# Estimation of Graph Isomorphism Distance in the Query World 

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#### Abstract

The graph isomorphism distance between two graphs $G_{u}$ and $G_{k}$ is the fraction of entries in the adjacency matrix that has to be changed to make $G_{u}$ isomorphic to $G_{k}$. We study the problem of estimating, up to a constant additive factor, the graph isomorphism distance between two graphs in the query model. In other words, if $G_{k}$ is a known graph and $G_{u}$ is an unknown graph whose adjacency matrix has to be accessed by querying the entries, what is the query complexity for testing whether the graph isomorphism distance between $G_{u}$ and $G_{k}$ is less than $\gamma_{1}$ or more than $\gamma_{2}$, where $\gamma_{1}$ and $\gamma_{2}$ are two constants with $0 \leq \gamma_{1}<\gamma_{2} \leq 1$. It is also called the tolerant property testing of graph isomorphism in the dense graph model. The non-tolerant version (where $\gamma_{1}$ is 0 ) has been studied by Fischer and Matsliah (SICOMP'08).

In this paper, we study both the upper and lower bounds of tolerant graph isomorphism testing. We prove an upper bound of $\widetilde{\mathcal{O}}(n)$ for this problem. Our upper bound algorithm crucially uses the tolerant testing of the well studied Earth Mover Distance (EMD), as the main subroutine, in a slightly different setting from what is generally studied in property testing literature.

Testing tolerant EMD between two probability distributions is equivalent to testing EMD between two multi-sets, where the multiplicity of each element is taken appropriately, and we sample elements from the unknown multi-set with replacement. In this paper, our (main conceptual) contribution is to introduce the problem of (tolerant) EMD testing between multi-sets (over Hamming cube) when we get samples from the unknown multi-set without replacement and to show that this variant of tolerant testing of EMD is as hard as tolerant testing of graph isomorphism between two graphs. Thus, while testing of equivalence between distributions is at the heart of the non-tolerant testing of graph isomorphism, we are showing that the estimation of the EMD over a Hamming cube (when we are allowed to sample without replacement) is at the heart of tolerant graph isomorphism. We believe that the introduction of the problem of testing EMD between multi-sets (when we get samples without replacement) opens an entirely new direction in the world of testing properties of distributions.


[^0]
## 1 Introduction

Graph isomorphism (GI) has been one of the most celebrated problems in computer science. Roughly speaking, the graph isomorphism problem asks whether two graphs are structurepreserving. Namely, given two graphs $G_{u}$ and $G_{k}$, graph isomorphism of $G_{u}$ and $G_{k}$ is a bijection $\psi: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ such that for all pair of vertices $u, v \in V\left(G_{u}\right)$, the edges $\{u, v\} \in E\left(G_{u}\right)$ if and only if $\{\psi(u), \psi(v)\} \in E\left(G_{k}\right){ }^{1}$. One central open problem in complexity theory is whether the graph isomorphism problem can be solved in polynomial time. Recently in a breakthrough result, Babai [Bab16] proved that the graph isomorphism problem could be decided in quasi-polynomial time.

For a central problem like the graph isomorphism, naturally, one would like to understand its (and related problems) computational complexity for various models of computation. While most of the focus has been on the standard time complexity in the RAM model for various classes of graphs (and hyper-graphs), other complexity measures like space complexity, parameterized complexity, and query complexity have also been studied over the past few decades (see the Dagstuhl Report [BDST15] and PhD thesis of Sun [Sun16]).

A natural extension of the GI problem is to estimate the "graph isomorphism distance" between two graphs. In other words, given two graphs $G_{u}$ and $G_{k}$, what fraction of edges are necessary to add or delete to make the graphs isomorphic.

Definition 1.1. Let $G_{u}=\left(V_{u}, E_{u}\right)$ and $G_{k}=\left(V_{k}, E_{k}\right)$ be two graphs with $\left|V_{u}\right|=\left|V_{k}\right|=n$. Given a bijection $\phi: V_{u} \rightarrow V_{k}$, the distance between the graphs $G_{u}$ and $G_{k}$ with respect to the bijection $\phi$ is

$$
d_{\phi}\left(G_{u}, G_{k}\right):=\mid\left\{(u, v): \text { Exactly one among }(u, v) \in E_{u} \text { or }(\phi(u), \phi(v)) \in E_{k} \text { holds }\right\} \mid .
$$

The Graph Isomorphism Distance (or GI-distance in short) between graphs $G_{u}$ and $G_{k}$ is defined as $\min _{\phi: V_{u} \rightarrow V_{k}} d_{\phi}\left(G_{u}, G_{k}\right) / n^{2}$, and is denoted by $\delta_{G I}\left(G_{u}, G_{k}\right)$ (we will use $d\left(G_{u}, G_{k}\right)$ to mean $\left.n^{2} \delta_{G I}\left(G_{u}, G_{k}\right)\right)$.

The problem of computing GI-distance between two graphs is known to be \#P-hard [Lin94]. The next natural question is:

What is the complexity for approximating (either by a constant additive or multiplicative factor) the graph isomorphism distance between two graphs?

In [Lin94], it was also proven that the problem of computing GI-distance between two graphs is APX-hard. So, approximating $\delta_{G I}\left(G_{u}, G_{k}\right)$ up to a constant multiplicative factor is $N P$-hard. In this paper, we study this problem of approximating (up to a constant additive factor) the GI-distance between two graphs in the query model.

### 1.1 Property Testing of Graph Isomorphism

Formally speaking, the main problem is: given two graphs $G_{u}$ and $G_{k}$ and an approximation parameter $\zeta \in(0,1)$, the goal is to output an estimate $\alpha$ such that

$$
\delta_{G I}\left(G_{u}, G_{k}\right)-\zeta \leq \alpha \leq \delta_{G I}\left(G_{u}, G_{k}\right)+\zeta .
$$

[^1]In the query model, the problem is equivalent (up to a constant factor) to the tolerant property testing of graph isomorphism in the dense graph model (introduced in the work of Parnas, Ron and Rubinfeld [PRR06]). For $0 \leq \gamma<1$, two graphs $G_{u}$ and $G_{k}$, with $n$ vertices, are called $\gamma$-close or $\gamma$-far to isomorphi ${ }^{2}$ if $d\left(G_{u}, G_{k}\right) \leq \gamma n^{2}$ or $d\left(G_{u}, G_{k}\right) \geq \gamma n^{2}$ respectively. In $\left(\gamma_{1}, \gamma_{2}\right)$-tolerant GI testing, we are given two graphs $G_{u}$ and $G_{k}$, and two parameters $0 \leq \gamma_{1}<\gamma_{2} \leq 1$, with the guarantee that either the graphs are $\gamma_{1}$-close or $\gamma_{2}$-far. One of the graphs (usually denoted as $G_{u}$ ) is accessed by querying the entries of its adjacency matrix. In contrast, the other graph (usually denoted as $G_{k}{ }^{3}$ ) is known to the query algorithm, and no cost for accessing the entries of the adjacency matrix of $G_{k}$ is incurred. The query complexity is the number of queries (to the adjacency matrix of $G_{u}$ ) that are required for testing, (with correctness probability at least $2 / 3{ }^{4}$ ), whether $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close or $\gamma_{2}$-far. The query algorithm is assumed to have unbounded computational power.

The non-tolerant property testing version of the graph isomorphism problem (that is, when $\gamma_{1}=$ 0) was first studied by Fischer and Matsliah [FM08] and subsequently, Babai and Chakraborty [BC10] studied the non-tolerant property testing version of the hypergraph isomorphism problem. Like many other problems in property testing, the core difficulty in testing of GI is understanding certain properties of distributions. In the case of the non-tolerant version of GI, it was shown in [FM08] that the core problem is the testing the variation distance between two distributions. In fact, their upper bound result can be restated as: if there is a property testing algorithm, with query complexity $q(n)$ for testing equivalence between two distributions, on support size $n n^{5}$, then GI can be tested using $\widetilde{\mathcal{O}}(q(n))$ queries, where the tilde hides a polylogarithmic factor of $n$ (number of vertices). And since the query complexity for testing equivalence of distributions (from [ $\left.\mathrm{BFF}^{+} 01\right]$ ) is known to be $\widetilde{\mathcal{O}}(\sqrt{n})$, the query complexity for GI-testing was $\widetilde{\mathcal{O}}(\sqrt{n})$. In the lower bound proof of [FM08], there was no direct reduction of the graph isomorphism problem to the variation distance problem. But it is important to note that lower bound proofs for both of these problems use the tightness of the birthday paradox. So in some sense, one can say that the heart of the non-tolerant testing of GI is in the testing of variation distance between two distributions.

In this paper, we consider both the upper and lower bound on the query complexity of the tolerant version of the GI between a known and an unknown graph. Similar to the case of nontolerant testing of GI, we show that the heart of the problem of tolerant testing of GI is in testing a certain property of distributions - but with a slight and surprising twist.

### 1.2 Earth Mover's Distance (EMD)

Let $H=\{0,1\}^{n}$ be a Hamming cube of dimension $n$, and $p, q$ be two probability distributions on H. The Earth Mover's Distance between $p$ and $q$ is denoted by $\operatorname{EMD}(p, q)$ and defined as the optimum solution to the following linear program:

$$
\text { Minimize } \sum_{i, j \in H} f_{i j} d_{H}(x, y) \quad \text { Subject to } \sum_{j \in H} f_{i j}=p(i) \forall i \in H \text {, and } \sum_{i \in H} f_{i j}=q(j) \forall j \in H \text {. }
$$

A standard way to think of sampling from any probability distribution is to consider it as a

[^2]multi-set of elements with appropriate multiplicities, and samples are drawn with replacement from that multi-set. While estimating EMD between two multi-sets, although the most natural way to access the unknown multi-set is sampling with replacement, we introduce the problem of tolerant EMD testing over multi-sets with the access of samples without replacement.

Definition 1.2 (EMD over multi-sets while sampling with and without replacement). Let $S_{k}$ and $S_{u}$ denote the known and the unknown multi-sets, respectively, over $n$-dimensional Hamming cube $H=\{0,1\}^{n}$ such that $\left|S_{u}\right|=\left|S_{k}\right|=n$. Consider the two distributions $p_{u}$ and $p_{k}$ over the Hamming cube $H$ that are naturally defined by the sets $S_{u}$ and $S_{k}$ where for all $x \in H$ probability of $x$ in $p_{u}$ (and $p_{k}$ ) is the number of occurrences of $x$ in $S_{u}$ (and $S_{k}$ ) divided by $n$. We then define the EMD between the multi-sets $S_{u}$ and $S_{k}$ as

$$
E M D\left(S_{u}, S_{k}\right) \triangleq n \cdot E M D\left(p_{u}, p_{k}\right)
$$

The problem of estimating the EMD over multi-sets while sampling with (or without) replacement means designing an algorithm, that given any two constants $\beta_{1}, \beta_{2}$ such that $0 \leq \beta_{1}<\beta_{2} \leq 1$, and access to the unknown set $S_{u}$ by sampling with (or without) replacement decides whether $E M D\left(S_{k}, S_{u}\right) \leq \beta_{1} n^{2}$ or $E M D\left(S_{k}, S_{u}\right) \geq \beta_{2} n^{2}$ with probability at least $2 / 3$.

Note that estimating the EMD over multi-sets while sampling with replacement is exactly same as estimating EMD between the distributions $p_{u}$ and $p_{k}$ with samples drawn according to $p_{u}$.

We will denote by $\operatorname{QWR}_{\operatorname{EMD}}\left(n, \beta_{1}, \beta_{2}\right)$ (and $\left.\operatorname{QWOR}_{\operatorname{EMD}}\left(n, \beta_{1}, \beta_{2}\right)\right)$ the number of samples with (or without) replacement required to decide the above from the unknown multi-set $S_{u}$. For ease of presentation, we will write $\operatorname{QWOR}_{\operatorname{EMD}^{(n)}\left(\operatorname{QWR}_{\mathrm{EMD}}(n)\right) \text { instead of } \operatorname{QWOR}_{\operatorname{EMD}}\left(n, \beta_{1}, \beta_{2}\right)}$ $\left.\operatorname{QWR}_{\mathrm{EMD}}\left(n, \beta_{1}, \beta_{2}\right)\right)$ when the proximity parameters are clear from the context.

Earth Mover's Distance (EMD) is a fundamental metric over the space of distributions supported on a fixed metric space. Estimating EMD between two distributions, up to a multiplicative factor, has been extensively studied in mathematics and computer science. It is closely related to the embedding of the EMD metric into a $\ell_{1}$ metric. Even the problem of estimation of EMD between distributions up to an additive factor has been well studied. The hardness of estimating EMD between distributions depends heavily on the structure of the domain on which the distributions are supported. In [DBNNR11], the authors have proved a lower bound of $\Omega\left((\Delta / \epsilon)^{d}\right)$ on the query complexity for estimating (up to an additive error of $\epsilon$ ) EMD between two distributions supported on the real cube $[0, \Delta]^{d}$. At the same time, it is not hard to see that if the support has certain structures, estimating EMD may be easy. In this paper, we focus on the estimation of EMD between two distribution when the metric space is the Hamming cube.

As noted earlier, sample access to a probability distribution is precisely the same as uniform sampling from a multi-set with replacement. Thus from the results of Valiant and Valiant [VV11], it can be shown that the sample complexity for estimating the EMD between two distribution over the Hamming cube of dimension $n$ is $\Omega(n / \log n)$. In other words, $\operatorname{QWR}_{E M D}(n)=\Omega(n / \log n)$, and this is tight ignoring polynomial factor in $\log n$ (See Theorem B.10 of AppendixB). But what about $\operatorname{QWOR}_{\operatorname{EMD}}(n)$ ? To the best of our knowledge, the sample complexity measure when the distributions are accessed by sampling a multi-set without replacement has never been studied before, even for other properties of distributions. But it can be shown that: if $\operatorname{QWOR}_{\operatorname{EMD}}(n)=$ $o(\sqrt{n})$, then $\operatorname{QWR}_{\mathrm{EMD}}(n)=o(\sqrt{n})$ (See Proposition B.7 of Appendix B. As $\mathrm{QWR}_{\mathrm{EMD}}(n)=$ $\Omega(n / \log n)$, we have a lower bound of $\Omega(\sqrt{n})$ on $\operatorname{QWOR}_{\left.\mathrm{EMD}^{( }\right)}(n)$. To the best of our knowledge, there is no technique or result that would help us obtain a better lower bound than $\Omega(\sqrt{n})$ for
$\operatorname{QWOR}_{\operatorname{EMD}}(n)$, although a lower bound of $\Omega(n / \log n)$ exists for $\operatorname{QWR}_{\operatorname{EMD}}(n)$. We present the following conjecture:

Conjecture 1. There exist two constants $\beta_{1}$ and $\beta_{2}$ with $0<\beta_{1}<\beta_{2}<1$ such that in order to decide whether $E M D\left(S_{k}, S_{u}\right) \leq \beta_{1} n^{2}$ or $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq \beta_{2} n^{2}$, with probability at least $2 / 3, \Omega\left(\frac{n}{\log n}\right)$ samples without replacement from the unknown multi-set $S_{u}$ are necessary.

One of our main contributions in this paper is introducing this complexity measure of QWOR EMD $^{(n)}$ as well as the above conjecture. In the rest of the paper, we prove the central role of this problem plays in understanding the query complexity of tolerant GI-testing.

For a formal discussion on EMD over Hamming cube, please refer to Appendix B.

### 1.3 Our Results

Our main result of this paper is that we prove estimating GI-distance is as hard as tolerant EMD testing over multi-sets with the access of samples without replacement over the unknown multi-set $S_{u}$, ignoring polynomial factors of $\log n$.
Theorem 1.3. Let $G_{k}$ and $G_{u}$ denote the known and the unknown graphs on $n$ vertices, respectively, and $Q_{G I}\left(G_{u}, G_{k}\right)$ denotes the number of adjacency queries to $G_{u}$, required by the best algorithm that takes two constants $\gamma_{1}, \gamma_{2}$ with $0 \leq \gamma_{1}<\gamma_{2} \leq 1$ and decides whether $d\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$ or $d\left(G_{u}, G_{k}\right) \geq \gamma_{2} n^{2}$ with probability at least $2 / 3$. Then

$$
Q_{G I}\left(G_{u}, G_{k}\right)=\widetilde{\Theta}\left(\operatorname{QWOR}_{\mathrm{EMD}}(n)\right)
$$

where $\widetilde{\Theta}(\cdot)$ hides polynomial factors in $\frac{1}{\gamma_{2}-\gamma_{1}}$ and $\log n$.
Note that $\mathrm{QWor}_{\operatorname{EMD}}(n)=\mathcal{O}(n)$. As a corollary to the above theorem, we obtain an upper bound on the query complexity of estimating GI-distance.
Corollary 1.4 (Upper bound of estimating GI-distance). Given a known graph $G_{k}$ and an unknown graph $G_{u}$ and any approximation parameter $\zeta \in(0,1)$, there is a query algorithm that makes $\widetilde{\mathcal{O}}(n)$ queries and outputs a number $\alpha$ such that, with probability at least $2 / 3$, the following holds:

$$
\delta_{G I}\left(G_{u}, G_{k}\right)-\zeta \leq \alpha \leq \delta_{G I}\left(G_{u}, G_{k}\right)+\zeta .
$$

Let us now consider the case when $\beta_{1}=0$ and $\beta_{2}=\gamma$ in Definition 1.2 For this set of parameters, it can be shown that $\operatorname{QWR}_{\mathrm{EMD}}(n)=\Omega(\sqrt{n})$, which follows from the result on sample complexity of identity testing of distributions by Batu et.al [ $\left.\mathrm{BFF}^{+} 01\right]$. This implies that for $\beta_{1}=0$ and $\beta_{2}=\gamma, \operatorname{QWOR}_{\operatorname{EMD}}(n)=\Omega(\sqrt{n})$. Following Proposition B.7 along with Theorem 1.3, we can get an alternative proof of the following lower bound proved by Fischer and Matsliah [FM08].
Corollary 1.5 (Fischer and Matsliah [FM08]). There exists a constant $\zeta \in(0,1)$ such that any query algorithm that decides, with probability at least $2 / 3$, if a known graph $G_{k}$ and an unknown graph $G_{u}$ is isomorphic or $\gamma$-far from isomorphic, with $\gamma \leq \zeta$, must make $\Omega(\sqrt{n})$ queries.

Although we do not have any non-trivial lower bound of tolerant EMD testing over multi-sets, we conjecture (in Conjecture 1) that the bound is tight, ignoring polynomial factors of $\log n$. Note that if Conjecture 1 is true, then following Theorem 1.3. we can say that there exists a constant $\zeta \in(0,1)$ such that any query algorithm that estimates the GI-distance between a known graph $G_{k}$ and an unknown graph $G_{u}$ up to an additive factor of $\zeta$, with correctness probability at least 2/3, must make $\Omega(n / \log n)$ queries.

Organization of the paper. In Section 2, we discuss the proof techniques of our main results. We present the lower bound and upper bound proofs of Theorem 1.3 in Sections 3 and 4 respectively. We finally conclude in Section 5 . Every theorem, lemma, and claim, whose proof has been moved to the appendix, is marked with $\star$.

Notations All graphs considered here are undirected, unweighted, and have no self-loops or parallel edges. For a graph $G(V, E), V(G)$ and $E(G)$ will denote the vertex set and the edge set of $G$, respectively. Since we are considering undirected graphs, we write an edge $(u, v) \in E(G)$ as $\{u, v\}$. The Hamming distance between two points $x$ and $y$ in a Hamming cube $\{0,1\}^{k}$ will be denoted by $d_{H}(x, y)$.

## 2 Discussion on our Proofs

### 2.1 Discussion on the lower bound proof for query complexity

For the lower bound part of our Theorem 1.3, we give a reduction from estimating EMD of multi-sets over the Hamming cube without replacement to estimating the GI-distance between two graphs.

In this reduction, we have crucially used the fact that the multi-sets are composed of elements from the Hamming cube. The reduction is kind of a clever but somewhat involved gadget construction. In fact we show the lower bound for a slightly more powerful query rather than the standard adjacency matrix query that is commonly used in the dense graph model of property testing. The most interesting part of our lower bound proof is that thanks to our reduction, we get to observe the importance of the model of accessing the multi-set without replacement in the context of EMD testing. We are not aware of any previous work in property testing where this model of accessing a set by sampling without replacement has been studied.

