

# On the Locally Testable Code of Dinur *et al.* (2021)

Oded Goldreich

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## Abstract

This text provides a high-level description of the locally testable code constructed by Dinur, Evra, Livne, Lubotzky, and Mozes (*ECCC*, TR21-151). In particular, the group theoretic aspects are abstracted as much as possible.

## 1 The result

Ever since Dinur’s seminal proof of the PCP Theorem [4], which provided as a “by product” a locally testable code (LTC) of  $1/\text{polylog}$  rate, the question resolved by Dinur *et al.* [5] was on the table. I would not say that this question was on the table before [4], because I think that even the  $1/\text{polylog}$  rate was not seen on the horizon. Prior to [4], we were still making slow progress at much lower rates (i.e., even rate  $n^{-o(1)}$ , for block-length  $n$ , was not known).

In any case, inspired by prior studies of High-Dimensional Expanders, but actually stepping away from them, the current work provides a LTC of constant rate, where here and above I refer to the regime of constant number of queries (as opposed to prior work that achieved constant rate with a quasi-polylogarithmic number of queries [6, Sec. 13.4.3]) and take constant relative distance for granted.

Needless to say, the current work challenges the two-regimes perspective (i.e., the constant query regime vs the constant rate regime) as well as the possibility that there is a trade-off between the level of locality (i.e., number of queries) and the rate of the code.

The result of Dinur *et al.* [5] refers to the strongest used notion of locally testable codes (cf. [6, Sec. 13.2]). Specifically, it is required that the tester always accepts any codeword, and that any non-codeword is rejected with probability that is proportional to its distance from the code. Needless to say, things are stated in asymptotic terms, where  $n$  is viewed as a varying parameter, but all other parameters (i.e., rate, relative distance, and the number of queries made by the tester) are all constants.

**Definition 1.1** (LTC, for this text, loosely stated): *The code  $C \subset \{0, 1\}^n$  has rate  $\frac{\log_2 |C|}{n}$  and (relative) distance  $\min_{x \neq y \in C} \{\Delta(x, y)\}$ , where  $\Delta(x, y) = |\{i \in [n] : x_i \neq y_i\}|/n$ . We say that  $C$  is locally testable if there exists an oracle machine,  $T$ , that makes a constant number of queries and satisfies the following two conditions:*

1. For every  $x \in C$ , it holds that  $\Pr[T^x(n)=1] = 1$ .
2. For every  $x \in \{0, 1\}^n \setminus C$ , it holds that  $\Pr[T^x(n) \neq 1] = \Omega(\Delta_C(x))$ , where  $\Delta_C(x) = \min_{y \in C} \{\Delta(x, y)\}$ .

In this case, we say that  $C$  is a locally testable code.

In terms of property testing, a tester as in Definition 1.1 constitutes a proximity oblivious tester with linear detection probability for the property  $C$  [6, Def. 1.7]. The main result of Dinur *et al.* [5] is thus stated as follow.

**Theorem 1.2** (LTCs exist and can be explicitly constructed): *For any  $n$ , there exists a locally testable code  $C \subset \{0, 1\}^n$  of constant rate and constant relative distance. Furthermore,  $C$  is a linear subspace, and a basis for it can be found in  $\text{poly}(n)$ -time.*

It follows that  $C$  has an efficient encoding algorithm (a bijection mapping  $\Omega(n)$ -bit strings to codewords of  $C$ ). It also has an efficient decoding (with errors) algorithm; but this (only) follows from the proof provided in [5]. The presentation in [5] only supports  $n$ 's in a “linearly dense” set (i.e.,  $n_{i+1} - n_i = O(n_i)$ , where  $n_j$  is the  $j^{\text{th}}$  smallest integer in the set), but this can be fixed by padding.

## 2 The construction

The construction “lifts” the expander codes of [10], where the lifting is highly non-trivial because of an extra feature required from the ingredients (cf., the 4-cycles). This feature (and its utilization) is the key to the success of the new construction.

