j)$ is due to an edge $(x, y) \in M^{(0)}$ with $y_1 = j$. Thus, we can charge each of these edges of $A$ (arbitrarily, but uniquely) to $w^-(j)$ different $y \in S_j$, the $j$th slice. Furthermore, any $z \in \ell$ with $z_1 \leq j$ satisfies $z < y$. In sum, each $(i, j) \in A$ can be uniquely charged to an $x \in \ell$ with $x_1 = i$ and $y \in S_j$ such that (a) $(x, y)$ forms a violation, (b) $x, y$ were matched in $M^{(0)}$, and (c) $x_1, y_1 \in T$. Therefore, $|M^{(0)}_T| \geq |A|$ since the LHS is the maximum cardinality matching.

**Lemma 4.3.** For any $T \subseteq [n]$, we have

$$\nu(G_T) = \sum_{j \in T} w^-(j) - \max_{t \in T} \sum_{s \in T; s \leq t} (w^-(s) - w^+(s))$$

**Proof.** By Hall’s theorem, the maximum $w$-matching in $G_T$ is given by the total weight on the $V^-_T$ side, that is, $\sum_{j \in T} w^-(j)$, minus the total deficit $\delta(T) := \max_{S \subseteq V^-_T} \left( \sum_{s \in S} w^-(s) - \sum_{s \in \Gamma_T(S)} w^+(s) \right)$ where for $S \subseteq V^-_T$, $\Gamma_T(S) \subseteq V^+_T$ is the neighborhood of $S$ in $G_T$. Consider such a maximizer $S$, and let $t$ be the largest index present in $S$. Then note that $\sum_{s \in \Gamma_T(S)} w^+(s)$ is precisely $\sum_{s \in T; s \leq t} w^+(s)$. Furthermore note that adding any $s \leq t$ from $V^-_T$ won’t increase $|\Gamma_T(S)|$. Thus, given that the largest index present in $S$ is $t$, we get that $\delta(T)$ is precisely the summation in the second term of the RHS. $\delta(T)$ is maximized by choosing the $t$ which maximizes the summation.

Next, we bound the expectation of the RHS in Lemma 4.3. Recall that $T := \{s_1, \ldots, s_k\}$ is a multiset where each $s_i$ is u.a.r. picked from $[n]$. For the first term, we have

$$E_T \left[ \sum_{j \in T} w^-(j) \right] = \sum_{i=1}^k \sum_{j=1}^n \Pr[s_i = j] \cdot w^-(j) = \frac{k}{n} \cdot \sum_{j=1}^n w^-(j) = \frac{k}{n} \cdot |M^{(0)}|.$$  \hspace{1cm} (6)

The second-last equality follows since $s_i$ is u.a.r in $[n]$ and the last equality follows since $\sum_j w^-(j)$ increases by exactly one for each edge in $M^{(0)}$. Next we upper bound the expectation of the second term. For a fixed $t$, define

$$Z_t := \sum_{s \in T; s \leq t} (w^-(s) - w^+(s)) = \sum_{i=1}^k X_{i,t} \text{ where } X_{i,t} = \begin{cases} w^-(s_i) - w^+(s_i) & \text{if } s_i \leq t \\ 0 & \text{otherwise} \end{cases}$$

Note that the $X_{i,t}$’s are i.i.d random variables with $X_{i,t} \in [-1, 1]$ with probability 1. Thus, applying Hoeffding’s inequality we get
\[ \Pr \left[ Z_t > \mathbb{E}[Z_t] + a \right] \leq 2 \exp \left( \frac{-a^2}{2k\lambda^2} \right) \]

Now we use Claim 4.1, part (3) to deduce that

\[ \mathbb{E}[Z_t] = \sum_{i=1}^{k} \mathbb{E}[X_{i,t}] = \sum_{i=1}^{k} \sum_{s \leq t} (w^-(s) - w^+(s)) \cdot \Pr[s_i = s] \leq 0 \]

since \( \Pr[s_i = s] = 1/n \). Therefore, the RHS of the Hoeffding bound is an upper-bound on \( \Pr[Z_t \geq a] \). In particular, invoking \( a := 2\lambda \sqrt{k \ln k} \) and applying a union bound, we get

\[ \Pr \left[ \max_{t \in T} Z_t > 2\lambda \sqrt{k \ln k} \right] = \Pr \left[ \exists t \in T : Z_t > 2\lambda \sqrt{k \ln k} \right] \leq k \cdot e^{-2\ln k} = 1/k \]  

(7)

and since \( \max_{t \in T} Z_t \) is trivially upper-bounded by \( \lambda k \), this implies that

\[ \mathbb{E}_T \left[ \max_{t \in T} \sum_{s \in T : s \leq t} w^-(s) - w^+(s) \right] \leq \lambda k \cdot \Pr \left[ \max_{t \in T} Z_t > a \right] + a \leq \lambda + a \leq 3\lambda \sqrt{k \ln k}. \]  

(8)

Lemma 1.6 follows from Lemma 4.2, Lemma 4.3, (6), and (8).

