



# Boolean Derivative Certificates and Maximal ANF Terms

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## Abstract

For a Boolean function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ , the higher-order Boolean derivative  $D_S f$  computes the parity of  $f$  over each  $S$ -dimensional subcube. We prove that  $D_S f \equiv 1$  exactly when  $S$  is a maximal monomial support in the algebraic normal form of  $f$ . This correspondence motivates the derivative certificate depth  $\Delta_\partial(f)$ , defined as the minimum degree of a nonempty maximal algebraic normal form monomial. We study the decision problem BCD: given  $f$  and  $k$ , decide whether  $\Delta_\partial(f) \leq k$ . We show that this problem is coNP-complete for every fixed constant  $k \geq 1$ , NP-complete when  $k = n$ , and belongs to  $\Sigma_2^{\oplus P}$  when  $k$  is part of the input; in the variable- $k$  case it is also both NP-hard and coNP-hard. These results identify the  $\exists\forall\oplus$  upper bound and leave  $\Sigma_2^{\oplus P}$ -completeness as an open problem.

## 1 Introduction

The *algebraic normal form* (ANF) of a Boolean function  $f$ , its unique representation as an  $\mathbb{F}_2$ -multilinear polynomial, has been quite foundational to Boolean function theory since Zhegalkin [17]. The supports of the monomials in the ANF form a finite subset of  $2^{[n]}$ . Its inclusion-maximal elements form an antichain and encode the top-level algebra of  $f$ .

*Boolean derivatives*, systematized by Thayse [14], offer another perspective. The first-order derivative  $D_i f$  measures sensitivity of  $f$  to flipping  $x_i$ , while  $D_S f$  tests simultaneous sensitivity to all of  $S$ . Applications include test generation [11], formal verification [16], and circuit complexity [6].

The main equivalence connecting these two objects does not appear to be widely emphasized in the literature:

$$D_S f \equiv 1 \iff S \text{ is a maximal ANF monomial support of } f.$$

The condition  $D_S f \equiv 1$  is a *parity certificate* for satisfiability, it guarantees that every  $S$ -dimensional subcube contains an odd number of satisfying assignments, hence at least one. We call  $S$  a *constant derivative certificate*. Whenever such a nonempty certificate exists, it gives stronger evidence for satisfiability than a single point witness: the subcube-parity condition holds universally over all  $2^{n-|S|}$  base vectors  $b$ , whereas a point witness is a single evaluation. We define  $\Delta_\partial(f)$  as the minimum cardinality of a constant derivative certificate.

We study the decision problem BCD: does  $f$  admit a constant derivative certificate of size  $\leq k$ ? Its natural  $\exists\forall\oplus$  formulation separates the analysis into three cases: fixed  $k$ , where the problem is coNP-complete;  $k = n$ , where it is NP-complete; and variable  $k$ , where it lies in  $\Sigma_2^{\oplus P}$ .

**Related work.** Boolean derivatives appear in Boolean difference calculus, including Thayse's monograph [14], and in applications such as test generation [11], formal verification [16], and symmetric cryptography [2]. Polynomial representations of Boolean functions over finite fields are foundational in algebraic approaches to circuit lower bounds, including the Razborov–Smolensky method [10, 12]. Toda's theorem [15] shows the uses of counting and parity in complexity theory. The polynomial-time hierarchy originates with Stockmeyer [13]; parity-oracle variants are related to work of Papadimitriou and Zachos [8].

**Organization.** Section 2 recalls Boolean derivatives and ANF. Section 3 proves the derivative–ANF correspondence. Section 4 introduces derivative certificate depth. Sections 5–9 establish the complexity results.

## 2 Preliminaries

Throughout,  $[n] := \{1, \dots, n\}$  and  $f: \{0, 1\}^n \rightarrow \{0, 1\}$ . All arithmetic on Boolean values is over  $\mathbb{F}_2$  unless otherwise stated.