### 2.1 The ingredients

For a sufficiently large constant  $d$ , we use two  $d$ -regular (expander) graphs,  $G'$  and  $G''$ , on the same vertex set  $V$ . These graphs are represented by their incidence functions  $g'_i, g''_i : V \rightarrow V$  (for  $i \in [d]$ ) such that  $g'_i(v)$  (resp.,  $g''_i(v)$ ) denotes the  $i^{\text{th}}$  neighbor of  $v$  in the first (resp., second) graph.<sup>1</sup> Furthermore, we assume that these functions are actually bijections. Indeed, each of these graphs is an expander in the sense that its second eigenvalue (i.e., random-walk convergence rate) is sufficiently small (as a function of other parameters). Moreover, we require:

1. *The neighborhoods of a vertex in the two graphs are disjoint*; that is, for every  $v \in V$  and  $i, j \in [d]$ , it holds that  $g'_i(v) \neq g''_j(v)$ .
2. *Symmetry of the incidence functions*; that is, for every  $i \in [d]$  there exists  $j \in [d]$  such that  $g'_j(g'_i(v)) = v$  holds for all  $v \in V$ . Without loss of generality, we may assume that  $g'_{2i-1}$  is the inverse of  $g'_{2i}$ ; that is,  $g'_{2i-1}(g'_{2i}(v)) = v$ . Ditto for  $g''_i$ .
3. *Two interleaving steps form a 4-cycle in  $G' \cup G''$* : For every  $v \in V$  and  $i, j \in [d]$ , it holds that  $g''_j(g'_i(v)) = g'_i(g''_j(v))$ . Hence,  $c_{v,i,j} \stackrel{\text{def}}{=} (v, g'_i(v), g''_j(g'_i(v)), g''_j(v), v)$  forms a 4-cycle in the graph  $G = (V, E)$  that is formed by superimposing  $G'$  and  $G''$  (i.e.,  $E = (V, E' \cup E'')$ , where  $G' = (V, E')$  and  $G'' = (V, E'')$ ). We denote this set of (ordered) 4-cycles by  $Q$ ; that is,

$$Q \stackrel{\text{def}}{=} \{(v, g'_i(v), g''_j(g'_i(v)), g''_j(v), v) : v \in V \ \& \ i, j \in [d]\}. \quad (1)$$

Note: Although there may be other 4-cycles in the graph  $G$ , in the sequel, whenever we refer to 4-cycles, we mean the 4-cycles in  $Q$  only.

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<sup>1</sup>For simplicity, we use the same degree in both graphs and the same bound on the second eigenvalue.

Indeed, the last requirement appears hardest to meet. Dinur *et al.* [5] achieve it by using left and right multiplication (in a non-Abelian group). Specifically, they use Cayley graphs over the vertex-set (group)  $V$ , with adequate generator-sets  $A = \{a_i : i \in [d]\}$  and  $B = \{b_i : i \in [d]\}$ , and let  $g'_i(v) = a_i \cdot v$  and  $g''_i(v) = v \cdot b_i$ .

**Base codes:** We also use constant-size codes  $C', C'' \subset \{0, 1\}^d$  of rate  $r_0 > 3/4$  and relative distance  $\delta_0 > \lambda$ , where  $\lambda > 0$  is an upper bound on the (normalized) second eigenvalue of each of the graphs. Furthermore, we pick these codes so that their tensoring yields a relatively “robust” tensor code (see [5, Def. 2.8 & Lem. 2.9]).<sup>2</sup>

## 2.2 The constructed code and its tester

For a function  $f : Q \rightarrow \{0, 1\}$ , we denote by  $f_v$  its restriction to the set of 4-cycles that are “rooted” at the vertex  $v \in V$ ; that is, 4-cycles that have the form  $(v, g'_i(v), g''_j(g'_i(v)), g''_j(v), v) = c_{v,i,j}$  for some  $i, j \in [d]$ . Indeed, letting  $Q_v = \{c_{v,i,j} : i, j \in [d]\}$ , the function  $f_v : Q_v \rightarrow \{0, 1\}^{d \times d}$  is viewed as a  $d$ -by- $d$  Boolean matrix in which the  $(i, j)$ <sup>th</sup> entry equals  $f(v, g'_i(v), g''_j(g'_i(v)), g''_j(v), v)$ . The new code, denoted  $C$ , consists of all Boolean functions  $f : Q \rightarrow \{0, 1\}$  whose  $f_v$ -restrictions are codewords of the tensor code  $C' \otimes C''$ , where  $C' \otimes C''$  is the set of all  $d$ -by- $d$  matrices whose rows are codewords of  $C'$  and columns are codewords of  $C''$ . That is,

$$C \stackrel{\text{def}}{=} \{f : Q \rightarrow \{0, 1\} \mid (\forall v \in V) f_v \in C' \otimes C''\}. \quad (2)$$