One might compare our proof technique to the lower bound proof of (non-tolerant) testing of GI from [FM08]. In [FM08], $\Omega(\sqrt{n})$ lower bound was proved directly (using Yao's lemma) by constructing two distributions of YES instances and NO instances - the construction of the YES and NO instances were inspired from the tightness of the birthday paradox, which was also the core idea behind the lower bound proof of the equivalence testing of two probability distributions. But, there was no direct reduction from equivalence testing of two probability distributions to GI testing. But in our lower bound proof, we establish a direct reduction to estimating EMD of multi-sets on the Hamming cube without replacement. This can be of much importance, mainly while considering other models of computation, like in the communication model. From our reduction, we can obtain an alternative proof of $\Omega(\sqrt{n})$ lower bound for the (non-tolerant) GI testing via the $\Omega(\sqrt{n})$ lower bound of the equivalence testing of distributions, as pointed out in Corollary 1.5

### 2.2 Discussion on the upper bound proof for query complexity

The upper bound part of Theorem 1.3 is the main technical contribution of this paper. For the upper bound proof of the tolerant GI testing, our query algorithm is inspired by the algorithm of Fischer and Matsliah [FM08] for non-tolerant GI testing, but at the same time, our algorithm and its analysis are very different from that of [FM08] and is way more complicated and involved.

Fischer-Matsliah's algorithm is very much tuned for the non-tolerant version of GI testing. They essentially use the fact that if $G_{u}$ and $G_{k}$ are isomorphic, then there is a mapping between the vertex sets that makes the edge sets identical. Their algorithm tries to find whether such a mapping exists by cleverly querying induced subgraphs of $G_{u}$ and checking if there exists a mapping of the queried vertices into the vertex set of $G_{k}$ that can be extended to the whole of the vertex set. So, if for a mapping, there is an edge in $G_{u}$ but not in $G_{k}$ (or vice versa), it is rejected immediately. Let us first recollect Fischer-Matsliah's algorithm (FM-ALG).

FM-ALG has two phases. In the first phase, they query an induced subgraph (on $\mathcal{O}\left(\log ^{2} n\right)$ vertices) of $G_{u}$. The set of vertices of the induced graph is called the "core" set of vertices. They identify all the possible placements of the core set in the known graph $G_{k}$. Since they were only interested in the non-tolerant setting, a possible placement is a mapping of the vertices in the core set into the vertices of $G_{k}$ such that the edge sets are not conflicting. The core set of vertices defines a label for each vertex in $G_{u}$ : label of vertex $v$ is the vector representing its neighbors in the core set. The collection of labels of vertices in $G_{u}$ can be thought of as a distribution $\mu_{u}$ on the set of all possible labels. Similarly, for each placement $c$, of the core set into $G_{k}$, the labels of the vertices in $G_{k}$ gives the distribution $\mu_{k}^{c}$. Finally, in Phase 1, they test a "global property" of the graph by testing if for a particular placement $c$, the variation distance between $\mu_{k}^{c}$ and $\mu_{u}$ is zero or more than $\epsilon$. This can be done simultaneously for all possible placements with query complexity $\widetilde{\mathcal{O}}(\sqrt{n})$, using (non-tolerant) testing algorithm for equivalence of distributions from [ $\mathrm{BFF}^{+} 01$ ]. Only those placements that pass the test are kept as "possible placements". In Phase 2, a newly induced subgraph of $G_{u}$ (on $\mathcal{O}\left(\log ^{4} n\right)$ vertices) is queried along with the labels of all the newly selected vertices. If there exists a possible placement that can be extended to a suitable placement of the new vertices, the tester outputs that $G_{u}$ is isomorphic to $G_{k}$.

FM-ALG cannot be adapted to tolerant GI testing. To start with, if $G_{u}$ and $G_{k}$ are close, every possible mapping of the core set into vertices of $G_{k}$ can be extended into a mapping of the whole vertex set such that the edge sets of $G_{u}$ and $G_{k}$ are close (but not necessarily identical). So, no placement can be ruled out easily. Likewise, if $G_{u}$ and $G_{k}$ are close, the distribution $\mu_{u}$ and $\mu_{k}^{c}$ may be close in variation distance (but not necessarily identical). So, one possible option is to use tolerant testing of distributions for $\mu_{u}$ and $\mu_{k}^{c}$. But, the proof of correctness of the algorithm would not go through even with the tolerant testing of the equivalence of distributions. The central innovation in our upper bound result is that we use Earth Mover's Distance instead of variation distance between the distributions $\mu_{u}$ and $\mu_{k}^{c}$ for testing the "global property". In order to handle all these technical hurdles, our algorithm and its analysis become much more delicate and involved.

## 3 Lower Bound Results

In this section, we prove that it is necessary to perform $\Omega\left(\operatorname{QWOR}_{\operatorname{EMD}}(n)\right)$ many queries to the adjacency matrix of $G_{u}$ to solve $\left(\gamma_{1}, \gamma_{2}\right)$-tolerant GI testing of $G_{k}$ and $G_{u}$.

Theorem 3.1 (Restatement of the lower bound part of Theorem 1.3). Let $G_{k}$ be the known and $G_{u}$ be the unknown graph on $n$ vertices, where $n \in N$ is sufficiently large. There exists a constant $\epsilon_{I S O} \in(0,1)$ such that for any given constants $\gamma_{1}, \gamma_{2}$ with $0<\gamma_{1}<\gamma_{2}<\epsilon_{I S O}$, any algorithm that decides whether the graphs are $\gamma_{1}$-close or $\gamma_{2}$-far, requires QWOR $_{\mathrm{EMD}^{( }{ }^{(n)} \text { adjacency queries to the unknown graph } \mathrm{G}_{u} \text { where }{ }^{\text {w }} \text {, }}$ QWOR ${ }_{E M D}$ is as defined in Definition 1.2

To prove Theorem 3.1, we show a reduction from tolerant GI testing to tolerant EMD testing over multi-sets when we have samples without replacement from the unknown multi-set.

Lemma 3.2. Suppose there is a constant $\epsilon_{0} \in\left(0, \frac{1}{2}\right)$ such that for all constants $\gamma_{1}, \gamma_{2}$ with $0<\gamma_{1}<$ $\gamma_{2}<\epsilon_{0}$ and any constant $T \in \mathbb{N}$, the following holds. There exists a $\left(\gamma_{1}, \gamma_{2}\right)$-tolerant tester for GI that, given a known graph $G_{k}$ and an unknown graph $G_{u}$ with $\left|V\left(G_{u}\right)\right|=\left|V\left(G_{k}\right)\right|=(T+1) n$, can distinguish whether $d\left(G_{u}, G_{k}\right) \leq \gamma_{1} \operatorname{Tn}^{2}$ or $d\left(G_{u}, G_{k}\right) \geq \gamma_{2} T n^{2}$ by performing $Q$ adjacency queries to $G_{u}$.

Then, for any constants $\beta_{1}$ and $\beta_{2}$ with $0<\beta_{1}<\beta_{2}<\frac{\epsilon_{0}}{2}$, the following holds where $\kappa=\frac{\beta_{2}-\beta_{1}}{8}$ and $T_{\kappa}=\left\lceil\frac{18}{\kappa(2-\kappa)}\right\rceil$. There is a tolerant tester for EMD such that, given a known and an unknown multi-set $S_{k}$ and $S_{u}$ respectively, of the Hamming cube $\{0,1\}^{T_{k} n}$ with $\left|S_{k}\right|=\left|S_{u}\right|=n$, can distinguish whether $\operatorname{EMD}\left(S_{k}, S_{u}\right) \leq \beta_{1} T_{k} n^{2}$ or $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq \beta_{2} T_{k} n^{2}$ with $Q$ many samples without replacement from $S_{u}$.

Remark 1. Observe that Lemma 3.2 talks about tolerant EMD testing between multi-sets with $n$ elements over a Hamming cube of dimension $T_{\kappa} n$. But Theorem 3.1 states the lower bound of $\mathrm{QWOR}_{\mathrm{EMD}}{ }^{(n)}$, that is, of tolerant $E M D$ testing of multi-sets with $n$ elements over a Hamming cube of dimension $n$. However, the query complexity of $E M D$ testing increases with the dimension of the Hamming cube (See Proposition B.9). So, we will be done with the proof of Theorem 3.1 by proving Lemma 3.2 .

### 3.1 Tolerant GI to Tolerant EMD testing: Proof of Lemma 3.2

To define the necessary reduction for the proof of Lemma 3.2. we need to show the existence of a graph $G_{p}$ satisfying some unique properties.

Lemma $3.3(\star)$. Let $\kappa \in(0,1)$ and $s \geq 3$ be given constants. Then for $C_{\kappa, s}=\left\lceil\frac{6 s}{\kappa(2-\kappa)}\right\rceil$ and sufficiently large $n \in \mathbb{N}^{6}$, there exists a graph $G_{p}$ with $C_{\kappa, s} n$ many vertices such that the following conditions hold.
(i) The degree of each vertex in $G_{p}$ is at least $\left((1-\kappa) C_{\kappa, s}+1\right) n-1$.
(ii) The cardinality of symmetric difference between the sets of neighbors of any two (distinct) vertices in $G_{p}$ is at least sn -2 .

The proof of Lemma 3.3 uses probabilistic method and is presented in the Appendix C.1.
Let $\operatorname{ALG}\left(\gamma_{1}, \gamma_{2}, T\right)$ be the algorithm that takes $\gamma_{1}$ and $\gamma_{2}$ with $0<\gamma_{1}<\gamma_{2}<\epsilon_{0}$ as input and decides whether $d\left(G_{k}, G_{u}\right) \leq \gamma_{1} T n^{2}$ or $d\left(G_{k}, G_{u}\right) \geq \gamma_{2} T n^{2}$, where $\left|V\left(G_{k}\right)\right|=\left|V\left(G_{u}\right)\right|=(T+1) n$. Now we show that for any two constants $\beta_{1}$ and $\beta_{2}$ with $0<\beta_{1}<\beta_{2}<\frac{\epsilon_{0}}{2}, \kappa=\frac{\beta_{2}-\beta_{1}}{8}$ and $T_{\kappa}=\left\lceil\frac{6 s}{\kappa(2-\kappa)}\right\rceil$, there exists an algorithm $\mathcal{A}\left(\beta_{1}, \beta_{2}, \kappa, T_{\kappa}\right)$ that can test whether two multi-sets $S_{k}$ and $S_{u}$ over the $T_{\kappa} n$-dimensional Hamming cube have EMD less than $T_{\kappa} \beta_{1} n^{2}$ or more than $T_{\kappa} \beta_{2} n^{2}$ with $Q$ many queries to the multi-set $S_{u}$. To be specific, algorithm $\mathcal{A}\left(\beta_{1}, \beta_{2}, \kappa, T_{\kappa}\right)$ for EMD testing will use algorithm $\operatorname{ALG}\left(\gamma_{1}, \gamma_{2}, T\right)$ for $\left(\gamma_{1}, \gamma_{2}\right)$-tolerant GI such that $\gamma_{1}=2 \beta_{1}, \gamma_{2}=2 \beta_{2}-2 \kappa$ and $T=T_{\kappa}$. Note that, as $0<\beta_{1}<\beta_{2}<\frac{\epsilon_{0}}{2}$ and $\kappa=\frac{\beta_{2}-\beta_{1}}{8}, 0<\gamma_{1}<\gamma_{2}<\epsilon_{0}$ holds. The details of the reduction, that is, algorithm $\mathcal{A}$ is described below.

[^3]
## Description of the reduction

Input: A known multi-set $S_{k}=\left\{k_{1}, \ldots, k_{n}\right\}$ over $H_{T_{\kappa} n}=\{0,1\}^{T_{\kappa} n}$ and query access to an unknown multi-set $S_{u}=\left\{u_{1}, \ldots, u_{n}\right\}$ over $H_{T_{\kappa} n}$.

Goal: To decide whether $\operatorname{EMD}\left(S_{k}, S_{u}\right) \leq T_{\kappa} \beta_{1} n^{2}$ or $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq T_{\kappa} \beta_{2} n^{2}$.
Construction of $G_{k}$ and $G_{u}$ from $S_{k}$ and $S_{u}$ : Let us first construct the graph $G_{k}$ from $S_{k}$. $G_{k}$ has $\left(T_{\kappa}+1\right) n$ vertices partitioned into two parts $A_{k}=\left\{a_{1}, \ldots, a_{n}\right\}$ and $B_{k}=\left\{b_{1}, \ldots, b_{T_{\kappa} n}\right\}$. Now the edges of $G_{k}$ are described as follows:

- $G_{k}\left[A_{k}\right]$ is a clique with $n$ vertices.
- $G_{k}\left[B_{k}\right]$ is a copy of the graph $G_{p}\left(V_{p}, E_{p}\right)$ on $T_{\kappa} n$ vertices as stated in Lemma 3.3 with parameters $s=3, \kappa=\frac{\beta_{2}-\beta_{1}}{8}$ and $T_{\kappa}=C_{\kappa, 3}$.
- For the cross edges between the vertices in $A_{k}$ and $B_{k}$, we add the edge $\left(a_{i}, b_{j}\right)$ to $E\left(G_{k}\right)$ if and only if the $j$-th coordinate of $k_{i}$ is 1 for all $i \in[n]$ and $j \in\left[T_{\kappa} n\right]$.

Note that the graph $G_{k}$ constructed above is unique for a given multi-set $S_{k}$. The graph $G_{u}$ with the vertex sets $A_{u}=\left\{a_{1}^{\prime}, \ldots, a_{n}^{\prime}\right\}$ and $B_{u}=\left\{b_{1}^{\prime}, \ldots, b_{T_{\kappa} n}^{\prime}\right\}$ is constructed from the multi-set $S_{u}$ in a similar fashion, but at the end, the vertices of $A_{u}$ are permuted using a random permutation. So,

- $G_{u}\left[A_{u}\right]$ is a clique with $n$ vertices.
- $G_{u}\left[B_{u}\right]$ is a copy of the graph $G_{p}\left(V_{p}, E_{p}\right)$ on $T_{\kappa} n$ vertices as stated in Lemma 3.3, with parameters $s=3, \kappa=\frac{\beta_{2}-\beta_{1}}{8}$ and $T_{\kappa}=C_{\kappa, 3}$.
- Let us first pick a random permutation $\pi$ on $[n]$. For the cross edges between the vertices in $A_{u}$ and $B_{u}$, we add the edge $\left(a_{\pi(i)}^{\prime}, b_{j}\right)$ to $E\left(G_{u}\right)$ if and only if the $j$-th coordinate of $u_{i}$ is 1 for all $i \in[n]$ and $j \in\left[T_{\kappa} n\right]$.

Note that our final objective is to prove a lower bound on the query complexity for tolerant testing of GI, that is, when we have an adjacency query access to $G_{u}$. We will instead show that the lower bound holds even if we have the following query access, named as $A_{u}$-neighborhood-query: the tester can choose a vertex $a_{i}^{\prime} \in A_{u}$ and in one go obtain the information about the entire neighborhood of $a_{i}^{\prime}$ in $B_{u}$.

Observe that the only part of $G_{u}$ that is not known to the tester is the cross edges between $A_{u}$ and $B_{u}$. So, in this case, the $A_{u}$-neighborhood query is way more stronger than the standard queries to $G_{u}$, and a lower bound for the $A_{u}$-neighborhood query would imply a lower bound on adjacency query.

## Simulating Queries to $G_{u}$ using samples drawn from $S_{u}$ without replacement

Following the above discussion, we will only have to show how to simulate $A_{u}$-neighborhood queries using samples drawn from $S_{u}$ without replacement. So, we can assume that the queries are of the form: what are the neighbors of $a_{i}^{\prime}$ in $B_{u}$ ? And since in each query the entire neighborhood of $a_{i}^{\prime}$ is obtained, the tester would pick different $a_{i}^{\prime}$ for every query. Note that in $G_{u}$, by construction, the vertices of $A_{u}$ were permuted using a random permutation. So, from the point of view of the
tester, the $a_{i}^{\prime}$ are just randomly drawn from $A_{u}$ minus the set of $a_{i}^{\prime}$ already queried. In other word, the $a_{i}^{\prime}$ are just randomly drawn from $A_{u}$ without replacement. Now because of the way the edges between $A_{u}$ and $B_{u}$ are constructed, the neighborhood of a random $a_{i}^{\prime}$ drawn from $A_{u}$ without replacement is same as obtaining random samples from $S_{u}$ without replacement.

It is also important to note that because of the randomness, the queries made by the tester are actually non-adaptive.

## Description of algorithm $\mathcal{A}$ for testing $E M D\left(S_{k}, S_{u}\right)$

Run ALG on $G_{k}$ and $G_{u}$ with parameters $\gamma_{1}=2 \beta_{1}$ and $\gamma_{2}=2 \beta_{2}-2 \kappa$. If ALG reports $d\left(G_{k}, G_{u}\right) \leq T_{\kappa} \gamma_{1} n^{2}$, output that $E M D\left(S_{k}, S_{u}\right) \leq T_{\kappa} \beta_{1} n^{2}$. Similarly, if ALG reports that $d\left(G_{k}, G_{u}\right) \geq$ $T_{\kappa} \gamma_{2} n^{2}$, then output $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq T_{\kappa} \beta_{2} n^{2}$.

## Proof of Correctness of the reduction

To prove the correctness of the above reduction, let us first consider the following definition of Special bijection and its connection with $\operatorname{EMD}\left(S_{k}, S_{u}\right)$.

Definition 3.4 (Special bijections). A bijection $\phi$ from $V\left(G_{k}\right)$ to $V\left(G_{u}\right)$ is said to be Special if $\phi\left(A_{k}\right)=A_{u}, \phi\left(B_{k}\right)=B_{u}$ and $\phi\left(b_{i}\right)=b_{i}^{\prime}$ for all $b_{i} \in B_{k}$. The set of all special bijections from $V\left(G_{k}\right)$ to $V\left(G_{u}\right)$ will be denoted by $\Phi$, and $d_{\Phi}\left(G_{k}, G_{u}\right):=\min _{\phi \in \Phi} d_{\phi}\left(G_{k}, G_{u}\right)$.

Lemma 3.5. Let $S_{k}, S_{u}$ be the known and unknown multi-sets, respectively. Then $d_{\Phi}\left(G_{k}, G_{u}\right)=2$. $\operatorname{EMD}\left(S_{k}, S_{u}\right)$.

Proof. We will first prove that $d_{\Phi}\left(G_{k}, G_{u}\right) \leq 2 \cdot E M D\left(S_{k}, S_{u}\right)$.
Recall that $S_{k}=\left\{k_{1}, \ldots, k_{n}\right\}$ and $S_{u}=\left\{u_{1}, \ldots, u_{n}\right\}$ be the known and unknown multi-sets over the Hamming cube $H_{T_{\kappa} n}=\{0,1\}^{T_{\kappa} n}$. Also, note that $G_{u}$ and $G_{k}$ are the unknown and known graphs with vertex bipartitions $A_{u}, B_{u}$ and $A_{k}, B_{k}$ respectively as discussed earlier. Let $\psi: S_{k} \rightarrow S_{u}$ be an optimal bijection that realizes $E M D\left(S_{k}, S_{u}\right)$. Now, we will construct another bijection $\psi^{\prime} \in \Phi$ such that $d_{\psi^{\prime}}\left(G_{k}, G_{u}\right)=2 \cdot E M D\left(S_{k}, S_{u}\right)$.

We construct the bijection $\psi^{\prime} \in \Phi$ from $V\left(G_{k}\right)$ to $V\left(G_{u}\right)$ as follows: for each $i, j \in[n], \psi^{\prime}\left(a_{i}\right)$ $=a_{j}^{\prime}$ if and only if $\psi\left(k_{i}\right)=u_{j}$; for each $\ell \in\left[T_{\kappa} n\right], \psi^{\prime}\left(b_{\ell}\right)=b_{\ell}^{\prime}$. From the construction of $\psi^{\prime}$ and by the definition of $d_{\psi^{\prime}}\left(G_{k}, G_{u}\right)$ (See Definition 1.1), it is clear that $d_{\psi^{\prime}}\left(G_{k}, G_{u}\right)=2 \cdot E M D\left(S_{k}, S_{u}\right)$. Since $d_{\Phi}\left(G_{k}, G_{u}\right)=\min _{\phi \in \Phi} d_{\phi}\left(G_{k}, G_{u}\right)$, we can say $d_{\Phi}\left(G_{k}, G_{u}\right) \leq d_{\psi^{\prime}}\left(G_{k}, G_{u}\right)=2 \cdot \operatorname{EMD}\left(S_{k}, S_{u}\right)$.