### Boolean derivatives

**Definition 1.** The *Boolean derivative* of  $f$  with respect to  $x_i$  is

$$D_i f := f|_{x_i=0} \oplus f|_{x_i=1}.$$

For  $S \subseteq [n]$ , the *higher-order derivative* is  $D_S f := (\prod_{i \in S} D_i) f$ , where the product denotes operator composition. We set  $D_\emptyset f := f$ .

The operators  $D_i$  pairwise commute over  $\mathbb{F}_2$ : for any  $i \neq j$  and  $x \in \{0, 1\}^n$ , writing  $x^{(T)}$  for  $x$  with bits in  $T$  flipped,

$$D_i(D_j f)(x) = f(x) \oplus f(x^{(i)}) \oplus f(x^{(j)}) \oplus f(x^{(ij)}) = D_j(D_i f)(x).$$

Since the operators  $D_i$  commute,  $D_S f$  is independent of the order in which the variables of  $S$  are differentiated. Equivalently, if the variables outside  $S$  are fixed to  $b \in \{0, 1\}^{[n] \setminus S}$ , then

$$D_S f(b) = \bigoplus_{u \in \{0, 1\}^S} f(b, u). \quad (1)$$

Thus  $D_S f(b)$  is the parity of  $f$  on the  $S$ -dimensional coordinate subcube obtained by varying the variables in  $S$  and fixing all others according to  $b$ .

### Algebraic normal form

Every Boolean function has a unique *algebraic normal form*:

$$f(x) = \bigoplus_{T \subseteq [n]} c_T \prod_{i \in T} x_i, \quad c_T \in \{0, 1\},$$

with coefficients determined by Möbius inversion on the Boolean lattice:  $c_T = \bigoplus_{R \subseteq T} f(\mathbf{1}_R)$ , where  $\mathbf{1}_R$  denotes the indicator vector of  $R \subseteq [n]$  [6]. We write

$$\text{supp}(f) := \{T \subseteq [n] : c_T = 1\}$$

for the *monomial support* of  $f$ .

**Definition 2.** A set  $T \in \text{supp}(f)$  is a *maximal ANF monomial support* of  $f$  if no proper superset  $T' \supsetneq T$  lies in  $\text{supp}(f)$ .

## 3 The Derivative–ANF Correspondence

**Proposition 3** (Derivative formula). *For every  $f$  and every  $S \subseteq [n]$ ,*

$$D_S f = \bigoplus_{\substack{T \subseteq [n] \\ T \supseteq S}} c_T \prod_{i \in T \setminus S} x_i. \quad (2)$$

*Proof.* By  $\mathbb{F}_2$ -linearity of  $D_S$ , it suffices to verify (2) on each monomial  $m_T := \prod_{i \in T} x_i$ .

*Case  $S \not\subseteq T$ .* Pick  $j \in S \setminus T$ . Since  $m_T$  does not depend on  $x_j$ , we have  $D_j m_T = m_T \oplus m_T = 0$ , and therefore  $D_S m_T = 0$ . This is consistent with (2), which contributes no term from  $T$  (as  $T \not\supseteq S$ ).

*Case  $S \subseteq T$ .* For each  $j \in S$ :

$$D_j \left( \prod_{i \in T} x_i \right) = \prod_{i \in T} x_i \Big|_{x_j=0} \oplus \prod_{i \in T} x_i \Big|_{x_j=1} = 0 \oplus \prod_{i \in T \setminus \{j\}} x_i = \prod_{i \in T \setminus \{j\}} x_i.$$

Applying each  $D_j$  for  $j \in S$  iteratively (in any order, by commutativity) gives  $D_S m_T = \prod_{i \in T \setminus S} x_i$ , which matches the  $T$ -term in (2). Summing over  $T \supseteq S$  with  $c_T = 1$  completes the proof.  $\square$

**Theorem 4** (Derivative–ANF correspondence).  $D_S f \equiv 1$  if and only if  $S$  is a maximal ANF monomial support of  $f$ .

