

Sorting from Counterexamples

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Abstract

Consider the following problem of learning an unknown linear order on n items. In each round, the learner guesses a complete ordering of the items and receives either confirmation that the guess is correct or a counterexample: a pair of items in the wrong order. The goal is to identify the unknown order using as few queries as possible. We study this problem when up to k of the returned counterexamples may be untruthful, where k is not known in advance. We determine the optimal query complexity up to constant factors:

$$\Theta(n \log n + nk).$$

Thus, while the noiseless complexity matches the classical complexity of sorting, each untruthful counterexample incurs an additional cost of order n . The upper bound is based on a geometric representation of permutations and Grünbaum's theorem, while the lower bound combines sorting arguments with a Condorcet-type construction. We also study the case where the target ranking has a low-dimensional geometric representation: each item is represented by a point in $\mathbb{R}^d$, and the ranking is obtained by projecting the points onto an unknown direction. For these classes we give an upper bound of $O(d^2 \log n + dk)$ and a lower bound of $\Omega(d \log n + dk)$, leaving a factor of d gap in the noiseless term.

1 Introduction

Imagine asking a recommendation system where to go for dinner with your partner. It returns a ranked list of nearby restaurants, placing a sushi restaurant first and a falafel place near the bottom. What kind of feedback can such a system use to improve? Empirical studies have found pairwise preference feedback to be fast and consistent [CBCD08, SBB⁺14]. Such feedback can be much easier to provide than a full reranking and may require little active attention from the user: they can simply point out a pair that seems badly misordered: the falafel restaurant is buried near the bottom even though they strongly prefer it, while the sushi restaurant appears first despite being much less appealing. Such a pair is a natural counterexample because its relative order is badly wrong in the proposed ranking. This simple interaction motivates the problem we study: learning an unknown ranking from counterexamples.

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Ranking from counterexamples. There is an unknown target ranking π^* over n items. On each round:

1. The learner proposes a linear order π .
2. The oracle either declares that π is correct, in which case $\pi = \pi^*$ and the interaction terminates, or returns an unordered pair $\{i, j\}$, indicating that the relative order of i and j in π is wrong.

A returned pair is *truthful* if π and π^* indeed disagree on the relative order of i and j , and *untruthful* otherwise. We allow at most k untruthful counterexamples throughout the interaction, where k is not known to the learner. Declarations that the proposed ranking is correct are always truthful.

Thus, even if the learner proposes π^* , the oracle may conceal this fact by returning a counterexample, but such a counterexample is necessarily untruthful and therefore consumes one of the at most k allowed lies. For a randomized learner, we measure the worst-case expected number of queries, where the expectation is over the learner’s internal randomness.

This model can be viewed as a variation on the classical sorting problem. In comparison-based sorting, the algorithm chooses a pair of items and learns their relative order. Here, the learner instead proposes a complete ranking, and the feedback reveals one pair on which this proposal is allegedly incorrect. Our goal is to understand how many such rounds are needed to identify the target ranking.

Allowing untruthful counterexamples is also natural in the motivating example. A ranking may represent the typical preferences of a population of similar users, while feedback from an individual user may occasionally disagree with it. There are richer ways to model such variability, for example through probabilistic preference models such as the Bradley–Terry model [BT52]. In this work, we focus on a mathematically simpler formulation: the total number of untruthful counterexamples is bounded by k , where k is not known to the learner, and we make no further assumptions on when these counterexamples occur or how they are chosen. As we will see, even this basic setting already presents nontrivial challenges. A useful feature of our algorithms is that they do not use k as an input: the same learner works for every finite lie budget. This parameter-free viewpoint also makes the framework amenable to richer noise models, although we leave a systematic study of such models for future work.

At first sight, classical learning algorithms such as halving or weighted majority appear well suited to this problem. One can maintain a weight on every possible target ranking, initially assigning all rankings the same weight. Whenever a counterexample $\{i, j\}$ is returned, the weights of rankings that order i and j as in the learner’s proposal are decreased by a constant factor. The learner can then orient every pair according to the weighted majority of the candidate rankings. This approach is naturally robust to untruthful feedback: the total weight decreases whenever a counterexample is returned, whereas the weight of the target ranking is decreased only when the feedback is untruthful.

There is, however, a basic obstacle: the weighted-majority relation need not itself be a linear order. This is the familiar Condorcet phenomenon [Bla58].¹ For example, consider the three rankings

$$a \succ b \succ c, \quad b \succ c \succ a, \quad c \succ a \succ b.$$

A majority ranks a above b , b above c , and c above a , producing a directed cycle. Thus, although weighted majority gives a natural prediction for every pair separately, these predictions need not combine into a valid ranking. This makes *properness* central to the problem: on every round, the learner must output a genuine linear order rather than an arbitrary collection of pairwise predictions. The restriction is also natural in the motivating example: what the user seeks from the recommendation system is a

¹The Marquis de Condorcet (1743–1794) was a French mathematician and political philosopher who studied collective decision making and voting [dC85]. The phenomenon bearing his name shows that pairwise majority preferences can be cyclic even when each individual voter’s preferences form a linear order.

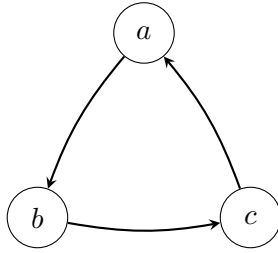


Figure 1: The pairwise majority relation may contain a Condorcet cycle, even though each individual ranking is a linear order.

ranked list of restaurants, rather than an arbitrary collection of pairwise recommendations. If improper predictions were allowed, the classical weighted-majority algorithm [LW94] would give

$$O(\log(n!) + k) = O(n \log n + k)$$

rounds, as reviewed in the proof overview below. As we show, requiring the learner to remain proper changes the picture: the optimal query complexity is

$$\Theta(n \log n + nk).$$

In particular, the cost of each untruthful counterexample increases by a factor of n . Our upper bound is obtained by a geometric modification of weighted majority, which allows us to maintain proper predictions using Grünbaum’s Theorem [Grü60], as discussed in detail below.

1.1 Our Results

We study this problem in two settings. We first consider the unrestricted setting, where the target may be any ranking of the n items. We then turn to ranking classes with additional geometric structure. Such classes arise naturally when rankings are governed by a small number of features. In the restaurant example, a restaurant might be represented by features such as price, distance, cuisine, and ambience, while a user’s preferences specify how much weight to place on each feature. Ranking the restaurants by the resulting scores gives a low-dimensional geometric ranking. More generally, items may be ranked by projection along an unknown direction or by distance from an unknown point.

Our first result gives a tight characterization of the query complexity in the unrestricted setting.

Theorem 1.1. *For an arbitrary target ranking over n items, in the presence of at most k untruthful counterexamples, the optimal number of queries is*

$$\Theta(n \log n + nk).$$

Moreover, the upper bound is achieved by a deterministic learner that does not know k .

The upper bound can be viewed as a geometric way of making weighted majority proper. The basic geometric picture is easiest to see when all counterexamples are truthful. Represent each ranking by a cell of the cube $[0, 1]^n$: a point $x = (x_1, \dots, x_n)$ induces the ranking obtained by sorting its coordinates, and the $n!$ possible rankings correspond to $n!$ equal-volume cells. A comparison between two items corresponds to a linear inequality between two coordinates, and therefore each counterexample restricts the possible points to a halfspace. Consequently, the points consistent with all counterexamples seen so far form a convex body.

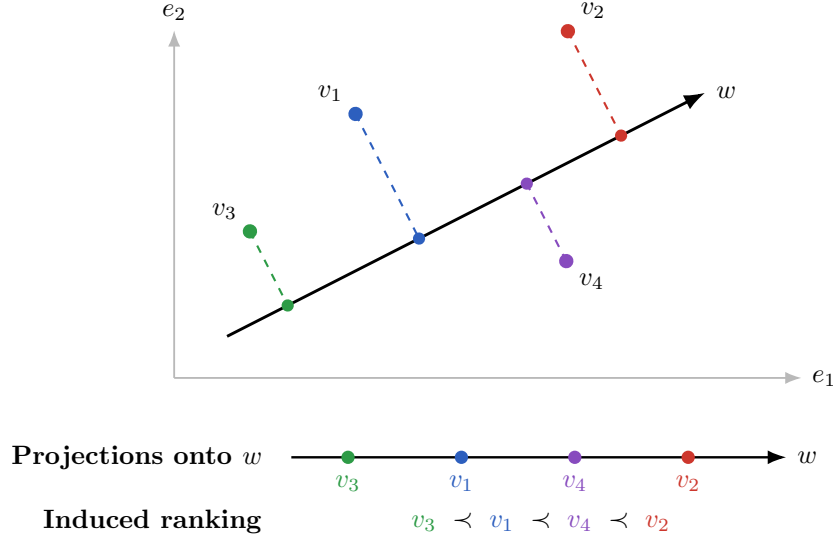


Figure 2: A geometric ranking in two dimensions. The items are represented by vectors $v_1, \dots, v_n \in \mathbb{R}^2$. A direction w induces a ranking by ordering the items according to their projections onto w . Dashed lines indicate orthogonal projections.

The learner queries the ranking induced by the center of gravity of this body. The key geometric ingredient is Grünbaum’s theorem, which says that a halfspace containing the center of gravity of a convex body must contain a constant fraction of its volume. Thus, if the proposed ranking is wrong, the returned counterexample eliminates a constant fraction of the remaining volume, and hence a constant fraction of the remaining rankings. This geometric viewpoint on linear orders goes back to Stanley [Sta81] and was developed further by Kahn and Saks [KS84]. We present this truthful case in the proof overview as a warm-up and explain the geometric argument there in a self-contained manner.