Now we will prove the other way around, that is, we will show that $E M D\left(S_{k}, S_{u}\right) \leq \frac{d_{\Phi}\left(G_{k}, G_{u}\right)}{2}$ holds as well. Let $\psi \in \Phi$ be a bijection from $V\left(G_{k}\right) \rightarrow V\left(G_{u}\right)$ that realizes $d_{\Phi}\left(G_{k}, G_{u}\right)$. By definition of $\Phi$, we can assume that $\psi\left(b_{i}\right)=b_{i}^{\prime}$ for each $i \in\left[T_{\kappa} n\right]$. Now, let us consider a bijection $\psi^{\prime}$ from the multi-set $S_{k}$ to $S_{u}$ defined as follows: $\psi^{\prime}\left(k_{i}\right)=u_{j}$ if and only if $\psi\left(a_{i}\right)=a_{j}^{\prime}$ for all $i, j \in[n]$. Observe that $\sum_{i \in[n]} d_{H}\left(k_{i}, \psi^{\prime}\left(k_{i}\right)\right)=\frac{d_{\psi}\left(G_{k}, G_{u}\right)}{2}$. Thus, $E M D\left(S_{k}, S_{u}\right) \leq \sum_{i \in[n]} d_{H}\left(k_{i}, \psi^{\prime}\left(k_{i}\right)\right)=\frac{d_{\psi}\left(G_{k}, G_{u}\right)}{2}=\frac{d_{\Phi}\left(G_{k}, G_{u}\right)}{2}$.

Putting everything together, we have $d_{\Phi}\left(G_{k}, G_{u}\right)=2 \cdot \operatorname{EMD}\left(S_{k}, S_{u}\right)$.
Now, using the following lemma, we will show how $d_{\Phi}\left(G_{k}, G_{u}\right)$ is related to $d\left(G_{u}, G_{k}\right)$, where $\Phi$ is the set of all Special bijections.

Lemma 3.6. Let $\Phi$ be the set of all Special bijections from $V\left(G_{k}\right)$ to $V\left(G_{u}\right)$. Also, let $d_{\Phi}\left(G_{k}, G_{u}\right)=$ $\min _{\phi \in \Phi} d_{\phi}\left(G_{k}, G_{u}\right)$. Then $d_{\Phi}\left(G_{k}, G_{u}\right)-2 \kappa T_{\kappa} n^{2} \leq d\left(G_{k}, G_{u}\right) \leq d_{\Phi}\left(G_{k}, G_{u}\right) .{ }^{7}$
Proof. Note that $d\left(G_{k}, G_{u}\right) \leq d_{\Phi}\left(G_{k}, G_{u}\right)$ follows from their definitions.
For the proof of the other side of the inequality, let us consider a bijection $\psi: V\left(G_{k}\right) \rightarrow V\left(G_{u}\right)$ that realizes $d\left(G_{k}, G_{u}\right)$, that is, $d\left(G_{k}, G_{u}\right)=d_{\psi}\left(G_{k}, G_{u}\right)$. If $\psi$ is a bijection such that $\psi \in \Phi$, then $d_{\Phi}\left(G_{k}, G_{u}\right)-2 \kappa T_{\kappa} n^{2} \leq d\left(G_{k}, G_{u}\right)$ holds. So, let us assume that $\psi \notin \Phi$. Then we will show that there exists a bijection $\phi \in \Phi$ such that $d_{\phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+2 \kappa T_{\kappa} n^{2}$, which will imply $d_{\Phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+2 \kappa T_{\kappa} n^{2}$, that is, $d_{\Phi}\left(G_{k}, G_{u}\right)-2 \kappa T_{\kappa} n^{2} \leq d\left(G_{k}, G_{u}\right)$.

We will now present the construction of $\phi \in \Phi$ from $\psi$. Let us first partition the vertices of $B_{k}$, with respect to $\psi$, into three parts: $B_{k}=B_{B I} \sqcup B_{B N} \sqcup B_{A}$; for each $b_{i} \in B_{B I}, \psi\left(b_{i}\right)=b_{i}^{\prime}$; for each $b_{i} \in B_{B N}, \psi\left(b_{i}\right) \in B_{u}$ but $\psi\left(b_{i}\right) \neq b_{i}^{\prime} ;$ for each $b_{i} \in B_{A}, \psi\left(b_{i}\right) \in A_{u}$. Also, we partition the vertices of $A_{k}$ into two parts: $A_{k}=A_{A} \sqcup A_{B}$; for each $a_{i} \in A_{A}, \psi\left(a_{i}\right) \in A_{u}$; for each $a_{i} \in A_{B}, \psi\left(a_{i}\right) \in B_{u}$. Let $\left|B_{A}\right|=\left|A_{B}\right|=x$ and $\left|B_{B N}\right|=y$, where $0 \leq x \leq n$ and $0 \leq x+y \leq T_{\kappa} n$. Now, we will construct the bijection $\phi \in \Phi($ from $\psi)$ by performing the following three steps in that order. Note that the construction of $\phi$ is not a part of our reduction. This is used for analysis purpose only.
Step (i) $\phi(u)=\psi(u)$ for all vertices $u \in B_{B I} \cup A_{A}$.
Step (ii) For each $a_{i} \in A_{B}, \phi\left(a_{i}\right) \in A_{u} \backslash \psi\left(A_{A}\right)$. Also, for each $b_{i} \in B_{A}, \phi\left(b_{i}\right)=b_{i}^{\prime} \in B_{u} \backslash \psi\left(B_{B I}\right)$.
Step (iii) For each $b_{i} \in B_{B N}, \phi\left(b_{i}\right)=b_{i}^{\prime}$.
Observe that $\phi\left(A_{k}\right)=A_{u}, \phi\left(B_{k}\right)=B_{u}$ and $\phi\left(b_{i}\right)=b_{i}^{\prime}$ for all $b_{i} \in B_{k}$, that is, $\phi$ is a SPECIAL bijection. It remains to show that

$$
\begin{equation*}
d_{\Phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+2 \kappa T_{\kappa} n^{2} . \tag{1}
\end{equation*}
$$

Recall that the graphs $G_{k}\left[B_{k}\right]$ and $G_{u}\left[B_{u}\right]$ are the same copies of $G_{p}\left(V_{p}, E_{p}\right)$, where $\left|V_{p}\right|=T_{\kappa} n$. Observe that

- From Lemma 3.3, the graphs $G_{k}\left[B_{k}\right]$ and $G_{u}\left[B_{u}\right]$ satisfy the following property ${ }^{8}$, cardinality of symmetric difference between the sets of neighbors of any two distinct vertices is at least $3 n-2$.
- Since $G_{k}\left[A_{k}\right]$ and $G_{u}\left[A_{u}\right]$ are cliques, the degree of each vertex in graphs $G_{k}\left[A_{k}\right]$ and $G_{u}\left[A_{u}\right]$ is exactly $n-1$.
To prove $d_{\Phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+2 \kappa T_{\kappa} n^{2}$, it will be sufficient to show that

$$
\begin{equation*}
d_{\phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+4 x\left|A_{k}\right|+4 x+2 y\left|A_{k}\right|-y(3 n-2) . \tag{2}
\end{equation*}
$$

From Equation 2, we will be done with the proof of Inequality 1 as

$$
\begin{aligned}
d_{\psi}\left(G_{k}, G_{u}\right)+4 x\left|A_{k}\right|+4 x+2 y\left|A_{k}\right|-y(3 n-2) & =d_{\psi}\left(G_{k}, G_{u}\right)+4 x n+4 x-y(n-2) \\
& \leq d_{\psi}\left(G_{k}, G_{u}\right)+8 n^{2} \leq d_{\psi}\left(G_{k}, G_{u}\right)+2 \kappa T_{\kappa} n^{2} .
\end{aligned}
$$

The last but one inequality follows from the fact that $0 \leq x \leq n$ and the last inequality follows from the fact that $T_{\kappa}=\left\lceil\frac{18}{\kappa(2-\kappa)}\right\rceil$. We present the proof of Inequality 2 in Appendix C. 2 .

The following lemma completes the proof of Lemma 3.2

[^4]Lemma 3.7. The described algorithm $\mathcal{A}$ for EMD, that uses Algorithm ALG on $G_{k}$ and $G_{u}$ with parameters $\gamma_{1}$ and $\gamma_{2}$ as a subroutine, determines whether $\operatorname{EMD}\left(S_{k}, S_{u}\right) \leq \beta_{1} T_{\kappa} n^{2}$ or $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq \beta_{2} T_{\kappa} n^{2}$ with probability at least $2 / 3$, where $\gamma_{1}=2 \beta_{1}, \gamma_{2}=2 \beta_{2}-2 \kappa$.

Proof. By the assumption of the existence of algorithm ALG that decides whether $d\left(G_{k}, G_{u}\right) \leq$ $T_{\kappa} \gamma_{1} n^{2}$ or $d\left(G_{k}, G_{u}\right) \geq T_{\kappa} \gamma_{2} n^{2}$, we will be done with the proof by showing the followings.
(i) If $E M D\left(S_{k}, S_{u}\right) \leq T_{\kappa} \beta_{1} n^{2}$, then $d\left(G_{k}, G_{u}\right) \leq T_{\kappa} \gamma_{1} n^{2}$,
(ii) If $E M D\left(S_{k}, S_{u}\right) \geq T_{\kappa} \beta_{2} n^{2}$, then $d\left(G_{k}, G_{u}\right) \geq T_{\kappa} \gamma_{2} n^{2}$.

We will first prove (i). From Lemma 3.5, we have $d_{\Phi}\left(G_{k}, G_{u}\right)=2 \cdot E M D\left(S_{k}, S_{u}\right)$, where $\Phi$ is the set of all SPECIAL bijections from $V\left(G_{k}\right)$ to $V\left(G_{u}\right)$. So, $E M D\left(S_{k}, S_{u}\right) \leq T_{\kappa} \beta_{1} n^{2}$ implies $d_{\Phi}\left(G_{k}, G_{u}\right) \leq$ $2 T_{\kappa} \beta_{1} n^{2}=T_{\kappa} \gamma_{1} n^{2}$. Now, following the definition of Special bijections (Definition 3.4) and Lemma 3.6, we can say that $d\left(G_{k}, G_{u}\right) \leq d_{\Phi}\left(G_{k}, G_{u}\right) \leq T_{\kappa} \gamma_{1} n^{2}$.

Now, for the proof of (ii), considering the fact that $d_{\Phi}\left(G_{k}, G_{u}\right)=2 \cdot E M D\left(S_{k}, S_{u}\right)$ as above, we can say that $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq T_{\kappa} \beta_{2} n^{2}$ implies $d_{\Phi}\left(G_{k}, G_{u}\right) \geq 2 T_{k} \beta_{2} n^{2}$. From Lemma 3.6, it follows that $d_{\Phi}\left(G_{k}, G_{u}\right)-2 \kappa T_{\kappa} n^{2} \leq d\left(G_{k}, G_{u}\right)$. Thus, $d\left(G_{k}, G_{u}\right) \geq T_{\kappa}\left(2 \beta_{2}-2 \kappa\right) n^{2}=T_{\kappa} \gamma_{2} n^{2}$.

## 4 Query Algorithm for Tolerant Graph Isomorphism Testing

In this section, we prove the following theorem.
Theorem 4.1. (Restatement of the upper bound part of Theorem 1.3) Let $G_{k}$ and $G_{u}$ be the known and unknown graphs, respectively. There exists an algorithm that takes parameters $\gamma_{1}$ and $\gamma_{2}$ as input such that $0 \leq \gamma_{1}<\gamma_{2} \leq 1$, performs $\widetilde{\mathcal{O}}\left(\operatorname{QWOR}_{\operatorname{EMD}^{(n)}}(n)\right.$ many queries to the adjacency matrix of $G_{u}$ for appropriate $\beta_{1}$ and $\beta_{2}$ depending on $\gamma_{1}$ and $\gamma_{2}$, and decides whether $d\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$ or $d\left(G_{u}, G_{k}\right) \geq$ $\gamma_{2} n^{2}$, with probability at least $2 / 3$. Here $\widetilde{\mathcal{O}}(\cdot)$ hides a polynomial factor in $\frac{1}{\beta_{2}-\beta_{1}}$ and $\log n$.
Remark 2. The theorem stated above works for any $\gamma_{1}, \gamma_{2}$ such that $0 \leq \gamma_{1}<\gamma_{2} \leq 1$. However, for simplicity of representation, we have assumed $\gamma_{2} \geq 11 \gamma_{1}$.
Remark 3. Note that Theorem 4.1 can also be stated in terms of $\operatorname{QWR}_{\operatorname{EMD}^{(n)}}$ as $^{\operatorname{QWOR}} \mathrm{EMD}^{(n)} \leq$ $\mathrm{QWR}_{\mathrm{EMD}}(n)$ as we can simulate samples with replacement when we have query access to samples without replacement (See Proposition B.5).

Our algorithm for tolerant GI testing, as stated in Theorem4.1, uses a special kind of tolerant EMD tester over multi-sets: we know $t$ many multi-sets, one multi-set is unknown and two parameters $\epsilon_{1}$ and $\epsilon_{2}$ are given; the objective is to test tolerant $E M D$ of each known multi-set with the unknown one. The following theorem gives us the special EMD tester.

Theorem 4.2. Let $H=\{0,1\}^{n}$ be a $n$-dimensional Hamming cube. Let $\left\{S_{k}^{i}: i \in[t]\right\} \cup\left\{S_{u}\right\}$ denote the multi-sets with $n$ elements from $H$ where $\left\{S_{k}^{i}: i \in[t]\right\}$ denote the set of t many known multi-sets and $S_{u}$ denotes the unknown multi-set. There exists an algorithm ALG-EMD that takes two proximity parameters $\epsilon_{1}, \epsilon_{2}$ with $0 \leq \epsilon_{1}<\epsilon_{2} \leq 1$ and a $\delta \in(0,1)$ as input and decides whether $\operatorname{EMD}\left(S_{u}, S_{k}^{i}\right) \leq \epsilon_{1} n^{2}$ or $\operatorname{EMD}\left(S_{u}, S_{k}^{i}\right) \geq \epsilon_{2} n^{2}$, with probability at least $1-\delta$, for each $i \in[t]$. Moreover, ALG-EMD uses $\mathrm{QWOR}_{\operatorname{EMD}}(n) \cdot \mathcal{O}\left(\log \frac{t}{\delta}\right)$ many samples without replacement from $S_{u}$.
 with union bound and standard argument for amplifying the success probability.

Remark 4. The algorithm of Theorem 4.1, to be discussed in Section 4.1. formulates a tolerant EMD instance of multi-sets having $n$ elements in $H=\{0,1\}^{d}$, where $d=\mathcal{O}\left(\log n /\left(\gamma_{2}-\gamma_{1}\right)\right)$. But ALG-EMD is an algorithm for tolerant EMD testing between two multi-sets having $n$ elements in $\{0,1\}^{n}$. This is not a problem as the query complexity of $E M D$ is an increasing function in dimension (See Proposition B.9 in Appendix B). Moreover, the algorithm in Section 4.1 calls ALGEMD with parameters $\epsilon_{1}=\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right), \epsilon_{2}=\gamma_{2} / 5, t=2^{\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$ and $\delta$ is a suitable constant depending upon $\gamma_{1}$ and $\gamma_{2}$, where $\gamma_{1}$ and $\gamma_{2}$ are parameters as stated in Theorem4.1. So, each call to ALG-EMD, in our context, makes $\widetilde{\mathcal{O}}\left(\operatorname{QWOR}_{\operatorname{EMD}}(n)\right)$ many queries.

### 4.1 Query Algorithm for Tolerant Graph Isomorphism

For our algorithm, we need the following definitions of label and embedding.
Definition 4.3. (Label of a vertex) Given a graph $G$ and $C \subset V(G)=\left\{c_{1}, \ldots c_{|C|}\right\}$, the $C$-labelling of $V(G)$ is a function $\mathcal{L}_{C}: V(G) \rightarrow\{0,1\}^{|C|}$ such that the $i$-th entry of $\mathcal{L}_{C}(v)$ is 1 if and only if $v$ is a neighbor of $c_{i} \in C$. Also, $\mathcal{L}_{C}(v)$ is referred as the label of $v$ under $C$-labelling of $V(G)$.

Definition 4.4. (Embedding of a Vertex Set into another Vertex Set) Let $G_{u}$ and $G_{k}$ be two graphs. Consider $A \subseteq V\left(G_{u}\right)$ and $B \subseteq V\left(G_{k}\right)$ such that $|A| \leq|B|$. An injective mapping $\eta$ from $A$ to $B$ is referred as an embedding of $A$ into $B$.

Now we present our query algorithm TolerantGI( $\left.G_{u}, G_{k}, \gamma_{1}, \gamma_{2}\right)$ that comprises three phases. Before proceeding to the formal description, we first give technical overview to get a flow of our algorithm.

## Technical Overview

In Phase 1, we first choose a $\mathcal{O}\left(\frac{1}{\gamma_{2}-\gamma_{1}}\right)$ size collection of random subset of vertices, i.e, coresets $\mathcal{C}_{u}$ from the unknown graph $G_{u}$ where each $C_{u} \in \mathcal{C}_{u}$ is of size $\mathcal{O}\left(\frac{\log n}{\gamma_{2}-\gamma_{1}}\right)$. Thereafter we find all embeddings of $C_{u}$ inside the known graph $G_{k}$. Let the embeddings be $\eta_{1}, \eta_{2}, \ldots, \eta_{J}$ where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$. Now each $C_{u}$ (as well as each $C_{k}^{i}$ ) defines a label distribution of the vertices of $G_{u}$ (as well as $G_{k}$ ). Let us denote the set of labels as $X_{C_{u}}$ (and $Y_{C_{k}^{i}}$ ). Now we test if the $E M D$ between $X_{C_{u}}$ and $Y_{C_{k}^{i}}$ is close or far for each $i \in[J]$. We keep only those $\left(C_{u}, \eta_{i}\right)$ for Phase 2 such that $E M D\left(X_{C_{u}}\right.$, $\left.Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$.

Although Phase 1 of our algorithm is similar to the algorithm of [FM08], there is a striking difference. Since the authors of [FM08] were testing the non-tolerant version of graph isomorphism, they were testing the identity of the label distributions of $X_{C_{u}}$ and $Y_{C_{k}^{C_{k}}}$. However, since we are solving the tolerant version of the problem, we need to allow some error among the label distributions. We need to pass only those placements of $C_{u}$ that under good bijections do not produce much error and testing of tolerant $E M D$ fits exactly for this purpose.

In Phase 2, we choose $\mathcal{O}\left(\frac{\log ^{2} n}{\left(\gamma_{2}-\gamma_{1}\right)^{3}}\right)$ many vertices from the unknown graph $G_{u}$ randomly and call it $W$. We further find the labels of all the vertices of $W$ under $C_{u}$-labelling by querying the corresponding entries of $G_{u}$ for each $C_{u}$ that has passed Phase 1. Then, we try to match the
vertices of $W$ to the set of possible labels $\left\{l_{1}, l_{2}, \ldots, l_{t}\right\}$ of the vertices of $G_{k}$ under $C_{k}^{i}$-labelling where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$, for those $\eta_{i}$ that have passed Phase 1. Ideally, we would like to find a mapping $\psi: W \rightarrow\left\{l_{1}, l_{2}, \ldots, l_{t}\right\}$ such that the total distance between the labels of the matched vertices is not too large. If no such $\psi$ is possible, we reject the current embedding and try some other embedding that has passed Phase 1.

In Phase 3, we construct a random partial bijection $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ that maps the vertices of $W$ to the vertices of $G_{k}$ while preserving the labels according to $\psi$. We achieve this by mapping each $w \in W$ to one vertex of $G_{k}$ randomly that has same label as determined by $\psi$. Finally, we randomly pair the vertices of $W$ and find the fraction of edge mismatches between the paired up vertices of $W$ and $\hat{\phi}(W)$. If this fraction is less than $5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)$, we accept and say that $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close. If there is no such embedding of any $C_{u} \in \mathcal{C}_{u}$ that achieves this, we report that $G_{u}$ and $G_{k}$ are $\gamma_{2}$-far.