5 Lower Bound for Domain Reduction

In this section we prove the following lower bound for the number of samples needed for a domain reduction result to hold for distance to monotonicity. Recall the domain reduction experiment: given \( f : [n]^d \rightarrow \{0, 1\} \) and an integer \( k \in \mathbb{Z}^+ \), we choose \( T := T_1 \times \cdots \times T_d \) where for each \( i \in [d], T_i \) is formed by taking \( k \) i.i.d. uniform draws from \([n]\). We then consider the restriction \( f_T \).

**Theorem 5.1 (Lower Bound for Domain Reduction).** There exists a function \( f : [n]^d \rightarrow \{0, 1\} \) with distance to monotonicity \( \varepsilon_f = \Omega(1) \), for which \( \mathbb{E}_T[\varepsilon_{f_T}] \leq O(k^2/d) \).

In particular, the above theorem implies that \( k = \Omega(\sqrt{d}) \) samples in each dimension is necessary to preserve distance to monotonicity.

5.1 Proof of Theorem 5.1

We define the function Centrist : \([0, 1]^d \rightarrow \{0, 1\}\). The continuous domain is just a matter of convenience; any \( n \) that is a multiple of \( d \) would suffice. It is easiest to think of \( d \) individuals voting for an outcome, where the \( i \)th vote \( x_i \) is the “strength” of the vote. Based on their vote, an individual is labeled as follows.

- \( x_i \in [0, 1 - 2/d] \): skeptic
- \( x_i \in (1 - 2/d, 1 - 1/d] \): supporter
- \( x_i \in (1 - 1/d, 1] \): fanatic

Centrist\((x) = 1\) iff there exists some individual who is a supporter. The non-monotonicity is created by fanaticism. If a unique supporter increases her vote to become a fanatic, the function value can decrease.
Claim 5.2. The distance to monotonicity of Centrist is $\Omega(1)$.

Proof. It is convenient to talk in terms of probability over the uniform distribution in $[0, 1]^d$. Define the following events, for $i \in [d]$.

- $S_i$: The $i$th individual is a supporter, and all others are skeptics.
- $F_i$: The $i$th individual is a fanatic, and all others are skeptics.

Observe that all these events are disjoint. Also, $\Pr[S_i] = \Pr[F_i] = (1/d)(1 - 2/d)^{d-1} = \Omega(1/d)$.

Note that $\forall i$, $\Pr[S_i] = 1$ and $\forall x \in S_i$, $\Pr[S_i] = 1$ and $\forall x \in F_i$, $\Pr[F_i] = 0$.

We construct a violation matching $M : \bigcup_i S_i \rightarrow \bigcup_i F_i$. For $x \in S_i$, $M(x) = x + e_i/d$, where $e_i$ is the unit vector in dimension $i$. For $x \in S_i$, $x_i \in (1 - 2/d, 1 - 1/d]$, so $M(x)_i \in (1 - 1/d, 1]$, and $M(x) \in F_i$. $M$ is a bijection between $S_i$ and $F_i$, and all the $S_i, F_i$ sets are disjoint. Thus, $M$ is a violation matching. Since $\Pr[\bigcup_i S_i] = \Omega(d \cdot 1/d)$, the distance to monotonicity is $\Omega(1)$.

Lemma 5.3. Let $k \in \mathbb{Z}^+$ be any positive integer. If $T := T_1 \times \cdots \times T_d$ is a randomly chosen hypergrid, where for each $i \in [d]$, $T_i$ is a set formed by taking $k$ i.i.d. samples from the uniform distribution on $[0, 1]$, then with probability $> 1 - 4k^2/d$, Centrist$_T$ is a monotone function.