When counterexamples may be untruthful, this argument cannot be applied directly: permanently discarding all rankings inconsistent with a counterexample might discard the target itself. We therefore replace hard elimination by a smooth analogue of the weighted-majority update. This creates a non-uniform distribution over the cube rather than a uniform distribution over a convex body. The update is chosen so that this distribution remains log-concave, allowing us to use the more general, log-concave form of Grünbaum’s theorem. In this way we retain constant progress in the total weight while ensuring that truthful counterexamples have only a small effect on the weight near the target; an untruthful counterexample may have a larger effect, but only by a factor of order n . This yields the $O(n \log n + nk)$ upper bound. The proof overview develops these ideas, including the required form of Grünbaum’s theorem, from scratch.

The two terms in the lower bound arise from different constructions. The $\Omega(n \log n)$ term already appears in the noiseless setting and follows from a connection with balanced comparison trees for sorting. The $\Omega(nk)$ term follows from a simple Condorcet-cycle construction. Thus, the same phenomenon that prevents pairwise majority from being proper also plays a role in showing that untruthful counterexamples are inherently more costly for proper learners.

Geometric rankings. Our second result concerns ranking classes with additional geometric structure. Consider n items represented by vectors $v_1, \dots, v_n \in \mathbb{R}^d$. Every direction $w \in \mathbb{R}^d$ induces a ranking by ordering the items according to

$$\langle v_1, w \rangle, \dots, \langle v_n, w \rangle.$$

We call a class of rankings *d-dimensional geometric* if it can be represented in this way.

We emphasize that the learner’s queries are still required to be genuine linear orders, but they need not themselves belong to the geometric class. In other words, the learner may propose an ordering that is not induced by any direction w in the given representation.

The geometric dimension can be much smaller than the number of items, and it is therefore natural to ask whether the query complexity can depend on d rather than directly on n .

Theorem 1.2. *Every d -dimensional geometric class of rankings over n items can be learned using*

$$O(d^2 \log n + dk)$$

queries in the presence of at most k untruthful counterexamples. Conversely, there are d -dimensional geometric classes for which every learner whose queries are linear orders requires

$$\Omega(d \log n + dk)$$

queries.

The upper bound follows from a different way of rounding a weighted majority of linear orders to a linear order. Ordinary majority may contain cycles, but for d -dimensional geometric rankings a sufficiently strong majority relation is acyclic. In particular, a threshold of roughly $1 - 1/d$ produces a relation that can be extended to a linear order. This allows us to use weighted majority more directly, at the cost of an additional factor of d in the progress made on each truthful round. Moreover, the upper bound can be achieved while choosing every query to be a ranking induced by some direction in the same geometric representation. Thus, when the class consists of all rankings induced by the representation, the learner can be proper in the usual sense. This may also be useful in feature-based applications. In the restaurant example, such a ranking is specified by only d coefficients, rather than by an arbitrary ordering of the n restaurants. This gives a compact representation that can also be applied to new items and may offer some interpretability through the relative importance assigned to the different features.

The dependence on k in the query complexity is tight, while a factor of d remains between the upper and lower bounds in the noiseless term. This leaves the following natural question open:

Can the $O(d^2 \log n)$ upper bound be improved to $O(d \log n)$?

Computational aspects. Our focus in this work is on query complexity, rather than on obtaining fully efficient implementations of the learning algorithms. In particular, our upper bound for arbitrary rankings is formulated in terms of barycenters of log-concave distributions, which we do not compute explicitly. The distributions arising in our algorithm are, however, efficiently evaluable log-concave distributions, and standard random-walk methods allow one to sample approximately from such distributions in randomized polynomial time [LV06, LV07]. Averaging sufficiently many samples provides a natural way to approximate the barycenter; related random-walk methods for replacing exact centroids by empirical approximations appear, for example, in [BV04]. This suggests that our approach should admit a randomized polynomial-time implementation, although we do not work out the required approximation guarantees here. We leave a systematic study of efficient algorithms for future work. In particular, it would be interesting to find efficient combinatorial algorithms for this problem. Besides avoiding general-purpose sampling machinery, such algorithms might also lead to more direct proofs of our upper bounds that circumvent the use of Grünbaum’s theorem.

Organization of the paper. We begin with a proof overview in Section 2, which develops the main ideas behind our results and explains the geometric and combinatorial ingredients used in the proofs.

We then discuss related work in Section 3, followed by the full arguments, first for arbitrary rankings in Section 4 and then for geometric ranking classes in Section 5. We conclude with several open questions and directions for future research in Section 6.

2 Proof Overview

The goal of this section is to explain the main ideas behind our proofs, focusing on the parts that are less routine and on the intuition behind the different constructions. Besides providing an overview of the proofs, we hope that this discussion will make the more detailed arguments in the following sections easier to follow. We first discuss the upper bounds, and then turn to the lower bounds.

2.1 Upper Bounds

Weighted majority as a benchmark. It is useful to begin by recalling the classical weighted-majority algorithm [LW94]. Think of each possible target ranking as an expert, and initially assign weight one to every expert.

Weighted majority (improper benchmark)

On each round:

1. For every unordered pair $\{i, j\}$, let $A_t(i \prec j)$ denote the total current weight of rankings that place i before j . Predict $i \prec j$ if $A_t(i \prec j) > A_t(j \prec i)$, and predict $j \prec i$ if $A_t(j \prec i) > A_t(i \prec j)$, breaking ties arbitrarily. These pairwise predictions constitute the output of this benchmark; they are not required to be transitive and therefore need not define a linear order.
2. If a counterexample $\{i, j\}$ is returned, multiply by $1/2$ the weight of every ranking that agrees with the learner's prediction on this pair.

The standard analysis is simple. Let W_t denote the total weight after t returned counterexamples; initially, $W_0 = n!$. Whenever a counterexample is returned, at least half of the total weight is multiplied by $1/2$, and hence the total weight decreases by a factor of at most $3/4$. On the other hand, the weight of the target ranking is decreased only when the counterexample is untruthful. Thus, after T rounds and at most k untruthful counterexamples,

$$2^{-k} \leq W_T \leq n! \left(\frac{3}{4}\right)^T,$$

and therefore

$$T = O(\log(n!) + k) = O(n \log n + k).$$

Arbitrary rankings: making majority geometric. We first consider the unrestricted class of all rankings. There are two main ideas in the proof. The first is to replace pairwise majority by a geometric notion of averaging that always produces a linear order. The second is to modify the weighted-majority update so that this geometric averaging continues to work in the presence of untruthful counterexamples.

We begin with the first idea, in the simpler setting where all counterexamples are truthful. In this case there is no need to maintain weights: once a ranking is contradicted by a truthful counterexample, it can be discarded permanently. Thus, instead of weighted majority, we may work with the simpler halving algorithm and maintain only the current version space $\mathcal{V}_t$ of rankings consistent with all counterexamples seen so far.

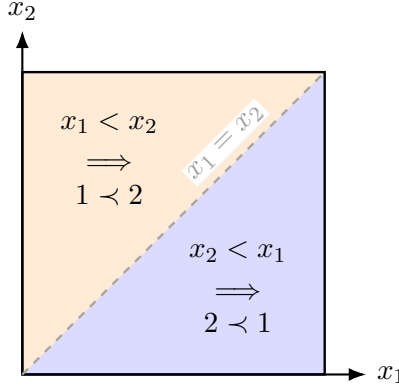


Figure 3: The geometric representation of rankings for $n = 2$. A point $x \in [0, 1]^2$ induces a ranking according to the order of its coordinates. The line $x_1 = x_2$ splits the square into the two cells corresponding to the two possible linear orders.

Define the majority relation on the items by putting an edge $i \rightarrow j$ whenever a strict majority of the rankings in $\mathcal{V}_t$ place i before j . If this relation were acyclic, we could extend it to a linear order and query that order. Any returned counterexample $\{i, j\}$ would then disagree with a majority edge, and therefore eliminate at least half of the rankings in $\mathcal{V}_t$. Starting from $n!$ possible rankings, this would identify the target after at most $\lceil \log_2(n!) \rceil$ rounds.

The difficulty is that the majority relation need not be acyclic: it may contain a Condorcet cycle. Our first geometric idea replaces this majority relation by a proper linear order while retaining constant-factor progress.

To obtain a proper analogue of halving, we use the geometric viewpoint on linear extensions initiated by Stanley [Sta81] and developed further by Kahn and Saks [KS84]. Consider the cube $[0, 1]^n$. A point $x = (x_1, \dots, x_n)$ with distinct coordinates induces a ranking by sorting its coordinates: i is ranked before j whenever $x_i < x_j$. The complement of the hyperplanes $x_i = x_j$ therefore consists of $n!$ open cells, one for each linear order, and all these cells have the same volume $1/n!$. Figure 3 depicts this representation in the simplest case $n = 2$, where the diagonal $x_1 = x_2$ separates the two possible rankings. Moreover, every comparison constraint is a halfspace constraint: for example, the requirement that i precedes j corresponds to

$$\{x \in [0, 1]^n : x_j - x_i > 0\}.$$

Consequently, the set K_t of points whose induced rankings are consistent with all counterexamples seen so far is a convex body, obtained by intersecting the cube with halfspaces. Since every ranking cell has volume $1/n!$,

$$\text{vol}(K_t) = \frac{|\mathcal{V}_t|}{n!}.$$

Centroid halving

Maintain the convex body $K_t \subseteq [0, 1]^n$ consisting of all points consistent with the counterexamples seen so far. On each round, let c_t be the centroid of K_t and query the ranking induced by the coordinates of c_t .