## Formal Description of TolerantGI $\left(G_{u}, G_{k}, \gamma_{1}, \gamma_{2}\right)$ :

The three phases of our algorithm are as follows:

### 4.1.1 Phase 1

The first phase of our algorithm consists of the following three steps.
$\underline{\text { Step } 1}$ First we sample a collection $\mathcal{C}_{u}$ of $\mathcal{O}\left(\frac{\log n}{\gamma_{2}-\gamma_{1}}\right)$ sized random subsets of $V\left(G_{u}\right)$ with $\left|\mathcal{C}_{u}\right|=$ $\mathcal{O}\left(\frac{1}{\gamma_{2}-\gamma_{1}}\right)$. We perform Step 2 and Step 3 for each $C_{u} \in \mathcal{C}_{u}$.
$\underline{\text { Step } 2}$ We determine all possible embeddings, that is, $\eta_{1}, \ldots, \eta_{J}$, of $C_{u}$ into $V\left(G_{k}\right)$, where $J=$ $\left(\underset{\mathcal{O}\left(\log n /\left(\gamma_{2}-\gamma_{1}\right)\right)}{n}\right) \leq 2^{\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$. For each $i \in[J]$, let $C_{k}^{i}$ be the set of images of $C_{u}$ under the $i$-th embedding of $C_{u}$ into $V\left(G_{k}\right)$, that is, $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$. For all $i \in[J]$, we construct the multi-set $Y_{C_{k}^{i}}$ that contains $C_{k}^{i}$-labellings of all the vertices of $G_{k}$.

Step 3 Now for each vertex $v \in V\left(G_{u}\right)$, there is a $C_{u}$-labelling of $v$. Let $X_{C_{u}}$ be the multi-set of $C_{u}$-labellings of all the vertices in $V\left(G_{u}\right)$. However, $X_{C_{u}}$ is unknown to the algorithm. We call ALG-EMD (as stated in Theorem4.2) by setting parameters as described in Remark 4 to decide whether $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ or $E M D\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \geq \gamma_{2} n\left|C_{u}\right| / 5$, for each $i \in[J]$. Let us pair up $C_{u}$ 's and their accepted embeddings into $G_{k}$ and call the set $\Gamma$, that is,

$$
\Gamma=\left\{\left(C_{u}, \eta_{i}\right) \mid \text { ALG-EMD decides EMD }\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|\right\} .
$$

Note that, at the end of the Phase 1, we have $\Gamma$ with $|\Gamma| \leq\left|\mathcal{C}_{u}\right| \cdot 2^{\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right.}=\mathcal{O}\left(2^{\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right)}\right)$. By the description of Step 3 above, Phase 1 of our algorithm calls ALG-EMD $\mathcal{O}\left(\left|\mathcal{C}_{u}\right|\right)$ times, once for each $C_{u} \in \mathcal{C}_{u}$. So, setting $\delta=\frac{1}{9|\Gamma|}$ in Theorem 4.2, we obtain the following observation about $\Gamma$ that will be used to prove the soundness of our algorithm.
Observation 4.5. Consider $\Gamma$, the set of accepted embeddings that have passed Phase 1 paired with corresponding $C_{u}$, as defined above. Then

$$
\mathbb{P}\left(\forall\left(C_{u}, \eta_{i}\right) \in \Gamma, E M D\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \gamma_{2} n\left|C_{u}\right| / 5\right) \geq \frac{8}{9} .
$$

### 4.1.2 Phase 2

In the second phase, the algorithm performs the following two steps.
Step 1 We sample a subset $W$ of $\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)^{3}\right)$ vertices randomly from $G_{u}$.
Step 2 For each $\left(C_{u}, \eta_{i}\right) \in \Gamma$ that has passed Phase 1, we perform the following steps:
(i) We find the $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$-labelling of the vertices of $G_{k}$. Let $l_{1}, \ldots, l_{t}$ be the labels of the vertices where $t=2^{\left|C_{k}^{i}\right|}$ and $V_{j} \subseteq V\left(G_{k}\right)$ be the set of vertices with label $l_{j}$.
(ii) We define a matrix $M$ of size $|W| \times 2^{\left|C_{k}^{i}\right|}$ where each row represents the label of a vertex $w \in W$ and each column represents one of the possible $C_{k}^{i}$-labelling of $V\left(G_{k}\right){ }^{9}$ The $(i, j)$-th entry of $M$ is defined as: $M_{i j}=d_{H}\left(\mathcal{L}_{C_{u}}\left(w_{i}\right), l_{j}\right)$.
(iii) We choose a function $\psi: W \rightarrow\left\{l_{1}, \ldots l_{t}\right\}$ randomly satisfying

$$
\begin{equation*}
\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W| \text { and }\left|\left\{w: \psi(w)=l_{j}\right\}\right| \leq\left|V_{j}\right| \forall j \in[t] . \tag{3}
\end{equation*}
$$

Let $\Gamma_{W}$ be the set of tuples such that

$$
\Gamma_{W}=\left\{\left(C_{u}, \eta_{i}, \psi\right):\left(C_{u}, \eta_{i}\right) \in \Gamma \text { and } \psi \text { satisfies Equation (3) }\right\} .
$$

Like Observation 4.5, the following observation about the set $\Gamma_{W}$ will be used to prove the soundness of our algorithm.

Observation 4.6. $\left|\Gamma_{W}\right| \leq|\Gamma| \leq 2^{\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$. Moreover, any $\left(C_{u}, \eta_{i}, \psi\right)$ that has passed this phase satisfies Equation (3).

### 4.1.3 Phase 3

The third phase of our algorithm comprises the following four steps.
Step 1 We randomly pair up the vertices of $W$. Let $\left\{\left(a_{1}, b_{1}\right), \ldots,\left(a_{p}, b_{p}\right)\right\}$ be the pairs of the vertices, where $p=\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)^{3}\right)$. We now determine which $\left(a_{i}, b_{i}\right)$ pairs form edges in $G_{u}$ by querying the corresponding entries of the adjacency matrix of $G_{u}$.

Step 2 For each $\left(C_{u}, \eta_{i}, \psi\right) \in \Gamma_{W}$ that has passed Phase 2, we perform Step 3 and Step 4 as follows.
Step 3 We choose an embedding $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ randomly, satisfying $\hat{\phi}(w) \in V_{j}$ if and only if $\psi(w)=l_{j}$ and modulo permutation of the vertices in $V_{j}$ for all $j \in[t]$. In other words, we map each $w \in W$ to a vertex in $G_{k}$ randomly having $\psi(w)=l_{j}$ as its $C_{k}^{i}$-labelling in $G_{k}$.
${ }^{9}$ Let $C_{u}=\left\{x_{1}, \ldots, x_{\mathcal{O}\left(\log n /\left(\gamma_{2}-\gamma_{1}\right)\right)}\right\}$. Note that for each $w_{i} \in W, \mathcal{L}_{C_{u}}\left(w_{i}\right) \in\{0,1\}^{\mathcal{O}\left(\log n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$ such that the $j$-th coordinate is 1 if and only if $w_{i}$ is a neighbour of $x_{j}$, where $i \in\left[\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)^{3}\right)\right]$ and $j \in\left[\mathcal{O}\left(\log n /\left(\gamma_{2}-\gamma_{1}\right)\right)\right]$. Similarly, $l_{j} \in\{0,1\}^{\mathcal{O}\left(\log n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$ such that the $i$-th coordinate of $l_{j}$ is 1 if and only if $\eta\left(x_{i}\right)$ is a neighbour of $v \in V_{j}$, where $j \in\left[2^{\left|C_{k}^{i}\right|}\right]$.

Step 4 We find the fraction $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)=\left|\left\{\left(a_{i}, b_{i}\right): \mathbb{1}_{\left(a_{i}, b_{i}\right)}=1\right\}\right| / p$, where $\mathbb{1}_{\left(a_{i}, b_{i}\right)}=1$ if exactly one among $\left(a_{i}, b_{i}\right) \in E\left(G_{u}\right)$ and $\left(\hat{\phi}\left(a_{i}\right), \hat{\phi}\left(b_{i}\right)\right) \in E\left(G_{k}\right)$ holds. If $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq$ $5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)$, then HALT and REPORT that $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close.
While executing Step 3 and Step 4 for each tuple in $\Gamma_{W}$, if we did not HALT, then we HALT now and REPORT that $G_{u}$ and $G_{k}$ are $\gamma_{2}$-far.

Observation 4.7. (i) The number of times our algorithm executes Step 2, Step 3 and Step 4 is at $\operatorname{most}\left|\Gamma_{W}\right| \leq 2^{\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$.
(ii) If there exists a $\left(C_{u}, \eta_{i}, \psi\right)$ such that $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)$, then our algorithm reports that $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close. Otherwise, $G_{u}$ and $G_{k}$ are reported to be $\gamma_{2}$-far.

### 4.2 Proof of Correctness

To prove the correctness of our algorithm, we need to show the following three properties:
Completeness Property If $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close to isomorphic, then our algorithm reports the same with probability at least $2 / 3$.

Soundness Property If $G_{u}$ and $G_{k}$ are $\gamma_{2}$-far from isomorphic, then the algorithm reports the same with probability at least $2 / 3$.
Query Complexity The query complexity of our algorithm is $\widetilde{\mathcal{O}}(n)$.

### 4.2.1 Proof of Completeness Property

In order to prove the completeness property as described above, we will first prove some claims. Finally, combining the claims, we would conclude the completeness property of our algorithm.

We will first prove that there exists a $C_{u} \in \mathcal{C}_{u}$ considered in Step 1 of Phase 1 of the algorithm and a corresponding embedding $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ in Step 2 of Phase 1 such that EMD $\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq$ $\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ holds with probability at least 20/21, where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$.
Claim 4.8. Let $\phi: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ be a bijection such that $d_{\phi}\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$. Then there exists a $C_{u} \in \mathcal{C}_{u}$ and an embedding $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ such that the following hold with probability at least 20/21.

- $\forall v \in C_{u}$, we have $\eta_{i}(v)=\phi(v)$, and
- $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$

Note that $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$ and $Y_{C_{k}^{i}}$ is set of $C_{k}^{i}$-labelling of $V\left(G_{k}\right) \cdot \cdot^{10}$
Proof. Consider a particular $C_{u} \in \mathcal{C}_{u}$ and an embedding $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ such that $\eta_{i}(v)=\phi(v)$ for all $v \in C_{u}$. Note that this embedding $\eta_{i}$ is considered in Step 2 of Phase 1 of the algorithm. Now we will show that $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ holds with probability at least a constant, to be specified later, that depends upon $\gamma_{1}$ and $\gamma_{2}$, where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$.

[^5]We know that $d_{\phi}\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$ and by Definition A.2, we have

$$
\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECiDER}_{\phi}(x)\right| \leq \gamma_{1} n^{2} .
$$

Thus,

$$
\begin{equation*}
\mathbb{E}\left[\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECiDER}_{\phi}(x) \cap C_{u}\right|\right] \leq \gamma_{1} n\left|C_{u}\right| \tag{4}
\end{equation*}
$$

From Definition A.2. we can say that

$$
\begin{aligned}
\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) & =\min _{f: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)} \sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{f}(x) \cap C_{u}\right| \\
& \leq \sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi}(x) \cap C_{u}\right|
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
\mathbb{E}\left[\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right)\right] & \leq \mathbb{E}\left[\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi}(x) \cap C_{u}\right|\right] \\
& \leq \gamma_{1} n\left|C_{u}\right| \quad \text { (From Equation(4) }
\end{aligned}
$$

Using Markov inequality, we can say that

$$
\mathbb{P}\left(\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|\right) \geq 1-\frac{\gamma_{1}}{\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}} .
$$

Note that $\left|\mathcal{C}_{u}\right|=\mathcal{O}\left(\frac{1}{\gamma_{2}-\gamma_{1}}\right)$ and we have been arguing for a particular $C_{u} \in \mathcal{C}_{u}$. So, taking $\left|\mathcal{C}_{u}\right|$ suitably, we get a $C_{u}$ and an embedding $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ satisfying the properties mentioned in the statement of this claim with probability at least 20/21.

The above claim discusses about the existence of a $C_{u} \in \mathcal{C}_{u}$ and its embeddings satisfying above mentioned desired properties. Now we discuss how our algorithm determines all $C_{u} \in \mathcal{C}_{u}$ that satisfy the properties. Note that Step $\mathbf{3}$ of Phase $\mathbf{1}$ of our algorithm calls ALG-EMD. Following the correctness of ALG-EMD (Theorem 4.2), we determine all embeddings $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ such that $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ holds with probability at least 20/21. The discussion in this paragraph is formalized in the following claim.

Claim 4.9. Let $C_{u} \in \mathcal{C}_{u}$ and $\eta_{1}, \ldots, \eta_{J}$ be the all possible embeddings of $C_{u}$ into $V\left(G_{k}\right)$. Then Step 3 of Phase 1 can determine the set $\Gamma=\left\{\left.\left(C_{u}, \eta_{i}\right)\left|E M D\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\right| C_{u} \right\rvert\,\right\}$ with probability at least 20/21. Note that $C_{k}^{i}=\eta_{i}\left(C_{u}\right), X_{C_{u}}$ is the set of $C_{u}$-labelling of $V\left(G_{u}\right)$ and $Y_{C_{k}^{i}}$ is set of $C_{k}^{i}$-labelling of $V\left(G_{k}\right)$.

As we are considering the case that $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close to being isomorphic, from Claim4.8, we can assume that there is an appropriate $\left(C_{u}, \eta_{i}\right) \in \Gamma$ such that EMD $\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\right.$ $\left.\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$. Now we will prove that there exists a function $\psi: W \rightarrow\left\{l_{1}, \ldots, l_{t}\right\}$ as considered in Step 2 (iii) in Phase 2 of our algorithm such that Equation (3) holds with probability at least 20/21.

Claim 4.10. Let us assume that $\phi: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ be a bijection such that $d_{\phi}\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$ and $\left(C_{u}, \eta_{i}\right) \in \Gamma$ where $C_{u} \in \mathcal{C}_{u}$ and $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ be an embedding such that

- $\forall v \in C_{u}$ we have $\eta_{i}(v)=\phi(v)$, and
- $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$.

Also, let $\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ be the all possible $C_{k}^{i}$-labellings of $V\left(G_{k}\right)$, where $t=\left[2\left|C_{k}^{i}\right|\right]$. Then there exists a mapping $\psi: W \rightarrow\left\{l_{1}, \ldots, l_{t}\right\}$ such that the following hold with probability at least 20/21.
(i) $\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$, and
(ii) $\forall j \in[t]$, we have $\left|\left\{w: \psi(w)=l_{j}\right\}\right| \leq\left|V_{j}\right|$.

Proof. From the conditions given in the statement of the claim, we can say that there exists $f$ : $V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ such that $f(v)=\eta_{i}(v)=\phi(v)$ for all $v \in C_{u}$ and $\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{f}(x) \cap C_{u}\right| \leq$ $\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$

Since $\left|\operatorname{DECIDER}_{f}(x) \cap C_{u}\right|=d_{H}\left(\mathcal{L}_{C_{u}}(x), \mathcal{L}_{C_{k}^{i}}(f(x))\right)$, we have

$$
\sum_{x \in V\left(G_{u}\right)} d_{H}\left(\mathcal{L}_{C_{u}}(x), \mathcal{L}_{C_{k}^{i}}(f(x))\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|
$$

Since we are taking the vertices in $W$ uniformly at random from $G_{u}$, we can say that

$$
\mathbb{E}\left[\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \mathcal{L}_{C_{k}^{i}}(f(w))\right)\right] \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right)\left|C_{u}\right||W|
$$

Using Hoeffding's inequality, we have

$$
\mathbb{P}\left(\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \mathcal{L}_{C_{k}^{i}}(f(w))\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|\right) \geq 1-e^{-\mathcal{O}(|W|)}
$$

Now, we define $\psi: W \rightarrow\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ such that $\psi(w)=\mathcal{L}_{C_{k}^{i}}(f(w))$. In other words, the $C_{k}^{i}-$ labelling of $f(w)$ is same as the labelling of $\psi(w)$ for each $w \in W$. Thus, the $\psi$ defined here satisfies the Condition $(i)$ of this claim, that is, $\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$.

Observe that

$$
\left|\left\{w \in W: \mathcal{L}_{\mathcal{C}_{k}^{i}}(f(w))=l_{j}\right\}\right| \leq\left|\left\{v \in V\left(G_{k}\right): \mathcal{L}_{\mathcal{C}_{k}^{i}}(v)=l_{j}\right\}\right| \leq\left|V_{j}\right| .
$$

So, by the definition of $\psi,\left|\left\{w \in W: \psi(w)=l_{j}\right\}\right| \leq\left|V_{j}\right|$. Hence $\psi$ considered above also satisfies Condition (ii) of the claim.

Now consider the situation when the algorithm is at Step 1 of Phase 3. If $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close, that is, there exists a bijection $\phi$ from $V\left(G_{u}\right)$ to $V\left(G_{k}\right)$ such that $d_{\phi}\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$, then there exists $C_{u} \in \mathcal{C}_{u}, \eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$, and $\psi$ satisfying the conditions given in Claims 4.8 and 4.10. However, we do not know $\phi$. If we construct, though inefficiently, a bijection $\phi^{\prime}$ that is same as $\phi$ with respect to the same $C_{u} \in \mathcal{C}_{u}, \eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ and $\psi$ (conditions given in Claims 4.8 and 4.10), then the following claim says that the difference between $d_{\phi^{\prime}}\left(G_{u}, G_{k}\right)$ and $d_{\phi}\left(G_{u}, G_{k}\right)$ is not too large.

Claim 4.11. Let us assume that $\phi: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ be a bijection such that $d_{\phi}\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$, and $\left(C_{u}, \eta_{i}\right) \in \Gamma$ where $C_{u} \in \mathcal{C}_{u}$ and $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ be an embedding such that

- $\forall v \in C_{u}$ we have $\eta_{i}(v)=\phi(v)$, and
- $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$.

Let $\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ be the all possible $C_{k}^{i}$-labellings of the vertices of $G_{k}$ where $t=\left[2^{\left|C_{k}^{i}\right|}\right]$, and $W$ be the set of vertices of $G_{u}$ sampled at random in Step 1 of Phase 2 and $\psi: W \rightarrow\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ be the mapping considered in Step 2 (iii) in Phase 2 such that

- $\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$, and
- $\forall j \in[t]$, we have $\left|\left\{w: \psi(w)=l_{j}\right\}\right| \leq\left|V_{j}\right|$.

Then, with probability at least $18 / 21$, there exists a bijection $\phi^{\prime}: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$, with $\phi^{\prime}(x)=$ $\phi(x)=\eta_{i}(x)$ for each $x \in C_{u}$ and $\phi^{\prime}(w)=\hat{\phi}(w)$ for each $w \in W$ such that

$$
d_{\phi^{\prime}}\left(G_{u}, G_{k}\right) \leq d_{\phi}\left(G_{u}, G_{k}\right)+\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}
$$

Proof. We will prove the claim by contradiction. Suppose that

$$
\begin{equation*}
d_{\phi^{\prime}}\left(G_{u}, G_{k}\right)>d_{\phi}\left(G_{u}, G_{k}\right)+\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2} \tag{5}
\end{equation*}
$$

By using Definition A.2, we write the above equation as

$$
\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECiDER}_{\phi^{\prime}}(x)\right|>\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi}(x)\right|+\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}
$$

So,

$$
\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi^{\prime}}(x) \Delta \operatorname{DECIDER}_{\phi}(x)\right|>\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}
$$

Let us denote $\operatorname{DECIDER}_{\phi^{\prime}}(x) \Delta \operatorname{DECIDER}_{\phi}(x)=\operatorname{Symm}_{\phi \phi^{\prime}}(x)$. Dividing the sum in the left hand side with respect to the values of $\left|\operatorname{DECIDER}_{\phi^{\prime}}(x) \Delta \operatorname{DECIDER}_{\phi}(x)\right|$ 's, that is, $\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right|$ 's, we get

$$
\sum_{\substack{x \in V\left(G_{u}\right) \\\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000}}}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right|+\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right|>\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}
$$

Note that the second sum of the left hand side is at most $\frac{\gamma_{2}-\gamma_{1}}{1000} n^{2}$. Therefore,

$$
\begin{equation*}
\sum_{x \in V\left(G_{u}\right):} \quad\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right|>\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}-\frac{\gamma_{2}-\gamma_{1}}{1000} n^{2} \tag{6}
\end{equation*}
$$

Before proceeding further, consider the following observation, which we will prove in Appendix D.1.