*Proof.* Decompose (2) by separating the  $T = S$  term:

$$D_S f = c_S + \bigoplus_{\substack{T \supseteq S \\ T \in \text{supp}(f)}} \prod_{i \in T \setminus S} x_i.$$

The first term is constant, while every term with  $T \supsetneq S$  is a nonconstant multilinear monomial in the remaining variables. By uniqueness of the ANF on the variables  $[n] \setminus S$ , this derivative is identically 1 if and only if

$$c_S = 1 \quad \text{and} \quad c_T = 0 \text{ for every } T \supsetneq S.$$

The first condition says that the monomial with support  $S$  appears in the ANF of  $f$ . The second says that no monomial whose support properly contains  $S$  appears in the ANF of  $f$ . Thus  $S$  is maximal among the ANF supports under set inclusion.  $\square$

*Remark 5.* Equation (2) shows that  $D_S$  acts on the ANF by *projecting onto monomials containing  $S$ , then cancelling the  $S$ -variables*. This is the Boolean analogue of partial differentiation in  $\mathbb{F}_2[x_1, \dots, x_n]$ .

## 4 Constant Derivative Certificates

**Definition 6.** A nonempty set  $S \subseteq [n]$  is a *constant derivative certificate* for  $f$  if  $D_S f \equiv 1$ . The *derivative certificate depth* of  $f$  is

$$\Delta_\partial(f) := \min\{|S| : \emptyset \neq S \subseteq [n], D_S f \equiv 1\},$$

with  $\Delta_\partial(f) = \infty$  if no such  $S$  exists. By Theorem 4,  $\Delta_\partial(f)$  equals the minimum degree of a nonempty maximal element of  $\text{supp}(f)$ .

**Proposition 7.**  $\Delta_\partial(f) < \infty$  if and only if  $f$  is nonconstant.

*Proof.* If  $f \equiv 0$ : then  $\text{supp}(f) = \emptyset$ , so no maximal element exists and  $\Delta_\partial(f) = \infty$ .

If  $f \equiv 1$ : then  $c_\emptyset = 1$  and  $c_T = 0$  for all  $T \neq \emptyset$  (since Möbius inversion gives  $c_\emptyset = f(\mathbf{0}) = 1$  and  $c_{\{i\}} = f(\mathbf{0}) \oplus f(\mathbf{e}_i) = 1 \oplus 1 = 0$ , etc.). So  $\text{supp}(f) = \{\emptyset\}$ , whose unique element is empty. Since Definition 6 requires a *nonempty* certificate,  $\Delta_\partial(f) = \infty$ .

If  $f$  is nonconstant:  $\text{supp}(f)$  contains at least one nonempty set. Since  $\text{supp}(f)$  is a finite nonempty poset, it has a maximal element  $S$ . If  $S = \emptyset$ , then every proper superset satisfies  $c_T = 0$ , and  $c_\emptyset = 1$ ; but then  $f \equiv 1$  by Möbius inversion, contradicting nonconstancy. So  $S \neq \emptyset$ , giving  $\Delta_\partial(f) \leq |S| < \infty$ .  $\square$

*Remark 8.* The proposition shows  $\Delta_\partial(f) = \infty$  for *both* constant functions, even though  $f \equiv 1$  is satisfiable. The parameter  $\Delta_\partial$  does not measure satisfiability.

## 5 Examples

**Example 9** (Linear functions). If  $f = x_{i_1} \oplus \cdots \oplus x_{i_k}$ , the ANF consists of  $k$  degree-one monomials  $\{i_1\}, \dots, \{i_k\}$ , each of which is maximal, since no higher-degree monomial appears. Hence  $\Delta_\partial(f) = 1$ .

**Example 10** (Pure conjunction).  $f = x_1 \cdots x_k$  has a single ANF monomial  $[k]$ , which is trivially maximal. Hence  $\Delta_\partial(f) = k$ , showing that the parameter can equal the degree of the unique maximal ANF monomial.