The reason this query makes constant progress is Grünbaum's theorem [Grü60]: if $K \subseteq \mathbb{R}^n$ is a convex body with centroid c , then every halfspace H containing c satisfies

$$\frac{\text{vol}(K \cap H)}{\text{vol}(K)} \geq \left(\frac{n}{n+1} \right)^n \geq \frac{1}{e}.$$

Suppose, for example, that the centroid ranks i before j , and the oracle returns $\{i, j\}$ as a counterexample. The halfspace corresponding to the centroid's orientation contains the centroid, and is therefore at least a $1/e$ fraction of the current volume. Since this is precisely the side eliminated by the counterexample, every round removes at least a $1/e$ fraction of the remaining volume. Hence

$$\text{vol}(K_{t+1}) \leq \left(1 - \frac{1}{e}\right) \text{vol}(K_t),$$

and again $O(\log(n!)) = O(n \log n)$ rounds suffice.

Thus, in the truthful setting, Grünbaum's theorem plays the role of halving: we lose the factor $1/2$, replacing it by another universal constant, but gain the important property that the prediction is always a linear order. This argument is closely connected to the classical Kahn–Saks theorem on balanced comparisons in linear extensions [KS84]; in particular, the geometric ingredient needed for our truthful upper bound already appears in their work and in the subsequent papers [KL91] and [KK91].

Allowing untruthful counterexamples. With untruthful counterexamples, we can no longer permanently discard a ranking when it becomes inconsistent with the feedback, so we replace hard halving by a weighted update. The obvious attempt is to lift weighted majority to the cube by assigning to every ranking cell the weight of the corresponding ranking. Unfortunately, the resulting piecewise-constant density is generally not log-concave, and hence the geometric argument above no longer applies.

Our second main idea is to replace this discontinuous update by a convex surrogate. We maintain a density over the cube rather than a discrete weight on each ranking.

Log-concave weighted majority

Maintain a log-concave density w_t on $[0, 1]^n$. On each round, let c_t be its barycenter and query the ranking induced by the coordinates of c_t .

Suppose the returned counterexample $\{i, j\}$ indicates that i should be ranked before j . Thus, the queried ranking places j before i . Define

$$z_t(x) := x_i - x_j, \quad \ell_t(x) := (1 + \gamma n z_t(x))_+,$$

where $(a)_+ := \max\{a, 0\}$. Since the query places j before i , we have $z_t(c_t) \geq 0$. Update

$$w_{t+1}(x) = w_t(x) e^{-\ell_t(x)},$$

where $\gamma > 0$ is a sufficiently large universal constant.

The particular form of this update is chosen for two reasons. First, $(1 + \gamma n z_t(x))_+$ is convex, and hence the update preserves log-concavity. We may therefore use the log-concave version of Grünbaum's inequality [LV07]: any halfspace containing the barycenter of a log-concave probability measure has probability at least $1/e$. Since $\ell_t \geq 1$ throughout the halfspace $\{z_t \geq 0\}$, a constant fraction of the total weight receives a constant multiplicative penalty. Thus, just as in ordinary weighted majority, the total weight decreases by a constant factor on every round.

Second, this update does not decrease the weight near the target ranking too quickly. Consider the cell of the cube corresponding to the true ranking. On a truthful round this entire cell lies on the correct side of the comparison hyperplane, and the surrogate loss is nonzero only in a thin strip of width $O(1/n)$ near that hyperplane. For a uniformly random point in a ranking cell, the gaps between consecutive coordinates are typically of order $1/n$; choosing the constant γ sufficiently large makes the expected surrogate loss on a truthful round arbitrarily small. In contrast, an untruthful counterexample may incur loss $O(n)$ on the target cell.

The resulting comparison of masses mirrors the elementary weighted-majority analysis. After T rounds, the total mass is at most ρ^T for some universal constant $\rho < 1$, while the mass inside the target cell is at least, up to constants in the exponent,

$$\frac{1}{n!} \exp(-O(T/\gamma) - O(nk)).$$

Choosing γ sufficiently large and comparing these two bounds gives

$$T = O(\log(n!) + nk) = O(n \log n + nk).$$

One minor subtlety in the formal argument is that the density inside the target cell is no longer uniform after the first update. We therefore analyze its total mass relative to the uniform measure on the target cell and use Jensen's inequality; this is where the detailed proof differs slightly from the informal calculation above.

Geometric ranking classes: making strong majority proper. For d -dimensional geometric ranking classes, we can stay much closer to the original weighted-majority algorithm. We keep an ordinary weight on every candidate ranking and, after a counterexample, multiply by $1/2$ the weights of the candidates that agree with the learner on the returned pair. The only question is again how to turn the resulting pairwise weighted preferences into a linear order.

Here geometric structure gives a different solution. Instead of keeping every pair supported by a simple majority, we keep only sufficiently strong majorities: roughly speaking, we orient i before j only when a $1 - O(1/d)$ fraction of the current weight ranks i before j . The key geometric fact is that this strong-majority relation is acyclic, and hence can be extended to a linear order.

To see the reason, represent the items by vectors $v_1, \dots, v_n \in \mathbb{R}^d$. A comparison $i \prec j$ corresponds to a linear inequality on the direction w ,

$$\langle v_j - v_i, w \rangle > 0.$$

If the strong-majority relation contained a directed cycle, the corresponding difference vectors would have a positive dependence whose sum is zero. By Carathéodory's theorem, such a dependence can already be witnessed by only $O(d)$ of these vectors. No direction w can satisfy all the corresponding inequalities simultaneously. Therefore every candidate ranking must disagree with at least one of these $O(d)$ comparisons. But if each of them were supported by all but an $O(1/d)$ fraction of the total weight, the union bound would give a contradiction. This is exactly what makes the strong-majority relation acyclic.

We query any linear extension of this relation. For every pair oriented by the resulting ranking, at least an $\Omega(1/d)$ fraction of the total weight supports that orientation; otherwise the reverse orientation would itself be a strong-majority edge. Consequently, whenever a counterexample is returned, an $\Omega(1/d)$ fraction of the total weight is multiplied by $1/2$. The total weight therefore decreases by a factor

$$1 - \Omega(1/d)$$

on every round, while the target weight is decreased only on the at most k untruthful rounds.

Finally, an arrangement of the $\binom{n}{2}$ comparison hyperplanes in $\mathbb{R}^d$ induces at most $n^{O(d)}$ distinct rankings, and hence the initial logarithmic weight is $O(d \log n)$. The usual weighted-majority calculation now gives

$$O(d \cdot (d \log n + k)) = O(d^2 \log n + dk)$$

queries.

There are also alternative geometric proofs of this upper bound, based on Helly's theorem or on the centerpoint theorem [Mat02]. These have the additional feature that the queried linear order can be chosen to be induced by a direction in the given representation; see Section 5.1.

2.2 Lower Bounds

The lower bounds are simpler and more direct than the upper bounds. We begin with two combinatorial arguments for unrestricted rankings, giving $\Omega(n \log n)$ and $\Omega(nk)$. We then extend these ideas to geometric rankings and use an additional polynomial construction to obtain the full $\Omega(d \log n + dk)$ lower bound.

For simplicity, throughout this overview we describe the lower bounds using an adversary that does not commit to the target ranking π^* in advance. Instead, the adversary maintains a set of possible targets and chooses its counterexamples so that this set remains nonempty, committing to a target only at the end of the interaction. This is slightly stronger than our formal model, where π^* is fixed from the outset, but makes the arguments more transparent. In the formal proofs, we recover the same lower bounds with a target chosen in advance, using a randomized construction.

Arbitrary rankings. The $\Omega(n \log n)$ bound follows directly from sorting. Fix a balanced comparison tree for sorting n items, in which every root-to-leaf path has length $\Omega(n \log n)$; for example, MergeSort induces such a tree. The adversary follows a path in this tree. At the current node, suppose the tree compares i and j . The learner's proposed ranking fixes an orientation of this pair. The adversary returns $\{i, j\}$ as a counterexample and follows the child corresponding to the opposite orientation. At the end of the interaction, the ranking at the resulting leaf is consistent with all the counterexamples that were returned. Thus the interaction is forced to traverse an entire root-to-leaf path, requiring $\Omega(n \log n)$ queries.

The $\Omega(nk)$ bound comes from essentially the same Condorcet cycle that obstructs pairwise majority. Consider the directed cycle

$$1 \rightarrow 2 \rightarrow \cdots \rightarrow n \rightarrow 1,$$

and, for each $r \in [n]$, let σ_r be the linear order obtained by breaking the cycle at its r -th edge. Every linear order violates at least one edge of the cycle. Whenever the learner proposes an order, the adversary returns such a violated edge as a counterexample. If edge r is returned, this counterexample is truthful for every candidate σ_s except σ_r . Consequently, σ_r remains a possible target as long as edge r has been returned at most k times. To rule out all but one of the n candidates, the adversary must therefore return at least $k + 1$ copies of at least $n - 1$ different edges. This gives

$$\Omega(nk)$$

queries. Together, the two arguments yield a lower bound of

$$\Omega(n \log n + nk)$$

on the number of queries.