Observation $4.12(\star)$. If $\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000}$, then

$$
\mathbb{P}\left(\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x) \cap C_{u}\right| \geq\left(1-\frac{1}{50}\right)\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \frac{\left|C_{u}\right|}{n}\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}
$$

This implies that the following holds with probability at least $1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}$.

$$
\begin{aligned}
\sum_{x \in V\left(G_{u}\right):}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x) \cap C_{u}\right| & \geq\left(1-\frac{1}{50}\right) \frac{\left|C_{u}\right|}{n} \sum_{x \in V\left(G_{u}\right):}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \\
\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000} & \\
& \left.=\frac{49}{50}\left(4 \gamma_{1}+\frac{499\left(\gamma_{2}-\gamma_{1}\right)}{1000}\right) n \right\rvert\, \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000}
\end{aligned} n\left|C_{u}\right| \cdot(\because \text { By Equation 6 })
$$

Hence, with probability at least $1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}$, the following event holds.

$$
\begin{equation*}
\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x) \cap C_{u}\right| \geq \frac{49}{50}\left(4 \gamma_{1}+\frac{499\left(\gamma_{2}-\gamma_{1}\right)}{1000}\right) n\left|C_{u}\right| . \tag{7}
\end{equation*}
$$

Assuming Equation (7) holds and using the fact that $W \subset V\left(G_{u}\right)$ is taken uniformly at random, we can say that

$$
\mathbb{E}\left[\sum_{w \in W}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x) \cap C_{u}\right|\right]>\frac{49}{50}\left(4 \gamma_{1}+\frac{499\left(\gamma_{2}-\gamma_{1}\right)}{1000}\right)\left|C_{u}\right||W|
$$

Using Hoeffding's inequality (See Lemma E.3), we get

$$
\left.\left.\mathbb{P}\left(\sum_{w \in W} \mid \operatorname{Symm}_{\phi \phi^{\prime}}(w) \cap C_{u}\right)\left|\leq\left(3 \gamma_{1}+\frac{11\left(\gamma_{2}-\gamma_{1}\right)}{24}\right)\right| C_{u}| | W \right\rvert\,\right) \leq e^{-\mathcal{O}\left(\frac{\left|C_{u}\right|^{2}|W|^{2}}{|W|\left|C C_{u}\right|^{2}}\right)}=e^{-\mathcal{O}(|W|)}
$$

As the above equation holds in the conditional space that Equation (7) holds, we have

$$
\begin{equation*}
\left.\left.\mathbb{P}\left(\sum_{w \in W} \mid \operatorname{Symm}_{\phi \phi^{\prime}} \cap C_{u}\right)\left|>\left(3 \gamma_{1}+\frac{11\left(\gamma_{2}-\gamma_{1}\right)}{24}\right)\right| C_{u}| | W \right\rvert\,\right) \geq 1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}-e^{-\mathcal{O}(|W|)} . \tag{8}
\end{equation*}
$$

Note that Equation (5) implies Equation (8). However, till now, we have not used any information given in the statement of Claim 4.11, except that $C_{u}$ and $W$ are taken uniformly at random. By using the fact that the sum of label differences of the vertices of $W$ under $C_{u}$-labelling and that of $\psi$ is bounded, we will deduce that

$$
\begin{equation*}
\mathbb{P}\left(\sum_{w \in W}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(w) \cap C_{u}\right| \leq\left(2 \gamma_{1}+\frac{9\left(\gamma_{2}-\gamma_{1}\right)}{20}\right)\left|C_{u}\right||W|\right) \geq 1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}-e^{-\mathcal{O}(|W|)} \tag{9}
\end{equation*}
$$

As Equation (5) implies Equation (8), and Equations (8) and (9) together implies that Equation (5) does not hold with probability at least $1-4 n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}-e^{-\mathcal{O}(|W|)}$. Hence, we are done with the proof of Claim 4.11 except that we need to show Equation (9).

By the definition of the bijection $\phi$, we have $\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi}(x)\right| \leq \gamma_{1} n^{2}$. This implies

$$
\sum_{\substack{x \in V\left(G_{u}\right) \\\left|\operatorname{DECIDER}_{\phi}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000}}}\left|\operatorname{DECIDER}_{\phi}(x)\right| \leq \gamma_{1} n^{2}
$$

To proceed further, we need the following observation.
Observation $4.13(\star)$. (i) If $\left|\operatorname{DECIDER}_{\phi}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000}$, then

$$
\mathbb{P}\left(\left|\operatorname{DECiDER}_{\phi}(x) \cap C_{u}\right| \geq\left(1+\frac{1}{50}\right) \left\lvert\,\left(\operatorname{DECIDER}_{\phi}(x) \left\lvert\, \frac{\left|C_{u}\right|}{n}\right.\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}\right.\right.
$$

(ii) If $\left|\operatorname{DECIDER}_{\phi}(x)\right|<\frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000}$, then $\mathbb{P}\left(\left|\operatorname{DECIDER}_{\phi}(x) \cap C_{u}\right| \geq \frac{\gamma_{2}-\gamma_{1}}{750}\left|C_{u}\right|\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}$.

The above observation follows from Chernoff bound (See Lemma E.1) and is presented in Appendix D.2, and it implies that the following holds with probability at least $1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}$.

$$
\begin{aligned}
& \sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECiDER}_{\phi}(x) \cap C_{u}\right| \\
& =\sum_{x \in V\left(G_{u}\right):}\left|\operatorname{DECIDER}_{\phi}(x) \cap C_{u}\right|+\sum_{x \in V\left(G_{u}\right):} \quad\left|\operatorname{DECIDER}_{\phi}(x) \cap C_{u}\right| \\
& \left|\operatorname{DECIDER}_{\phi}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000} \quad\left|\operatorname{DECIDER}_{\phi}(x)\right|<\frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000} \\
& \leq\left(1+\frac{1}{50}\right) \quad \sum_{x \in V\left(G_{u}\right):} \quad\left|\operatorname{DECIDER}_{\phi}(x)\right| \frac{\left|C_{u}\right|}{n}+\frac{\left(\gamma_{2}-\gamma_{1}\right) n\left|C_{u}\right|}{750} \\
& \left|\operatorname{DECIDER}_{\phi}(x)\right| \geq \frac{\left(\gamma_{2}-\gamma_{1}\right) n}{1000} \\
& \leq \frac{51}{50} \gamma_{1} n\left|C_{u}\right|+\frac{\left(\gamma_{2}-\gamma_{1}\right) n\left|C_{u}\right|}{750}
\end{aligned}
$$

Note that the last inequality follows from Equation (10). Summarizing the above calculation, we get that the following event occurs with probability at least $1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}$.

$$
\begin{equation*}
\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECiDER}_{\phi}(x) \cap C_{u}\right| \leq \frac{51}{50} \gamma_{1} n\left|C_{u}\right|+\frac{\left(\gamma_{2}-\gamma_{1}\right) n\left|C_{u}\right|}{750} . \tag{11}
\end{equation*}
$$

Let us assume Equation (11) holds. Since we are taking the vertices of $W$ uniformly at random from $V\left(G_{u}\right)$, we have

$$
\begin{aligned}
\mathbb{E}\left[\sum_{w \in W}\left|\operatorname{DECiDER}_{\phi}(w) \cap C_{u}\right|\right] & =\mathbb{E}\left[\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \mathcal{L}_{C_{k}^{i}}(\phi(w))\right]\right. \\
& \leq \frac{51}{50} \gamma_{1}\left|C_{u}\right||W|+\frac{\left(\gamma_{2}-\gamma_{1}\right)\left|C_{u}\right||W|}{750} .
\end{aligned}
$$

Similarly from Step 2 (iii) of Phase 2, we have

$$
\begin{aligned}
\sum_{w \in W}\left|\operatorname{DECIDER}_{\phi^{\prime}}(w) \cap C_{u}\right| & =\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \mathcal{L}_{C_{k}^{i}}\left(\phi^{\prime}(w)\right)\right) \\
& \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|
\end{aligned}
$$

Recall that $\operatorname{Symm}_{\phi \phi^{\prime}}(x)=\operatorname{DECiDER}_{\phi^{\prime}}(x) \Delta \operatorname{DECiDER}_{\phi}(x)$. Therefore,

$$
\begin{aligned}
\mathbb{E}\left[\sum_{w \in W}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x) \cap C_{u}\right|\right] & \leq \mathbb{E}\left[\sum_{w \in W}\left|\operatorname{DECIDER}_{\phi^{\prime}}(w) \cap C_{u}\right|\right]+\sum_{w \in W}\left|\operatorname{DECIDER}_{\phi}(w) \cap C_{u}\right| \\
& \leq\left(\frac{764}{750} \gamma_{1}+\frac{301\left(\gamma_{2}-\gamma_{1}\right)}{750}\right)\left|C_{u}\right||W|
\end{aligned}
$$

Using Hoeffding's inequality (see Lemma E.3), we can say that

$$
\mathbb{P}\left(\sum_{w \in W}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(w) \cap C_{u}\right|>\left(2 \gamma_{1}+\frac{9\left(\gamma_{2}-\gamma_{1}\right)}{20}\right)\left|C_{u}\right||W|\right) \leq e^{-\mathcal{O}\left(\frac{\left.\left|\mathcal{C}_{u} u^{2}\right| W\right|^{2}}{\left.|W| C_{u}\right|^{2}}\right)}=e^{-\mathcal{O}(|W|)} .
$$

Note that the above equation holds on the conditional space that Equation (11) holds. Hence,

$$
\mathbb{P}\left(\sum_{w \in W}\left|\operatorname{Symm}_{\phi \phi^{\prime}}(w) \cap C_{u}\right| \leq\left(2 \gamma_{1}+\frac{9\left(\gamma_{2}-\gamma_{1}\right)}{20}\right)\left|C_{u}\right||W|\right) \geq 1-n e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}-e^{-\mathcal{O}(|W|)} .
$$

If we had constructed a bijection $\phi^{\prime}$ as stated in the above claim, we could easily test by sampling suitable many random edges from $G_{u}$ and checking the corresponding edges in $G_{k}$. It is important to note that, it is not possible to construct $\phi^{\prime}$ efficiently. However, without constructing the bijection $\phi^{\prime}$, if we can test for presence of some randomly chosen edges in $G_{u}$ and their corresponding edges in $G_{k}$, we are done. In order to achieve this, we choose $W$ randomly in Step 1 of Phase 2 and pair up the vertices of $W$ in Step 1 of Phase 3. Using Step 2 (iii) of Phase 2 and Step 3 of Phase 3, we check if $\hat{\phi}(w)=\phi^{\prime}(w)$ for each $w \in W$. Note that $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ is the map constructed in Step 3 of Phase 3 and $\phi^{\prime}: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ is the bijection as stated in Claim4.11. Then we check the edge mismatches between the paired up vertices of $W$ in $G_{u}$ and their corresponding mapped vertices in $G_{k}$ in Step 4 of Phase 3, which is possible as we have constructed the mappings of the vertices in $W$ in Step 2 (iii) of Phase 2.

The following claim proves that if $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close, then $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)$, as considered in Step 4 of Phase 3 holds with probability at least 20/21.

Claim 4.14. Let us assume that $\phi: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$ be a bijection such that $d_{\phi}\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$, and $\left(C_{u}, \eta_{i}\right) \in \Gamma$ where $C_{u} \in \mathcal{C}_{u}$, and $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ be an embedding of $C_{u}$ such that

- $\forall v \in C_{u}$ we have $\eta_{i}(v)=\phi(v)$, and
- $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$.

Let $\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ be the all possible $C_{k}^{i}$-labellings of $G_{k}$ where $t=\left[2^{\left|C_{k}^{i}\right|}\right], W$ be the set of vertices of $G_{u}$ sampled at random in Step 1 of Phase 2, and $\psi: W \rightarrow\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ be the mapping considered in Step 2 (iii) of Phase 2 such that

- $\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$, and
- $\forall j \in[t]$, we have $\left|\left\{w: \psi(w)=l_{j}\right\}\right| \leq\left|V_{j}\right|$.

If we take an embedding $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ such that $\hat{\phi}(w) \in V_{j}$ if and only if $\psi(w)=\ell_{j}$, then

$$
\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)
$$

holds with probability at least 20/21, where $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)$ is as defined in Step 3 of Phase 3.
Proof. Recall that $W$ is a subset of $V\left(G_{u}\right)$ taken uniformly at random in Step 1 of Phase 2 and we paired up the vertices of $W$ randomly in Step 1 of Phase 3 respectively. Also, we are checking the edge mismatches of the paired up vertices of $W$ and their corresponding mapped vertices in $G_{k}$ according to the mapping $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ in Step 4 of Phase 3 to compute $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)$. Considering the conditions given in the statement of this claim and Claim4.11, one can think that we are checking the presence of $\frac{|W|}{2}$ many randomly chosen edges in $G_{u}$ and the corresponding edges in $G_{k}$ according to some bijection $\phi^{\prime}: V\left(G_{u}\right) \rightarrow V\left(G_{k}\right)$, where $\phi^{\prime}$ is a bijection with $d_{\phi^{\prime}}\left(G_{u}, G_{k}\right) \leq$ $\left(5 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}$.

So, $\mathbb{E}\left[\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)\right] \leq\left(5 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right)$. Now, applying Hoeffding's inequality (Lemma E.3) and taking $|W|=C^{\prime} \frac{\log ^{2} n}{\left(\gamma_{2}-\gamma_{1}\right)^{3}}$ for suitably large constant $C^{\prime}$, we have

$$
\begin{aligned}
\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)>5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right) & =\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)|W|>\left(5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right)|W|\right) \\
& \leq e^{-\mathcal{O}(|W|)} \leq \frac{1}{21}
\end{aligned}
$$

Now we are ready to prove the completeness property using Claims $4.8,4.10,4.11,4.14$ and Theorem4.2.

Lemma 4.15 (Completeness Lemma). If $G_{u}$ and $G_{k}$ are $\gamma_{1}$-close to isomorphic, then our algorithm reports the same with probability at least $2 / 3$.

Proof. Observe that from Claim 4.8, we know that, with probability at least 20/21, there exists a $C_{u} \in \mathcal{C}_{u}$ and an embedding $\eta_{i}: C_{u} \rightarrow V\left(G_{k}\right)$ such that EMD $\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$ where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$. Similarly, from Theorem4.2, we can say that, with probability at least 20/21, the algorithm ALG-EMD returns all embeddings $\eta_{i}$ such that EMD $\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right) n\left|C_{u}\right|$. Now from Claim4.10, we know that, with probability at least 20/21, conditions of Equation (3) hold. Again, from Claim 4.11, we can say that constructing partial bijection at Step 3 of Phase 3 does not change isomorphism distance by more than $\left(4 \gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2}\right) n^{2}$ with probability at least 18/21.

Finally, from Claim4.14, we can say that the algorithm will correctly detect the distance at Step 4 of Phase 3 by testing $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)$ with probability at least 20/21. Thus, using union bound, we can say that when $G_{k}$ and $G_{u}$ are $\gamma_{1}$-close to being isomorphic, TolerantGI( $G_{u}$, $G_{k}, \gamma_{1}, \gamma_{2}$ ) reports the same with probability at least $2 / 3$.

### 4.2.2 Proof of Soundness Property

Similarly for the soundness property of our algorithm, let us consider the case when $G_{u}$ and $G_{k}$ are $\gamma_{2}$-far from being isomorphic. Then we will show that the algorithm will output the correct answer with probability at least $2 / 3$.

Recall the definition of the set $\Gamma_{W}$ with which we started Phase 3 of our algorithm.

$$
\Gamma_{W}=\left\{\left(C_{u}, \eta_{i}, \psi\right):\left(C_{u}, \eta_{i}\right) \in \Gamma \text { such that Equation } 3 \text { holds }\right\} .
$$

By Observation 4.5, we have

$$
\begin{equation*}
\operatorname{Pr}\left(\forall\left(C_{u}, \eta_{i}, \psi\right) \in \Gamma_{W}, E M D\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \frac{\gamma_{2}}{5}\left|C_{u}\right| n\right) \geq \frac{8}{9} . \tag{12}
\end{equation*}
$$

From now on, we work on the conditional space where $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \frac{\gamma_{2}}{5}\left|C_{u}\right| n \forall\left(C_{u}, \eta_{i}, \psi\right)$ holds. By Observation 4.7 (i), we know that $\left|\Gamma_{W}\right| \leq 2^{\mathcal{O}\left(\log ^{2} n /\left(\gamma_{2}-\gamma_{1}\right)\right)}$. So, the following claim about any $\left(C_{u}, \eta_{i}, \psi\right) \in \Gamma_{W}$ along with union bound over all the elements in $\Gamma_{W}$, we will be done with the proof of soundness property.

Claim 4.16. Let $\left(C_{u}, \eta_{i}, \psi\right) \in \Gamma_{W}$ and $\hat{\phi}$ be the embedding of $W$ into $G_{k}$ constructed while executing Step 3 of Phase 3 for $\left(C_{u}, \eta_{i}, \psi\right)$. Also, let EMD $\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \frac{\gamma_{2}}{5}\left|C_{u}\right| n$, where $C_{k}^{i}=\eta_{i}\left(C_{u}\right)$. Then the following holds with probability at most $\frac{2}{9\left|\Gamma_{W}\right|}$ :

$$
\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right) .
$$

Proof. Let $\Phi\left(C_{u}, C_{k}^{i}\right)$ be the class of all bijections such that the following hold for each $\phi \in \Phi\left(C_{u}, C_{k}\right)$.

- $\phi(x)=\eta_{i}(x)$ for each $x \in C_{u}$, and
- $\sum_{v \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi}(v) \cap C_{u}\right| \leq \frac{\gamma_{2}}{5} n\left|C_{u}\right|$.

Consider the following observation, about the bijections in $\Phi$, that we will prove later.
Observation 4.17. Let $\phi$ be a bijection in $\Phi$. Then $\sum_{w \in W}\left|\operatorname{DECIDER}_{\phi}(w) \cap C_{u}\right| \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$ holds with probability at least $1-\frac{1}{9\left|\Gamma_{W}\right|}$.

Our algorithm constructs $\psi: W \rightarrow\left\{\ell_{1}, \ldots, \ell_{t}\right\}$ in Step 2 of Phase 2 satisfying

- $\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right) \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$, and
- $\forall j \in[t]$, we have $\left|\left\{w: \psi(w)=l_{j}\right\}\right| \leq\left|V_{j}\right|$.

Note that $\sum_{w \in W} d_{H}\left(\mathcal{L}_{C_{u}}(w), \psi(w)\right)=\sum_{w \in W}\left|\operatorname{DECiDER}_{\phi}(w) \cap C_{u}\right|$, where $\phi$ is some bijection in $\Phi$. After getting $\psi$, we construct a partial bijection $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ that satisfies the above two conditions. So, one can think of $W$ is taken uniformly at random from the set of all $W$ 's satisfying $\sum_{w \in W}\left|\operatorname{Decider}_{\phi}(w) \cap C_{u}\right| \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|$. Now, from Observation 4.17, we have the following observation.

Observation 4.18. $\hat{\phi}$ is a random restriction of a random bijection $\phi \in \Phi\left(C_{u}, C_{k}\right)$ by the set $W$ with probability at least $1-\frac{1}{9\left|\Gamma_{W}\right|}$.

Proof. Let us consider a $\phi$ such that $\left.\phi\right|_{W}=\hat{\phi}$. Let $\mathcal{W}=\left\{\hat{\phi}_{X}=\left.\phi\right|_{X}: X \subset V\left(G_{u}\right)\right.$ and $\left.|X|=|W|\right\}$, and $\mathcal{W}^{\prime} \subseteq \mathcal{W}$ is defined as:

$$
\mathcal{W}^{\prime}=\left\{\hat{\phi}_{X} \in \mathcal{W}: \sum_{w \in X}\left|\operatorname{DECiDER}_{\phi}(w) \cap C_{u}\right| \leq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|\right\}
$$

Observe that $\hat{\phi}=\hat{\phi}_{W} \in \mathcal{W}$. By Observation 4.17, we know that if we take a set $X \subset V\left(G_{u}\right)$ (i.e, a $\hat{\phi}_{X}$ uniformly at random from $\left.\mathcal{W}\right)$, then the probability that $\hat{\phi}_{X} \in \mathcal{W}^{\prime}$, is at least $1-\frac{1}{9 \mid \Gamma_{W}}$. So, $\left|\mathcal{W}^{\prime}\right| \geq\left(1-\frac{1}{9\left|\Gamma_{W}\right|}\right)|W|$.

Observe that the partial bijection $\hat{\phi}$, constructed by our algorithm, is same as that of $\hat{\phi}_{W}$, and $\hat{\phi}$ is in $\mathcal{W}^{\prime}$. Now, using the fact that $\left|\mathcal{W}^{\prime}\right| \geq\left(1-\frac{1}{9\left|\Gamma_{W}\right|}\right)|W|$, the observation follows.