The tester is the natural one; that is, it selects one condition at random and checks it. Specifically, given oracle access to  $f : Q \rightarrow \{0, 1\}$ , the tester select uniformly  $v \in V$ , retrieves the  $d$ -by- $d$  matrix  $f_v = (f(v, g'_i(v), g''_j(g'_i(v)), g''_j(v), v))_{i,j \in [d]}$  by querying  $f$  on all 4-cycles in  $Q_v$ , and accepts if and only if  $f_v$  is a codeword of  $C' \otimes C''$ .

**Comment:** In the foregoing presentation each 4-cycle is represented four times (since each of its vertices can be used as the “start vertex” (or “root”)).<sup>3</sup> In contrast, in [5], the four representations are identified so that the value on each of them is obtained from the value on a canonical representation of the relevant 4-cycle.<sup>4</sup>

## 3 The analysis (flavor only)

The analysis of the rate and distance of the code  $C$  follows the analysis of the expander codes of [10], but the real issue is analyzing the foregoing tester. (Recall that generic expander codes are not locally testable.)

<sup>2</sup>In Dinur *et al.* [5], the base codes are denoted  $C_A$  and  $C_B$ , and they are shown to exist in [5, Lem. 5.1].

<sup>3</sup>The other three representations of  $c_{v,i,j} = (v, g'_i(v), g''_j(g'_i(v)), g''_j(v), v)$  are  $c_{g'_i(v),i',j}$ ,  $c_{g'_i(v),i',j'}$  and  $c_{g''_j(v),i,j'}$ , where  $g'_{i'}$  is the inverse of  $g'_i$  and  $g''_{j'}$  is the inverse of  $g''_j$ .

<sup>4</sup>This operation is called *folding* [3]; it replaces a potential auxiliary test (which queries the four representations) that enforces all four representations to hold the same value.

**Rate.** Recalling that the code is a linear subspace, we lower-bound its dimension by  $\frac{1}{4} \cdot |V| \cdot d^2 - |V| \cdot 2d \cdot (d - r_0 \cdot d)$ , where  $\frac{1}{4}$  compensates for the four representations of each 4-cycle and  $2d \cdot (d - r_0 \cdot d)$  is an upper bound on the number of linear constraints imposed on each  $f_v$  (i.e.,  $2d$  is the number of rows and columns in each matrix  $Q_v$ , and  $d - r_0 \cdot d$  is the co-dimension of the base codes). Hence, we obtain a rate of at least  $\frac{1}{4} - 2 \cdot (1 - r_0)$ , which is a positive constant provided that  $r_0 > 7/8$ .

**Distance.** Since the code is linear, we lower-bound the weight of its non-zero codewords. For any  $f \in C$  and each  $i \in [n]$ , let  $f^{(i)}$  be a function on the edges of  $G''$  such that  $f^{(i)}(\{v, g_j''(v)\}) = f(c_{v,i,j})$ , which is well-defined by the folding (see Footnote 4). Now, assuming that  $f(c_{v^*,i^*,j^*}) = 1$  for some  $v^*, i^*, j^*$ , it follows (by the distance of  $C'$ ) that, for at least for a  $\delta_0$  fraction of the  $i \in [d]$ , it holds that the  $i^{\text{th}}$  row of  $f_{v^*}$  is not an all-zero codeword (of  $C'$ ). Hence, for at least a  $\delta_0$  fraction of the  $i \in [d]$ , the function  $f^{(i)}$  is non-zero. Considering only the graph  $G''$  (and the based code  $C''$ ), we apply the analysis of expander codes to  $f^{(i)}$  (see [5, Lem. 4.4], which reduces to [5, Lem. 2.1]). It follows that a non-zero  $f^{(i)}$  must have relative weight at least a  $\delta_0 \cdot (\delta_0 - \lambda)$ , where  $\lambda$  upper-bounds the second (normalized) eigenvalue of  $G''$ . Recalling that at least a  $\delta_0$  fraction of the  $f^{(i)}$ 's are non-zero, we conclude that the relative weight of non-codewords of  $C$  is at least a  $\delta_0^2 \cdot (\delta_0 - \lambda)$ .