Geometric rankings. Both lower bounds above already apply to geometric rankings when the number of items equals the dimension. Indeed, represent d items by the standard basis vectors $e_1, \dots, e_d \in \mathbb{R}^d$. Since $\langle e_i, w \rangle = w_i$, choosing the coordinates of w in any prescribed order realizes any desired linear order on the d items. The unrestricted lower bounds therefore immediately give

$$\Omega(d \log d + dk).$$

It remains to obtain the dependence on n in the noiseless term. For this we use polynomial rankings. Identify the items with the points $1, \dots, n$ on the real line, and let a polynomial p of degree at most d rank them according to

$$p(1), p(2), \dots, p(n).$$

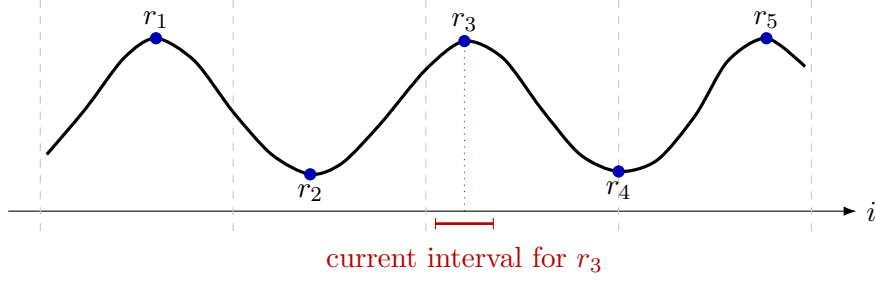


Figure 4: Schematic view of the polynomial construction. The items are consecutive points on the real line, and the polynomial has one turning point in each of $\Theta(d)$ disjoint intervals. A comparison of two consecutive items near the midpoint of the current uncertainty interval determines on which side the corresponding turning point may lie, yielding a binary-search-type lower bound.

These rankings are d -dimensional geometric: the constant term does not affect the ranking, and

$$p(i) = a_0 + \left\langle (a_1, \dots, a_d), (i, i^2, \dots, i^d) \right\rangle.$$

Thus, such polynomial orders are d -dimensional geometric with the items represented by points on the moment curve $\{(x, x^2, \dots, x^d) : x \in \mathbb{R}\}$.

We restrict attention to polynomials with $\Theta(d)$ turning points, with one turning point in each of $\Theta(d)$ disjoint intervals, each containing $\Theta(n/d)$ consecutive items; see Figure 4. The locations of these turning points can be chosen essentially independently by prescribing the roots of p' .

Consider one of these intervals. As long as the corresponding turning point is only known to lie in some subinterval, consider two consecutive items near its midpoint. Their relative order determines on which side of this location the turning point lies. The adversary returns this pair with the orientation opposite to the learner's proposed ranking, thereby retaining a realizable choice of the turning point in one of the two halves. Thus each counterexample reveals at most one step of a binary search, and locating a single turning point requires

$$\Omega(\log(n/d))$$

queries.

The adversary can repeat this argument separately for each of the $\Theta(d)$ turning points. Hence

$$\Omega(d \log(n/d))$$

queries are necessary.

Combining this with the previous $\Omega(d \log d)$ bound gives

$$\Omega(d \log n),$$

since

$$\max\{d \log d, d \log(n/d)\} \geq \frac{1}{2} d \log n.$$

Together with the $\Omega(dk)$ bound, this yields

$$\Omega(d \log n + dk).$$

3 Related Work

Learning and ranking from comparisons. Pairwise comparisons have a long history as a means of eliciting preferences and judgments, with classical statistical models including those of Thurstone and Bradley–Terry [Thu27, BT52]. They have also been studied extensively as a form of supervision in theoretical learning. Balcan, Vitercik, and White [BVW16] study learning real-valued combinatorial functions from pairwise comparisons, while Kane et al. [KLMZ17] study comparison queries in active classification. Related and subsequent work studies, among other questions, robustness to noisy comparisons and the power of comparisons for learning linear classifiers [XZM⁺17, HKL20, HKLM20].

A closely related literature studies learning rankings from pairwise comparisons, under both adaptive and non-adaptive sampling schemes [JN11, Ail11, ABE12, RA16, AAK17]. Of particular relevance to our geometric setting, Jamieson and Nowak [JN11] consider objects embedded in a low-dimensional Euclidean space, with rankings determined by distance from a common reference point, and show that this structure can substantially reduce the number of required comparisons. Related forms of relative supervision also arise in contrastive learning [AAE⁺24].

Our model differs in the direction of the interaction. Rather than choosing a pair and receiving its relative order, the learner proposes a complete ranking and the oracle returns a pair witnessing an error in that ranking. In particular, every learner query must itself be a linear order, making properness a central issue in our setting.

Another line of work studies ranking and preference learning from pairwise comparison data. Balcan et al. [BBB⁺07] give a robust reduction from AUC ranking to binary classification, showing how guarantees for the induced pairwise classification problem translate into guarantees for ranking. More recently, Pukdee, Balcan, and Ravikumar [PBR26] study preference learning from pairwise comparison data through the Bradley–Terry model, including the question of what is recovered when the model is misspecified. These works consider substantially different learning settings from ours, but share the perspective of pairwise preferences as a basic form of supervision.

Learning from equivalence queries. Our interaction is closely related to the classical model of learning from equivalence queries, developed by Angluin [Ang87, Ang88]. In that model, the learner proposes a hypothesis and, if it is incorrect, receives a counterexample witnessing a disagreement with the target. A substantial literature studies this model and variants of it; see, for example, [Vaa17] for a broader perspective on active model learning.

More recently, Braverman et al. [BLM⁺26] revisit equivalence-query learning from the perspective of proper learning and counterexample generation. They study less adversarial, symmetric counterexample generators, including random counterexamples previously considered in [AD17, Bha21, CFR24], and also consider a bandit-feedback variant in which the counterexample is returned without its correct label.

Our model can be viewed as a structured equivalence-query problem in which the hypotheses are rankings and counterexamples are pairs of misordered items. There are, however, two important differences. First, we allow a bounded number of untruthful counterexamples. Second, the structural requirement that every learner query be a linear order is central to our results; in the geometric setting, the queried order need not itself belong to the target geometric class.

Proper learning and projection. Our geometric upper bound is also related to techniques developed for proper learning. Kane et al. [KLMY19] use a majority-vote construction together with a mechanism for replacing it by a hypothesis from the prescribed class. Bousquet et al. [BHMZ20] formalize this idea through the *projection number*, which quantifies when the predictions on which a majority has sufficiently large margin can be simultaneously realized by a hypothesis from the class. Related questions about the price of restricting online learners to proper or otherwise simple predictors are studied by Hanneke, Livni, and Moran [HLM21].

The same principle appears in our geometric upper bound. We first form pairwise predictions supported by an overwhelming weighted majority and then show, using the geometry of the ranking class, that these strong predictions can be extended to a valid linear order. The settings and analyses are different—in particular, the projection arguments above are used in realizable learning, whereas we apply the same general principle in the presence of boundedly many untruthful counterexamples—but the underlying idea is closely related.

Sorting under partial information and linear extensions. The use of convex geometry in the study of linear extensions goes back to Stanley [Sta81], who applied the Aleksandrov–Fenchel inequalities to obtain log-concavity results for linear extensions of posets. Kahn and Saks [KS84] subsequently proved that every non-total partial order contains a pair whose two possible orientations each occur in a constant fraction of its linear extensions. More precisely, they obtained the constant $3/11$. As a consequence, the information-theoretic lower bound for sorting under partial information is tight up to a constant factor. Simpler geometric proofs were later found by Kahn and Linial [KL91] and by Karzanov and Khachiyan [KK91]. Both are based on the Brunn–Minkowski theorem and give the weaker constants $1/(2e)$ in [KL91] and $1/e^2$ in [KK91].

This line of work is particularly relevant to our upper bound. The geometric representation of linear extensions by regions in the cube [Sta86], and the use of convex-geometric inequalities to find balanced pairs, are closely related to the argument we use in the truthful setting. Our treatment with untruthful counterexamples requires going beyond the uniform measure on the set of linear extensions: the algorithm maintains a non-uniform log-concave density and uses the log-concave form of Grünbaum’s theorem.

Sorting with noisy comparisons. There is also an extensive literature on sorting and related comparison problems when individual comparison outcomes may be erroneous [RMK⁺80, FRPU94, BM08]. The feedback model studied here is different: the learner does not choose a pair to compare, but instead proposes an entire ranking and the oracle chooses which pair to return as a counterexample. In particular, the main difficulty in our setting is not only robustness to noise, but also the requirement that the learner’s pairwise predictions form a coherent linear order.

4 Arbitrary Rankings

In this section we prove the upper and lower bounds for the unrestricted class of all rankings. We begin with the upper bound.

4.1 The Upper Bound

We first recall the geometric representation used in the proof overview. For a ranking π of $[n]$, let

$$\mathcal{C}_\pi := \{x \in (0, 1)^n : x_{\pi(1)} < x_{\pi(2)} < \cdots < x_{\pi(n)}\}.$$

We refer to $\mathcal{C}_\pi$ as the *cell* corresponding to π . Up to their measure-zero boundaries, the $n!$ cells partition the cube $[0, 1]^n$, and by symmetry they all have volume $1/n!$.

This representation is closely related to the convex-geometric approach to linear extensions initiated by Stanley [Sta81]. Kahn and Saks [KS84] used this approach to prove that every non-total partial order contains a pair whose two possible orientations each occur in a constant fraction of its linear extensions. Kahn and Linial [KL91] later gave a Brunn–Minkowski proof of the same conclusion, with a slightly weaker constant; a similar independent proof was given by Karzanov and Khachiyan [KK91].