Recall that $W$ is a subset of $V\left(G_{u}\right)$ taken uniformly at random in Step 1 of Phase 2 and we paired up the vertices of $W$ randomly in Step 1 of Phase 3 respectively. Also, we are checking the edge mismatches of the paired up vertices of $W$ and their corresponding mapped vertices in $G_{k}$ according to the mapping $\hat{\phi}: W \rightarrow V\left(G_{k}\right)$ in Step 4 of Phase 3 to compute $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)$. Considering the discussion here, one can think of that, we are checking the presence of $\frac{|W|}{2}$ many randomly chosen edges in $G_{u}$ and the corresponding edges in $G_{k}$ according to some bijection $\phi \in \Phi$.

Note that $d_{\phi}\left(G_{u}, G_{k}\right) \geq \gamma_{2} n^{2}$. Thus, $\mathbb{E}\left[\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)\right] \geq \gamma_{2}|W|$. Now we can deduce the following. ${ }^{11}$

$$
\begin{aligned}
\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right) & =\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right)|W| \leq\left(5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right)|W|\right) \\
& \leq e^{-\mathcal{O}(|W|)} \\
& \leq \frac{1}{9\left|\Gamma_{W}\right|}
\end{aligned}
$$

Note that we were deriving the above bound on $\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right)$ assuming that $\hat{\phi}$ is a random restriction of a random $\phi \in \Phi$. Hence, combining Observation 4.18 with the above bound on $\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right)$ (when $\hat{\phi}$ is a random restriction of a random $\phi \in \Phi)$, we get

$$
\mathbb{P}\left(\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)\right) \leq \frac{2}{9\left|\Gamma_{W}\right|} .
$$

[^6]Proof of Observation 4.17 . Since $W$ is taken uniformly at random,

$$
\mathbb{E}\left[\sum_{w \in W}\left|\operatorname{Decider}_{\phi}(w) \cap C_{u}\right|\right] \leq \frac{\gamma_{2}}{5}\left|C_{u}\right||W|
$$

Using Hoeffding's inequality, we get

$$
\mathbb{P}\left(\sum_{w \in W}\left|\operatorname{DECIDER}_{\phi}(w) \cap C_{u}\right| \geq \frac{2 \gamma_{2}}{5}\left|C_{u}\right||W|\right) \leq e^{-\mathcal{O}(|W|)} \leq \frac{1}{9\left|\Gamma_{W}\right|}
$$

Now we are ready to prove the soundness property of our algorithm.
Lemma 4.19 (Soundness Lemma). If $G_{u}$ and $G_{k}$ are $\gamma_{2}$-far from isomorphic, then the algorithm reports the same with probability at least $2 / 3$.

Proof. From Observation 4.7 (i), we know that $\left|\Gamma_{W}\right|$ is at most $2^{C_{1} \frac{\log ^{2} n}{\gamma_{2}-\gamma_{1}}}$. In Claim 4.16. we are proving that $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\gamma_{1}\right)$ holds with probability at most $\frac{2}{9\left|\Gamma_{W}\right|}$ for any particular $\left(C_{u}, \eta_{i}, \psi\right) \in \Gamma_{W}$ with $\operatorname{EMD}\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \frac{\gamma_{2}}{5}\left|C_{u}\right| n$. So, by the union bound, the probability that there exists a $\left(C_{u}, \eta_{i}, \psi\right) \in \Gamma_{W}$ with $E M D\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \frac{\gamma_{2}}{5}\left|C_{u}\right| n$ such that $\zeta\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \leq 5 \gamma_{1}+\frac{3}{5}\left(\gamma_{2}-\right.$ $\left.\gamma_{1}\right)$, is at most $\frac{2}{9}$. Now From Equation 12 .

$$
\operatorname{Pr}\left(\forall\left(C_{u}, \eta_{i}, \psi, \hat{\phi}\right) \in \Gamma_{W}, E M D\left(X_{C_{u}}, Y_{C_{k}^{i}}\right) \leq \frac{\gamma_{2}}{5}\left|C_{u}\right| n\right) \geq \frac{8}{9}
$$

Putting everything together, the probability that the algorithm reports that $G_{u}$ and $G_{k}$ are $\gamma_{2}$-far, is at least $2 / 3$.

Till now we have proved the completeness and soundness property of our algorithm TolerantGI. We will prove the query complexity property in the next section when we prove the final theorem.

### 4.3 Proof of Theorem 4.1

Proof. From the Completeness Lemma (Lemma 4.15) and Soundness Lemma (Lemma 4.19), we can say that our algorithm TolerantGI correctly decides whether $d\left(G_{u}, G_{k}\right) \leq \gamma_{1} n^{2}$ or $d\left(G_{u}, G_{k}\right) \geq \gamma_{2} n^{2}$ with probability at least $2 / 3$.

Now, we calculate the query complexity of our algorithm. Note that Step 1 and Step 2 of Phase 1, Step 1 and Step 3 of Phase 2, Step 1, Step 2 and Step 3 of Phase 3, of the algorithm TolerantGI, do not require any query to the adjacency matrix of $G_{u}$. Let $\operatorname{CosT}_{C_{u}}$ denote the query complexity corresponding to a particular $C_{u} \in \mathcal{C}_{u}$. So, the total query complexity of the algorithm TolerantGI is $\sum_{\mathcal{C}_{u} \in \mathcal{C}_{u}} \operatorname{CosT}_{C_{u}}$. Observe that

$$
\operatorname{CosT}_{C_{u}}=\text { Query Complexity of algorithm ALG-EMD }+\operatorname{CosT}_{C_{u}, W}
$$

where $\operatorname{Cos}^{C_{u}, W}$ denotes the query complexity of Step 1 of Phase 2 corresponding to $W$ and $\mathcal{C}_{u} \in \mathcal{C}_{u}$.

Note that ALG-EMD is the algorithm corresponding to Theorem4.2. In Step $\mathbf{3}$ of Phase $\mathbf{1}$ of our algorithm, for each $C_{u} \in \mathcal{C}_{u}$, we call ALG-EMD with parameters $d=\mathcal{O}\left(\frac{\log n}{\gamma_{2}-\gamma_{1}}\right), t=2^{\mathcal{O}\left(\frac{\log ^{2} n}{\gamma_{2}-\gamma_{1}}\right)}$, $\epsilon_{1}=\left(\gamma_{1}+\frac{\gamma_{2}-\gamma_{1}}{2000}\right), \epsilon_{2}=\frac{\gamma_{2}}{5}$ and $\delta=\Theta(1)$. So, the query complexity of each call, to ALG-EMD from our algorithm, is $\widetilde{\mathcal{O}}\left(\min \left\{n, 2^{d}\right\}\right)=\widetilde{\mathcal{O}}(n)$.

Further note that, from the description Step 1 of Phase $2, \operatorname{CosT}_{C_{u}, W}=\mathcal{O}\left(\frac{\log ^{2} n}{\gamma_{2}-\gamma_{1}}\right)$. Since $\left|\mathcal{C}_{u}\right|=\mathcal{O}\left(\frac{1}{\gamma_{2}-\gamma_{1}}\right)$, the total query complexity of our algorithm is $\widetilde{\mathcal{O}}(n)$.

## 5 Conclusion

In this paper, we proved that the query complexity of tolerant GI testing between a known graph $G_{k}$ and an unknown graph $G_{u}$ is the same as (up to polylogarithmic factor) testing of $E M D$ between a known multi-set $S_{k}$ and an unknown multi-set $S_{u}$ when we have samples without replacement from $S_{u}$. In Lemma B.10, we have shown that the sample complexity of testing of EMD between a known multi-set $S_{k}$ and an unknown multi-set $S_{u}$ when we have samples with replacement from $S_{u}$ is $\Omega(n / \log n)$. Thus the natural open question is

What is the query complexity of tolerant EMD testing when we have samples without replacement from the unknown multi-set?

It is also interesting to note that our lower bound proof is via a pure reduction from graph isomorphism to testing $E M D$ of multi-sets over the Hamming cube using samples without replacement. Using our lower bound technique (and Proposition B.7), we can get an alternative proof of Fischer and Matsliah's lower bound result for testing non-tolerant graph isomorphism [FM08]. Our upper bound proof is also a pure reduction from testing EMD of multi-sets over the Hamming cube to tolerant graph isomorphism problem. Thus our reductions also hold for other computational models such as the communication complexity model. So, in the communication model (that is, when Alice and Bob have graphs $G_{A}$ and $G_{B}$ respectively and they want to estimate the GI-distance between them), the amount of bits of communication is same (up to a polylogarithmic factors) to the problem of estimating the $E M D$ distance between two distributions over Hamming cube, where Alice and Bob have access to one distribution each. The question we would like to pose is:

## What is the randomized communication complexity of testing tolerant graph isomorphism problem?

Fischer and Matsliah [FM08] studied the non-tolerant version of the graph isomorphism problem in two scenarios: (i) one graph is known and the other graph is unknown, (ii) both the graphs are unknown. They resolved the query complexity of (i), whereas Onak and Sun [OS18] resolved (ii). With this paper, we initiate the study of tolerant graph isomorphism problem in the query world and settled the question completely when one graph is unknown, and the other graph is known. So, another natural open question to look for is:

> What is the query complexity of tolerant graph isomorphism
> when both the graphs are unknown?

## 6 Acknowledgement

The authors would like to thank the anonymous reviewer for pointing out a mistake in an earlier version of this paper.

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## A Preliminaries

All graphs considered here are undirected, unweighted and have no self-loops or parallel edges. For a graph $G(V, E), V(G)$ and $E(G)$ will denote the vertex set and the edge set of $G$, respectively. Since we are considering undirected graphs, we write an edge $(u, v) \in E(G)$ as $\{u, v\}$. The Hamming distance between two points $x$ and $y$ in a Hamming cube $\{0,1\}^{k}$ will be denoted by $d_{H}(x, y)$.

## A. 1 Notion of distance between two graphs

First let us define the notion of DECIDER of a vertex and then the notion of distance between two graphs, using decider of vertices, that is conceptually same as that of GRAPH ISOMORPHISM Distance defined in Definition 1.1 .

Definition A.1. (DECIDER of a vertex) Given two graphs $G_{k}$ and $G_{u}$ and a bijection $\phi: V\left(G_{u}\right) \rightarrow$ $V\left(G_{k}\right)$, DECIDER of a vertex $x \in V\left(G_{u}\right)$ with respect to $\phi$ is defined as the set of vertices of $G_{u}$ that create the edge difference in $x$ and $\phi(x)$ 's neighbourhood in $G_{u}$ and $G_{k}$, respectively. Formally,
$\operatorname{DECIDER}_{\phi}(x):=\left\{y \in V\left(G_{u}\right):\right.$ one of the edges $\{x, y\}$ and $\{\phi(x), \phi(y)\}$ is not present $\}$
Definition A.2. (DISTANCE between two graphs) Let $G_{u}$ and $G_{k}$ be two graphs and $\phi: V\left(G_{u}\right) \rightarrow$ $V\left(G_{k}\right)$ be a bijection from the vertex set of $G_{u}$ to that of $G_{k}$. The distance between $G_{u}$ and $G_{k}$ under $\phi$ is defined as the sum of the sizes of the deciders of all the vertices in $G_{u}$, that is,

$$
d_{\phi}\left(G_{u}, G_{k}\right):=\sum_{x \in V\left(G_{u}\right)}\left|\operatorname{DECIDER}_{\phi}(x)\right| .
$$

The distance between two graphs $G_{u}$ and $G_{k}$ is the minimum distance under all possible bijections $\phi$ from $V\left(G_{u}\right)$ to $V\left(G_{k}\right)$, that is, $d\left(G_{u}, G_{k}\right):=\min _{\phi} d_{\phi}\left(G_{u}, G_{k}\right)$.

Remark 5. Recall the definition of $\delta_{G I}\left(G_{u}, G_{k}\right)$, GRAPH ISOMORPHISM DISTANCE between $G_{u}$ and $G_{k}$, that is given in Definition 1.1. Observe that $d\left(G_{u}, G_{k}\right)=2\binom{n}{2} \delta_{G I}\left(G_{u}, G_{k}\right)$. Though, $d\left(G_{u}, G_{k}\right)$ and $\delta_{G I}\left(G_{u}, G_{k}\right)$ represent the same thing, conceptually, we will do our calculations by using $d\left(G_{u}, G_{k}\right)$ for simplicity of presentation.

Next we define the concept of closeness between two graphs.

Definition A.3. (CLOSE and FAR) For $\gamma \in[0,1)$, two graphs $G_{u}$ and $G_{k}$ with $n$ vertices are $\gamma$-close to isomorphic if $d\left(G_{u}, G_{k}\right) \leq \gamma n^{2}$. Otherwise, we say $G_{u}$ and $G_{k}$ are $\gamma$-far from being isomorphic. ${ }^{12}$

## A. 2 Property Testing of Distribution Properties

Understanding different properties of probability distributions have been an active area of research in property testing (For reference, see [Can15]). The authors studied these problems assuming random sample access from the unknown distributions. Considering the relation between the distributions and their corresponding representative multi-sets, we can say that all these results hold for multi-sets along with access over sampling with replacement.

Although it seems that the change of query model from sample with replacement to sample without replacement does not make much difference, following the work of Freedman [Fre77], we know that the variation distance between probability distributions when accessed via samples with and without replacement, becomes arbitrary close to $1 / 2$ when the number of samples is $\Omega(\sqrt{n})$. Because of this reason, many techniques developed for sampling with replacement for various problems no longer work anymore. Most importantly, proving any lower bound better than $\Omega(\sqrt{n})$ is often nontrivial.

## B Earth Mover's Distance (EMD) over Hamming Cube

In this section, we study some properties of Earth Mover's distance (EMD) over probability distributions and multi-sets, which are crucial in the context of both our lower and upper bound. Before proceeding to the discussion on EMD, let us first recall the definition of $\ell_{1}$ distance between two distributions.

Definition B. 1 ( $\ell_{1}$ distance between two distributions). Let $p$ and $q$ be two probability distributions over $\left[n\right.$ ]. The $\ell_{1}$ distance between $p$ and $q$ is defined as

$$
d_{l_{1}}(p, q)=\sum_{i=1}^{n}|p(i)-q(i)|
$$

Definition B. 2 (EMD between two probability distributions). Let $H=\{0,1\}^{d}$ be a Hamming cube of dimension $d$, and $p, q$ be two probability distributions on $H$. The EMD between $p$ and $q$ is denoted by $E M D(p, q)$ and defined as the optimum solution to the following linear program:

$$
\begin{array}{ll}
\text { Minimize } & \sum_{x, y \in H} f_{x y} d_{H}(x, y) \\
\text { Subject to } & \sum_{y \in H} f_{x y}=p(x) \forall x \in H, \text { and } \sum_{x \in H} f_{x y}=q(y) \forall y \in H .
\end{array}
$$

Now we define EMD between two multi-sets.
Definition B. 3 (EMD between two multi-sets). Let $S_{1}, S_{2}$ be two multi-sets on Hamming cube $H=\{0,1\}^{d}$ of dimension $d$ with $\left|S_{1}\right|=\left|S_{2}\right|$. The EMD between $S_{1}$ and $S_{2}$ is denoted by $\operatorname{EMD}\left(S_{1}, S_{2}\right)$ and defined as $\operatorname{EMD}\left(S_{1}, S_{2}\right)=\min _{\phi: S_{1} \rightarrow S_{2}} \sum_{x \in S_{1}} d_{H}(x, \phi(x))$ where $\phi$ is a bijection from $S_{1}$ to $S_{2}$.

[^7]Note that an unknown distribution $p$ is accessed by taking samples from $p$. However, a multi-set is accessed as follows:

Definition B. 4 (Query accesses to multi-sets). A multi-set $S$ of $n$ elements is accessed in one of the following ways:

Sample Access with replacement: Each element of $S$ is reported uniformly at random independent of all previous queries.

Sample Access without replacement: Let us assume we make $Q$ queries to $S$, where $Q \leq n$. The answer to the first query, say $s_{1}$, is an element from $S$ chosen uniformly at random. For any $2 \leq i \leq Q$, the answer of the $i$-th query is an element chosen uniformly at random from $S \backslash\left\{s_{1}, \ldots, s_{i-1}\right\}$. Here $s_{j}, 1 \leq j \leq Q$, denotes the answer to the $j$-th query.

Although sampling with replacement is more natural query model, we need sampling without replacement for our lower bound proof. We now show that we can simulate samples with replacement when we have samples without replacement.

Proposition B. 5 (Simulating samples with replacement from samples without replacement). Given $Q$ many samples without replacement from an unknown multi-set $S_{u}$ with n elements, we can simulate $Q$ many samples with replacement from $S_{u}$ where $Q \leq n$.

Proof. Consider the following procedure to get $Q$ many samples with replacement (say $x_{1}, \ldots, x_{Q}$ ) when we have $Q$ many samples without replacement $\left(s_{1}, \ldots, s_{Q}\right)$ from the unknown multi-set $S_{u}$ with $Q \leq n$.

We first set $x_{1}=s_{1}$. For each $i$ with $2 \leq i \leq Q$, we set $x_{i}$ as follows: with probability $1-\frac{i-1}{n}$, we select one of the element from $\left\{s_{1}, \ldots, s_{i-1}\right\}$ uniformly at random as $x_{i}$; with probability $\frac{i-1}{n}$, we set $x_{i}=s_{i}$. From the description of procedure to generate $x_{i}$ 's, we have $\mathbb{P}\left(x_{i}=s_{i}\right)=\frac{1}{n}$.

Thus we can simulate $Q$ many samples with replacement from $Q$ many samples without replacement from the unknown multi-set $S_{u}$.

The following observation connects the EMD between two probability distributions with that of between two multi-sets.

Observation B.6. Let $p, q$ be two probability distributions, having support size $K$, on a $n$ dimensional Hamming cube $H=\{0,1\}^{n}$. Then $p$ and $q$ induces two multi-sets $S_{1}$ and $S_{2}$ on $H$, respectively, as follows. $S_{1}\left(S_{2}\right)$ is the multi-set containing $x \in H$ with multiplicity $p(x) K(q(x) K)$ for each $x \in H$. Moreover, $\operatorname{EMD}(p, q)=\frac{\operatorname{EMD}\left(S_{1}, S_{2}\right)}{K}$.

Proof. Recall the definitions of EMD between two distributions and two multi-sets given in Definition B.2 and B.3. respectively. We will be done with the proof by showing $\operatorname{EMD}\left(S_{1}, S_{2}\right) \leq$ $K \cdot E M D(p, q)$ and $K \cdot E M D(p, q) \leq E M D\left(S_{1}, S_{2}\right)$, separately.

For $E M D\left(S_{1}, S_{2}\right) \leq K \cdot E M D(p, q)$, let $\left\{f_{i j}^{*}: i, j \in H\right\}$ be the set of variables that realizes $\operatorname{EMD}(p, q)$, that is, $\operatorname{EMD}(p, q)=\sum_{i, j \in H} f_{i j}^{*} d_{H}(i, j)$. Consider a bijection $\phi$ from $S_{1}$ to $S_{2}$ where $\phi(i)=j$ for $g_{i j}$ many $i$ 's. Hence, by Definition B.3.

$$
E M D\left(S_{1}, S_{2}\right) \leq \sum_{x \in S_{1}} d_{H}(x, \phi(x))=\sum_{i, j \in H} K \cdot f_{i j}^{*} d_{H}(i, j)=K \cdot E M D(p, q) .
$$

Now, we show $K \cdot \operatorname{EMD}(p, q) \leq \operatorname{EMD}\left(S_{1}, S_{2}\right)$. Let $\phi^{*}$ be a bijection from $S_{1}$ to $S_{2}$ that realizes $\operatorname{EMD}\left(S_{1}, S_{2}\right)$, that is, $\operatorname{EMD}\left(S_{1}, S_{2}\right)=\sum_{x \in S_{1}} d_{H}\left(x, \phi^{*}(x)\right)$. For any $x, y \in H$, let $f_{x y}$ be the number of elements, of the form $(x, y)$ in $S_{1} \times S_{2}$ such that $x$ is mapped to $y$ under $\phi$, divided by $K^{2}$. Observe that $f_{x y} \geq 0$. Also, $f_{x y}>0$ if and only if $(x, y) \in S_{1} \times S_{2}$. More over, $\left\{f_{i j}: i, j \in H\right\}$ satisfies $\sum_{i \in H} f_{i j}=p(j) \forall j \in H$ and $\sum_{j \in H} f_{i j}=q(i) \forall i \in H$. Hence, by Definition B.2,

$$
\begin{aligned}
K \cdot E M D(p, q) \leq K \sum_{x, y \in H} f_{x y} d_{H}(x, y) & =\sum_{(x, y) \in S_{1} \times S_{2}} K \cdot f_{x y} d_{H}(x, y) \\
& =\sum_{x \in S_{1}} d_{H}\left(x, \phi^{*}(x)\right)=\operatorname{EMD}\left(S_{1}, S_{2}\right) .
\end{aligned}
$$

Remark 6. Note that sample access from a probability distribution is exactly same as uniform sampling from a multi-set with replacement.