**Local testability – take 1.** *How come the new code is locally testable whereas expander codes are not?* As observed by numerous experts, generic expander codes (as generic LDPC codes) are defined in terms of a *low-density parity-check* matrix, which (generically) may be of full rank. In that case, removing a single parity-check from the matrix yield a larger code that may still have large distance. But then the resulting code contains codewords that are far from the original code, although they violate a single linear constraint of the original code. Hence, the natural tester that checks a single linear constraint (in the original matrix) fails poorly.

In contrast, the tester associated with the new code  $C$  selects at random a set of highly dependent linear constraints, which are associated with a (random) vertex, such that the sets associated with different choices (i.e., vertices) have significant pairwise intersections. Specifically, for every two neighboring vertices,  $u$  and  $v$ , the inspected  $d$ -by- $d$  matrices (i.e.,  $f_u$  and  $f_v$ ) share  $d$ -entries that correspond to the edge  $\{u, v\}$ . Hence, violating a single constraint (of  $C$ ) leads to violating many other (different) constraints. In particular, dropping few constraints from the low-density parity-check matrix that corresponds to  $C$  leaves the code invariant.

Needless to say, the foregoing is extremely far from establishing the local testability of  $C$ . It merely asserts that  $C$  passes a sanity check that the expander codes fail.

**Local testability – take 2.** As is often the case in property testing (cf. [9, Chap. 3]), the analysis of the foregoing tester uses a self-correction process (in order to establish the contrapositive). Specifically, Dinur *et al.* [5] present a decoding algorithm and prove that if the *natural tester* (which selects a random vertex  $v \in V$  and accepts if and only if  $f_v \in C' \otimes C''$ ) rejects  $f$  with probability  $\eta$ , then the decoding algorithm finds a codeword (of  $C$ ) that is  $O(\eta)$ -close to  $f$ .<sup>5</sup> It follows (by the contrapositive) that each  $f : Q \rightarrow \{0, 1\}$  is rejected by the natural test with probability that is lower-bounded by a constant fraction of  $f$ 's distance from  $C$ .

<sup>5</sup>The actual constant in the  $O$ -notation is  $4(2d+1)$ , and the claim holds provided that  $\lambda \leq \alpha \cdot \delta_0$ , where  $\alpha$  depends on the “robustness” parameter of the tensor code  $C' \otimes C''$ .

The key issue, of course, is to design and analyze a decoding algorithm that satisfies the foregoing condition. That is, given any  $f : Q \rightarrow \{0,1\}$ , the decoder must find a codeword of  $C$  that is  $O(\eta(f))$ -close to  $f$ , where  $\eta(f)$  is the probability that the natural tester rejects  $f$ . A natural idea is to iteratively modify  $f$  such that in each iteration we select an arbitrary 4-cycle  $c$  and reset  $f(c)$  such that it satisfies a majority of the checks that look at it (i.e.,  $f(c) = \sigma$  if  $c$  is assigned  $\sigma$  in a majority of the  $d$ -by- $d$  matrices  $f_v$  that contain  $c$ ).<sup>6</sup> The decoding process terminates when no addition modification is possible (i.e., where for each  $c \in Q$  the value of  $f(c)$  equals the majority value assigned to  $c$  by the relevant  $f_v$ 's).

The foregoing decoder is analogous to the one used for decoding expander codes. It seems that this candidate decoder works well (i.e., correctly decodes  $f$ ) in the case that  $f$  is close to  $C$ , but the intended application of this decoder is showing that every  $f$  is  $O(\eta(f))$ -close to  $C$  (by showing that, on any input  $f$ , the decoder finds a codeword that is  $O(\eta(f))$ -close to  $f$ ).<sup>7</sup> We stress that it may be that the foregoing decoder works well on any input  $f$  (i.e., it always finds a codeword that is  $O(\eta(f))$ -close to  $f$ ), but this is currently unknown.