We will use the following form of Grünbaum's theorem. Recall that a probability density p on $\mathbb{R}^n$ is *log-concave* if

$$p(\lambda x + (1 - \lambda)y) \geq p(x)^\lambda p(y)^{1-\lambda}$$

for every $x, y \in \mathbb{R}^n$ and $\lambda \in [0, 1]$. Equivalently, $\log p$ is concave on its support. In particular, the uniform distribution on any convex body is log-concave.

Theorem 4.1 (Grünbaum's inequality). *Let p be a log-concave probability density on $\mathbb{R}^n$, and let c denote its barycenter. Then every halfspace H containing c satisfies*

$$\Pr_{X \sim p}[X \in H] \geq \frac{1}{e}.$$

For the uniform distribution on a convex body, this is the classical inequality of Grünbaum [Grü60]. The formulation above for general log-concave densities follows, for example, from [LV07, Lemma 5.12].

When all counterexamples are truthful, one may simply maintain the convex body of points consistent with the feedback and query the ranking induced by its centroid. Grünbaum's theorem then gives constant-factor progress on every round; this is the argument discussed in Section 2 and is closely related to the classical Kahn–Saks approach [KS84]. We now turn directly to the additional ingredient needed in the presence of untruthful counterexamples.

The weighted update. Fix a sufficiently large universal constant $\gamma > 0$. We maintain a nonnegative density w_t on $[0, 1]^n$. Initially,

$$w_0(x) = 1.$$

Let

$$W_t := \int_{[0,1]^n} w_t(x) dx \quad \text{and} \quad p_t(x) := \frac{w_t(x)}{W_t}.$$

On round $t + 1$, let

$$c_t := \mathbb{E}_{X \sim p_t}[X]$$

be the barycenter of p_t , and query the ranking obtained by sorting the coordinates of c_t , breaking ties arbitrarily.

Suppose that the returned counterexample is $\{i, j\}$ and that the queried ranking places i before j . Thus

$$(c_t)_i \leq (c_t)_j.$$

Define

$$z_t(x) := x_j - x_i$$

and the surrogate loss

$$\ell_t(x) := (1 + \gamma n z_t(x))_+, \quad (a)_+ := \max\{a, 0\}.$$

We update

$$w_{t+1}(x) := w_t(x) e^{-\ell_t(x)}. \tag{1}$$

Importantly, the learner does not need to know the lie budget k in order to perform this update.

Log-concavity and decrease of the total mass. We first show that the update retains the geometric property needed to apply Grünbaum's theorem.

Lemma 4.2. *For every t , the density w_t is log-concave on $[0, 1]^n$.*

Proof. The initial density is uniform on the convex set $[0, 1]^n$, and is therefore log-concave. Moreover, z_t is affine, so

$$x \mapsto (1 + \gamma n z_t(x))_+$$

is convex. Hence $-\ell_t$ is concave, and multiplying a log-concave density by $e^{-\ell_t}$ preserves log-concavity. $\square$

The next lemma is the analogue of the usual weighted-majority progress bound.

Lemma 4.3. *There is a universal constant $\rho < 1$ such that*

$$W_{t+1} \leq \rho W_t$$

on every round.

Proof. Let

$$H_t := \{x : z_t(x) \geq 0\} = \{x : x_i \leq x_j\}.$$

By construction, $c_t \in H_t$. Since p_t is log-concave, Theorem 4.1 gives

$$p_t(H_t) \geq \frac{1}{e}.$$

For every $x \in H_t$, we have $\ell_t(x) \geq 1$, and hence

$$e^{-\ell_t(x)} \leq e^{-1}.$$

Consequently,

$$\begin{aligned} \frac{W_{t+1}}{W_t} &= \mathbb{E}_{X \sim p_t} [e^{-\ell_t(X)}] \\ &\leq p_t(H_t) e^{-1} + (1 - p_t(H_t)) \\ &\leq 1 - \frac{1 - e^{-1}}{e}. \end{aligned}$$

Thus the claim holds with

$$\rho := 1 - \frac{1 - e^{-1}}{e} < 1.$$

$\square$

It follows that after T counterexamples,

$$W_T \leq \rho^T. \tag{2}$$

The mass of the target cell. Let π^* be the target ranking and let

$$\mathcal{C}^* := \mathcal{C}_{\pi^*}$$

be its cell. Define

$$M_T := \int_{\mathcal{C}^*} w_T(x) dx.$$

The key point is that, although the density becomes non-uniform inside $\mathcal{C}^*$, its total mass cannot decrease too quickly.

Let Q denote the uniform distribution on $\mathcal{C}^*$. Since $\text{vol}(\mathcal{C}^*) = 1/n!$, iterating (1) gives

$$\begin{aligned} M_T &= \frac{1}{n!} \mathbb{E}_{X \sim Q} \left[\exp \left(- \sum_{t=0}^{T-1} \ell_t(X) \right) \right] \\ &\geq \frac{1}{n!} \exp \left(- \sum_{t=0}^{T-1} \mathbb{E}_{X \sim Q} [\ell_t(X)] \right), \end{aligned} \quad (3)$$

where the inequality follows from Jensen's inequality.

We next bound the expected loss in a truthful and in an untruthful round.

Lemma 4.4. *Let $\gamma > 0$ be the universal constant fixed in the weighted update above. For X uniform on $\mathcal{C}^*$:*

(i) *on a truthful round,*

$$\mathbb{E}[\ell_t(X)] \leq \frac{1}{\gamma};$$

(ii) *on an untruthful round,*

$$\mathbb{E}[\ell_t(X)] \leq 1 + \gamma n.$$

Proof. Suppose, as above, that the query places i before j .

Consider first a truthful round. The target then places j before i . Thus, throughout $\mathcal{C}^*$,

$$X_j < X_i.$$

Write

$$D := X_i - X_j > 0.$$

Then

$$\ell_t(X) = (1 - \gamma n D)_+. \quad (4)$$

A uniformly random point in any ranking cell has the same distribution, after permuting its coordinates, as the order statistics of n independent uniform random variables on $[0, 1]$. More explicitly, if $U_1, \dots, U_n$ are independent and uniform on $[0, 1]$, and

$$U_{(1)} < U_{(2)} < \dots < U_{(n)}$$

are these random variables arranged in increasing order, then $(U_{(1)}, \dots, U_{(n)})$ is uniformly distributed over the cell

$$\{0 < x_1 < \dots < x_n < 1\}.$$

We use a standard fact about the spacings between uniform order statistics [Pyk65]. The $n+1$ gaps

$$U_{(1)}, U_{(2)} - U_{(1)}, \dots, U_{(n)} - U_{(n-1)}, 1 - U_{(n)}$$

are jointly uniform over the simplex of nonnegative vectors whose coordinates sum to one (equivalently, they have the Dirichlet(1, ..., 1) distribution). In particular, every individual gap G satisfies

$$\Pr(G \leq s) = 1 - (1 - s)^n \leq ns, \quad 0 \leq s \leq 1. \quad (5)$$

The difference $D = X_i - X_j$ is a sum of one or more consecutive spacings. Choose any one spacing G appearing in this sum. Since $D \geq G$, (4) and (5) give

$$\begin{aligned} \mathbb{E}[\ell_t(X)] &\leq \Pr \left(D \leq \frac{1}{\gamma n} \right) \\ &\leq \Pr \left(G \leq \frac{1}{\gamma n} \right) \leq \frac{1}{\gamma}. \end{aligned}$$

On an untruthful round, the target agrees with the query on $\{i, j\}$, and hence $0 < X_j - X_i < 1$ throughout $\mathcal{C}^*$. Thus,

$$\ell_t(X) = 1 + \gamma n(X_j - X_i) \leq 1 + \gamma n.$$

□

Suppose now that among the first T returned counterexamples at most k are untruthful. Lemma 4.4 and (3) give

$$M_T \geq \frac{1}{n!} \exp\left(-\frac{T}{\gamma} - k(1 + \gamma n)\right). \quad (6)$$

Completing the proof. Since the target cell is contained in the cube,

$$M_T \leq W_T.$$

Combining (2) and (6),

$$\frac{1}{n!} \exp\left(-\frac{T}{\gamma} - k(1 + \gamma n)\right) \leq \rho^T.$$

Let

$$\alpha := -\log \rho > 0.$$

Taking logarithms and rearranging gives

$$\left(\alpha - \frac{1}{\gamma}\right) T \leq \log(n!) + k(1 + \gamma n).$$

Choose the universal constant γ sufficiently large that $1/\gamma \leq \alpha/2$. Then

$$T = O(\log(n!) + nk) = O(n \log n + nk).$$

Thus the oracle cannot return counterexamples for more than $O(n \log n + nk)$ rounds; by that time the learner must have proposed the target ranking. The algorithm is deterministic, proper, and its definition does not use k . This proves the upper bound.

4.2 The Lower Bound

We now prove the matching lower bound. The two terms have different origins. The $\Omega(n \log n)$ term is already necessary when all counterexamples are truthful and follows from a sorting argument. The $\Omega(nk)$ term captures the additional cost of untruthful counterexamples and is based on a Condorcet cycle.

Theorem 4.5. *For every $n \geq 3$ and $k \geq 0$, every possibly randomized proper learner for arbitrary rankings has worst-case expected query complexity*

$$\Omega(n \log n + nk).$$

Proof. We prove the two terms separately.