Proposition B.7. Let $\mathcal{D}$ be the set of all multi-sets of size $n$ over a universe $[m]$; let $S_{k}$ and $S_{u}$ in $\mathcal{D}$ denote the known and unknown multi-sets over $[n]$; and PROP : $\mathcal{D} \times \mathcal{D} \rightarrow\{0,1\}$ be a boolean function. Then the following holds:

If there exists an algorithm that determines PROP by $Q$ many samples without replacement from $S_{u}$ with probability at least $2 / 3$, then there exists an algorithm that determines Prop by $\min \{Q, \sqrt{\min \{n, m\}}\}$ many samples with replacement from $S_{u}$ with probability at least $2 / 3-o(1)$.

This follows from the fact that when $Q=o(\sqrt{n})$ and $D_{W R}\left(D_{W o R}\right)$ be the probability distribution over all the subsets having $Q$ elements from $[n]$ with (without) replacement, the $\ell_{1}$ distance between $D_{W R}$ and $D_{W o R}$ is $o(1)$.

Definition B. 8 (EMD over multi-sets while sampling with and without replacement). Let $S_{k}$ and $S_{u}$ denote the known and the unknown multi-sets, respectively, over $n$-dimensional Hamming cube $H=\{0,1\}^{n}$ such that $\left|S_{u}\right|=\left|S_{k}\right|=n$. Consider the two distributions $p_{u}$ and $p_{k}$ over the Hamming cube $H$ that are naturally defined by the sets $S_{u}$ and $S_{k}$ where for all $x \in H$ probability of $x$ in $p_{u}$ (and $p_{k}$ ) is the number of occurrences of $x$ in $S_{u}$ (and $S_{k}$ ) divided by $n$. We then define the EMD between the multi-sets $S_{u}$ and $S_{k}$ as

$$
E M D\left(S_{u}, S_{k}\right) \triangleq n \cdot E M D\left(p_{u}, p_{k}\right)
$$

The problem of estimating the EMD over multi-sets while sampling with (or without) replacement means designing an algorithm, that given any two constants $\beta_{1}, \beta_{2}$ such that $0 \leq \beta_{1}<\beta_{2} \leq 1$, and access to the unknown set $S_{u}$ by sampling with (or without) replacement decides whether $E M D\left(S_{k}, S_{u}\right) \leq \beta_{1} n^{2}$ or $\operatorname{EMD}\left(S_{k}, S_{u}\right) \geq \beta_{2} n^{2}$ with probability at least $2 / 3$.

Note that estimating the EMD over multi-sets while sampling with replacement is exactly same as estimating EMD between the distributions $p_{u}$ and $p_{k}$ with samples drawn according to $p_{u}$.

Let $\operatorname{QWR}_{\operatorname{EMD}}\left(n, d, \beta_{1}, \beta_{2}\right)\left(\operatorname{QWOR}_{\operatorname{EMD}}\left(n, d, \beta_{1}, \beta_{2}\right)\right)$ denote the number of samples with (without) replacement required to decide the above from the unknown multi-set $S_{u}$. For ease of presentation, we write $\operatorname{QWOR}_{\operatorname{EMD}}(n, d)\left(\operatorname{QWR}_{\operatorname{EMD}}(n, d)\right)$ instead of $\operatorname{QWOR}_{\operatorname{EMD}^{(n, d)}}\left(\operatorname{QWR}_{\operatorname{EMD}}\left(n, \beta_{1}, \beta_{2}\right)\right)$ when the proximity parameters are clear from the context.

Proposition B. 9 (Query complexity of EMD increases with number of points as well as dimension). Let $n, n_{1}, n_{2}, d, d_{1}, d_{2} \in \mathbb{N}$ be such that $d_{1} \leq d_{2}$ and $n_{1} \leq n_{2}$. Then
(i) $\operatorname{QWR}_{E M D}\left(n_{1}, d\right) \leq \operatorname{QWR}_{\operatorname{EMD}}\left(n_{2}, d\right)$ and $\operatorname{QWOR}_{E M D}\left(n_{1}, d\right) \leq \operatorname{QWor}_{\operatorname{EMD}}\left(n_{2}, d\right)$;
(ii) $\operatorname{QWR}_{\operatorname{EMD}}\left(n, d_{1}\right) \leq \operatorname{QWR}_{\operatorname{EMD}}\left(n, d_{2}\right)$ and $\operatorname{QWOR}_{\operatorname{EMD}}\left(n, d_{1}\right) \leq \operatorname{QWOR}_{\operatorname{EMD}}{ }^{\left(n, d_{2}\right)}$.

Remark 7. For $d=n$ (as considered in Definition 1.2), $\operatorname{QWOR}_{\operatorname{EMD}}(n, d)\left(\operatorname{QWR}_{\mathrm{EMD}}(n, d)\right)$ are


Now let us state the lower bound of $\mathrm{QWR}_{\operatorname{EMD}^{(n)}}{ }^{(n)}$

Thus following Proposition B.7, we have
Theorem B.11. QWOR $_{E M D}(n)=\Omega(\sqrt{n})$.
Note that an upper bound of $\operatorname{QWOR}_{\operatorname{EMD}}(n)=\widetilde{\mathcal{O}}(n)$ is trivial. In the rest of the section, we focus on proving Theorem B. 10 that states the lower bound on $\mathrm{QWR}_{\mathrm{EMD}}(n)$. We also provide an upper bound for $\operatorname{QWR}_{\operatorname{EMD}}(n)$ at Lemma B.16 that shows that $\widetilde{\mathcal{O}}(n)$ many samples with replacement from $S_{u}$ to estimate $\mathrm{QWR}_{\mathrm{EMD}^{(n)} \text {. Note that by Remark } 6 \text {, it is enough to show the }}$ following lemma that states the lower bound for tolerant EMD testing between two distributions.

Lemma B.12. Let $p$ and $q$ be two known and unknown distributions, respectively, supported over a subset $S$ of a Hamming cube $H=\{0,1\}^{n}$ with $|S|=n$. Then there exists a constant $\epsilon_{E M D}$ such that the following holds. Given two constants $\beta_{1}, \beta_{2}$ with $0<\beta_{1}<\beta_{2}<\epsilon_{E M D}(c), \Omega\left(\frac{n}{\log n}\right)$ samples from the distribution $q$ are necessary in order to decide whether $\operatorname{EMD}(p, q) \leq \beta_{1} n$ or $\operatorname{EMD}(p, q) \geq \beta_{2} n$. More over, $\epsilon_{E M D}=\frac{1-\epsilon_{\ell_{1}}}{4}$, where $\epsilon_{\ell_{1}}$ is the constant that is mentioned in Theorem B. 14

To prove the above lower bound, let us first consider the following lower bound for tolerant $\ell_{1}$ testing between two probability distributions.

Theorem B. 13 (Valiant and Valiant [VV11]). Let $p$ and $q$ be two known and unknown probability distributions respectively over $[n]$. There is an absolute constant $\epsilon$ such that in order to decide whether $\|p-q\|_{1} \leq \epsilon$ or $\|p-q\|_{1} \geq 1-\epsilon, \Omega\left(\frac{n}{\log n}\right)$ samples, from the distribution $q$, are necessary. ${ }^{13}$

Now, we restate the above result for our purpose.
Theorem B.14. Let $p$ and $q$ be two known and unknown probability distributions, having support size $n$, over a Hamming cube $H=\{0,1\}^{n}$. There is an absolute constant $\epsilon_{\ell_{1}}$ such that in order to decide whether $\|p-q\|_{1} \leq \alpha_{1}$ or $\|p-q\|_{1} \geq \alpha_{2}$ with $0<\alpha_{1}<\alpha_{2} \leq 1-\epsilon_{\ell_{1}}, \Omega\left(\frac{n}{\log n}\right)$ samples, from the distribution $q$, are necessary.

As noted earlier, we will prove Theorem B.10 by using Lemma B. 14 . However, Theorem B. 10 is regarding EMD between two distributions whereas Lemma B.14 is regarding $\ell_{1}$ distance between two distributions. The following observation (from [DBNNR11]) gives a connection between EMD between two distributions with the $\ell_{1}$ distance between them, which will be required in lower bound proof.

[^8]Proposition B. 15 ([DBNNR11]). Let $(M, D)$ be a finite metric space and $p$ and $q$ be two probability distributions on $M$. Minimum distance between any two points of $M$ is $\Delta_{\min }$ and diameter of $M$ is $\Delta_{\max }$. Then the following condition holds:

$$
\frac{\|p-q\|_{1} \Delta_{\min }}{2} \leq E M D(p, q) \leq \frac{\|p-q\|_{1} \Delta_{\max }}{2}
$$

Note that the above observation is useful when $\frac{\Delta_{\max }}{\Delta_{\text {min }}}$ is bounded above by a constant. So, in Lemma B.12, we consider $S \subset H=\{0,1\}^{n}$ to be such that the pairwise Hamming distance between any two elements in $S$ is at least $\frac{n}{2}$, to have $\frac{\Delta_{\max }}{\Delta_{\text {min }}} \leq 2$ in our context. It is well known that, there exists such a $S$ with $|S|=\Omega(n)$.

Proof of Lemma B.12. We will show that if there exists an algorithm $\mathcal{A}$ that decides $E M D(p, q) \leq \beta_{1} n$ or $E M D(p, q) \geq \beta_{2} n$ by using $t$ samples from $q$, then there exists an algorithm $\mathcal{P}$ that decides whether $\|p-q\|_{1} \leq \alpha_{1}$ or $\|p-q\|_{1} \geq \alpha_{2}$ by using $t$ samples from $q$, where $\alpha_{1}=2 \beta_{1}$ and $\alpha_{2}=4 \beta_{2}$. Note that we have $0<\beta_{1}<\beta_{2}<\frac{1-\epsilon_{\ell_{1}}}{4}$. So, $0<\alpha_{1}<\alpha_{2}<1-\epsilon_{\ell_{1}}$, which satisfies the requirement of Theorem B. 14 .

## Algorithm $\mathcal{P}$ :

(1) First run algorithm $\mathcal{A}$.
(2) If the output of algorithm $\mathcal{A}$ is $\operatorname{EMD}(p, q) \leq \beta_{1} n$, algorithm $\mathcal{P}$ returns $\|p-q\|_{1} \leq \alpha_{1}$.
(3) If the output of algorithm $\mathcal{A}$ is $\operatorname{EMD}(p, q) \geq \beta_{2} n$, algorithm $\mathcal{P}$ returns $\|p-q\|_{1} \geq \alpha_{2}$.

To complete the proof, we only need to show that $\mathcal{P}$ gives desired output with probability at least $2 / 3$. The result then follows from Theorem B. 14

Let us first consider the case $\|p-q\|_{1} \leq \alpha_{1}$. Then by Observation B.15, we can say that $E M D(p, q) \leq \frac{\alpha_{1} n}{2}=\beta_{1} n$. Therefore algorithm $\mathcal{A}$ will output that $E M D(p, q) \leq \beta_{1} n$. This implies that the algorithm $\mathcal{P}$ will output $\|p-q\|_{1} \leq \alpha_{1}$.

Now, let us consider the case $\|p-q\|_{1} \geq \alpha_{2}$. Using the fact that any pair elements in $S \subset H$ is at least $\frac{n}{2}$ along with ObservationB.15, we get $E M D(p, q) \geq \frac{\alpha_{2} n}{4}=\beta_{2} n$. This implies $\mathcal{P}$ will output $\|p-q\|_{1} \geq \alpha_{2}$.

Till now, we were discussing the proof of Lemma B. 12 that states $\mathrm{QWR}_{\operatorname{EMD}}(n)=\Omega\left(\frac{n}{\log n}\right)$. The lower bound is almost tight, up to a polynomial factor of $\log n$. The upper bound is stated in the following observation.
Observation B.16. $\operatorname{QWR}_{\operatorname{EMD}}(n)=\widetilde{\mathcal{O}}(n)$, where $\widetilde{\mathcal{O}}(\cdot)$ hides a polynomial factor in $\frac{1}{\beta_{2}-\beta_{1}}$ and $\log n$.

Instead of proving the above observation, we prove the following lemma that states the upper bound of tolerant EMD testing between two distributions when we know one distribution and have sample access to the unknown distribution. By Remark 6, we will be done with the proof of Observation B.16,

Lemma B.17. Let $H=\{0,1\}^{n}$ be a n-dimensional Hamming cube, and let $p$ and $q$ denote two known and unknown n-grained distribution over $H$. There exists an algorithm that takes two parameters $\beta_{1}, \beta_{2}$ with $0 \leq \beta_{1}<\beta_{2} \leq 1$ and a $\delta \in(0,1)$ as input and decides whether $\operatorname{EMD}(p, q) \leq \beta_{1} n$ or $\operatorname{EMD}(p, q) \geq \beta_{2} n$ with probability at least $1-\delta$. Moreover, the algorithm ALG-EMD queries for $\widetilde{\mathcal{O}}(n)$ many samples from $q$, where $\widetilde{\mathcal{O}}(\cdot)$ hides a polynomial factor in $\frac{1}{\beta_{2}-\beta_{1}}$ and $\log n$.

Proof. Let $\epsilon$ be a constant less than $\left(\beta_{2}-\beta_{1}\right)$. We construct a probability distribution $q^{\prime}$ such that the $\ell_{1}$ distance between $q$ and $q^{\prime}$ will be at most $\epsilon$, that is, $\sum_{i \in[L]}\left|q(i)-q^{\prime}(i)\right| \leq \epsilon$. Note that such a $q^{\prime}$ can be constructed with probability at least $1-\delta$ by querying for $\widetilde{\mathcal{O}}(n)$ many samples of $q$ which follows from [DL12]. Then, we find $E M D\left(p, q^{\prime}\right)$. Observe that $\left|E M D(p, q)-E M D\left(p, q^{\prime}\right)\right| \leq \frac{\epsilon n}{2}$. This is because

$$
\begin{aligned}
\left|E M D(p, q)-E M D\left(p, q^{\prime}\right)\right| & \leq\left|E M D\left(p, q^{\prime}\right)+E M D\left(q^{\prime}, q\right)-E M D\left(p, q^{\prime}\right)\right| \\
& \leq E M D\left(q, q^{\prime}\right) \\
& \leq \frac{\epsilon d}{2}(\text { By Proposition B.15 }
\end{aligned}
$$

As $\operatorname{EMD}(p, q) \leq \beta_{1} n$ or $\operatorname{EMD}(p, q) \geq \beta_{2} n$, by the above observation, we will get either $\operatorname{EMD}\left(p, q^{\prime}\right) \leq\left(\beta_{1}+\frac{\epsilon}{2}\right) n$ or $\operatorname{EMD}\left(p, q^{\prime}\right) \geq\left(\beta_{1}+\frac{\epsilon}{2}\right) n$, respectively. By our choice of $\epsilon<\beta_{2}-\beta_{1}$, we can decide $E M D(p, q) \leq \beta_{1} n$ or $E M D(p, q) \geq \beta_{2} n$ from the value of $E M D\left(p, q^{\prime}\right)$.

## C Missing proofs of Section 3

## C. 1 Proof of Lemma 3.3

Lemma C. 1 (Lemma 3.3 restated). Let $\kappa \in(0,1)$ and $s \geq 3$ be given constants. Then for $C_{\kappa, s}=\left\lceil\frac{6 \mathrm{~s}}{\kappa(2-\kappa)}\right\rceil$ and sufficiently large $n \in \mathbb{N}{ }^{14}$, there exists a graph $G_{p}$ with $C_{\kappa, s} n$ many vertices such that the following conditions hold.
(i) The degree of each vertex in $G_{p}$ is at least $\left((1-\kappa) C_{\kappa, s}+1\right) n-1$.
(ii) The cardinality of symmetric difference between the sets of neighbors of any two (distinct) vertices in $G_{p}$ is at least $s n-2$.

Proof. To prove the claim, we use probabilistic method to show the existence of a graph $G_{p}^{\prime}$, with $V\left(G_{p}^{\prime}\right)=C_{\kappa, s} n$, that can have (possible) self loops and satisfy the followings.
(i) The degree of each vertex in $G_{p}^{\prime}$ is at least $\left((1-\kappa) C_{\kappa, s}+1\right) n$.
(ii) The cardinality of symmetric difference between the sets of neighbors of any two (distinct) vertices in $G_{p}^{\prime}$ is at least $s n$.

Let us construct a random graph having the vertex set $V\left(G_{p}^{\prime}\right)$ such that each pair $\{u, v\}$, with $u, v \in V\left(G_{p}^{\prime}\right)$, is an edge with probability $1-\frac{\kappa}{2}$ independent of other pairs.

[^9]Now we compute the probability that the degree of a vertex $v \in G\left(V_{p}^{\prime}\right)$, that is $\operatorname{deg}_{G_{p}^{\prime}}(v)$, is at $\operatorname{most}\left((1-\kappa) C_{\kappa, s}+1\right) n$. For each $v^{\prime} \in V\left(G_{p}^{\prime}\right)$, let $X_{v^{\prime}}$ be the indicator random variable that takes value 1 if and only if $\left\{v, v^{\prime}\right\} \in E\left(G_{p}^{\prime}\right)$. Note that $\operatorname{deg}_{G_{p}^{\prime}}(v)=\sum_{v^{\prime} \in V\left(G_{p}^{\prime}\right)} X_{v^{\prime}}$. Also, $\mathbb{P}\left(X_{v^{\prime}}=1\right)=1-\frac{\kappa}{2}$. So, the expected value of $\operatorname{deg}_{G_{p}^{\prime}}(v)$ is $\left(1-\frac{\kappa}{2}\right) C_{\kappa, s} \eta$. By using Chernoff bound E.1. we have

$$
\begin{aligned}
& \mathbb{P}\left(\operatorname{deg}_{G_{p}^{\prime}}(v) \leq\left((1-\kappa) C_{\kappa, s}+1\right) n\right) \\
& =\mathbb{P}\left(\operatorname{deg}_{G_{p}^{\prime}}(v) \leq(1-\epsilon)\left(1-\frac{\kappa}{2}\right) C_{\kappa, s} n\right) \quad\left(\text { where } \epsilon=\frac{\kappa C_{\kappa, s}-2}{(2-\kappa) C_{\kappa, S}}<1\right) \\
& \leq e^{-\frac{\epsilon^{2}\left(2-\kappa \kappa C_{K, s}\right.}{6}}
\end{aligned}
$$

Let $\mathcal{E}_{1}$ be the event that there exists a vertex $v \in V\left(G_{p}^{\prime}\right)$ such that the degree of $v$ in $G_{p}^{\prime}$ is at $\operatorname{most}\left((1-\kappa) C_{\kappa, s}+1\right) n$. Using union bound, we can say that $\mathbb{P}\left(\mathcal{E}_{1}\right) \leq\left|V\left(G_{p}^{\prime}\right)\right| e^{-\frac{\epsilon^{2}(2-\kappa) C_{\kappa, s} n}{6}} \leq C_{\kappa, s} n$. $e^{-\frac{\varepsilon^{2}(2-k) C_{k, s n}}{6}}$. Let $\mathcal{E}_{2}$ be the event that there exists two (distinct) vertices $u, v$ with $\left|N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)\right| \geq$ $s n$, where $N_{G_{p}^{\prime}}(u)$ denotes the set of neighbors of $u$ in $G_{p}^{\prime}$. Our goal is to show that $G_{p}^{\prime}$ exists which satisfies the required conditions. Observe that, $G_{p}^{\prime}$ satisfies the required conditions if and only if $\mathbb{P}\left(\mathcal{E}_{1}^{c} \cap \mathcal{E}_{2}^{c}\right)>0$. The rest of the work in this proof is to show $\mathbb{P}\left(\mathcal{E}_{1}^{c} \cap \mathcal{E}_{2}^{c}\right)>0$.