**Example 11** (Majority on three variables).  $f = x_1x_2 \oplus x_1x_3 \oplus x_2x_3$ . Möbius inversion gives  $c_{\{1,2,3\}} = \bigoplus_{R \subseteq \{1,2,3\}} f(\mathbf{1}_R) = 0$ , so the degree-three monomial is absent. All three degree-two monomials are present and maximal. Hence  $\Delta_\partial(f) = 2$ .

**Example 12** (Constant functions).  $\Delta_\partial(f) = \infty$  for  $f \equiv 0$  and  $f \equiv 1$  by Proposition 7.

## 6 The Decision Problem

**Problem 13** (BOUNDED CONSTANT DERIVATIVE (BCD)). Given a Boolean circuit  $f(x_1, \dots, x_n)$  and an integer  $1 \leq k \leq n$ , decide whether  $\Delta_\partial(f) \leq k$ .

By Theorem 4, BCD asks whether  $\text{supp}(f)$  has a maximal element of cardinality  $\leq k$ . Expanding via (1):

$$\exists S \subseteq [n], 0 < |S| \leq k \quad \forall b \in \{0,1\}^{[n] \setminus S} \quad \bigoplus_{u \in \{0,1\}^S} f(b, u) = 1. \quad (*)$$

The  $\exists \forall \oplus$  quantifier structure of  $(*)$  controls the complexity of BCD. The three layers work differently with  $k$ : at fixed  $k$  the parity layer ( $\oplus$ ) collapses to polynomial time; at  $k = n$  the  $\forall$ -layer ranges over the single empty tuple; for general  $k$  all three are utilized.

## 7 Fixed-Depth Complexity

**Theorem 14.** For every fixed constant  $K \geq 1$ , the problem  $\text{BCD}_K$  is coNP-complete.

*Proof.* **coNP-membership.** We show  $\overline{\text{BCD}_K} \in \text{NP}$ . An instance  $(f, K)$  is a no-instance iff every nonempty  $S \subseteq [n]$  with  $|S| \leq K$  satisfies  $D_S f \not\equiv 1$ , i.e., there exists  $b_S \in \{0,1\}^{[n] \setminus S}$  with  $D_S f(b_S) = 0$ . A nondeterministic machine guesses the family  $\{b_S\}_S$  and verifies each condition

$$\bigoplus_{u \in \{0,1\}^S} f(b_S, u) = 0$$

by evaluating  $f$  at at most  $2^K$  points. Since  $K$  is fixed and there are  $\sum_{j=1}^K \binom{n}{j} = O(n^K)$  choices of  $S$ , verification is polynomial in  $n$ . Hence  $\overline{\text{BCD}_K} \in \text{NP}$ , so  $\text{BCD}_K \in \text{coNP}$ .

**coNP-hardness.** We give a polynomial-time many-one reduction from TAUTOLOGY to  $\text{BCD}_K$ . Given a formula  $\psi(y_1, \dots, y_m)$ , introduce variables  $x_1, \dots, x_K$  (disjoint from  $y$ ) and define

$$f(x_1, \dots, x_K, y_1, \dots, y_m) := x_1 \cdots x_K \cdot \psi(y_1, \dots, y_m).$$

Let  $X := \{1, \dots, K\}$  denote the indices of the  $x$ -variables.

*Step 1: ANF of  $f$ .* Since the  $x$ -variables and  $y$ -variables are disjoint, the product distributes as

$$f = \left( \prod_{i \in X} x_i \right) \cdot \left( \bigoplus_{T \subseteq [m]} c_T^\psi \prod_{j \in T} y_j \right) = \bigoplus_{T \subseteq [m]} c_T^\psi \left( \prod_{i \in X} x_i \right) \left( \prod_{j \in T} y_j \right),$$

where  $c_T^\psi$  denotes the ANF coefficient of  $\psi$  for the monomial  $\prod_{j \in T} y_j$ . For any  $T \subseteq [m]$ , let  $T' := \{j + K : j \in T\}$  be the corresponding indices in  $f$ . Hence

$$\text{supp}(f) = \{X \cup T' : T \subseteq [m], c_T^\psi = 1\}.$$

Thus every ANF monomial of  $f$  contains  $X$  as a subset and has degree  $\geq K$ .