We first establish the $\Omega(n \log n)$ lower bound using only truthful counterexamples. For simplicity assume that n is a power of two; for general n , we may restrict attention to the largest power of two below n . Consider the comparison tree induced by MergeSort. Every root-to-leaf path in this tree has length

$$D = \Omega(n \log n).$$

Indeed, at every level of the recursion, merging pairs of equal-size lists requires altogether $\Omega(n)$ comparisons, and there are $\Theta(\log n)$ levels.

Choose a random root-to-leaf branch of this tree by choosing each of the two children with probability $1/2$ at every internal node. The resulting leaf determines a target ranking π^* , which is thus fixed before the interaction begins.

We describe a truthful oracle for this target. The oracle maintains a current node on the chosen branch, initially the root. Suppose that the learner proposes a ranking π . If π disagrees with the outcome of some comparison on the portion of the branch already traversed, the oracle may simply return such a comparison as a truthful counterexample.

Otherwise, starting from the current node, the oracle follows the chosen branch down the comparison tree. As long as π agrees with the outcome of the comparison at the current node, the oracle proceeds to the next node without returning anything. At the first comparison on which π disagrees with the chosen branch, the oracle returns that pair as a counterexample and makes this node part of the traversed portion of the branch. If no such comparison is encountered before reaching the leaf, then π agrees with every comparison on the root-to-leaf path and hence $\pi = \pi^*$; the oracle then declares the ranking correct.

All counterexamples produced by this strategy are truthful. We now bound how quickly a learner can move down the random branch. Let A_t denote the number of previously untraversed edges of the comparison tree that are traversed on the t -th query. If the learner contradicts an earlier comparison then $A_t = 0$. Otherwise, conditional on everything that has happened so far and on the learner's current query, every new branch choice encountered by the oracle is still an independent fair choice between the two children. At each such node, the learner's ranking prescribes one of the two possible outcomes. Hence it agrees with the random branch with probability $1/2$, and disagrees with probability $1/2$.

Consequently, A_t is dominated by a geometric random variable with mean 2, and therefore

$$\mathbb{E}[A_t \mid \text{history before query } t] \leq 2.$$

This remains true when the learner is randomized, since we may condition also on its internal randomness up to this point.

Let Q be the number of queries made before the target is identified. By the time the interaction terminates, the entire root-to-leaf path has been traversed, so

$$\sum_{t=1}^Q A_t \geq D.$$

Therefore

$$\begin{aligned} D &\leq \mathbb{E} \left[\sum_{t=1}^Q A_t \right] \\ &= \sum_{t \geq 1} \mathbb{E} [\mathbf{1}_{\{Q \geq t\}} A_t] \\ &\leq 2 \sum_{t \geq 1} \Pr(Q \geq t) = 2\mathbb{E}[Q]. \end{aligned}$$

Thus

$$\mathbb{E}[Q] \geq D/2 = \Omega(n \log n),$$

where the expectation is over both the random branch and the learner's randomness. Averaging over the choice of the branch, there must therefore exist a fixed branch, and hence a fixed target ranking π^* , for which the learner requires $\Omega(n \log n)$ queries in expectation.

We next establish the $\Omega(nk)$ term. Consider the directed cycle

$$1 \rightarrow 2 \rightarrow \cdots \rightarrow n \rightarrow 1,$$

and denote its edges by $e_1, \dots, e_n$. For each $r \in [n]$, let σ_r be the linear order obtained by deleting e_r from the cycle and taking the resulting directed path as the order. Thus σ_r agrees with every cycle edge except e_r .

Every linear order π violates at least one edge of the cycle. Moreover, if π violates e_r and the oracle returns this pair, then the counterexample is truthful with respect to every σ_s , $s \neq r$, and untruthful with respect to σ_r .

Define a reference interaction that does not depend on the target. Whenever the learner proposes a ranking π , choose, according to any fixed rule, one cycle edge violated by π and return it. For example, choose the violated edge of smallest index. This produces an infinite sequence of edges

$$e_{r_1}, e_{r_2}, \dots$$

that depends on the learner's randomness, but not on the choice of the target.

For each $r \in [n]$, let τ_r be the round on which e_r is returned for the $(k+1)$ -st time in this reference interaction, with $\tau_r = \infty$ if this never occurs. Let

$$\tau_{(1)} \leq \tau_{(2)} \leq \cdots \leq \tau_{(n)}$$

be these values arranged in increasing order. Then

$$\tau_{(j)} \geq j(k+1), \quad j = 1, \dots, n. \quad (21)$$

Indeed, by round $\tau_{(j)}$, at least j distinct cycle edges have each been returned at least $k+1$ times, so at least $j(k+1)$ counterexamples must have been returned in total. Consequently,

$$\frac{1}{n} \sum_{r=1}^n \tau_r \geq \frac{1}{n} \sum_{j=1}^n j(k+1) = \frac{(n+1)(k+1)}{2}. \quad (22)$$

If some $\tau_r = \infty$, this inequality is immediate.

Now choose R uniformly from $[n]$, independently of the learner, and set

$$\pi^\star = \sigma_R.$$

Thus the target is fixed before the interaction begins.

We define an oracle for this target by following the reference interaction until round τ_R . Before this round, the edge e_R has been returned at most k times. Each occurrence of e_R is an untruthful counterexample with respect to σ_R , while every other returned cycle edge is truthful. Hence all these responses are valid and use at most k untruthful counterexamples.

On round τ_R , the reference rule is about to return e_R for the $(k+1)$ -st time. If the learner's query is σ_R , the oracle declares it correct. Otherwise, the query violates some cycle edge other than e_R , and the oracle returns such an edge instead; this counterexample is truthful. Indeed, a ranking whose only violated cycle edge is e_R must be exactly σ_R . From this point on, whenever the learner proposes a ranking different from σ_R , the oracle may return any truthful counterexample, and it declares the ranking correct when σ_R is proposed. Thus this defines a valid oracle using at most k untruthful counterexamples.

Let Q denote the number of queries before the interaction terminates. Under the coupling above, the learner cannot terminate before round τ_R , and therefore

$$Q \geq \tau_R.$$

Taking expectation over both the random choice of R and the learner's internal randomness, and using (22), gives

$$\begin{aligned}\mathbb{E}[Q] &\geq \mathbb{E}[\tau_R] \\ &= \mathbb{E}\left[\frac{1}{n} \sum_{r=1}^n \tau_r\right] \\ &\geq \frac{(n+1)(k+1)}{2} = \Omega(nk).\end{aligned}$$

Averaging over R , there is therefore some fixed target σ_R for which the expected number of queries, over the learner's randomness, is $\Omega(nk)$.

We have proved that the worst-case expected query complexity of every randomized proper learner is both $\Omega(n \log n)$ and $\Omega(nk)$. Consequently,

$$\max\{\Omega(n \log n), \Omega(nk)\} = \Omega(n \log n + nk),$$

up to a universal constant. □

5 Geometric Rankings

We now turn to ranking classes with a low-dimensional geometric representation. Let $\mathcal{H}$ be a class of rankings of $[n]$ for which there exist vectors

$$v_1, \dots, v_n \in \mathbb{R}^d$$

such that every $\pi \in \mathcal{H}$ is induced by some direction $w \in \mathbb{R}^d$: namely,

$$i \prec_\pi j \iff \langle v_i, w \rangle < \langle v_j, w \rangle.$$

We consider only directions that induce strict linear orders.

5.1 The Upper Bound

Let $\mathcal{H}$ be a d -dimensional geometric class of rankings over $[n]$, represented by vectors

$$v_1, \dots, v_n \in \mathbb{R}^d.$$

Thus every $\pi \in \mathcal{H}$ is induced by some direction $w \in \mathbb{R}^d$, in the sense that

$$i \prec_\pi j \iff \langle v_i, w \rangle < \langle v_j, w \rangle.$$

We consider only directions that induce strict linear orders.

The algorithm is based on weighted majority. The key point is that, although the pairwise weighted-majority predictions may not themselves form a linear order, sufficiently strong majorities are always acyclic in a d -dimensional geometric class. We can therefore complete them to a genuine linear order. This queried order need not itself belong to $\mathcal{H}$.

Theorem 5.1. *Every d -dimensional geometric class $\mathcal{H}$ of rankings over n items can be learned using*

$$O(d^2 \log n + dk)$$

queries in the presence of at most k untruthful counterexamples. Every query made by the learner is a linear order, but need not belong to $\mathcal{H}$. The learner is deterministic and does not need to know k .

Proof. We maintain a weight $q_t(\pi)$ for every ranking $\pi \in \mathcal{H}$. Initially,

$$q_0(\pi) = 1 \quad \text{for every } \pi \in \mathcal{H}.$$

Let

$$Q_t := \sum_{\pi \in \mathcal{H}} q_t(\pi),$$

and let P_t be the probability distribution on $\mathcal{H}$ obtained by normalizing these weights:

$$P_t(\pi) := \frac{q_t(\pi)}{Q_t}. \quad (13)$$

Thus, when we write

$$\Pi_t \sim P_t,$$

we mean that Π_t is a random ranking from $\mathcal{H}$, sampled according to the current normalized weights.

For two distinct items i, j , define

$$p_t(i, j) := \Pr_{\Pi_t \sim P_t} [i \prec_{\Pi_t} j]. \quad (14)$$

Since every ranking is a linear order,

$$p_t(i, j) + p_t(j, i) = 1.$$

We form a directed graph G_t on the n items by putting an edge $i \rightarrow j$ whenever

$$p_t(i, j) > 1 - \frac{1}{d+1}. \quad (15)$$

Thus G_t contains the comparisons supported by an overwhelming majority of the current weight. The main geometric observation is that this relation cannot contain a directed cycle.