**Local testability – take 3.** In light of the foregoing, a different approach to decoding is taken. The following decoding algorithm is based on the agreement testing paradigm, which arose with the proof composition paradigm of PCPs [2, 1]. The foregoing paradigm links the agreement probability of partial assignments to suitable intersecting subsets of the domain (i.e., “local agreement”) to the existence of a global function that approximately fits these partial assignments (i.e., “global agreement”). This paradigm will be applied here to the set of  $d$ -by- $d$  matrices that correspond to the codewords of  $C' \otimes C''$  that are closest to the matrices  $f_v$  (for all  $v \in V$ ). Note that  $d$ -by- $d$  matrices that correspond to neighboring vertices have a common row (or column)<sup>8</sup>, and the agreement test will be applied (as a mental experiment) to these pairs of matrices. Also, the disagreement probability (between the foregoing pairs of codewords) is at most twice  $\eta(f)$ ; see [5, Eq. (4.5)].

In general, for every  $\bar{w} = (w_v)_{v \in V} \in (\{0,1\}^{d \times d})^{|V|}$ , we define the local disagreement of  $\bar{w}$  as the probability that the pair of matrices that correspond to a random edge agree on the row (or column) that corresponds to the 4-cycles that contain this edge. That is, we consider

$$D(\bar{w}) \stackrel{\text{def}}{=} \Pr_{e=\{u,v\} \in E} [w_u|e \neq w_v|e] \tag{3}$$

where  $w_u|e$  (resp.,  $w_v|e$ ) denotes the restriction of  $w_u$  (resp.,  $w_v$ ) to the row (or column) that corresponds to the 4-cycles that contain the edge  $e$  (i.e., the 4-cycles in  $Q_u \cap Q_v$ , where  $\{u,v\} = e$ ). (Recall that  $E$  is the edge-set of the graph defined in Section 2.1.)

Decoding is done in iterations such that in each iteration we pick an arbitrary vertex  $v$  and modify the current  $w_v$  so to minimize  $D(\bar{w})$  subject to the new  $w_v$  being in  $C' \otimes C''$ ; that is,  $w_v$  is replaced by  $w' \in C' \otimes C''$  if  $w'$  minimizes  $\Pr_{e=\{u,v\} \in E} [w_u|e \neq w'|e]$  (over all  $C' \otimes C''$ ). Initially, on input  $f : Q \rightarrow \{0,1\}$ , for every  $v \in V$ , we let  $w_v$  be a codeword of  $C' \otimes C''$  that is closest to  $f_v$ , and the decoder halts when no modification is possible (i.e., no modification decreases the value of

<sup>6</sup>That is, we consider all  $f_v$ 's such that  $c = c_{v,i,j}$  for some  $i, j \in [d]$ .

<sup>7</sup>Hence, the foregoing is insufficient for two reasons. First, we need the decoder to work on any input  $f$ , and not only on inputs that are close to  $C$ ; that is, the closeness to  $C$  is the desired conclusion, and can not be the hypothesis. Second, even in case  $f$  is  $o(1)$ -close to  $C$ , which implies that  $\eta(f) = o(d^2) = o(1)$ , we need to upper-bound  $f$ 's distance to  $C$  in terms of  $\eta(f)$ ; that is, we seek a quantitative result (i.e.,  $O(\eta(f))$ -closeness) not merely a qualitative result (e.g., if  $\eta(f) = o(1)$ , then  $f$  is  $o(1)$ -close to  $C$ ).

<sup>8</sup>In contrast, in the case of expander codes, neighboring vertices have only a single edge in common.

D).<sup>9</sup> At termination, either  $D(\bar{w}) > 0$ , which is considered a failure, or  $D(\bar{w}) = 0$ , which implies that  $\bar{w}$  corresponds to a codeword of  $C$  (i.e., there exists  $f' \in C$  such that  $w_v = f'_v$  for every  $v \in V$ ).