*Step 2: Any certificate of size  $\leq K$  must equal  $X$ .* Suppose  $S \subseteq [n]$  with  $|S| \leq K$  is a constant derivative certificate, so  $D_S f \equiv 1$ . We first show  $X \subseteq S$ . Suppose for contradiction that  $X \not\subseteq S$ , and pick any  $j \in X \setminus S$ . By Proposition 3,

$$D_S f = \bigoplus_{\substack{M \in \text{supp}(f) \\ M \supseteq S}} \prod_{i \in M \setminus S} x_i.$$

Since every  $M \in \text{supp}(f)$  contains all of  $X$ , we have  $j \in M \setminus S$  for every contributing term. Thus the variable  $x_j$  divides every summand, giving  $D_S f = x_j \cdot g$  for some Boolean polynomial  $g$ . Setting  $x_j = 0$  then yields  $D_S f|_{x_j=0} \equiv 0 \neq 1$ , contradicting  $D_S f \equiv 1$ . Hence  $X \subseteq S$ . Combined with  $|S| \leq K = |X|$ , we get  $S = X$ .

*Step 3:  $\Delta_\partial(f) \leq K$  iff  $\psi \equiv 1$ .* By Step 2,  $\Delta_\partial(f) \leq K$  iff  $D_X f \equiv 1$ . Applying Proposition 3 with  $S = X$ :

$$D_X f = \bigoplus_{T \subseteq [m]} c_T^\psi \prod_{j \in T} y_j = \psi.$$

Hence  $D_X f \equiv 1$  iff  $\psi \equiv 1$ . The reduction is polynomial-time and TAUTOLOGY is coNP-complete [3].  $\square$

## 8 The Unrestricted Case: $k = n$

**Theorem 15.** BCD with  $k = n$  is NP-complete.

*Proof.* When  $k = n$ , the condition  $\Delta_\partial(f) \leq n$  is equivalent, by Proposition 7, to  $f$  being nonconstant (since every nonempty monomial has degree  $\leq n$ ).

**NP-membership.** A pair of assignments  $a, b \in \{0, 1\}^n$  with  $f(a) \neq f(b)$  is a polynomial-time verifiable witness for nonconstancy.

**NP-hardness.** We reduce SAT to nonconstancy. Given  $\varphi(y_1, \dots, y_m)$ , introduce a variable  $z$  and define  $f(y_1, \dots, y_m, z) := z \cdot \varphi(y_1, \dots, y_m)$ .

If  $\varphi$  is unsatisfiable, then  $\varphi \equiv 0$  as a Boolean function, so  $f \equiv 0$  is constant. If  $\varphi$  is satisfiable with witness  $a \in \{0, 1\}^m$ , then  $f(a, 0) = 0 \neq 1 = f(a, 1)$ , so  $f$  is nonconstant. The reduction runs in polynomial time.  $\square$

*Remark 16.* The transition from coNP to NP as  $k$  grows is quite interesting. In  $(*)$ , the  $\forall$ -layer ranges over  $2^{n-k}$  base vectors: at fixed  $k$  this is exponential, making the  $\forall$ -layer the bottleneck; at  $k = n$  it ranges over  $\{0, 1\}^0 = \{()\}$ , a single empty tuple, making it vacuous. As  $k$  increases, the  $\forall$ -layer collapses and the complexity seems to go from coNP toward NP.