To bound $\mathbb{P}\left(\mathcal{E}_{2}\right)$, consider two distinct vertices $u$ and $v$. For $w \in V\left(G_{p}^{\prime}\right)$, let $Y_{w}$ be the indicator random variable that takes value 1 if and only if $w \in N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)$. Note that $\left|N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)\right|=\sum_{w \in V\left(G_{p}^{\prime}\right)} Y_{w}$ and $\mathbb{P}\left(Y_{w}=1\right)=2 \cdot \frac{\kappa}{2}\left(1-\frac{\kappa}{2}\right)$. So, the expected value of $\left|N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)\right|$, that is,

$$
\mathbb{E}\left[\left|N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)\right|\right]=2 \cdot \frac{\kappa}{2}\left(1-\frac{\kappa}{2}\right) C_{\kappa, s} n .
$$

As $C_{\kappa, s}=\left\lceil\frac{6 s}{\kappa(2-\kappa)}\right\rceil, \mathbb{E}\left[\left|N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)\right|\right] \geq 3 s n$. Using Chernoff bound E.1. we have

$$
\mathbb{P}\left(\left|N_{G_{p}^{\prime}}(u) \Delta N_{G_{p}^{\prime}}(v)\right| \leq s n\right) \leq e^{-\frac{4 s n}{9}}
$$

Now, by using union bound, we can say that $\mathbb{P}\left(\mathcal{E}_{2}\right) \leq\left|V\left(G_{p}^{\prime}\right)\right|^{2} e^{-\frac{4 s n}{9}}=C_{\kappa, s}^{2} n^{2} e^{-\frac{45 n}{9}}$. Finally using union bound one more time and the fact that $n$ is sufficiently large, we have

$$
\mathbb{P}\left(\mathcal{E}_{1} \cup \mathcal{E}_{2}\right) \leq C_{\kappa, s} n \cdot e^{-\frac{\epsilon^{2}(2-\kappa) C_{k, s} n}{6}}+C_{\kappa, s}^{2} n^{2} e^{-\frac{4 s n}{9}}<1 .
$$

Hence, $\mathbb{P}\left(\mathcal{E}_{1}^{c} \cap \mathcal{E}_{2}^{c}\right)>0$.

## C. 2 Proof of Inequality 2 of Lemma 3.6

Here we prove that

$$
\begin{equation*}
d_{\phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+4 x\left|A_{k}\right|+4 x+2 y\left|A_{k}\right|-y(3 n-2) . \tag{13}
\end{equation*}
$$

To obtain Inequality (13), let us first consider the case when $x=1$ and $y=0$. So, let us assume that $a_{i} \in A_{k}, a_{j}^{\prime} \in A_{u}, b_{s} \in B_{k}$ and $b_{s}^{\prime} \in B_{u}$ be such that the following holds: $\psi\left(a_{i}\right)=b_{s}^{\prime}$ and $\psi\left(b_{s}\right)=a_{j}^{\prime}, \psi(x) \in A_{u}$ for each $x \in A_{k} \backslash\left\{a_{i}\right\}$, and $\phi\left(b_{t}\right)=b_{t}^{\prime} \in B_{u}$ for each $b_{t} \in B_{k} \backslash\left\{b_{s}\right\}$. By the description of Steps (i), (ii) and (iii) of generating $\phi$ from $\psi$, as discussed in Lemma 3.6, we have the following observation.

Observation C.2. For $x=1$ and $y=0$, we have $\psi\left(a_{i}\right)=b_{s}^{\prime}$ and $\psi\left(b_{s}\right)=a_{j}^{\prime} ; \phi\left(a_{i}\right)=a_{j}^{\prime}$ and $\phi\left(b_{s}\right)=b_{s}^{\prime} ;$ For any $x \in\left(A_{k} \cup B_{k}\right) \backslash\left\{a_{i}, b_{s}\right\}, \phi(x)=\psi(x)$.

We can think of $\phi$ is generated by performing a swap operation, that means, the mappings of $a_{i}$ and $b_{s}$ are swapped while generating $\phi$ from $\psi$. Now we show (for the special case of $x=1$ and $y=0$ ) that:

$$
\begin{equation*}
d_{\phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+4\left(\left|A_{k}\right|+1\right) . \tag{14}
\end{equation*}
$$

By Observation C.2, $\phi(x)=\psi(x)$ for all vertices $x \in\left(A_{k} \cup B_{k}\right) \backslash\left\{a_{i}, b_{s}\right\}$. So, any pair of vertices in $\left(A_{k} \cup B_{k}\right) \backslash\left\{a_{i}, b_{s}\right\}$ has no effect on $d_{\phi}\left(G_{u}, G_{k}\right)-d_{\psi}\left(G_{u}, G_{k}\right)$. Following Definition 1.1 and Definition A.2. we can say that
$d_{\phi}\left(G_{u}, G_{k}\right)-d_{\psi}\left(G_{u}, G_{k}\right) \leq 2\left[\left|\operatorname{DECiDER}_{\phi}\left(a_{i}\right)\right|-\left|\operatorname{DECider}_{\psi}\left(a_{i}\right)\right|+\left|\operatorname{DECider}_{\phi}\left(b_{s}\right)\right|-\left|\operatorname{DECiDER}_{\psi}\left(b_{s}\right)\right|\right]$
Note that the first term above can be written as $\operatorname{DECiDER}_{\phi}\left(a_{i}\right)=\left(\operatorname{DECIDER}_{\phi}\left(a_{i}\right) \cap\left(A_{k} \cup\left\{b_{s}\right\}\right)\right) \cup$ ( $\left.\operatorname{DECIDER}_{\phi}\left(a_{i}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right)$. Breaking other terms in the above expression similarly, we have

$$
\begin{aligned}
& \quad d_{\phi}\left(G_{u}, G_{k}\right)-d_{\psi}\left(G_{u}, G_{k}\right) \\
& \leq 2\left[2\left(\left|A_{k}\right|+1\right)+\left|\operatorname{DECIDER}_{\phi}\left(a_{i}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|-\left|\operatorname{DECIDER}_{\psi}\left(a_{i}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|\right. \\
& \left.\quad+\left|\operatorname{DECIDER}_{\phi}\left(b_{s}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|-\left|\operatorname{DECIDER}_{\psi}\left(b_{s}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|\right] \\
& =4\left|A_{k}\right|+4+2 Z, \operatorname{where}^{2} \\
& \quad Z=\left|\operatorname{DECIDER}_{\phi}\left(a_{i}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|-\left|\operatorname{DECIDER}_{\psi}\left(a_{i}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right| \\
& \quad+\left|\operatorname{DECIDER}_{\phi}\left(b_{s}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|-\left|\operatorname{DECIDER}_{\psi}\left(b_{s}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)\right|
\end{aligned}
$$

By showing $Z \leq 0$, we will be done with the proof of Inequality (14). Observe that we can say $\operatorname{DECIDER}_{\phi}\left(a_{i}\right) \cap\left(B_{k} \backslash\left\{b_{s}\right\}\right)=\phi\left(N_{B_{k}}\left(a_{i}\right)\right) \Delta N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\phi\left(a_{i}\right)\right)$. Also, writing the other terms in the expression of $Z$ in the similar fashion, we get

$$
\begin{aligned}
Z \leq & \left|\phi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(a_{i}\right)\right) \Delta\left(N_{B_{u} \backslash\left\{b_{b}^{\prime}\right\}}\left(\phi\left(a_{i}\right)\right)\right)\right|-\left|\psi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(a_{i}\right)\right) \Delta\left(N_{B_{u} \backslash\left\{b_{b}^{\prime}\right\}}\left(\psi\left(a_{i}\right)\right)\right)\right| \\
& +\left|\phi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(b_{s}\right)\right) \Delta\left(N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\phi\left(b_{s}\right)\right)\right)\right|-\left|\psi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(b_{s}\right)\right) \Delta\left(N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\psi\left(b_{s}\right)\right)\right)\right|
\end{aligned}
$$

Once again, from Observation C.2,

$$
\begin{aligned}
& \phi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(a_{i}\right)\right)=\psi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(a_{i}\right)\right)\left(\text { Say I } I_{1}\right) \\
& N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\phi\left(a_{i}\right)\right)=N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\psi\left(b_{s}\right)\right)\left(\text { Say } I_{2}\right) \\
& \phi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(b_{s}\right)\right)=\phi\left(N_{B_{k} \backslash\left\{b_{s}\right\}}\left(b_{s}\right)\right)\left(\text { Say I } I_{3}\right) \\
& N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\psi\left(a_{i}\right)\right)=N_{B_{u} \backslash\left\{b_{s}^{\prime}\right\}}\left(\phi\left(b_{s}\right)\right)\left(\text { Say I } I_{4}\right)
\end{aligned}
$$

Hence, the upper bound on $Z$ can be expressed as follows:

$$
\begin{aligned}
Z & \leq\left|I_{1} \Delta I_{2}\right|-\left|I_{1} \Delta I_{4}\right|+\left|I_{3} \Delta I_{4}\right|-\left|I_{3} \Delta I_{2}\right| \\
& \leq\left(\left|I_{1} \Delta I_{4}\right|+\left|I_{2} \Delta I_{4}\right|\right)-\left|I_{1} \Delta I_{4}\right|+\left|I_{3} \Delta I_{4}\right|-\left|I_{3} \Delta I_{2}\right| \\
& \leq 0
\end{aligned}
$$

Here the first two inequalities follow from the triangle inequality.
Note that we were discussing the proof of Inequality (14), which is a special case of Inequality (13) when $x=1$ and $y=0$. Observe that, the proof of Inequality (14) does not use any structure of the subgraphs induced by $A_{k}$ and $B_{k}$ that changes while performing the swap operation. To prove Inequality (13), we can think of generating $\phi$ from $\psi$, by first performing $x$ many swap operations, to generate an intermediate bijection $\phi_{1}$ such that

$$
d_{\phi_{1}}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+4 x\left(\left|A_{k}\right|+1\right)
$$

Observe that $\phi_{1}\left(A_{k}\right)=A_{u}$ and $\phi_{1}\left(B_{k}\right)=B_{u}$. Then we generate $\phi$ from $\phi_{1}$, such that $\phi$ is a SPECIAL bijection, that is, $\phi\left(b_{i}\right)=b_{i}^{\prime}$ for each $b_{i} \in B_{k}$ along with $\phi_{1}\left(A_{k}\right)=A_{u}$ and $\phi_{1}\left(B_{k}\right)=B_{u}$ as follows. The process of generation of $\phi$ from $\phi_{1}$, can be thought of, as if, we are performing $y$ many swap operation between mappings of the vertices in $B_{B N}$. The difference between, the distance between $G_{u}$ and $G_{k}$ w.r.t. the bijections after and before each of the above swaps, is at most $2\left|A_{k}\right|-(3 n-2)$. The term $3 n-2$ comes from the structure of $G\left[B_{k}\right]$ and $G\left[B_{u}\right]$. Since $\left|B_{B N}\right|=y, d_{\phi_{1}}\left(G_{k}, G_{u}\right)-d_{\phi}\left(G_{k}, G_{u}\right)$ is at most $2 y\left|A_{k}\right|-y(3 n-2)$. Also, we have argued that $d_{\phi_{1}}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+4 x\left(\left|A_{k}\right|+1\right)$. Hence, we can finally say that

$$
d_{\phi}\left(G_{k}, G_{u}\right) \leq d_{\psi}\left(G_{k}, G_{u}\right)+4 x\left(\left|A_{k}\right|+1\right)+2 y\left|A_{k}\right|-y(3 n-2) .
$$

## D Missing Proofs of Section 4

## D.1 Proof of Observation 4.12

Observation D. 1 (Observation 4.12 restated). If $\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \geq \frac{\gamma_{2}-\gamma_{1}}{1000} n$, then

$$
\mathbb{P}\left(\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x) \cap C_{u}\right| \geq\left(1-\frac{1}{50}\right)\left|\operatorname{Symm}_{\phi \phi^{\prime}}(x)\right| \frac{\left|C_{u}\right|}{n}\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)} .
$$

Proof. Since $C_{u}$ is taken uniformly at random, we can say that

$$
\mathbb{E}\left[\left|\left(\operatorname{Decider}_{\phi^{\prime}}(x) \Delta \operatorname{Decider}_{\phi}(x)\right) \cap \mathcal{C}_{u}\right|\right]=\left|\operatorname{DECIDER}_{\phi^{\prime}}(x) \Delta \operatorname{Decider}_{\phi}(x)\right| \frac{\left|C_{u}\right|}{n}
$$

So, using the Chernoff bound mentioned in Lemma E.1, we can say that

$$
\begin{aligned}
& \mathbb{P}\left(\left|\left(\operatorname{DECiDER}_{\phi^{\prime}}(x) \Delta \operatorname{DECiDER}_{\phi}(x)\right) \cap C_{u}\right| \geq \frac{49}{50}\left|\operatorname{DECiDER}_{\phi^{\prime}}(x) \Delta \operatorname{DECiDER}_{\phi}(x)\right| \frac{\left|C_{u}\right|}{n}\right) \\
& \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}
\end{aligned}
$$

## D. 2 Proof of Observation 4.13

Observation D. 2 (Observation 4.13 restated). (i) If $\left|\operatorname{DECIDER}_{\phi}(x)\right| \geq \frac{\gamma_{2}-\gamma_{1}}{1000} n$, then

$$
\mathbb{P}\left(\left|\operatorname{DECiDER}_{\phi}(x) \cap C_{u}\right| \geq\left(1+\frac{1}{50}\right) \left\lvert\,\left(\operatorname{DECIDER}_{\phi}(x) \left\lvert\, \frac{\left|C_{u}\right|}{n}\right.\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}\right.\right.
$$

(ii) If $\left|\operatorname{DECider}_{\phi}(x)\right|<\frac{\gamma_{2}-\gamma_{1}}{1000} n$, then $\mathbb{P}\left(\left|\operatorname{DECIDER}_{\phi}(x) \cap C_{u}\right| \geq \frac{\gamma_{2}-\gamma_{1}}{750}\left|C_{u}\right|\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}$.

Proof. (i) Since $C_{u}$ is taken uniformly at random, we have

$$
\mathbb{E}\left[\left|\left(\operatorname{Decider}_{\phi}(x) \cap C_{u} \mid\right]=\left|\operatorname{Decider}_{\phi}(x)\right| \frac{\left|C_{u}\right|}{n} .\right.\right.
$$

So, using the Chernoff bound mentioned in Lemma E.1. we have

$$
\mathbb{P}\left(\left|\operatorname{DECider}_{\phi}(x)\right| \geq \frac{51}{50}\left|\operatorname{DECiDER}_{\phi}(x)\right| \frac{\left|C_{u}\right|}{n}\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}
$$

(ii) Since $C_{u}$ is taken uniformly at random, we have

$$
\mathbb{E}\left[\left.\left|\left(\operatorname{DECIDER}_{\phi}(x) \cap C_{u} \mid\right] \leq\left(\frac{\gamma_{2}-\gamma_{1}}{1000}\right)\right| C_{u} \right\rvert\, .\right.
$$

So, using the Chernoff bound mentioned in Lemma E.1. we have

$$
\mathbb{P}\left(\left|\operatorname{DECiDER}_{\phi}(x) \cap C_{u}\right| \geq\left(\frac{\gamma_{2}-\gamma_{1}}{750}\right)\left|C_{u}\right|\right) \leq e^{-\mathcal{O}\left(\left|C_{u}\right|\right)}
$$

## E Some probability results

Lemma E. 1 (Chernoff-Hoeffding bound, see [DP09]). Let $X_{1}, \ldots, X_{n}$ be independent random variables such that $X_{i} \in[0,1]$. For $X=\sum_{i=1}^{n} X_{i}$ and $\mu=\mathbb{E}[X]$, the following holds for all $0 \leq \delta \leq 1$

$$
\mathbb{P}(|X-\mu| \geq \delta \mu) \leq 2 \exp \left(\frac{-\mu \delta^{2}}{3}\right)
$$

Lemma E. 2 (Chernoff-Hoeffding bound, see [DP09]). Let $X_{1}, \ldots, X_{n}$ be independent random variables such that $X_{i} \in[0,1]$. For $X=\sum_{i=1}^{n} X_{i}$ and $\mu_{l} \leq \mathbb{E}[X] \leq \mu_{h}$, the followings hold for any $\delta>0$.
(i) $\mathbb{P}\left(X \geq \mu_{h}+\delta\right) \leq \exp \left(\frac{-2 \delta^{2}}{n}\right)$.
(ii) $\mathbb{P}\left(X \leq \mu_{l}-\delta\right) \leq \exp \left(\frac{-2 \delta^{2}}{n}\right)$.

Lemma E. 3 (Hoeffding's Inequality). Let $X_{1}, \ldots, X_{n}$ be independent random variables such that $a_{i} \leq$ $X_{i} \leq b_{i}$ and $X=\sum_{i=1}^{n} X_{i}$. Then, for all $\delta>0$,

$$
\mathbb{P}(|X-\mathbb{E}[X]| \geq \delta) \leq 2 \exp \left(\frac{-2 \delta^{2}}{\sum_{i=1}^{n}\left(b_{i}-a_{i}\right)^{2}}\right)
$$

Lemma E. 4 (Theorem 3.2 in [DP09]). Let $X_{1}, \ldots, X_{n}$ be random variables such that $a_{i} \leq X_{i} \leq b_{i}$ and $X=\sum_{i=1}^{n} X_{i}$. Let $\mathcal{D}$ be the dependent graph, with vertex set $V(\mathcal{D})=\left\{X_{1}, \ldots, X_{n}\right\}$ and edge set $E(\mathcal{D})=\left\{\left(X_{i}, X_{j}\right): X_{i}\right.$ and $X_{j}$ are dependent $\}$. Then, for all $\delta>0$,

$$
\mathbb{P}(|X-\mathbb{E}[X]| \geq \delta) \leq 2 \exp \left(\frac{-2 \delta^{2}}{\chi^{*}(\mathcal{D}) \sum_{i=1}^{n}\left(b_{i}-a_{i}\right)^{2}}\right)
$$

where $\chi^{*}(\mathcal{D})$ denotes the fractional chromatic number of $\mathcal{D}$.
The following lemma directly follows from Lemma E. 4
Lemma E. 5 (Chernoff bound for bounded dependency). Let $X_{1}, \ldots, X_{n}$ be indicator random variables such that there are at most d many $X_{j}$ 's on which an $X_{i}$ depends. For $X=\sum_{i=1}^{n} X_{i}$ and $\mu_{l} \leq \mathbb{E}[X] \leq \mu_{h}$, the followings hold for any $\delta>0$.
(i) $\mathbb{P}\left(X \geq \mu_{h}+\delta\right) \leq \exp \left(\frac{-2 \delta^{2}}{(d+1) n}\right)$,
(ii) $\mathbb{P}\left(X \leq \mu_{\ell}-\delta\right) \leq \exp \left(\frac{-2 \delta^{2}}{(d+1) n}\right)$.


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[^1]:    ${ }^{1}$ In a graph $G, V(G)$ and $E(G)$ denote the sets of vertices and edges in $G$, respectively.

[^2]:    ${ }^{2}$ As a shorthand, rather than saying $\gamma$-close or $\gamma$-far to isomorphic, we will just say $\gamma$-close or $\gamma$-far respectively.
    ${ }^{3} G_{u}$ and $G_{k}$ denote the unknown and known graphs respectively.
    ${ }^{4}$ The correctness probability can be made any $1-\delta$ by incurring a multiplicative factor of $O\left(\log \frac{1}{\delta}\right)$ in the query complexity
    ${ }^{5}$ Testing equivalence between two distributions means to test if the unknown distribution (from where the samples are drawn) is identical to the known distribution or is the variation distance between them more than $\epsilon$.

[^3]:    ${ }^{6}$ The lower bound of $n$ is a constant that depends on $\kappa$ and $s$.

[^4]:    ${ }^{7}$ Note that this relation does not hold in general. However this is true for the graphs $G_{k}$ and $G_{u}$ constructed in the reduction.
    ${ }^{8}$ Note that we are using Lemma 3.3 with parameters $s=3, \kappa=\frac{\beta_{2}-\beta_{1}}{8}$ and $T_{\kappa}=C_{\kappa, 3}$.

[^5]:    ${ }^{10} C_{k}^{i}$ and $Y_{C_{k}^{i}}$ are defined in Step 2 of Phase 1.

[^6]:    ${ }^{11}$ Here we are assuming $\gamma_{2} \geq 11 \gamma_{1}$.

[^7]:    ${ }^{12}$ By abuse of notation, we will say $G_{u}$ and $G_{k}$ are $\gamma$-far when $d\left(G_{u}, G_{k}\right) \geq \gamma n^{2}$.

[^8]:    ${ }^{13}$ Note that this is rephrasing of the result proved in [VV11]. For reference, see Chapter 3 of the survey by Canonne Can15.

[^9]:    ${ }^{14}$ The lower bound of $n$ is a constant that depends on $\kappa$ and $s$.