Indeed, the main result of [5, Sec. 4] is that this decoder works well, which yields the desired LTC, once a suitable graph is constructed (in [5, Sec. 5]). Specifically, Dinur *et al.* [5] proved

**Theorem 3.1** (the foregoing decoder works well [5, Prop. 4.7&4.8]): *Let  $f : Q \rightarrow \{0, 1\}$  and  $\eta(f) \stackrel{\text{def}}{=} \Pr_{v \in V}[f_v \notin C' \otimes C'']$ . For some universal constant  $\eta_0 > 0$  (i.e.,  $\eta_0 = (\Omega(\delta_0) - \lambda)/2d$ ), if  $\eta(f) < \eta_0$ , then the foregoing decoder never fails but rather outputs a codeword of  $C$  that is at distance at most  $O(d) \cdot \eta(f)$  from  $f$ .*

In particular, [5, Prop. 4.8] asserts that if  $\eta(f) < \eta_0$ , then the decoder does not fail, whereas [5, Prop. 4.7] asserts that in this case the output (codeword of  $C$ ) is  $O(d) \cdot \eta(f)$ -close to  $f$ .<sup>10</sup> Needless to say, if  $\eta(f) \geq \eta_0$ , then the claim holds trivially (since every  $f$  is  $O(\eta_0)$ -close to  $C$ ).

**Theorem 3.2** (construction of suitable graphs, follows from [5, Lem. 5.2]): *For every  $\lambda > 0$ , there exists a constant  $d$  such that, for every  $n \in \mathbb{N}$ , a pair of  $\Theta(n)$ -vertex graphs as in Section 2.1 can be constructed in  $\text{poly}(n)$ -time. In particular, each graph is  $d$ -regular and its second (normalized) eigenvalue is at most  $\lambda$ . Furthermore, incidence queries regarding each of the graphs can be answered in  $\text{poly}(\log n)$ -time.*

(The foregoing is simplified: Dinur *et al.* [5, Lem. 5.2] obtain such graphs for any  $d$  that is a multiple of some  $d_0 \in \mathbb{N}$ , and use this fact in order to present suitable base codes (see [5, Lem. 5.1]).<sup>11</sup>)

**On the proof of Theorem 3.1.** The easy part (proved in [5, Prop. 4.7]) is showing that if the decoder does not fail, then the codeword  $f'$  that it outputs is  $O(\eta(f))$ -close to  $f$ . Letting  $\bar{w}^{\text{init}}$  (resp.,  $\bar{w}^{\text{fin}}$ ) denote the initial (resp., final) value of  $\bar{w}$ , observe that  $\Delta(f, f') \leq \frac{|V^{\text{init}}| + |V^{\text{fin}}|}{|V|}$ , where  $V^{\text{init}} = \{v \in V : w_v^{\text{init}} \neq f_v\}$  and  $V^{\text{fin}} = \{v \in V : w_v^{\text{fin}} \neq w_v^{\text{init}}\}$ . Next, note that  $|V^{\text{init}}| \leq \eta(f) \cdot |V|$  (since  $f_v \in C' \otimes C''$  implies  $w_v^{\text{init}} = f_v$ ) and  $|V^{\text{fin}}| \leq D(\bar{w}^{\text{init}}) \cdot |E|$  (since each modification step decreases  $D$  by at least  $1/|E|$ ), whereas  $D(\bar{w}^{\text{init}}) \leq 2\eta(f)$  (since  $\{u, v\}$  contributes to  $D(\bar{w}^{\text{init}})$  only if either  $f_u \notin C' \otimes C''$  or  $f_v \notin C' \otimes C''$ )<sup>12</sup> and  $|E| = d \cdot |V|$ .

The more difficulty part (proved in [5, Prop. 4.8]) is showing that the decoder may fail only when  $\eta(f) \geq \eta_0$ . It is actually shown that if the algorithm fails (i.e.,  $D(\bar{w}^{\text{fin}}) > 0$ ), then  $D(\bar{w}^{\text{fin}}) \geq 2\eta_0$  must hold, which implies  $\eta(f) \geq \eta_0$ . (Recall that  $\bar{w}^{\text{fin}}$  is stable in the sense that  $D$  cannot be decreased by any modification to  $\bar{w}^{\text{fin}}$ .)