## 9 The Variable- $k$ Case and $\Sigma_2^{\oplus P}$

We define  $\Sigma_2^{\oplus P}$  as the class of decision problems of the form

$$x \in L \iff \exists S \in \{0, 1\}^{p(|x|)} \forall b \in \{0, 1\}^{q(|x|)} \bigoplus_{u \in \{0, 1\}^{r(|x|)}} C(x, S, b, u) = 1$$

for some polynomial-time computable Boolean circuit  $C$  and polynomials  $p, q, r$ . This is the parity-oracle analogue of the second existential–universal level; equivalently, one may view it as  $\text{NP}^{\Pi_1^{\oplus P}}$ , where  $\Pi_1^{\oplus P} = \text{coNP}^{\oplus P}$ , as considered by Papadimitriou and Zachos [8].

**Proposition 17.** *The general problem BCD (variable  $k$ ) lies in  $\Sigma_2^{\oplus P}$  and is both NP-hard and coNP-hard under polynomial-time many-one reductions.*

*Proof. Hardness.* Immediate from Theorems 14 and 15: the fixed- $K$  and  $k = n$  specializations of BCD are coNP-hard and NP-hard, respectively.

$\Sigma_2^{\oplus P}$ -**membership.** The quantifier structure  $(*)$  directly witnesses membership. Equivalently, a  $\text{NP}^{\Pi_1^{\oplus P}}$  algorithm proceeds as follows. First, nondeterministically guess  $S \subseteq [n]$  and check in polynomial time that  $0 < |S| \leq k$ . For this fixed  $S$ , the required verification condition is

$$\forall b \in \{0, 1\}^{[n] \setminus S} \quad \bigoplus_{u \in \{0, 1\}^S} f(b, u) = 1.$$

For fixed  $S$  and  $b$ , the inner parity predicate is decidable by an  $\oplus P$  oracle: it asks whether the number of  $u \in \{0, 1\}^S$  satisfying  $f(b, u) = 1$  is odd. Hence the universal verification condition lies in  $\text{coNP}^{\oplus P} = \Pi_1^{\oplus P}$ . The outer nondeterministic machine accepts exactly when this  $\Pi_1^{\oplus P}$ -oracle verifies the condition.

Formally, encode  $S$  by its length- $n$  characteristic vector. Let  $b$  and  $u$  range over  $\{0, 1\}^n$ , with the coordinates of  $b$  inside  $S$  ignored. Define

$$x_i(S, b, u) = \begin{cases} u_i, & i \in S, \\ b_i, & i \notin S. \end{cases}$$

Now define the polynomial-time predicate

$$C(f, S, b, u) = \begin{cases} f(x(S, b, u)), & \text{if } u_i = 0 \text{ for every } i \notin S, \\ 0, & \text{otherwise.} \end{cases}$$

Then

$$\bigoplus_{u \in \{0, 1\}^n} C(f, S, b, u) = \bigoplus_{u \in \{0, 1\}^S} f(b, u).$$

Thus the variable-length parity over  $\{0, 1\}^S$  can be represented as a fixed  $n$ -bit parity predicate, placing the verification condition in  $\Pi_1^{\oplus P} = \text{coNP}^{\oplus P}$ . Since the outer machine nondeterministically guesses  $S$  and then invokes this  $\Pi_1^{\oplus P}$  verification condition, we obtain  $\text{BCD} \in \text{NP}^{\Pi_1^{\oplus P}} = \Sigma_2^{\oplus P}$ .  $\square$

At fixed  $k = K$ , the inner parity  $\bigoplus_{u \in \{0, 1\}^K} f(b, u)$  is computable in polynomial time because  $K$  is constant. Thus the parity-oracle layer disappears, consistent with the coNP-completeness result above. At  $k = n$ , the  $\forall$ -layer is vacuous and the problem reduces to pure NP, consistent with Theorem 15.

The class  $\Sigma_2^{\oplus P}$  contains the ordinary  $\Sigma_2^P$  as a special case: take the inner parity range to have size one and let the circuit compute an ordinary polynomial-time predicate. It is also contained in PSPACE, since a polynomial-space machine can enumerate the existential witness, universally check all  $b$ , and compute each inner parity by enumeration. Thus we use only the conservative containments

$$\text{NP}, \text{coNP} \subseteq \Sigma_2^P \subseteq \Sigma_2^{\oplus P} \subseteq \text{PSPACE}.$$

We do not rely on any strict separations among these classes.