Lemma 5.2. *The directed graph G_t is acyclic.*

Proof. Suppose, towards a contradiction, that G_t contains a directed cycle

$$i_1 \rightarrow i_2 \rightarrow \cdots \rightarrow i_m \rightarrow i_1.$$

For each edge of the cycle, define

$$a_r := v_{i_{r+1}} - v_{i_r}, \quad r = 1, \dots, m,$$

where $i_{m+1} := i_1$. These vectors telescope, and hence

$$\sum_{r=1}^m a_r = 0.$$

In particular,

$$0 \in \text{conv}\{a_1, \dots, a_m\}.$$

By Carathéodory's theorem [Mat02], there is a set $R \subseteq [m]$ with

$$|R| \leq d+1$$

and coefficients $\lambda_r > 0$, $r \in R$, such that

$$\sum_{r \in R} \lambda_r = 1 \quad \text{and} \quad \sum_{r \in R} \lambda_r a_r = 0. \quad (16)$$

Here we have simply discarded the indices with zero coefficient.

Now sample a ranking

$$\Pi_t \sim P_t$$

according to the current normalized weights. For every $r \in R$, the edge $i_r \rightarrow i_{r+1}$ belongs to G_t , so by (15),

$$\Pr[i_r \prec_{\Pi_t} i_{r+1}] > 1 - \frac{1}{d+1}.$$

Equivalently,

$$\Pr[i_{r+1} \prec_{\Pi_t} i_r] < \frac{1}{d+1}.$$

Since $|R| \leq d+1$, the union bound gives

$$\begin{aligned} & \Pr[i_r \prec_{\Pi_t} i_{r+1} \text{ for every } r \in R] \\ & \geq 1 - \sum_{r \in R} \Pr[i_{r+1} \prec_{\Pi_t} i_r] > 0. \end{aligned}$$

Therefore there exists at least one ranking $\pi \in \mathcal{H}$ satisfying all the comparisons

$$i_r \prec_{\pi} i_{r+1}, \quad r \in R.$$

Since $\pi \in \mathcal{H}$, it is induced by some direction $w \in \mathbb{R}^d$. Hence, for every $r \in R$,

$$\langle v_{i_r}, w \rangle < \langle v_{i_{r+1}}, w \rangle,$$

and therefore

$$\langle a_r, w \rangle > 0.$$

Multiplying by $\lambda_r > 0$ and summing gives

$$\left\langle \sum_{r \in R} \lambda_r a_r, w \right\rangle > 0,$$

contradicting (16). Thus G_t is acyclic. □

Since G_t is acyclic, it has a linear extension. The learner chooses any such extension $\hat{\pi}_t$ and queries it. Notice that $\hat{\pi}_t$ is a genuine linear order, but need not belong to $\mathcal{H}$.

The choice of threshold in (15) ensures that every comparison made by $\hat{\pi}_t$ still has noticeable support under the current weighted distribution.

Lemma 5.3. *If $\hat{\pi}_t$ places i before j , then*

$$p_t(i, j) \geq \frac{1}{d+1}.$$

Proof. Suppose instead that

$$p_t(i, j) < \frac{1}{d+1}.$$

Then

$$p_t(j, i) = 1 - p_t(i, j) > 1 - \frac{1}{d+1},$$

so G_t contains the edge $j \rightarrow i$. This contradicts the fact that $\hat{\pi}_t$ is a linear extension of G_t . □

Suppose now that the oracle returns the pair $\{i, j\}$, and orient the notation so that $\hat{\pi}_t$ places i before j . We perform the standard weighted-majority update [LW94]:

$$q_{t+1}(\pi) := \begin{cases} \frac{1}{2}q_t(\pi), & \text{if } i \prec_{\pi} j, \\ q_t(\pi), & \text{if } j \prec_{\pi} i. \end{cases} \quad (17)$$

Thus we halve the weight of precisely those rankings in $\mathcal{H}$ that agree with the learner's proposed order on the returned pair.

By Lemma 5.3, these rankings carry at least a $1/(d+1)$ fraction of the total weight. Therefore

$$\begin{aligned} Q_{t+1} &\leq \left(1 - \frac{1}{d+1}\right) Q_t + \frac{1}{2} \frac{1}{d+1} Q_t \\ &= \left(1 - \frac{1}{2(d+1)}\right) Q_t. \end{aligned}$$

Hence

$$Q_{t+1} \leq \left(1 - \frac{1}{2(d+1)}\right) Q_t. \quad (18)$$

This decrease occurs on every round, regardless of whether the returned counterexample is truthful.

Consider now the target ranking $\pi^* \in \mathcal{H}$. On a truthful round, π^* disagrees with the learner on the returned pair, so its weight is unchanged. On an untruthful round, π^* agrees with the learner on that pair, so its weight is halved. Consequently, after T rounds containing at most k untruthful counterexamples,

$$q_T(\pi^*) \geq 2^{-k}. \quad (19)$$

It remains to bound the initial total weight

$$Q_0 = |\mathcal{H}|.$$

For every pair $\{i, j\}$, its relative order under a direction w is determined by the sign of

$$\langle v_i - v_j, w \rangle.$$

Thus every ranking in $\mathcal{H}$ corresponds to a full-dimensional cell in the arrangement of the

$$N := \binom{n}{2}$$

hyperplanes

$$\langle v_i - v_j, w \rangle = 0, \quad 1 \leq i < j \leq n.$$

All these hyperplanes pass through the origin. A central arrangement of N hyperplanes in $\mathbb{R}^d$ has at most

$$2 \sum_{r=0}^{d-1} \binom{N-1}{r}$$

full-dimensional cells [Mat02]. Since here $N = \binom{n}{2}$, we obtain

$$|\mathcal{H}| \leq 2 \sum_{r=0}^{d-1} \binom{\binom{n}{2} - 1}{r} = n^{O(d)},$$

and hence

$$\log |\mathcal{H}| = O(d \log n). \quad (20)$$

Finally, since

$$q_T(\pi^\star) \leq Q_T,$$

iterating (18) and using (19) gives

$$2^{-k} \leq Q_T \leq |\mathcal{H}| \left(1 - \frac{1}{2(d+1)}\right)^T.$$

Taking logarithms yields

$$T \left(-\log \left(1 - \frac{1}{2(d+1)}\right) \right) \leq \log |\mathcal{H}| + k \log 2.$$

Using

$$-\log(1-x) \geq x \quad (0 < x < 1),$$

we conclude that

$$T \leq 2(d+1)(\log |\mathcal{H}| + k \log 2).$$

Together with (20), this gives

$$T = O(d^2 \log n + dk).$$

Since the learner does not use k , this completes the proof. $\square$

A centerpoint alternative and geometric realizability. The same upper bound can alternatively be obtained from the weighted centerpoint theorem [Mat02]. This approach is closely analogous to the Grünbaum-based algorithm for unrestricted rankings. For every $\pi \in \mathcal{H}$, choose a unit direction $w_\pi \in \mathbb{R}^d$ that realizes π , and place mass $q_t(\pi)$ at w_π . Let c_t be a weighted centerpoint of this discrete measure, and query the ranking induced by a generic direction sufficiently close to c_t , chosen only to break possible ties among the projections at c_t .

For every pair oriented by this order, the corresponding closed halfspace of directions contains c_t . The centerpoint theorem therefore implies that this halfspace contains at least a $1/(d+1)$ fraction of the current weight. Consequently, if the oracle returns this pair, halving the weights of the rankings that agree with the query decreases the total weight by a factor of at most

$$1 - \frac{1}{2(d+1)}.$$

The target weight is halved only on untruthful rounds. Since $\log |\mathcal{H}| = O(d \log n)$, the usual weighted-majority calculation again gives

$$O(d^2 \log n + dk)$$

queries.

This alternative has the additional feature that every query is induced by a direction in the given geometric representation. Thus, if $\mathcal{H}$ consists of all rankings induced by this representation, the learner is proper in the usual sense. Under our more general convention, where $\mathcal{H}$ may be an arbitrary subclass of the rankings induced by the representation, the queried ranking need not itself belong to $\mathcal{H}$, but it is always geometrically realizable.

This property may also be useful from a practical perspective. In the restaurant example from the introduction, a geometrically realizable ranking is specified by only d coefficients, one for each feature. Such a representation may be more convenient to evaluate at prediction time and can also offer a degree of interpretability, since the coefficients indicate the relative importance assigned to the different features.

The parallel with the unrestricted algorithm is that there the learner queries the ranking induced by the barycenter of a log-concave measure and uses Grünbaum's theorem to control the mass of every relevant halfspace, whereas here the barycenter is replaced by a centerpoint of the discrete weighted measure on realizing directions.

5.2 The Lower Bound

We now prove the lower bound for geometric ranking classes. In fact, a single natural class—rankings induced by low-degree polynomials—already gives all the terms in the lower bound.

Theorem 5.4. *For every $2 \leq d \leq n$, there is a d -dimensional geometric class of rankings over n items for which every possibly randomized learner whose queries are linear orders has worst-case expected query complexity*

$$\Omega(d \log n + dk)$$

in the presence of at most k untruthful counterexamples.

Proof. Identify the n items with the points $1, \dots, n$ on the real line, and let $\mathcal{P}_{n,d}$ be the class of rankings obtained by ordering these points according to the values of a polynomial p of degree at most d . We restrict to polynomials for which

$$p(1), \dots, p(n)$$

are all distinct.