Proof. Each $T_i$ consists of $k$ u.a.r. elements in $[0, 1]$. We can think of each as a sampling of the $i$th individual’s vote. For a fixed $i$, let us upper bound the probability that $T_i$ contains strictly more than one non-skeptic vote. This probability is

$$1 - (1 - 2/d)^k - k(1 - 2/d)^{k-1}(2/d) = 1 - (1 - 2/d)^{k-1}(1 - 2/d + 2k/d) \leq 1 - \left(1 - \frac{2(k - 1)}{d}\right) \left(1 + \frac{2(k - 1)}{d}\right) \leq 4k^2/d^2$$

where we have used the bound $(1 - x)^r \geq 1 - xr$, for any $x \in [0, 1]$ and $r \geq 1$. By the union bound over all dimensions, with probability $> 1 - 4k^2/d$, all $T_i$’s contain at most one non-skeptic vote. Consider Centrist$_T$, some $x \in T$, and a dimension $i \in [d]$. If the $i$th individual increases her vote (from $x$), there are three possibilities.

- The vote does not change. Then the function value does not change.
- The vote goes from a skeptic to a supporter. The function value can possibly increase, but not decrease.
- The vote goes from a skeptic to a fanatic. If Centrist$_T(x) = 1$, there must exist some $j \neq i$ that is a supporter. Thus, the function value remains 1 regardless of $i$’s vote.

In no case does the function value decrease. Thus, Centrist$_T$ is monotone.

Theorem 5.1 follows from Claim 5.2 and Lemma 5.3.

References


A Domain Reduction for Variance

In this section, we prove that, given \( f : [n]^d \to \{0,1\} \), restricting \( f \) to a random hypercube (domain reduction with \( k = 2 \)) suffices to preserve the variance of \( f \).
**Theorem A.1** (Domain Reduction for Variance). Let \( f : [n]^d \rightarrow \{0, 1\} \) be any function. If \( T := T_1 \times \cdots \times T_d \) is a randomly chosen sub-hypercube, where for each \( i \in [d] \), \( T_i \) is a (multi)-set formed by taking \( 2 \) i.i.d. samples from the uniform distribution on \([n]\), then \( E_T[\text{var}(f_T)] \geq \text{var}(f)/2 \).

**Proof.** We will interpret \( f \) as a Boolean function with \( d \log n \) (Boolean) inputs, so \( f : \{-1, 1\}^{d \log n} \rightarrow \{-1, 1\} \). We will index the inputs in \([d \log n]\), where the interval \( I_i := [(i - 1) \log n + 1, i \log n] \) (the \( i \)-th block) corresponds to the \( i \)-th input in the original representation. Henceforth, \( i \) will always index a block (and thereby, an input in the original representation). We use \( x_j \) to denote the \( j \)-th input bit.

Let us think of the restriction in Boolean terms. Note that \( f_T : \{-1, 1\}^d \rightarrow \{-1, 1\} \), and we use \( y \) to denote an input to the restriction. In Boolean terms, \( T_i \) picks two u.a.r \( \log n \) bit strings, and forces the \( i \)-th block of inputs, \( I_i \), to be one of these. The choice between these is decided by \( y_i \). Let us think of \( T_i \) as follows. For every \( j \in I_i \), it adds it to a set \( R_i \) with probability \( 1/2 \). All the inputs in \( R_i \) will be fixed, while the inputs in \( I_i \setminus R_i \) are alive (but correlated by \( y_i \)). Then, for every \( j \in I_i \), it picks a.u.a.r bit \( b_j \). (Call this string \( B_i \).) This is interpreted as follows. For every \( j \in R_i \), \( x_j \) is fixed to \( b_j \). For every \( j \in I_i \setminus R_i \), \( x_j \) is set to \( y_i b_j \). The randomness of \( T_i \) can therefore be represented as independently choosing \( R_i \) and \( B_i \).

Consider some non-empty \( S \subseteq I_i \).

\[
\prod_{j \in S} x_j = \prod_{j \in S \cap R_i} b_j \prod_{j \in S \setminus R_i} b_j y_i = y_i^{|S\setminus R_i|} \prod_{j \in S} b_j \tag{9}
\]

The expected value of the Fourier basis function is (as expected) zero. Recall that \( S \) is non-empty.

\[
E_{T_i} \left[ E_y \left[ \prod_{j \in S} x_j \right] \right] = E_{R_i,B_i} \left[ E_y \left[ y_i^{|S\setminus R_i|} \prod_{j \in S} b_j \right] \right] = E_{R_i} \left[ E_y \left[ y_i^{|S\setminus R_i|} \right] \right] \cdot E_{B_i} \left[ \prod_{j \in S} b_j \right] = 0 \tag{10}
\]