We conjecture that BCD is  $\Sigma_2^{\oplus P}$ -complete. A proof would reduce a  $\exists S \forall b [\bigoplus_u C(S, b, u) = 1]$ -complete problem to BCD by constructing a circuit  $f$  for which  $\bigoplus_u f(b, u)$  simulates  $\bigoplus_u C(S, b, u)$  under the identification  $S \leftrightarrow$  existential witness,  $b \leftrightarrow$  universal input; we leave this open.

The complexity of BCD as  $k$  varies is summarized in Table 1.

$k$	Established complexity	Active quantifier layers
Fixed constant $K$	coNP-complete	$\forall$ -layer dominates; the $\oplus$ -layer is polynomial-time
Variable $k$	In $\Sigma_2^{\oplus P}$ ; NP-hard and coNP-hard	$\exists, \forall$ , and $\oplus$ layers can all be active; completeness is left open
$k = n$	NP-complete	$\forall$ -layer is vacuous; the problem reduces to nonconstancy

Table 1: Established complexity of BCD as  $k$  varies.

## The Derivative Lattice

The family of all higher-order derivatives of  $f$  can be organized as the *derivative lattice*: nodes are the derivatives  $D_S f$  for  $S \subseteq [n]$ , ordered by inclusion of  $S$ , with an edge from  $D_S f$  to  $D_{S \cup \{i\}} f$  whenever  $i \notin S$ . Level  $k$  contains exactly  $\binom{n}{k}$  nodes, the derivatives of order  $k$ . This is actually the Hasse diagram of the Boolean lattice  $2^{[n]}$ , shown by the fact that the operators  $D_i$  commute: the node reached by applying  $D_i$  then  $D_j$  is the same as the node reached by applying  $D_j$  then  $D_i$ .

In this picture, Theorem 4 says that a node  $D_S f$  is *accepting* (identically 1) if and only if  $S$  is a maximal ANF monomial support of  $f$ . The derivative certificate depth  $\Delta_{\partial}(f)$  is then the *minimum level* containing an accepting node. Figure 1 illustrates this for  $n = 3$ .

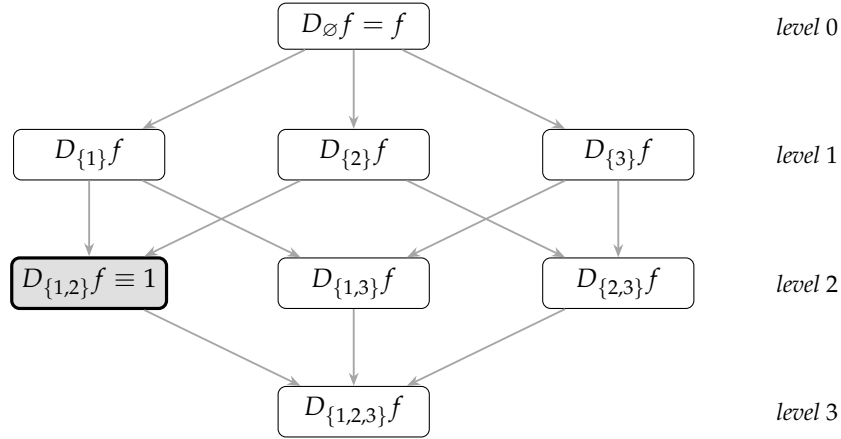


Figure 1: The derivative lattice for  $n = 3$ . Each node  $D_S f$  sits at level  $|S|$ ; edges go from  $D_S f$  to  $D_{S \cup \{i\}} f$  for  $i \notin S$ . A node is *accepting* (shaded, bold border) when  $D_S f \equiv 1$ , equivalently when  $S$  is a maximal ANF monomial support of  $f$ . In the example shown, an accepting node first appears at level 2, so  $\Delta_{\partial}(f) = 2$ .

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