This is a d -dimensional geometric class. Indeed, writing

$$p(x) = a_0 + a_1x + \dots + a_dx^d,$$

the constant term does not affect the ranking, and

$$p(i) = a_0 + \langle (i, i^2, \dots, i^d), (a_1, \dots, a_d) \rangle.$$

Thus $\mathcal{P}_{n,d}$ is represented by the points

$$v_i = (i, i^2, \dots, i^d) \in \mathbb{R}^d$$

on the moment curve.

We first observe that $\mathcal{P}_{n,d}$ already inherits the unrestricted lower bounds on d items. Fix any set S of d items. Every linear order on S can be realized by a polynomial of degree at most $d - 1$: assign distinct real values to the points of S in the desired order and interpolate a polynomial through them.

Consequently, the two adversaries from Theorem 4.5 may be applied using only comparisons between items in S . The resulting target ranking can always be chosen from $\mathcal{P}_{n,d}$. Hence every learner for $\mathcal{P}_{n,d}$ has worst-case expected query complexity at least

$$\Omega(d \log d + dk). \tag{23}$$

It remains to obtain the dependence on n in the noiseless term. We show that, when n is sufficiently larger than d ,

$$\Omega(d \log(n/d)) \tag{24}$$

truthful counterexamples may be necessary.

Let

$$m := d - 1.$$

Choose a power of two

$$M = \Theta(n/d),$$

and choose m disjoint blocks $B_1, \dots, B_m$ of consecutive items, ordered from left to right, each containing $\Theta(M)$ items. Within each block B_r , choose M possible locations for a root of the derivative, separated by a constant distance. For example, we may take

$$a_{r,s} = b_r + 2s + \frac{1}{2}, \quad s = 0, \dots, M - 1,$$

where the integers b_r are chosen so that all these points lie in B_r .

For every

$$\mathbf{s} = (s_1, \dots, s_m) \in \{0, \dots, M-1\}^m,$$

define

$$q_{\mathbf{s}}(x) := \prod_{r=1}^m (x - a_{r,s_r}),$$

and let $p_{\mathbf{s}}$ be an antiderivative of $q_{\mathbf{s}}$. Thus

$$p'_{\mathbf{s}} = q_{\mathbf{s}},$$

and $p_{\mathbf{s}}$ has degree $m+1 = d$. Its derivative has exactly one simple zero in each block B_r , namely a_{r,s_r} . Equivalently, $p_{\mathbf{s}}$ has one turning point in each block, whose location can be chosen among M possibilities.

We now construct a balanced comparison tree that determines these roots one at a time. Consider a block B_r , and suppose that the possible values of s_r currently form a consecutive interval. Split this interval into two equal halves, say between q and $q+1$. By the choice of the candidate locations, there are two consecutive items $j, j+1$ lying strictly between $a_{r,q}$ and $a_{r,q+1}$.

For $x \in [j, j+1]$, all factors

$$x - a_{\ell,s_{\ell}}, \quad \ell \neq r,$$

have signs that are independent of the choices of $s_1, \dots, s_m$: the corresponding roots lie in blocks entirely to the left or entirely to the right of B_r . On the other hand, the sign of

$$x - a_{r,s_r}$$

depends on which half contains s_r . If $s_r \leq q$, then $a_{r,s_r} < j$, whereas if $s_r \geq q+1$, then $a_{r,s_r} > j+1$. Consequently, the sign of $p'_{\mathbf{s}}(x)$ throughout $[j, j+1]$ is opposite in the two cases. Therefore the sign of $p_{\mathbf{s}}(j+1) - p_{\mathbf{s}}(j)$ is also opposite. In other words, the relative order of the two consecutive items j and $j+1$ determines which half contains the root of $p'_{\mathbf{s}}$ in B_r .

Thus the location of the root in each block can be determined by a balanced binary search of depth $\log_2 M$. Performing these searches successively for the $m = d-1$ blocks gives a comparison tree in which every root-to-leaf path has depth

$$(d-1) \log_2 M = \Omega(d \log(n/d)).$$

Each leaf specifies one root location in every block and hence a degree- d polynomial $p_{\mathbf{s}}$ consistent with every comparison along the corresponding path.

Finally, apply the same random-branch argument as in the sorting lower bound. Choose the hidden branch of this comparison tree by choosing each child independently and uniformly, and fix a polynomial ranking associated with the resulting leaf as the target. On each query, the oracle follows the hidden branch until reaching the first comparison on which the learner's proposed order disagrees, and returns this pair as a truthful counterexample.

Conditional on the entire interaction so far, each newly encountered branch is still a fair independent choice. Hence a single query traverses at most two new edges of the hidden branch in expectation. Since the branch has depth

$$\Omega(d \log(n/d)),$$

the expected number of queries is

$$\Omega(d \log(n/d)).$$

Averaging over the random choice of the target, there is therefore a fixed polynomial ranking for which every randomized learner requires this many queries in expectation. This proves (24). $\square$

6 Open Questions and Future Directions

Our results leave several natural questions open.

Geometric ranking classes. Perhaps the most immediate question concerns geometric ranking classes. For a d -dimensional geometric class over n items, we prove an upper bound of

$$O(d^2 \log n + dk)$$

and a lower bound of

$$\Omega(d \log n + dk).$$

Thus the dependence on the number of untruthful counterexamples is tight, while a factor of d remains in the noiseless term. It would be interesting to determine whether the upper bound can be improved to $O(d \log n + dk)$, or whether there are geometric classes requiring $\Omega(d^2 \log n)$ queries.

Starting from partial information. Another natural extension is to assume that some comparisons are known in advance. In the recommendation-system example, for instance, the user may have already specified preferences between certain pairs of restaurants. More abstractly, the known comparisons form a poset P , and the unknown target ranking is one of its L linear extensions.

In the truthful setting, the optimal deterministic query complexity in this more general problem is $\Theta(\log L)$. The upper bound follows from essentially the same geometric argument used above, applied to the order polytope of P . For the lower bound, recall the theorem of Kahn and Saks: whenever P is not already a total order, there is an incomparable pair i, j such that at least a $3/11$ fraction of the linear extensions place i before j , and at least a $3/11$ fraction place j before i . Applying this theorem recursively gives a balanced comparison tree for the L linear extensions: at every internal node we compare such a pair and restrict to the linear extensions consistent with the chosen orientation. Since either child retains at least a $3/11$ fraction of the current linear extensions, every root-to-leaf path has depth $\Omega(\log L)$. The same random-branch argument used in our lower bound for unrestricted rankings then implies that $\Omega(\log L)$ queries are necessary.

The situation becomes less clear when untruthful counterexamples are allowed. Let x denote the width of P (i.e. the largest possible size of an antichain in P). A maximum antichain of size x gives, by applying our Condorcet-cycle construction to these items, the lower bound

$$\Omega(\log L + xk).$$

On the other hand, the strong-majority argument used above can be adapted to give

$$O(x(\log L + k)).$$

This upper bound is not always tight: when P is an antichain, $x = n$ and $L = n!$, whereas our main result gives the sharper bound

$$\Theta(\log L + xk) = \Theta(n \log n + nk).$$

It would be interesting to characterize, up to constant factors, the optimal query complexity for every starting poset P and every k . In particular, it is not clear whether this complexity is determined by L and x alone, or whether additional structural parameters of the poset are needed.

Optimal constants for unrestricted rankings. Even for unrestricted rankings, where our bounds are tight up to constant factors, the precise query complexity remains open. In particular, it would be interesting to determine the optimal constants in front of the $n \log n$ and nk terms. The two terms arise from rather different phenomena—sorting in the noiseless case and the Condorcet-cycle construction in the noisy case—and it is not clear whether a single optimal strategy can simultaneously achieve the best constants for both.

Computational efficiency. In this work we focus on query complexity and do not develop fully efficient implementations of our algorithms. As discussed above, the log-concave distributions arising in the unrestricted upper bound can in principle be sampled using standard random-walk methods, allowing the relevant barycenters to be approximated in randomized polynomial time. It would be useful to make this implementation explicit and to understand its computational complexity more precisely. More ambitiously, we would like to find efficient combinatorial algorithms for these problems. Such algorithms might also lead to more direct proofs of our upper bounds, avoiding the use of Grünbaum’s theorem and perhaps shedding new light on the classical balanced-pair phenomenon for linear extensions.

Richer noise models. Our noise model is deliberately simple: we only assume that the total number of untruthful counterexamples is bounded. A natural next step is to study richer stochastic noise models. For example, fix $p < 1/2$ and suppose that on each round, conditional on the entire history, the oracle may return an arbitrary untruthful counterexample with probability at most p , while otherwise its response must be truthful. It would be interesting to determine the optimal query complexity in this model and whether our weighted approach extends to it. One could also consider feedback generated from an underlying preference model, such as Bradley–Terry [BT52]. The methods developed here may extend to some such settings, but a systematic study remains open.

AI disclosure

ChatGPT was used in several stages of the preparation of this paper. First, GPT-5.6 Sol with Extra High reasoning was used for editing and drafting the manuscript, as well as for checking references and searching for additional related work. Second, GPT-5.6 Sol with Extra High reasoning was used to assist with calculations and verification surrounding the surrogate log-concave update used in the upper bound for unrestricted rankings. Finally, GPT-5.6 Sol Pro was asked to investigate the open questions suggested by this work. It made some progress on improving constants and suggested several possible approaches, but did not resolve any of these questions. All mathematical arguments and claims appearing in the paper were found and checked by the authors and are their responsibility.

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