At a very high level, the foregoing claim is proved as follows. First, it is proved (in [5, Clm. 4.10]) that if some edge  $e$  contributes to  $D(\bar{w}^{\text{fin}})$  (per the r.h.s of Eq. (3)), then a constant fraction of the edges that participate in 4-cycles that contain  $e$  also contribute to this count (i.e, to  $D(\bar{w}^{\text{fin}})$ ). This means that disagreements are propagated locally; that is, disagreement propagates from a single

<sup>9</sup>Note that if  $D$  is decreased by the modification, then  $D$  decreases by at least  $1/|E|$  units.

<sup>10</sup>In [5, Prop. 4.7] the constant factor is  $4 \cdot (2d + 1)$ , but our presentation is a bit different (i.e., we use all four representations of each 4-cycle) and this may affect the constant.

<sup>11</sup>The point is that they used a result that requires  $d$  to be a multiple of some given  $d_0$ . We believe that this is not really necessary. Alternatively, obtaining  $d$  that is a multiple of  $d_0$  is quite trivial if one does not aim at optimal expansion (i.e., Ramanujan graphs), which is immaterial for the current application.

<sup>12</sup>Otherwise,  $w_u^{\text{init}} = f_u$  and  $w_v^{\text{init}} = f_v$ , which contradicts the hypothesis regarding  $\{u, v\}$ . Note, however, that the same vertex may contribute to  $2d$  edges. Hence, we have  $D(\bar{w}^{\text{init}}) \cdot |E| \leq 2d \cdot \eta(f) \cdot |V|$ .

edge to many edges in the various 4-cycles that contain this edge. Next, using the robustness of the tensor code  $C' \otimes C''$  (and the stability of  $\overline{w}^{\text{fin}}$ ), it is proved (in [5, Clm. 4.11]) that disagreements on edges that are incident at a vertex  $v$  translate to a proportional number of disagreements on the edges that are in 4-cycles that contain vertex  $v$  but are not incident to it. Finally, the expansion properties of the graphs are used in order to prove (in [5, Clm. 4.12 & Lem. 4.13]) that these local disagreements translate to global ones; that is, if there are many disagreements in the 4-cycles that touch a vertex, then there are many disagreements globally (i.e., in the entire graph). This means that  $D(\overline{w}^{\text{fin}}) > 0$  implies  $D(\overline{w}^{\text{fin}}) = \Omega(1)$ .

**On the proof of Theorem 3.2.** One may indeed wonder whether there exist pairs of graphs satisfying the conditions stated in Section 2.1. The cue is using left and right multiplication (in a non-Abelian group); specifically, Dinur *et al.* [5, Lem. 5.2] use Cayley graphs over the vertex-set (group)  $V$ , with generator-sets  $A = \{a_i : i \in [d]\}$  and  $B = \{b_i : i \in [d]\}$ , and let  $g'_i(v) = a_i \cdot v$  and  $g''_i(v) = v \cdot b_i$ . Hence,  $g'_i \circ g''_j = g''_j \circ g'_i$ , whereas guaranteeing the  $g'_i(v) \neq g''_j(v)$  holds (for all  $v \in V$  and  $i, j \in [d]$ ) does not seem problematic (yet, it is far from trivial, since we need these graphs to be expanders (see [5, Sec. 6])).

## 4 Concluding comments

An interesting feature of the locally testable code of Dinur *et al.* [5] is that it is the first known LTC of subquadratic block-length that comes in a single-step construction, which (in particular) does not utilize any PCP machinery.<sup>13</sup> (We mention that the LTCs of Meir [7] and Viderman [11, 12] also avoids PCP machinery, but these constructions proceed in several steps, which mimic various ideas of PCP constructions.)

I was told that Pantelev and Kalachev [8] have, independently but later, also proved Theorem 1.2.<sup>14</sup> Their construction seems (essentially) identical to the one of Dinur *et al.* [5], but their analysis seems somewhat different.

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<sup>13</sup>An explicit LTC of almost quadratic block-length that does not utilize any PCP machinery follows by starting from a suitable low-degree test and using alphabet reduction; see [6, Sec. 13.3.2.1].

<sup>14</sup>The result of Dinur *et al.* [5] was publicly announced in September 2021.

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