If \( |S \setminus R_i| \) is even, then \( \prod_{j \in S} x_j \) is independent of \( y \). Then, \( E_y \left[ \prod_{j \in S} x_j \right]^2 = 1 \). If \( |S \setminus R_i| \) is odd, then \( \prod_{j \in S} x_j \) is linear in \( y_i \) and \( E_y \left[ \prod_{j \in S} x_j \right] = 0 \).

\[
E_{T_i} \left[ E_y \left[ \prod_{j \in S} x_j \right]^2 \right] = \Pr_{R_i \mid |S \setminus R_i| \text{ is even}} = 1/2 \tag{11}
\]

Let us write out the Fourier expansion of \( f \).

\[
f(x) = \sum_{S \in [d \log n]} \hat{f}_S \cdot \chi_S(x) = \sum_{S = S_1 \cup \cdots \cup S_d \atop \forall i, S_i \subseteq I_i} \hat{f}(S) \prod_{i \in [d]} \prod_{x_j \in S_i} x_j
\]

Let us write an expression for the square of the zeroth Fourier coefficient of the restriction.

\[
E_T \left[ \hat{f}_T(\emptyset)^2 \right] = E_T \left[ \left( \sum_{S \in [d \log n]} \hat{f}_S E_y[\chi_S(x)] \right)^2 \right]
\]

We stress that the choice of \( x \) inside the expectations depend on \( y \) (or \( y' \)) in the manner described before
We will write $S = S_1 \cup S_2 \cdots \cup S_d$, where all $S_i$'s are non-empty. We deal with the first term, using (11).

$$\mathbb{E}_T \left[ \hat{f}_T(\emptyset)^2 \right] = \mathbb{E}_T \left[ \sum_S \hat{f}_{S}^2 \mathbb{E}_y [\mathcal{X}_S(x)]^2 + \sum_{S,T; S \neq T} \hat{f}_S \hat{f}_T \mathbb{E}_y [\mathcal{X}_S(x)] \mathbb{E}_y [\mathcal{X}_T(x)] \right]$$

(12)

$$= \sum_S \hat{f}_S^2 \mathbb{E}_T \left[ \mathbb{E}_y [\mathcal{X}_S(x)]^2 \right] + \sum_{S,T; S \neq T} \hat{f}_S \hat{f}_T \mathbb{E}_T \left[ \mathbb{E}_y [\mathcal{X}_S(x)] \mathbb{E}_y [\mathcal{X}_T(x)] \right]$$

(13)

The cross terms will be zero, using calculations analogous for (10) (which is not directly used). We write $S = S_1 \cup \cdots \cup S_d$, where some of these may be empty.

$$\mathbb{E}_T \left[ \mathbb{E}_y [\mathcal{X}_S(x)] \mathbb{E}_y [\mathcal{X}_T(x)] \right] = \mathbb{E}_T \left[ \mathbb{E}_y \left[ \prod_{i \in [d]} \prod_{j \in S_i} x_j \right] \mathbb{E}_y \left[ \prod_{j \in [d]} \prod_{i \in T_j} x_j \right] \right]$$

$$= \prod_{i \in [d]} \mathbb{E}_{R_i,B_i} \left[ \mathbb{E}_{y_{i}} \left[ \prod_{j \in S_i \setminus R_i} x_j \right] \mathbb{E}_{y_{i}} \left[ \prod_{j \in T_j \setminus R_i} x_j \right] \mathbb{E}_{B_i} \left[ \prod_{j \in S_i \Delta T_i} b_j \right] \right]$$

There must exist some $i$ such that $S_i \Delta T_i \neq \emptyset$. For that $i$, $\mathbb{E}_{B_i} \left[ \prod_{j \in S_i \Delta T_i} b_j \right] = 0$, and thus for $S \neq T$, $\mathbb{E}_T \left[ \mathbb{E}_y [\mathcal{X}_S(x)] \mathbb{E}_y [\mathcal{X}_T(x)] \right] = 0$. Plugging these bounds in,

$$\mathbb{E}_T \left[ \hat{f}_T(\emptyset)^2 \right] \leq \hat{f}(\emptyset)^2 + \sum_{S \neq \emptyset} \hat{f}(S)^2 / 2 = 1 - \text{var}(f) + \text{var}(f) / 2 = 1 - \text{var}(f) / 2$$

We rearrange to get $\mathbb{E}_T [\text{var}(f)] = \mathbb{E}_T \left[ 1 - \hat{f}_T(\emptyset)^2 \right] \geq \text{var}(f) / 2$. ■